

SCHOOL OF ELECTRICAL ENGINEERING

M. Tech Power Electronics and Drives

(M.Tech MPE)

Curriculum (2022-2023 admitted students)



VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research.

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international industries & universities for productivity and economic development.

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

To be a leader for academic excellence in the field of electrical, instrumentation and control engineering imparting high quality education and research leading to global competence for the societal and industrial developments.

MISSION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

- Impart high quality education and interdisciplinary research by providing conducive teaching learning environment and team spirit resulting in innovation and product development.
- Enhance the core competency of the students to cater to the needs of the industries and society by providing solutions in the field of electrical, electronics, instrumentation and automation engineering.
- Develop analytical skills, leadership quality and team spirit through balanced curriculum.



PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

- 1. Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems.
- 2. Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry.
- 3. Graduates will function in their profession with social awareness and responsibility.
- 4. Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country.
- 5. Graduates will be successful in pursuing higher studies in engineering or management.
- 6. Graduates will pursue career paths in teaching or research.



PROGRAMME OUTCOMES (POs)

PO_01: Having an ability to apply mathematics and science in engineering applications.

PO_02: Having an ability to design a component or a product applying all the relevant standards and with realistic constraints

PO_03: Having an ability to design and conduct experiments, as well as to analyze and interpret data

PO_04: Having an ability to use techniques, skills and modern engineering tools necessary for engineering practice

PO_05: Having problem solving ability- solving social issues and engineering problems

PO_06: Having adaptive thinking and adaptability

PO_07: Having a clear understanding of professional and ethical responsibility

PO_08: Having a good cognitive load management [discriminate and filter the available data] skills



PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of M. Tech. (Power Electronics and Drives) programme, graduates will be able to

- PSO1: Apply technical knowledge, skills and analytical ability to design, develop and test power electronic converters and drives using modern tools and technologies.
- PSO2: Solve the real world problems in the emerging fields like smart grid, renewable energy interfaces, and electric vehicles and to develop innovative technologies relevant to social, ethical, economic and environmental issues
- PSO3: Solve research gaps and provide solutions to socioeconomic, and environmental problems.



CREDIT STRUCTURE

Category-wise Credit distribution

NEW (CREDIT STRUCTURE	CREDITS			
Core C	Core Courses				
Discip	line Elective Courses	12			
(3 Cre	(3 Credits/Elective Course)				
Open	Open Elective Courses				
Skill Er	nhansement courses	5			
1.	Technical report writing-2				
2.	Qualitative Skills Practice -1.5				
3.	Quantitative Skills Practice- 1.5				
Projec	t/ Internship	26			
1.	Study oriented project-2				
2.	Design Project-2				
3.	Internship/Dissertation I-10				
4.	Internship/Dissertation II-22				
Total	Graded Credit Requirement	70			



DETAILED CURRICULUM

Discipline Core

S. No.	Course Code	Course Title	L	Т	Р	C
1	MPED501L	Advanced Semiconductor Devices	3	0	0	3
2	MPED502L	Analysis of Power Converters	3	0	0	3
	MPED502P	Analysis of Power Converters	0	0	2	1
3	MPED503L	Switched Mode Power Supplies	2	0	0	2
4	MPED504L	Generalized Machine Theory	3	1	0	4
5	MPED505L	Industrial Electrical Drives	3	0	0	3
	MPED505P	Industrial Electrical Drives	0	0	2	1
6	MPED506L	Special Machines and Control	3	0	0	3
7	MPED507L	Advanced Processors for Power Converters	3	0	0	3
	MPED507P	Advanced Processors for Power Converters	0	0	2	1
		Total Credits				24



Discipline Elective

S. No.	Course Code	Course Title	L	Т	Р	C
1	MPED601L	Modern Control Theory	3	0	0	3
2	MPED602L	Intelligent Control	3	0	0	3
3	MPED603L	Energy Storage Systems	3	0	0	3
4	MPED604L	Solar Photo Voltaic Systems	3	0	0	3
5	MPED605L	Electric and Hybrid Electric Vehicles	3	0	0	3
6	MPED606L	Wind Energy Conversion Systems	3	0	0	3
7	MPED607L	Microgrid Technologies	3	0	0	3
8	MPED608L	Integrated Circuits for Power Conversion	2	0	0	2
	MPED608P	Integrated Circuits for Power Conversion	0	0	2	1
9	MPED609L	Power Electronics Applications in Power Systems	3	0	0	3



Curriculum (Semester wise	Break up)
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Semester-1	Category	L	Τ	Р	С
Advanced Semiconductor Devices	DC-1	3	0	0	3
Analysis of Power Converters	DC-2	3	0	0	3
Analysis of Power Converters Lab	DC-2 L	0	0	2	1
Generalized Machine Theory	DC-3	3	1	0	4
Advanced Processors for Power Converters	DC-4	3	0	0	3
Advanced Processors for Power Converters Lab	DC-4 L	0	0	2	1
Discipline Elective-1	DE-1	3	0	0	3
Technical Report Writing	Core				2
Qualitative Skills Practice	Core				1.5
Study Oriented Project	Core				2
Total Credits (Seme	ester-1)				23. 5

Semester-2	Category	L	Т	Р	С
Switched Mode Power Supplies	DC-5	2	0	0	2
Industrial Electrical Drives	DC-6	3	0	0	3
Industrial Electrical Drives Lab	DC-6 L	0	0	2	1
Special Machines and Control	DC-7	3	0	0	3
Discipline Elective-2	DE-2	3	0	0	3
Discipline Elective-3	DE-3	3	0	0	3
Discipline Elective-4	DE-4	3	0	0	3
Open Elective-1/ Discipline Elective-5	OE-1/DE-5	3	0	0	3
Quantitative Skills practice	Core				1.5
Design Project	Core				2



Semester-3	Semester-3 Category	
Internship I/ Dissertation I	Project/ Internship	10

Semester-4	Category	Credits
Internship II/ Dissertation II	Project/ Internship	12



Discipline Core

Course code				
	Course Title	L		PC
MPED501L	Advanced Semiconductor Devices	3	0	0 3
Pre-requisite		Syllab		
		versio		
		1	0.1	
Course Objective				
application rec 2. Understand th and protection	e various power semiconductor device characteristics and significanc circuits.			/e
Expected Course	e course the student will be able to			
 Appropriate de Examine and voltage, currer Analyze the cl 	ategorize power electronic switches based on its rating evice selection suitable for application classify various power semiconductor switching characteristics and su th controlled devices haracteristics of new emerging power semiconductor devices. oriate protection circuits to overcome problems associated with power			I
Module:1 Semic	conductor device selection		6 h	ours
	r Diodes ructure, operating principle, switching characteristics, type	es, for		
Power diodes: St	r Diodes ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character			ours anc
Power diodes: St reverse characteri	ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character		ward	anc
Power diodes: St reverse characteri Module:3 Powe Power Thyristors: switching character	ructure, operating principle, switching characteristics, type	istics	ward 6 h Gate a ries a	anc ours and and
Power diodes: St reverse characteri Module:3 Powe Power Thyristors: switching character parallel operation; characteristics	ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character r Thyristors Physics of operation, Two transistor analogy; concept of latc eristics; converter grade and inverter grade and other type steady state and dynamic models of Thyristor; simulation of	istics	6 h Gate a ries a thyri	and and and stor
Power diodes: St reverse characteri Module:3 Powe Power Thyristors: switching character parallel operation; characteristics Module:4 Powe Power Transistor characteristics; N Darlington; Safe o	ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character r Thyristors Physics of operation, Two transistor analogy; concept of latc eristics; converter grade and inverter grade and other type	istics hing; G es; se power tion, s	6 h Gate a ries a thyri 6 h witch	and and stor ours ning wer
Power diodes: St reverse characteriModule:3PowePower Thyristors: switching character parallel operation; characteristicsModule:4PowePower Transistor characteristics; Darlington; Safe o simulation of powe	ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character Thyristors Physics of operation, Two transistor analogy; concept of latc eristics; converter grade and inverter grade and other type steady state and dynamic models of Thyristor; simulation of Transistors s: Construction, static characteristics, physics of operat legative temperature co-efficient and secondary break perating regions; dynamic models of BJT; comparison of BJT	istics hing; G es; se power tion, s	6 h Gate a ries a thyri 6 h Witch Po hyris	and and and stor ours wer stor;
Power diodes: St reverse characteriModule:3PowePower Thyristors: switching character parallel operation; characteristicsModule:4PowePower Transistor characteristics;Nodule:5PowePrinciple of voltage and switching character	ructure, operating principle, switching characteristics, type stics; device datasheet; simulation of power diode character Thyristors Physics of operation, Two transistor analogy; concept of latc eristics; converter grade and inverter grade and other type steady state and dynamic models of Thyristor; simulation of Transistors s: Construction, static characteristics, physics of operat legative temperature co-efficient and secondary break berating regions; dynamic models of BJT; comparison of BJT er transistor characteristics	tion, s down; and T ce, type	6 h Gate a ries a thyri 6 h witch Po hyris 7 h	and ours and and stor <u>ours</u> stor; ours atic



Smart power devices; Intelligent Power Modules; Silicon Carbide Devices; Wide band gap devices: Vertical and lateral structures, Turn-on and Turn-off characteristics of the device; device datasheet

Mod	ule:7	Gate Driving and Protecti	on			6 hours
and	l wide b	cuits: pulse transformer, op andgap power devices; I pes; simulation of gate driv	Design of snubbe			
Mod	ule:8	Contemporary issues				2 hours
				Total L	ecture hours:	45 hours
Tex	t Book(s)				
1.		han, Tore M. Undeland, "P ley & Sons, 3rd edition 2007		- Converte	ers, Applications	s and Design",
2.		M.H., "Power Electronics: Ci lune 2014.	ircuits, Devices an	d Applicat	ions ", Pearson	Education, 4th
Ref	erence	Books				
1.	-	, Z. Zhang and E. A. Jones , IET, ISBN-13: 978-178561		of Wide B	andgap Power S	Semiconductor
2.		ga, "Gallium Nitride and Sili ıy (3 Feb. 2017).	con Carbide Powe	er Devices	s," World Scienti	fic Publishing
Red	commen	ded by Board of Studies	09-07-2022			
App	proved by	y Academic Council	No. 67	Date	08-08-2022	



Course Code	Course Title	L	. Т	Ρ	С
MPED502L	Analysis of Power Converters	3	6 0	0	3
Pre-requisite	Nil	Sylla			
		versi			
			1.0		
Course Objective		_			
• •	stematic approach for transient and steady state analysis o	of powe	er ele	ctro	nic
	h passive and active loads.				
	advanced converters such as multi-level inverters and comp	are diff	eren	t PV	VM
techniques fo	r their control.				
Expected Course	e Outcome				
	of this course the student will be able to				
	he working principle and analyse the different types single pha	ase rect	ifiers	-	
	e working principle and analyse the different types three phase				
	lesign the different configurations of DC-DC converters.				
•	us types of Inverters and Examine the harmonics.				
•	various types of power electronic converters.				
Module:1 SIN	GLE PHASE CONTROLLED RECTIFIER		7	hou	ırs
	GLE PHASE CONTROLLED RECTIFIER to DC controlled converter configurations: Semi-converter all	nd Full		hou htrol	
Single Phase AC	GLE PHASE CONTROLLED RECTIFIER to DC controlled converter configurations: Semi-converter and RL, RLE load; Continuous and discontinuous conduction		у со	ntrol	led
Single Phase AC converter with R, supply side powe	to DC controlled converter configurations: Semi-converter at RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s	mode;	y coi Anal	ntroll ysis	led of
Single Phase AC converter with R,	to DC controlled converter configurations: Semi-converter at RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s	mode;	y coi Anal	ntroll ysis	led of
Single Phase AC converter with R, supply side powe Dual converter; P	to DC controlled converter configurations: Semi-converter an RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier	mode;	y cor Anal indu	ntroll ysis ctan	led of ce;
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THF	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER	mode; source	y cor Anal indu 8	ntroll ysis ctane hoı	led of ce;
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THR Three Phase AC	to DC controlled converter configurations: Semi-converter and RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a	mode; source	y cor Anal indu 8 y cor	ntroll ysis ctan hou ntroll	led of ce; urs led
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THR Three Phase AC converter with R	to DC controlled converter configurations: Semi-converter and RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction	mode; source Ind Full	y cor Anal indu 8 y cor	ntroll ysis ctan hou ntroll	led of ce; urs
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THR Three Phase AC converter with R	to DC controlled converter configurations: Semi-converter and RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a	mode; source Ind Full	y cor Anal indu 8 y cor	ntroll ysis ctan hou ntroll	led of ce; urs
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THR Three Phase AC converter with R analysis; Effect of	to DC controlled converter configurations: Semi-converter and RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction	mode; source Ind Full	y con Anal indu indu 8 y con ; Ha	ntroll ysis ctan hou ntroll	led of ce; urs led nic
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THF Three Phase AC converter with R analysis; Effect of Module:3 DC- Configurations: B	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a , RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse converter DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter	mode; source and Full mode verter ters; S	y con Anal indu y con ; Ha 7 ynch	htroll ysis ctand hou ntroll rmo hou ronc	led of ce; urs led nic
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THF Three Phase AC converter with R analysis; Effect of Module:3 DC- Configurations: B	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse con DC CONVERTERS	mode; source and Full mode verter ters; S	y con Anal indu y con ; Ha 7 ynch	htroll ysis ctand hou ntroll rmo hou ronc	led of ce; urs led nic
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THF Three Phase AC converter with R analysis; Effect of Module:3 DC- Configurations: B converters; Desig	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse com DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter n and control of DC-DC converter; Multi-quadrant choppers and	mode; source and Full mode verter ters; S	y con Anal induc y con ; Ha y con ; Ha	htroll ysis ctan htroll ntroll rmo hou ronc ons	led of ce; led nic urs ous
Single Phase AC converter with R, supply side powe Dual converter; PModule:2THFThree Phase AC converter with R analysis; Effect ofModule:3DC- Configurations: B converters; DesigModule:4DC-	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a , RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse converter DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter	mode; source and Full mode verter ters; S nd appl	y con Anal induc 8 y con ; Ha 7 ynch icatio	htroll ysis ctan hou htroll rmo hou pns hou	led of ce; led nic urs ous
Single Phase AC converter with R, supply side powe Dual converter; PModule:2THFModule:2THFThree Phase AC converter with R analysis; Effect ofModule:3DC-Configurations: B converters; DesigModule:4DC-Single phase Volt	to DC controlled converter configurations: Semi-converter at RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a , RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse con DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter n and control of DC-DC converter; Multi-quadrant choppers at AC INVERTERS	mode; source and Full mode verter ters; S nd appl	y con Anal indu y con ; Ha y con ; Ha 7 ynch icatio 9 e pha	htroll ysis ctan hou ntroll rmo hou pns hou se \	led of ce; led nic urs ous urs /SI
Single Phase AC converter with R, supply side powe Dual converter; PModule:2THFThree Phase AC converter with R analysis; Effect ofModule:3DC- Configurations: B converters; DesigModule:4DC- Single phase Volt and CSI: 120° and	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a , RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse con DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter n and control of DC-DC converter; Multi-quadrant choppers ar AC INVERTERS age Source Inverter (VSI) and Current Source Inverter (CSI)	mode; source ind Full mode verter ters; S nd appl ; Three pace ve	y con Anal induc y con ; Ha y con ; Ha y con ; Ha y con ; Ha y con y con	htroll ysis ctan hou ntroll rmo <u>hou</u> ronc <u>ons</u> <u>hou</u> se V PW	led of ce; led nic urs ous urs (SI 'M;
Single Phase AC converter with R, supply side powe Dual converter; PModule:2THFThree Phase AC converter with R analysis; Effect ofModule:3DC- Configurations: B converters; DesigModule:4DC- Single phase Volt and CSI: 120° an Multilevel Inverter	to DC controlled converter configurations: Semi-converter al RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse com DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter n and control of DC-DC converter; Multi-quadrant choppers ar AC INVERTERS age Source Inverter (VSI) and Current Source Inverter (CSI) d 180° modes of operation; PWM techniques: Sine PWM, sp	mode; source ind Full mode verter ters; S nd appl ; Three pace ve	y con Anal induc y con ; Ha y con ; Ha y con ; Ha y con ; Ha y con y con	htroll ysis ctan hou ntroll rmo <u>hou</u> ronc <u>ons</u> <u>hou</u> se V PW	led of ce; led nic urs ous urs (SI 'M;
Single Phase AC converter with R, supply side powe Dual converter; P Module:2 THF Three Phase AC converter with R analysis; Effect of Module:3 DC- Configurations: B converters; Desig Module:4 DC- Single phase Volt and CSI: 120° an Multilevel Inverter Harmonic mitigati	to DC controlled converter configurations: Semi-converter at RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a , RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse con DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved convertent n and control of DC-DC converter; Multi-quadrant choppers at AC INVERTERS age Source Inverter (VSI) and Current Source Inverter (CSI) d 180° modes of operation; PWM techniques: Sine PWM, sp s: Types, voltage control and applications; Harmonic spectrum on techniques; Filter design; Device selections	mode; source ind Full mode verter ters; S nd appl ; Three pace ve	y con Anal induc 8 y con ; Ha ynch icatio 9 e pha ector analy	htroll ysis ctan hou ntroll rmo hou ntroll rmo bns hou se \ PW sis a	led of ce; led nic urs ous urs /SI 'M; ind
Single Phase AC converter with R, supply side powe Dual converter; PModule:2THFThree Phase AC converter with R analysis; Effect ofModule:3DC- Configurations: B converters; DesigModule:4DC- Single phase Volt and CSI: 120° an Multilevel Inverter Harmonic mitigatiModule:5AC	to DC controlled converter configurations: Semi-converter at RL, RLE load; Continuous and discontinuous conduction r factor and power factor improvement techniques; Effect of s WM rectifier EE PHASE CONTROLLED RECTIFIER to DC controlled converters configurations: Semi-converter a RL, RLE load; Continuous and discontinuous conduction source inductance; Multi-quadrant converter; Multi-pulse con DC CONVERTERS uck, Boost, Buck-Boost; Multi-port and interleaved converter n and control of DC-DC converter; Multi-quadrant choppers at AC INVERTERS age Source Inverter (VSI) and Current Source Inverter (CSI) d 180° modes of operation; PWM techniques: Sine PWM, sp s: Types, voltage control and applications; Harmonic spectrum	mode; source ind Full mode verter ters; S nd appl ; Three pace ve : THD a	y con Anal induc y con ; Ha y con ; Ha y con ; Ha y con y con y con y con y con y con y con y con y con y co	htroll ysis ctand hou htroll rmo hou ronc ons hou PW sis a hou	led of ce; led nic urs vus /SI /M; und



Mod	lule:6	POWER CONVERTERS A	PPLICATION			6 hours
		ications; Front end rectifie				
com	pensatio	on; UPS; Induction heating; P	ower converters i	n renewable e	energy and el	ectric vehicles
					r	
Mod	lule:7	Contemporary issues				2 hours
					r	
			То	tal Lecture h	ours:	45 hours
Mod	e of Ev	aluation: CAT / Assignment	/ Quiz / FAT			
			/			
Text	book(s)				
1.	Rashi	d M.H., "Power Electronics-	Circuits, Devices	and Applica	tions", Prenti	ice Hall India,
		Delhi, 2017.	·		,	
2.	Ned M	<u>1ohan, Tore M. Undeland,</u> "F	ower Electronics	- Converters	, Applications	s and Design",
	John	Wiley & Sons, 2008.				-
Refe	erence l	Books				
1.		h Vithayathil, "Power Electi	onics – Principle	es and Applic	cations", Tata	a McGraw-Hill
2.		n, 2010. u, Mehdi Narimani, "High-Po	wor Convortors a	nd AC Drives'		8 Song 2017
<u>2.</u> 3.		· · · ·				
J.	2004.	n Shepherd and Li Zhang, "				ne, new rork,
Raci		led by Board of Studies	09-07-2022			
11000				Date	08-08-2022	
Ann	covid hi	/ Academic Council	No. 67			



Course Code	Course Title	L	Т	Ρ	С
MPED502P	Analysis of Power Converters Lab	0	0	2	1
Pre-requisite	Nil	Syllabus version			
	<u> </u>		1.	0	
1. To acquire	Ives knowledge on the design of power converters and implement using the second sec	ing ci	mul	otion	and
hardware.	knowledge of the design of power converters and implement ds				
Expected Cou	rse Outcome				
On the complet	ion of this course the student will be able to				
•	mulate the power electronic converter topologies bricate the various types of power electronic converters				
Indicative Exp	eriments		ho	ours	
1. Implemer (SCR/MC	ntation of driver circuits for power switching devices SFET/IGBT)				
2. Losses a	nd thermal estimation of power converters				
3. Switching	characteristics and driver circuits for wide band gap devices				
4. Performa converter	nce analysis of Single-phase controlled AC-DC one-pulse				
5. Performa converter	nce analysis of Single-phase controlled AC-DC two-pulse (R, RL-Load)				
6. Performa (R, RL-Lo	nce analysis of Three-phase controlled AC-DC six-pulse converter bad)				
7. Performa	nce analysis of AC-AC voltage regulator				
8. Performa	nce analysis of AC-AC cyclo-converter				
9. Voltage c	ontrol of Single-phase inverter- R, RL load				
10. Implemer	tation of Three-phase inverter- R load				
11. Duty ratio	-controlled DC-DC converters (Buck, Boost, Buck-Boost)				
12. Implemen	ntation of Multi quadrant chopper				
13. PWM cor	trol of DC-AC inverters				
14. Harmonic	mitigations of VSI				
15. Power fac	ctor correction circuit				
I	Total Laboratory Hours:		4	30 h	ours

Text	book(s)
1.	Rashid M.H., "Power Electronics-Circuits, Devices and Applications", Prentice Hall India, New
	Delhi, 2017.



Ned Mohan, Tore M. Undeland, "Power Electronics – Converters, Applications and Design",						
John Wiley & Sons, 2008.						
Reference Books						
1. Joseph Vithayathil, "Power Electronics – Principles and Applications", Tata McGraw-Hill						
edition, 2010.						
2. Bin Wu, Mehdi Narimani, "High-Power Converters and AC Drives", John Wiley & Sons, 2017.						
Recommended by Board of Studies 09-07-2022						
oved by Academic Council	No. 67	Date	08-08-2022			
	John Wiley & Sons, 2008. rence Books Joseph Vithayathil, "Power Electroni edition, 2010. Bin Wu, Mehdi Narimani, "High-Power mmended by Board of Studies	John Wiley & Sons, 2008. rence Books Joseph Vithayathil, "Power Electronics – Principles edition, 2010. Bin Wu, Mehdi Narimani, "High-Power Converters an mmended by Board of Studies 09-07-2022	John Wiley & Sons, 2008. rence Books Joseph Vithayathil, "Power Electronics – Principles and App edition, 2010. Bin Wu, Mehdi Narimani, "High-Power Converters and AC Drive mmended by Board of Studies 09-07-2022			



Course Code	Course Title		T	P	<u>C</u>
MPED503L	Switched Mode Power Supplies	2	0	0	2
Pre-requisite	Nil	Syllab			on
Course Objective			1.0		
Course Objective					
•	knowledge on switch mode power conversion concepts	nling f	or 0	ortio	
application	d Development of appropriate switched mode power sup	plies i	σιρ	anic	ular
Course Outcome					
he end of the cours	se the student will be able to				
1. Analyse dif	ferent non isolated DC-DC converters for steady-state operati	on.			
2. Develop ci	cuit models for different dc –dc converters				
•	solated and non-isolated dc-dc converters				
•	gnetic components of dc-dc converters				
0	nic and small signal model of switched mode power converter	s			
		0.			
Madula				<u> </u>	
	-Isolated DC-DC converters	(0014			ours
•	ysis: ideal Buck, Boost, Buck – Boost and Cuk Converter	•			(IVI),
operating principle	s, constituent elements, characteristics, comparisons and sele	ection c	riter	a	
Module:2 Mod	elling and Analysis of Non-Isolated converters			4 hc	ours
	sis: non-ideal Buck, Boost, Buck–Boost and Cuk Converters, Ic	osses a	nd e	fficie	ency
Module:3 Isola	ated converters			4 hc	ours
Significance of iso	lated converters; Steady State Analysis: Forward Converter,	Fly-bac	k Co	onve	rter,
Push pull, Half and	d full bridge Converter				
	netic circuit Design				ours
0 0	equency Inductor, transformer and capacitors for SMPS app	olication	n; In	put	filter
design					
Module:5 Dyna	amic Analysis and Control of Switching Converters			5 hc	ours
	cuit modelling of converters: dynamic equation of buck, boo	st and			
•	signal model and converter transfer functions; Control of conv				
	rol; PWM controller Integrated circuits	vortoro,	von	ugo	ana
Module:6 Res	onant Converters			3 ha	ours
	ies resonant circuit-parallel resonant circuits ;Resonant swit	ches :			
	current switching; Soft switched bidirectional dual active brid				<u>-</u>
0	<u> </u>	0			
	lications of SMPC				ours
	ection in Switching Power Supplies: Low Input SMPS for Lap	•	•		
	c devices, EV charging systems; Case studies: SMPC sim	ulation	usii	ng c	pen
Portable Electroni					
Portable Electroni source tools	ntemporary Topics				ours



		Tota	al Lecture ho	ours:	30 hours		
Text	book(s)						
1.	Robert W. Erickson and DraganMaksi	movic, "Fundan	nentals of Pov	wer Electron	ics", Springer,		
	3rd edition, 2020.						
2.	Simon Ang, Alejandro Oliva, "Power-S	witching Conve	erters", CRC F	Press, Vol. N	lo., 3rd		
	Edition, 2010.						
Refe	erence Books						
1.	Philip T Krein, "Elements of Power Ele	ctronics ", Oxfo	ord University	Press, 2nd I	Edition, 2017.		
2.	Ned Mohan, Undeland and Robbin, "P	ower Electronic	cs 3ed (An Ind	dian Adaptat	ion):		
	converters, Application and design" W	iley India Pvt Lt	d, 3rd Edition	i, 2022.	-		
Mode	e of Evaluation: Continuous Assessmen	t Test, Digital A	Assignment, C	Quiz and Fin	al Assessment		
Test	Test						
Reco	ommended by Board of Studies	09-07-2022					
Appr	oved by Academic Council	No. 67	Date 0	8-08-2022			



	Course Title	LTP	С			
MPED504L	Generalized Machine Theory	3 1 0	4			
Pre-requisite	NIL	Syllabus ve	rsion			
		1.0				
Course Objectives						
	niques and analytical methods for dealing with and	solving opera	tional			
•	electrical machines.					
2. Develop and	practise their research skills and find solutions to real p	roblems.				
Course Outcome						
	Irse, the student will be able to					
	onversion and utilization of electric energy systems.					
•	nation of three-phase to two-phase axis model.					
	dynamic models of the DC machine, the synchronous r	machine induc	tion			
•	special machine.					
	dge about the limitations for a dynamic model of an elec	ctrical machine.				
	dge on the dynamic analysis of Interconnected machine					
Module:1 Princi	ples of Electromagnetic Conversion	7 h	ours			
	le excited systems; Field energy ,co-energy and					
	energy conversion ;Single and Multiple excited systems					
expression	shergy conversion, omgie and manple excited systems		10100			
Module:2 Linea	r Transformation and Reference Frame Theory	9 h	ours			
	r Transformation and Reference Frame Theory					
Kron's theory ; Trans	formation from three phase to two phase ; Transformatic					
Kron's theory ; Trans to stationary axes; P	formation from three phase to two phase ; Transformatic ark's transformation ;Physical interpretation;	on from rotating	axes			
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(Deemed to be University under section 3 of UGC Act, 1956)	
Module:7 Modelling of Inter connected machines	8 hours
Dynamical Analysis of Interconnected Machines; Machine interconne	ection matrices;
Transformation of voltage and Torque equations using interconnection matr	rix; Large signal
transient analysis using transformed equations	
Module:8 Contemporary issues	2 Hours
Total Lecture hours:	60 hours
Text Book(s)	
Krause PC, Wasynczuk O, Sudhoff SD (2013) Analysis of electrical mac	hinery and drive
1. systems, 3 rd edition. IEEE Press	-
2. Bimal K.bose, (2015), Modern Power Electronics and AC Drives, Prentice	Hall.
Reference Books	
1. R. Krishnan, (2015) Electric motor drives, modeling, analysis and control, F	Pearson.
A. E. Eitzgerald, Charles Kingsley, and Stephen D. Ilmans. (2020). Electric	
2. Graw Hill , Indian Edition.	
3. Ion Boldea, (2017) Variable speed generators, CRC Press.	
Mode of Evaluation: Continuous Assessment Tests, Quizzes, Assignment, Final	Assessment
Test	
Recommended by Board of Studies 09-07-2022	
Approved by Academic Council No. 67 Date 08-08-	



MPED505L		Course Tit	le		L	Т	Ρ	С
		Industrial Electri	cal Drives		3	0	0	3
Pre-requisite	MPED502			Sy	llab	us ve	ersio	on
	MPED504							
	•					1.0		
Course Object			<u> </u>					
		ts of load and drive intera			epts c	of ac	and	dc
		enerative braking aspect		ogy.				
2. To analyze	EIVII and mitiga	te Harmonics in energy e	efficient drives.					
Expected Cou	rse Outcome							
•		se the student will be able	e to					
•		ics and identify the suital		ratings				
	-	of DC drives and constru	•	0				
•	••	of AC drives and constru						
•		standards and different e		nes.				
Module:1 D	rive Dynamics	and Power Ratings				7	' hoi	urs
Dynamics of E	ectric Drives:	Julti quadrant operation,	Moment of inertia	, Torqu	e an	d po	wer	for
		ds; Selection of motor po						
heating and co	oling; Selection	of power converters: Dire	ect converters, conv	verters v	with i	ntern	nedi	ate
	•	motor specification, Fact	ors for drive select	tion, Ov	erloa	ad ca	apac	ity,
Control range,	Derating factor	Efficiency						
	ontrol of DC N							
Lastara asystem			tralled reatifier has					
	ng speed and	orque of DC motors, Cor				ntrol:	Sin	gle
quadrant, Two	ng speed and quadrant and f	orque of DC motors, Cor our quadrant-controlled D				ntrol:	Sin	gle
quadrant, Two	ng speed and quadrant and f	orque of DC motors, Cor				ntrol:	Sin	
quadrant, Two Four quadrant	ng speed and quadrant and f pperations; Clo	orque of DC motors, Cor our quadrant-controlled E sed loop control				ntrol: eed (: Sin cont	gle rol:
quadrant, Two Four quadrant of Module:3 C	ng speed and quadrant and f operations; Clo ontrol of Indu	orque of DC motors, Cor our quadrant-controlled E sed loop control ction Motor Drive	OC motor drive; Cho	opper fe	ed spo	ntrol: eed (7	: Sin cont ′ ho i	gle rol: u rs
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quadrant, TwoFour quadrantModule:3CStator side corcontrol techniq	ng speed and quadrant and f operations; Clo ontrol of Indu atrol: Characte ues: Stator vo	orque of DC motors, Cor our quadrant-controlled E sed loop control ction Motor Drive	C motor drive; Cho cuit of poly-phase equency control, V	inductio	n morrol; S	ntrol: eed o 7 otor; Soft s	Sin cont <u>hou</u> Spe	gle rol: u rs eed
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quadrant, Two Four quadrant Four quadrant Module:3 C Stator side cor control techniq methods, brake Scherbius drive	ng speed and quadrant and f operations; Clo ontrol of Indu trol: Characte ues: Stator vo ng methods; I o, doubly fed ind	orque of DC motors, Cor our quadrant-controlled E sed loop control ction Motor Drive istics and equivalent circ tage control, variable fr Rotor side control: static luction motor drive	C motor drive; Cho cuit of poly-phase equency control, V rotor resistance of	inductic	n morrol; S	ntrol: eed o 7 otor; Soft s mer's	Sin cont / ho Spe start dri	gle rol: u rs eed ing ve,
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quadrant, TwoFour quadrant, TwoFour quadrantModule:3CStator side corcontrol techniqmethods, brakiScherbius driveModule:4VPrinciple of vecflux-oriented cospeed sensor leModule:5CSteady-state ed	ng speed and quadrant and f operations; Clo ontrol of Indu trol: Character ues: Stator vo ng methods; I doubly fed ind ector Control tor control, type ontrol, stator flu ess control, Co ontrol of Sync quivalent circuit	orque of DC motors, Cor our quadrant-controlled D sed loop control ction Motor Drive istics and equivalent circles tage control, variable fr Rotor side control: static luction motor drive of Induction Motor Drive es of vector control, direct x-oriented control, air gat neept of space vectors, D hronous Machine Drive s and dynamic model of	C motor drive; Cho cuit of poly-phase equency control, V rotor resistance of vector control, indi p flux-oriented con TC control strategy es synchronous mach	inductic //f control, control, dec of indu	ed spe on me rol; S Krar ctor c coupl ction ro d-	ntrol: eed o otor; Soft s mer's 8 ontro ing o moto 7 axis	Sin cont <u>'hou</u> Spe start dri bl, rc bl, rc bl, rc circu or <u>'hou</u> curr	gle rol: urs eed ing ve, urs otor its-
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quadrant, Two Four quadrant, Two Four quadrant, Two Four quadrant, Two Module:3 C Stator side cor control techniq methods, braki Scherbius drive Module:4 V Principle of vec flux-oriented co speed sensor le Module:5 C Steady-state equation	ng speed and quadrant and f operations; Clo ontrol of Indu trol: Character ues: Stator vo ng methods; I doubly fed ind ector Control tor control, type ontrol, stator flu ess control, Co ontrol of Sync quivalent circui um torque per a	orque of DC motors, Cor bur quadrant-controlled E sed loop control ction Motor Drive istics and equivalent circles tage control, variable fr Rotor side control: static luction motor drive of Induction Motor Drive es of vector control, direct x-oriented control, air gat the sof space vectors, D hronous Machine Drive s and dynamic model of mpere control, direct toro	C motor drive; Cho cuit of poly-phase equency control, N rotor resistance of vector control, indi p flux-oriented con TC control strategy es synchronous mach ue control, and pov	inductic //f control, control, dec of indu	ed spe on me rol; S Krar ctor c coupl ction ro d-	ntrol: eed o otor; Soft s mer's eontro ing o moto 7 axis ntrol	Sin cont <u>'hou</u> Spe start dri bl, rc bl, rc bl, rc circu or	gle rol: urs eed ing ve, btor its- urs ent
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Module:3CModule:3CStator side corcontrol techniqmethods, brakiScherbius driveModule:4VPrinciple of vecflux-oriented cospeed sensor leModule:5CSteady-state edcontrol, maximuModule:6EIntroduction to	ng speed and quadrant and f operations; Clo ontrol of Indu atrol: Characte ues: Stator vo ng methods; I doubly fed ind ector Control tor control, type ontrol, stator flu ess control, co ontrol of Sync quivalent circui im torque per a lectromagneti EMI and EMC	orque of DC motors, Cor bur quadrant-controlled E sed loop control ction Motor Drive istics and equivalent circ tage control, variable fr Rotor side control: static luction motor drive of Induction Motor Drive es of vector control, direct x-oriented control, air ga acept of space vectors, D hronous Machine Drive s and dynamic model of mpere control, direct torc c Interference and Harn EMC for power converter	C motor drive; Cho cuit of poly-phase equency control, N rotor resistance of vector control, indi p flux-oriented con TC control strategy synchronous mach ue control, and povention ponics ers, grounding and	ppper fe	ctor c coupl ction ro d- or co	ntrol: eed o 7 otor; Soft s mer's mer's 8 ontrol 8 ontrol 7 axis ntrol 4 MC o	Sin cont Spe start dri bl, rc bl, rc	gle rol: urs eed ing ve, urs tor its- urs ent urs ses
quadrant, Two Four quadrant Four quadrant Four quadrant Module:3 C Stator side cor control techniq methods, braki Scherbius drive Module:4 V Principle of vec flux-oriented cc speed sensor le Module:5 C Steady-state ed control, maximu Module:6 E Introduction to	ng speed and quadrant and f operations; Clo ontrol of Indu atrol: Characte ues: Stator vo ng methods; I doubly fed ind ector Control tor control, type ontrol, stator flu ess control, co ontrol of Sync quivalent circui im torque per a lectromagneti EMI and EMC	orque of DC motors, Cor bur quadrant-controlled E sed loop control ction Motor Drive istics and equivalent circ tage control, variable fr Rotor side control: static luction motor drive of Induction Motor Drive s of vector control, direct x-oriented control, air ga neept of space vectors, D hronous Machine Drive s and dynamic model of mpere control, direct torc c Interference and Harn	C motor drive; Cho cuit of poly-phase equency control, N rotor resistance of vector control, indi p flux-oriented con TC control strategy synchronous mach ue control, and povention ponics ers, grounding and	ppper fe	ctor c coupl ction ro d- or co	ntrol: eed o 7 otor; Soft s mer's mer's 8 ontrol 8 ontrol 7 axis ntrol 4 MC o	Sin cont Spe start dri bl, rc bl, rc	gle rol: urs ed ing ve, tor its- its- ent urs ses



Module:7	Energy Saving in Electric Drives	4 hours
	n of energy efficiency, Energy efficient motor starting and contr with variable and constant torque, Life cycle costs and sys power	

Module:8 Contemporary issues

Total Lecture hours:

45 hours

2 hours

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

Textbook(s)

Γ

Text	book(s)				
1.	Bimal K Bose, "Modern Power Electro	nics and AC Dr	ives", Pear	son Education Asia, 2012.	
2.	R. Krishnan, Electric Motor Drives: Modelling, Analysis, and Control, 2015, Second edition, Pearson Education India.				
Refe	rence Books				
1.	Gopal K Dubey, "Fundamentals of Ele	ctrical Drives", (CRC Press	s, Second Edition, 2015.	
2.	Peter vas, Vector control of AC Machin	nes –Oxford un	iversity pre	ess, 1990.	
3.	R. Raja Singh, Energy Conservation Strategies for Asynchronous Machine Drives, Lap Lambert Academic Publishing, Germany, 2021.				
4.	Danfoss Handbook on VLT Frequency Converters, "Facts Worth Knowing about Frequency Converters", PE-MSMBM Publications, 2014.				
5.					
Reco	ommended by Board of Studies	09-07-2022			
Appr	oved by Academic Council	No. 67	Date	08-08-2022	



Cour	rse Code	(Deemed to be University under section 3 of UGC Act, 1936) Course Title	L	т	Р	С
	D505P	Industrial Electrical Drives Lab	0	0	г 2	1
	requisite	MPED502L	Syllal	-		on
	-	MPED504L		4.0		
Cour	rse Objective	S		1.0)	
		d the performance of Electrical drives experimentally under	vario	us o	pera	ting
	onditions.					-
2. T	o implement	the various speed control strategies for electric drives				
Evno	atad Course	Outcomo				
-	ected Course	of this course the student will be able to				
	•	conduct experiments, as well as analyse and interpret data.				
	. - ·					
	ative Experim			H	ours	
1.	Design and s	speed control of AC to DC converter fed DC motor drive				
2.	Design and	speed control of DC to DC converter fed DC motor drive				
3.	Design and	control of DC motor drive under four quadrants				
4.	Design and	control AC to AC regulator fed induction motor drive				
5.	Speed control	ol of induction motor drive using V/f control				
6.	Speed control	ol of induction motor drive using VVC+ control				
7.	Speed control	ol of induction motor drive using field-oriented control				
8.	Speed control	ol of induction motor drive using flux sensor less control				
9.	Dynamic bra	king of induction motor drive				
10.	Automatic m	otor adaption for machine parameter estimation and formation				
11.	Performance	e analysis of the induction motor drive with regenerative loading				
12.	Speed control	ol of slip ring induction motor using static rotor resistance contro	ol			
13.	Speed control	ol of permanent magnet synchronous motor (PMSM) drive				
14.	Speed control	ol of synchronous drive using PI/PID controller				
15.	Speed contro	ol of synchronous reluctance motor (Syn.RM) drive				
16.	Performance	e analysis of the PMSM drive with regenerative loading				
17.	Performance	e analysis of the Syn.RM drive with regenerative loading				
18.	Speed contro	ol using static Kramer drive and static Scherbius drive				
19.	Performance	e analysis of doubly fed induction motor				



20.	Drive power and harmonics measurements		
		Total Laboratory Hours:	30 hours

Tex	tbook(s)			
1.	Bimal K Bose, "Modern Power Electro	onics and AC D	rives", Pea	arson Education Asia, 2012.
2.	R. Krishnan, Electric Motor Drives: Pearson Education India.	Modelling, An	alysis, an	d Control, 2015, Second edition,
Ref	erence Books			
1.	Gopal K Dubey, "Fundamentals of Ele	ectrical Drives",	CRC Pres	ss, Second Edition, 2015.
2.	Peter vas, Vector control of AC Machi	nes –Oxford ur	niversity pr	ress, 1990.
Rec	ommended by Board of Studies	09-07-2022		
App	roved by Academic Council	No. 67	Date	08-08-2022



MPED506L			Т	Ρ	С
		3	0	0	3
Pre-requisite	MPED502L	Sylla	-	-	-
			v. 1.		
Course Object					
	art knowledge on special types of electro-mechanical energy con	version m	ach	ines	anc
	portance.				
2. To sele	ect the appropriate special machine drive for the specific purpose				
Expected Co.					
	Irse Outcome: tion of this course the student will be able to:				
	manent magnet material property and circuits				
	stepper motor with the drive circuits				
	switched reluctance motor from synchronous reluctance motor				
	are wave and sine wave permanent magnet brushless motor drive				
5. Appraise th motors	e advanced synchronous motor and develop the linear motors	from the	con	/ent	ional
motors					
	Stepper Motors				ours
	and working; Modes of excitation: Drive circuits, Control Asp	ects; Con	cep	t of	lead
angle					
Module:2	Switched Reluctance Motors			6 h	ours
Constructional	and working; Power Converters and controllers; Methods of rot	tor positio	n se	ensir	ng
Module:3	Synchronous Reluctance Motors			6 h	ours
	and working; Significance of direct and quadrature inductances;	Phasor			
	, <u>,</u>		U		
	Permanent Magnet Brushless DC Motors				ours
	agnet materials, Magnet Characteristics, Permeance coeffici				
closed loop co	BLDC; EMF and torque equations; Power Converters; Hall-effect	sensor; C	omn	nuta	ition;
	Permanent Magnet Synchronous Motors				ours
•	peration; EMF and Torque equations; Synchronous Reactan	ce; Phas	or	diag	ram;
Converter Volt	-ampere requirements				
Module:6	Advanced Synchronous Machines			5 h	ours
	nd working: Flux Switching and Flux Reversal Machines, Claw I	Pole Alter			
CI 8.4 I.	applications				
	Linear Motors			5 h	ours
Module:7					
Module:7 Construction a	nd working: Linear DC Motors, Linear Induction Motors, Linear	Synchror			otors,
Module:7 Construction a	nd working: Linear DC Motors, Linear Induction Motors, Linear ed Reluctance Motors; applications	Synchror			otors,
Module:7 Construction a Linear Switche	•	Synchror	nous	Мо	otors, ours
Module:7 Construction a Linear Switche	ed Reluctance Motors; applications	Synchror	nous	Мо 2 h	



Toyt	Book(s)			
1.		nent Magnet and	Reluctance	e Motor Drives", Clarendon Press
2.	R. Krishnan, "Permanent Magr 2010.	net and Brushless	DC Motor	s Drives", CRC Press, New York
Refe	rence Books			
1.	T. Kenjo and S. Nagamori, "Pe London 1988.	rmanent Magnet	and Brush	less DC Motor", Clarendon Press
2.	T. Kenjo, "Stepper Motors and	their Microproces	sor Contro	bls", Clarendon Press, London.
3.	Ion Boldea, "Linear Electric I London, 2013.	Machines, Drives	and MA	GLEVs Handbook", CRC Press
4.	P. P. Aearnely, "A Guide to Mo London, 1982.	tor Theory and P	ractice Ste	pper Motors", Peter Perengrinus,
5.	T. Kenjo and S. Nagamori, "Pe London 1988.	rmanent Magnet	and Brush	less DC Motor", Clarendon Press
Reco	mmended by Board of Studies	09-07-2022		
Appr	oved by Academic Council	No. 67	Date	08-08-2022



	Course Title		Т	Р	C
Course Code Course Title L T P C MPED507L Advanced Processors for Power Converters 3 0 0 3 Pre-requisite Nil Syllabus version 1.0 Course Objectives 1.0 0					
		-	-	-	-
•					
Course Objective					
 Overview of r generate pulse Overview of p 	esources available in ARM Processor and DSP-controller whees. rogramming frame work, software building blocks and Interrup				
Expected Course	Outcome				
 Understand th Use the Timer Experiment wire electronic circ Apply digital s 	e Arm processor architecture s and PWM to generate triggering pulses for power electronic o th the exceptions of ARM processor to vary the triggering pulse uits. ignal processing in ARM processor.	es fo	r po\	ver	
Module:1	ARM Processors			51	hours
	Timers and PWM			61	hours
		VΜ ι	usino		
•					nerate
triggering pulses f	or power converters			•	
triggering pulses for Module:3 System Control;	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co	ontrol	ller	61	hours
triggering pulses for Module:3 System Control; Communication in	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co terface; UART, I2C Bus Serial Interface, SPI, SSP Serial Interface	ontrol	ller	6 I with	h ours DMA
triggering pulses for Module:3 System Control; Communication in Module:4 Exception handlir Interrupt, PWM Int	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co	ontrol aces	ller	6 I with 6 I	hours DMA hours Time
triggering pulses for Module:3 System Control; Communication in Module:4 Exception handlir Interrupt, PWM Int Programming	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co terface; UART, I2C Bus Serial Interface, SPI, SSP Serial Interface Exception and Interrupt Handling ag overview; Interrupts; Interrupt Handling Schemes; Extern errupt, ADC Interrupt; Utility of interrupts in closed loop control of	ontrol aces	ller	6 I with <u>6 I</u> upt, me sy	hours DMA hours Time rstem
triggering pulses for Module:3 System Control; Communication in Module:4 Exception handlir Interrupt, PWM Interrupt, PWM	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co terface; UART, I2C Bus Serial Interface, SPI, SSP Serial Interface Exception and Interrupt Handling ng overview; Interrupts; Interrupt Handling Schemes; Extern	ntrol aces nal li f a re	ller nterr	6 I with upt, me sy 6 I	hours DMA hours Timer rstem
triggering pulses for Module:3 System Control; Communication in Module:4 Exception handlir Interrupt, PWM Interrupt, PWM	Component Interfacing and Networks RTC, Watch Dog Timer, USB 2.0 Full-Speed device co terface; UART, I2C Bus Serial Interface, SPI, SSP Serial Interface Exception and Interrupt Handling ng overview; Interrupts; Interrupt Handling Schemes; Extern errupt, ADC Interrupt; Utility of interrupts in closed loop control of Digital Signal Processing with ARM Digital Signal; Introduction to DSP on the ARM; Industry need	ntrol aces nal li f a re	ller nterr	6 I with upt, me sy 6 I the	hours DMA hours Time rstem



Mar	nagers (EVA, E	VB); PWM signal generation	for single phase inv	rerter	
	dule:7	Real Time Digital Signal I			5 hours
		cessing; Frame Based Proce			Usage of Buffers in
Frai	me-Based Proc	essing; Overlap Methods for	Frame-Based Proc	essing	
Мо	dule:8	Lecture by industry expe	rts		2 hours
			Total Leo	ture hours:	45 hours
Tex	tbook(s)				
1.		ss, Dominic Symes, Chris Wr stem Software" Morgan Kaufi			Guide Designing and
2.		yat, Steven Campbell, "DSP ork, Washington Dc, 2012.	based electromech	anical motion	control", CRC
Ref	erence Books				
1.	Second Editio	Christopher Hinds "ARM Asse n, CRC Press Taylor & Franc	is Group 2015.		
2.		vor Arjeski "ARM Assembly La		vare Experime	ents", Springer 2015
		Board of Studies	09-07-2022	L _	
App	roved by Acad	emic Council	No. 67	Date	08-08-2022



Cours	se Code	Course Title	L	Τ	Ρ	С
	D507P	Advanced Processors for Power Converters Lab	0	0	2	1
Pre-re	equisite	Nil	Syllab		ersi	on
Cour	se Objectivo			1.0		
1. U	-	Irces available with ARM and DSP controller to generate control	signals	s for	pow	er
Expe	cted Course	e Outcome				
		n of this course the student will be able to onduct experiments, as well as analyze and interpret data.				
Indica	ative Experi	ments		hou	irs	
1.	Control sigr	al for obtaining variable duty cycle.				
2.	Obtaining p	ulse width modulated signal from a saw tooth and DC signal.				
3.	Processor b	based control of a single phase half-wave controlled converter				
4.	Single phas	e single quadrant DC-DC converter and its control.				
5.	Control of a	single phase single quadrant bridge type AC-DC converter.				
6.	Single pha processor.	se two quadrant AC-DC converter controlled through ARM	Λ			
7.	High power	single quadrant bridge type AC-DC converter and its control				
8.	Control of a	High power two quadrant bridge type AC-DC converter.				
9.	ARM proces	ssor based control of a residential UPS.				
10.	Digital conti	ol of high power industrial inverter.				
11.	Control of the	nree phase AC voltage controller				
12.	Single phas	e step down cycloconverter and its control.				
13.	PWM contro	ol of single quadrant DC chopper				
14.	DSP based	implementation of PWM techniques to control an inverter.				
15.	Control of s	ingle phase half controlled converter using DSP processor				
16.	Control of c	hopper circuit in TRC and variable frequency method				
		Total Laboratory Hours	:	30) ho	urs

Text	book(s)
1.	Andrew N.Sloss, Dominic Symes, Chris Wright, "ARM System Developer's Guide
	Designing and Optimizing System Software" Morgan Kaufmann Publishers, 2011.



2.	Hamid A. Toliyat, Steven Campbell, "DSI	P based electrom	echanical	motion control", CRC
	press, New York, Washington Dc, 2012.			
Refe	rence Books			
1.	William Hohl, Christopher Hinds "ARM	Assembly Lar	nguage –	Fundamentals and Techniques"
	Second Edition, CRC Press Taylor & F	Francis Group 2	2015.	
2.	Ata Elahi, Trevor Arjeski "ARM Asse	mbly Languag	e with Ha	ardware Experiments", Springer
	2015,			_
Reco	mmended by Board of Studies	09-07-2022		
Appr	oved by Academic Council	No. 67	Date	08-08-2022



		Course Title L	ΤP	С
MPED601L		Modern Control system 3	0 0	3
MPED601L Modern Control system Pre-requisite NIL Course Objectives		1.0		
•		linear and nonlinear systems and to analyze the physic	cal sys	tems
	•			
-		÷ .		
	<u> </u>	concepts.		
		t will be able to		
•		•		
•				
	•	• •		
	<u></u>			
Module:1	Linear Systems		9 h	our
			sfer fun	ction
			nical f	orms
			0 4	
		-		
observer; Ext				
Module:4	Nonlinear Systems		7 h	ours
	amics: common nonli	inearities, features of nonlinear systems; Modelling		
				linea
systems: equ	ilibrium points, lineariz	zation, state space averaging; Nonlinear phenomer		linea
systems: equ				linea
systems: equ converters: b	ilibrium points, lineari: furcation and chaos		na in p	linea oowe
systems: equ converters: b Module:5	ilibrium points, linearia furcation and chaos Stability Analysis	zation, state space averaging; Nonlinear phenomer	na in p 6 h	linea owe
systems: equ converters: b Module:5 Stability of L	ilibrium points, lineari: furcation and chaos Stability Analysis T Systems: BIBO stab	zation, state space averaging; Nonlinear phenomer	na in p 6 h of Lyap	linea owe nours unov
systems: equ converters: b Module:5 Stability of L	ilibrium points, lineari: furcation and chaos Stability Analysis T Systems: BIBO stab	zation, state space averaging; Nonlinear phenomer	na in p 6 h of Lyap	linea owe nours unov
systems: equ converters: b Module:5 Stability of L	ilibrium points, lineari furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con	zation, state space averaging; Nonlinear phenomer bility; Nyquist stability criteria; Stability in the sense of instruction; Stability analysis: Lyapunov direct and indir	na in p 6 h of Lyap ect me	linea bowe nours unov thod
systems: equ converters: b Module:5 Stability of L Lyapunov fur Module:6	ilibrium points, lineari: furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con Nonlinear Control Te	zation, state space averaging; Nonlinear phenomer bility; Nyquist stability criteria; Stability in the sense of instruction; Stability analysis: Lyapunov direct and indir	na in p 6 h of Lyap rect me 6 h	linea powe nours unov thod
systems: equ converters: b Module:5 Stability of L Lyapunov fur Module:6 Lyapunov ba	ilibrium points, lineari: furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con Nonlinear Control Te sed control; Control de	zation, state space averaging; Nonlinear phenomer pility; Nyquist stability criteria; Stability in the sense o instruction; Stability analysis: Lyapunov direct and indir echniques	na in p 6 h of Lyap rect me 6 h	linea powe nours unov thod
systems: equ converters: b Module:5 Stability of L' Lyapunov fur Module:6 Lyapunov ba output lineari	ilibrium points, lineari furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con Nonlinear Control Te sed control; Control de cation; Sliding mode co	zation, state space averaging; Nonlinear phenomer bility; Nyquist stability criteria; Stability in the sense of astruction; Stability analysis: Lyapunov direct and indir echniques esign using feedback linearization: input-state lineariz pontrol; Design examples	na in p 6 h of Lyap rect me 6 h ration, i	linea powe nours unov thod nours input
systems: equ converters: b Module:5 Stability of L Lyapunov fur Module:6 Lyapunov ba	ilibrium points, lineari: furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con Nonlinear Control Te sed control; Control de	zation, state space averaging; Nonlinear phenomer bility; Nyquist stability criteria; Stability in the sense of astruction; Stability analysis: Lyapunov direct and indir echniques esign using feedback linearization: input-state lineariz pontrol; Design examples	na in p 6 h of Lyap rect me 6 h ration, i	linea powe nours unov thod
systems: equ converters: b Module:5 Stability of L' Lyapunov fur Module:6 Lyapunov ba output lineari	ilibrium points, lineari furcation and chaos Stability Analysis T Systems: BIBO stab ctions: methods of con Nonlinear Control Te sed control; Control de cation; Sliding mode co	zation, state space averaging; Nonlinear phenomer bility; Nyquist stability criteria; Stability in the sense of astruction; Stability analysis: Lyapunov direct and indir echniques esign using feedback linearization: input-state lineariz pontrol; Design examples	na in p 6 h of Lyap rect me 6 h ration, i	linea powe unov thod nours



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Text	book(s)				
1.	Ogata, K. (2010). Modern control e	ngineering (Vol. 5).	. Upper Sa	ddle River, NJ: Prentice hall.	
2.	Slotine, J. J. E., & Li, W. (1991). Ap	oplied nonlinear cor	ntrol (Vol. 1	99, No. 1, p. 705).	
Ζ.	Englewood Cliffs, NJ: Prentice hall.				
Refe	rence Books				
1.	Chi-Tsong Chen, 'Linear System T	heory and Design',	Oxford Un	iversity Press,1984	
2.	Khalil, H. K. (2015). Nonlinear cont	rol (Vol. 406). New	York: Pea	rson.	
3.	Sira-Ramirez, H. J., & Silva-Ortigoz	a, R. (2006). Contro	ol design te	chniques in power electronics	
з.	devices. Springer Science & Busine	ess Media.	-		
4.	Banerjee, S., & Verghese, G. C. (Eds.). (2001). Nonlinear phenomena in power electronics:				
4.	Bifurcations, chaos, control, and ap	plications. Wiley-IE	EEE Press.	-	
F	Tymerski R, Chuinard A, Rytkone	n F. Applied classi	cal and m	odern control system design.	
5.	Lecture Notes, ECE451, Portland S	State University.			
6.	Donald, E. (2016). Optimal control	theory: an introduct	tion. Dover	Publications.	
7	G. F. Franklin, J. D. Powell and	M Workman, 'Dig	ital Contro	l of Dynamic Systems', PHI	
7.	(Pearson), 2008.				
Mode	e of Evaluation : Continuous Assessr	nent Tests, Quizze	s, Assignm	ent, Final Assessment Test	
Reco	ommended by Board of Studies	09-07-2022			
Appr	oved by Academic Council	No. 67	Date	08-08-2022	
				1	



Course Code	Course Title	L	Т	Ρ	С
MPED602L	Intelligent Control	3	0	0	3
Pre-requisite	NIL			ersi	on
Course Objective			1.0		
Course Objectives 1. Apply neural networks, fuzzy logic and optimization techniques for obtaining desired output. 2. Design multilayer neural networks with proper architecture. 3. Deploy intelligent techniques for real time applications. Expected Course Outcome On the completion of this course the student will be able to: 1. Understand the mathematical model of a neuron and demonstrate the concepts of feedforward neural networks. 2. Apply the backpropagation training technique and recurrent networks for solving the engineering problems. 3. Estimate the appropriate the fuzzy logic control for real time applications. 4. Analyse the optimisation methods for real time applications. 5. Develop suitable artificial intelligent technique for solving typical task. Module:1 Artificial Neural Network Mathematical model of a neuron; Neuron models: Single / multi inputs; Activation functions; Network Architecture: single / multiple layers, perceptron network, leaning rule, pattern classification, linear separability limitation Module:2 Supervised learning 7 hours Feedforward Neural Network; Learning mechanism: Supervised learning, multilayer perceptron or pattern classification and function approximation; Back propagation algorithm; Drawbacks in Back propagation; Variants of back propagation algorithm; Levenburg Marguardt Algorithm; Other supervised learning methods: supervised Hebb's rule, Widrow Hoff learning rule, Adaline network Module:3					
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Pre-requisite NIL Syllabus version Course Objectives 1.0 Course Objectives 1.0 1. Apply neural networks, fuzzy logic and optimization techniques for obtaining desired output. 2. Design multilayer neural networks with proper architecture. 3. Deploy intelligent techniques for real time applications. Expected Course Outcome On the completion of this course the student will be able to: 1. Understand the mathematical model of a neuron and demonstrate the concepts of feedforward neural networks. 2. Apply the backpropagation training technique and recurrent networks for solving the engineering problems. 3. Estimate the appropriate the fuzzy logic control for real time applications. 3. Develop suitable artificial intelligent technique for solving typical task. 6 hours Module:1 Artificial Neural Network 6 hours Mathematical model of a neuron; Neuron models: Single / multi inputs; Activation functions; Network Architecture: single / multiple layers, perceptron network, leaning rule, pattern classification, linear separability limitation 7 hours Module:2 Supervised learning 7 hours Feedforward Neural Network; Learning mechanism: Supervised learning, multilayer perceptron for pattern classification and function approximation; Back propagation algorithm; Drawbacks in Back propagation; Variants of back propagation algorithm; Levenburg Marguardt Algorithm; Other supervised learning					
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2. Apply the	backpropagation training technique and recurrent networks	for s	solvir	ng t	he
engineerin	g problems.				
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Module:7 Contemporary issues:					2 hours		
		Total	Lecture h	ours:	45 hours		
Text E	Book(s)						
1.	Jack M. Zurada, "Introduction to Artificial Neural Systems", Jaico Publishing House, 2016.						
2.	Timothy J. Ross, "Fuzzy Logic with Engineering Application", McGrw Hill International						
	Editions, 2014.						
Reference Books							
1.	J.S.R Jang, C.T Sun, E.Mizutani, "Neuro-Fuzzy Soft Computing", Pearson Education, 2011.						
2.	 Nguyen, Prasad, Walker, and Walker, "A First Course in Fuzzy and Neural Control", Chapmar Hall /CRC Press, 2003. 						
3.	Orłowska-Kowalska, Teresa, Blaabjerg, Frede, Rodríguez, José, "Advanced and						
Intelligent Control in Power Electronics and Drives", Springer, 2014.							
4.	······································						
Publishing Co., 1997.							
Recommended by Board of Studies 09-07-2022							
Approved by Academic Council No.67 Date 08-08-2022							



Course code	(Deemed to be University under section 3 of UGC Act, 1956) Course Title	1	т	PC
MPED603L	Energy Storage Systems	3		
Pre-requisite		-	-	versior
		Cynax	1.0	010101
Course Objectives	5			
	and different types of Energy Storages.			
2. To describ	e basic physics, chemistry, and engineering issues of	ener	gy s	storage
devices, suc	ch as batteries, thermoelectric converters, fuel cells, supercapa	acitors		
3. To design e	nergy storage systems for different applications.			
Course Outcome				
	e the student will be able to			
-	erent energy storage techniques and recent trends.			
	fferent battery technologies and its characteristics.			
	l cells, supercapacitors and its applications.			
4. Discuss the	applications of energy storage in PV.			
Module:1 Ener	gy Storage		7	' hours
	cal and chemical energy storage systems and its applications;	Availa		
	econd law efficiency; Helmholtz & Gibb's function; Recent trends			
systems; Energy m				
Module:2 Class	sical Battery		7	' hours
	ttery performance: charging and discharging, storage density, e	energy	dens	sity and
safety issues; Mode	elling of batteries			
Module:3 Mode	ern batteries		7	' hours
	ride, Lithium battery; State of charge; Technology challenges			nours
	nde, Eliniam Ballery, Blate of Bharge, Teenhology shallenges			
Module:4 Supe	er capacitors		7	' hours
	Types of electrodes and electrolytes; Electrode materials:	high s	urfac	e area
• •	, metal oxide and conducting polymers; Electrolyte: aqu	•		
disadvantages and	advantages of super capacitors; Modelling of super capacitor	ors; Ap	oplica	ation o
super capacitors				
	cells			hours
	energy conversion; Modelling of Fuel Cells, maximum intrins			
	nverter; Physical interpretation; Carnot efficiency factor in elect			
phosphoric fuel cell	of fuel cells: hydrogen oxygen cells, hydrogen air cell, alka	anne n	uer c	en and
Module:6 Ener	gy Storage Applications		7	' hours
	er Electronics Converters in Energy Storage Systems; Stand	alone		
	nected systems; Power smoothing, grid ancillary services, en			
case studies and si				-
	· · ·			
Module:7 Cor	ntemporary issues:		2	hours
	Total Lecture hours:		45	hours
			٦J	nours



Text Book(s)							
1.	Yves Brunet, "Energy Storage", Wiley-ISTE, 1 st Edition, 2010.						
2.	Robert A.Huggins, "Energy Storage", Springer, 2 nd Edition, 2015.						
Reference Books							
1.	Andrei G. Ter-Gazarian, "Energy storage systems for Power systems", 2nd edition, IET 2011.						
2.	R M. Dell, D.A.J. Rand, "Understanding Batteries" RSC Publications, 1 st edition, 2012.						
3.	Tetsuya Osaka, Madhav Datta, "Energy Storage Systems in Electronics-New Trends in Electrochemical Technology", CRC Press, 2000.						
Mode of Evaluation : Continuous Assessment Tests, Quizzes, Assignment, Final Assessment Test							
Recommended by Board of Studies 09-07-2022							
Approve	ed by Academic Council	No. 67	Date	08-08-2022			
Approved by Academic Council No. 67 Date 08-08-2022							



MPED604L	Course Title		-	Ρ	<u>C</u>
- · · ·	Solar Photo Voltaic Systems	3	0	0	3
Pre-requisite	MPED501L	Sylla			ion
Course Objective		1.	0		
Course Objective	and the importance and applications of Solar Energy				
	em acquainted with power electronic interface circuits for Solar	Enor	N/		
Z. TO Make ii		LIIEIQ) y		
Course Outcome					
	se the student will be able to				
	techniques for estimation of solar PV cell parameters				
•	ew tracking techniques and reconfiguration methods for improve	ed pow	er e	xtrac	ction
	PV systems				
- ·	hotovoltaic system and its interfacing circuits for stand-alone, gr			-	
-	ne cost analysis and payback period of solar PV installations and	categ	oriz	e var	IOUS
	ntal impacts of PV.		0.10	0.000	
5. Understand	d the different standards and communication system used in sol	ar Pv	sys	ems	•
	r PV cell fundamentals solar energy conversion; Solar cell: types, material propertie			5 ho	
· · · · · · · · · · · · · · · · · · ·	ng techniques; performance parameters: cell efficiency ,fill facto	,		6 hc	
	odules and arrays: series and parallel combination, effect of sha	dina u			
	es; Need for Maximum power tracking: effects of irradiation and				
	acking techniques and array reconfiguration methods for maximu				
	<u></u>	111 201			
		in por			
Module:3 Star	dalone PV Systems			7 ho	
Module:3 Star Standalone PV sy	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of	control	lers;	7 ho Off	gric
Module:3 Star Standalone PV sy inverters; Balance	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of of system (BOS) for power plant: Supporting structures, mounti	control	lers; d ins	7 ho Off	-gric
Module:3 Star Standalone PV sy inverters; Balance cables, maintenan	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of	control	lers; d ins	7 ho Off	-gric
Module:3 Star Standalone PV sy inverters; Balance	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of of system (BOS) for power plant: Supporting structures, mounti	control	lers; d ins	7 ho Off	-gric
Module:3 Star Standalone PV sy inverters; Balance cables, maintenan pumping	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of of system (BOS) for power plant: Supporting structures, mounti	control	lers; d ins	7 ho Off	gric tion atei
Module:3StarStandalonePV syinverters;Balancecables,maintenanpumpingModule:4Module:4GridInterfacing with the	Indalone PV Systems Instant Instant <t< td=""><td>control ing and syste</td><td>lers; d ins m, a</td><td>7 ho Off- italla nd w 8 ho Bala</td><td>gric tion ater ours</td></t<>	control ing and syste	lers; d ins m, a	7 ho Off- italla nd w 8 ho Bala	gric tion ater ours
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildin	Indalone PV Systems Instant Instant <t< td=""><td>control ing and syste</td><td>lers; d ins m, a</td><td>7 ho Off- italla nd w 8 ho Bala</td><td>gric tion ater ours</td></t<>	control ing and syste	lers; d ins m, a	7 ho Off- italla nd w 8 ho Bala	gric tion ater ours
Module:3StarStandalonePV syinverters;Balancecables,maintenanpumpingModule:4Module:4GridInterfacing with theof system;Buildin	Indalone PV Systems Instant Instant <t< td=""><td>control ing and syste</td><td>lers; d ins m, a</td><td>7 ho Off- italla nd w 8 ho Bala</td><td>gric tion ater ours</td></t<>	control ing and syste	lers; d ins m, a	7 ho Off- italla nd w 8 ho Bala	gric tion ater ours
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financial	Indalone PV Systems Instant Instant <t< td=""><td>control ing and syste</td><td>lers; d ins m, a</td><td>7 ho Off- italla nd w 8 ho Bala</td><td>ogric tion vater ours ance</td></t<>	control ing and syste	lers; d ins m, a	7 ho Off- italla nd w 8 ho Bala	ogric tion vater ours ance
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financialModule:5Energy	Indalone PV Systems Instem: design, schematics, array and battery sizing; Charge of system (BOS) for power plant: Supporting structures, mounting; Typical applications: design of Home lighting Interface and monitoring; Typical applications: design of Home lighting Connected PV Systems Image: power grid: Schematics ,Interface Components, Types of grid gs integrated PV systems: analysis and performance; PV SYS evaluation	control ng and syste interfa ST; pre	lers; d ins m, a ace, epar	7 ho Offectalla nd w 8 ho Bala ing I	ogric tion vater ours ance DPR
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financialModule:5EnergyEnergy storage deLow and High Te	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of system (BOS) for power plant: Supporting structures, mountice and monitoring; Typical applications: design of Home lighting Connected PV Systems e power grid: Schematics ,Interface Components, Types of grid gs integrated PV systems: analysis and performance; PV SYS evaluation rgy Storage evices: Structure, Different types, and Materials for Energy Storage Applications; Measurement of battery period	control ing and syste interfa ST; pre	lers; d ins m, a ace, epar	7 hc Off- talla nd w 8 hc Bala ing I 6 hc erials	ours ours ours ours ours ours
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financialModule:5EnergyEnergy storage deLow and High Te	dalone PV Systems rstem: design, schematics, array and battery sizing; Charge of system (BOS) for power plant: Supporting structures, mountice and monitoring; Typical applications: design of Home lighting Connected PV Systems e power grid: Schematics ,Interface Components, Types of grid gs integrated PV systems: analysis and performance; PV SYS evaluation rgy Storage evices: Structure, Different types, and Materials for Energy Store	control ing and syste interfa ST; pre	lers; d ins m, a ace, epar	7 hc Off- talla nd w 8 hc Bala ing I 6 hc erials	ours ours ours ours ours ours
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financialModule:5EnergyEnergy storage deLow and High Tedischarge cycle of	dalone PV Systems rstem: design, schematics, array and battery sizing; Charge of system (BOS) for power plant: Supporting structures, mountice and monitoring; Typical applications: design of Home lighting Connected PV Systems e power grid: Schematics ,Interface Components, Types of grid gs integrated PV systems: analysis and performance; PV SYS evaluation rgy Storage evices: Structure, Different types, and Materials for Energy Storage a battery; Estimation techniques	control ing and syste interfa ST; pre	lers; d ins m, a ace, epar	7 hc Off talla nd w 8 hc Bala ing I 6 hc erials , cha	gric tion ater ours ance DPR ours for
Module:3StarStandalonePV syinverters; Balancecables, maintenanpumpingModule:4GridInterfacing with theof system; Buildinincluding financialModule:5EnergyEnergy storage deLow and High Tedischarge cycle ofModule:6Cos	dalone PV Systems stem: design, schematics, array and battery sizing; Charge of system (BOS) for power plant: Supporting structures, mountice and monitoring; Typical applications: design of Home lighting Connected PV Systems e power grid: Schematics ,Interface Components, Types of grid gs integrated PV systems: analysis and performance; PV SYS evaluation rgy Storage evices: Structure, Different types, and Materials for Energy Storage Applications; Measurement of battery period	control ng and syste syste i interfa ST; pro prage; rforma	lers; d ins m, a m, a ace, ace, ace, ace, ace, ace, ace, ace	7 hc Off- talla nd w 8 hc Bala ing I 6 hc 6 hc	ours ours ours ours ours ours



and operating costs; Environmental and safety issues; protection systems; Performance monitoring; Techno-economic analysis of solar PV power plants: Environmental considerations, Site selection and land requirements

Module:7 Standards and communication							5 hours	
IEEE	IEEE Standard 1547; Elements of communication and networking: architectures, standards, PLC, Zigbee, GSM,							
BPL,	Local A	rea Network (LAN); House Area	Netv	vork (HAN)	;Wide Are	ea Network (V	WAN)	
Mod	ule:8	Contemporary Topics					2 hours	
				Т	otal Lect	ure hours:	45 hours	
1	Textboo							
1.		el Boxwell, "Solar Electricity Ha						
		 designing and installing sola 	ır ph	otovoltaic	systems",	Greenstrea	m Publishing, UK,	
	2021							
2.		n Singh Solanki "Solar PV tech	nolo	ogy and sys	stem", PH	I learning pri	vate limited, 2015	
		ce Books						
1.	-	hani, "Design of Smart Power	Gric	Renewab	le Energy	Systems", 3	^{ra} Edition John	
		& Sons, 2019.						
2.	D. Yog	<u>ii Goswami , "Principles of Sola</u>	ar Er	ngineering'	' 3 rd Editio	n, , CRC Pre	ess, 2015	
3.	Sukha	tme S.P., "Solar Energy", Tata	McC	Graw Hills	P Co., 3rc	I Edition, 200)8	
4.	Roger	Messenger, Amir Abtahi, "Pho	tovo	ltaic Syste	ms Engin	eering", 4 th e	edition, CRC Press,	
	2017							
5.	Kenne	th C.Budka, Jayant G. Deshpa	nde	, Marina Tl	hottan, 'Co	ommunicatio	on Networks for	
Smart Grids', Springer, 2014								
Mode	e of Eva	luation: Continuous Assessme	ent T	^r est, Digita	ıl Assignm	nent, Quiz ai	nd Final Assessment	
Test								
Reco	ommend	ed by Board of Studies		09-07-20	22			
Appr	oved by	Academic Council	No	. 67	Date	08-08-	2022	

Course Code	Course Title		L	Т	Ρ	С		
MPED605L	Electric and Hybrid Electric Vehicles		3	0	0	3		
Pre-requisite	MPED502L	Sy	/llab	us v	ers	ion		
				1.0				
Course Objective	S							
1. Providing k	nowledge on Electric vehicles and its architectures.							
2. Selection o	f suitable motor drive and battery for Electric vehicles.							
3. Charging infrastructure and methods of charging of EVs.								
Course Outcome								
On the completion of this course the student will be able to:								
1. Understand	1. Understand the environmental issues of conventional vehicles and need of Electric vehicles							
2. Describe the different architectures of Hybrid Electric and Electric vehicles								

- 3. Analyse the characteristics of electric motor drives for Electric vehicles
- 4. Develop battery pack, battery management system and estimate SoC of the battery.



nn o di i loi 1		A 1
	Vehicle dynamics	6 hours
Electric vehi	conventional Vehicles; Social and environmental impacts of ICE veh cles; Evolution of hybrid electric, Electric and fuel cell vehicles; Vehi ehicle resistive forces and Tractive effort	
Module:2	Hybrid Electric vehicle architectures	5 hours
systems an	n: Micro, Mild, Full HEV; Architectures: Series, Parallel and Series d components; Hybrid drive train topologies: Power flow control, nplete structure of HEV	•
Module:3	Electric vehicle architectures	5 hours
Components	s of electric vehicle; Electric drivetrain topologies: Power flow control, dern electric drive trains; complete structure of EV	
Module:4	Electric Motor drives for EVs	7 hours
drives; PMS	n and control of DC Motor drives; Three-phase Induction Motor driv M drives; Switched Reluctance Motor drives; Synchronous reluc e Braking Characteristics; Hub/In-wheel motors for EVs; Driving Cycl	tance motor drives
Module:5	Battery and Energy Storage Systems for EVs	8 hours
	Contract Over an exact the stand Only and the interaction that statistics the	
storage dev	tems: Super capacitor, Fuel Cell and their analysis; Hybridization ces	of different energ
Module:6	Ces Battery Management System	6 hours
Module:6 Functions, d	ces	<u>6 hours</u> ncing: Types of ce
Module:6 Functions, o balancing; S	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filte	6 hours ncing: Types of ce er method
Module:6 Functions, o balancing; S Module:7 Components	Ces Battery Management System Jesign considerations and various components of BMS; Cell bala	6 hours ncing: Types of ce er method 6 hours
Module:6 Functions, o balancing; S Module:7 Components Wireless EV	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filter EV charging systems a of EV charging system; On-board and OFF board chargers; EV	6 hours ncing: Types of ce er method 6 hours
Module:6 Functions, o balancing; S Module:7 Components Wireless EV	Examples Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filter EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types	6 hours ncing: Types of ce er method 6 hours charging standards
Module:6 Functions, o balancing; S Module:7 Components Wireless EV Module:8	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filter EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types Contemporary issues Total Lecture hours:	6 hours ncing: Types of ce er method 6 hours charging standards 2 hours 45 hours
Module:6 Functions, o balancing; S Module:7 Components Wireless EV Module:8 Module:8	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filte EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types Contemporary issues Total Lecture hours: s) Larminie, John Lowry "Electric Vehicle Technology Explained", tions, 2012.	6 hours ncing: Types of ce er method 6 hours charging standards 2 hours 45 hours 2nd edition, Wile
Module:6 Functions, o balancing; S Module:7 Components Wireless EV Module:8 Text Book(s 1. James publica 2 Mehrda Cell Ve	Ces Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filter EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types Contemporary issues Larminie, John Lowry "Electric Vehicle Technology Explained", tions, 2012. ad Ehsani, Yimin Gao, Sebastien E. Gay and Ali Emadi, "Modern Electric Vehicle: Fundamentals", CRC Press, 2010.	6 hour ncing: Types of ce er method 6 hour charging standards 2 hour 45 hour 2nd edition, Wile
Module:6 Functions, o balancing; S Module:7 Components Wireless EV Module:8 Module:8 Text Book(1. James publica 2 Mehrda Cell Ve Reference I	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filter EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types Contemporary issues Larminie, John Lowry "Electric Vehicle Technology Explained", tions, 2012. ad Ehsani, Yimin Gao, Sebastien E. Gay and Ali Emadi, "Modern Electric Spooks	6 hours ncing: Types of ce er method 6 hours charging standards 2 hours 2nd edition, Wile ctric, Hybrid and Fue
balancing; S Module:7 Components Wireless EV Module:8 Module:8 Text Book(s 1. James publica 2 Mehrda Cell Ve Reference I	Battery Management System design considerations and various components of BMS; Cell bala oC estimation: Luenberger Observer method, Extended Kalman filte EV charging systems s of EV charging system; On-board and OFF board chargers; EV charging and types Contemporary issues Larminie, John Lowry "Electric Vehicle Technology Explained", tions, 2012. ad Ehsani, Yimin Gao, Sebastien E. Gay and Ali Emadi, "Modern Elechicles: Fundamentals", CRC Press, 2010. Books Hussain, "Electric and Hybrid Vehicles-Design Fundamentals"	6 hour ncing: Types of ce er method 6 hour charging standards 2 hour 45 hour 2nd edition, Wile ctric, Hybrid and Fue



	Practical Perspectives", Wiley, 2011.						
3.	Davide Andrea, "Battery managemen	t Systems for Lar	ge Lithium-	Ion Battery Packs", Artech			
э.							
4	Ottorino Veneri "Technologies and Ap	plications for Sm	art Chargin	g of Electric and Plug-in			
4	Hybrid Vehicles", Springer publishers	, 2017.	_				
Мос	Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz and Final Assessment						
Test							
Rec	commended by Board of Studies	09-07-2022					
Approved by Academic Council		No. 67	Date	08-08-2022			

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	Wind Energy Conversion Systems	L	Т	Р	С
MPED606L		3	0	0	3
Pre-requisite	MPED501L	Sylla	v	-	-
•		2	1.0		
Course Objec					
	ly different types of generators and appropriate power electronic co	ontrollers	for	ons	shor
	shore wind energy systems	mdanda			
2. To unc	lerstand the grid integration and power quality issues with their sta	anuarus			
Expected Cou	irse Outcome:				
<u> </u>	tion of this course the student will be able to:				
	basic concepts of wind turbines and their characteristics and discu	iss the co	ntro	1	
	wind turbines.				
	various generator configurations, power converters and their contra-		ique	s.	
	the grid integration, power quality issues and recommend the stan the offshore wind power generation.	idards.			
+. Summaries	the offshore while power generation.				
Module:1	Fundamental of Wind Energy Generation System			7 h	our
	Principles; design, Betz limit, and Power limitations. Componen	ts and ty			
	ating characteristics of wind turbine, wind turbine safety. Aerodyn				
flap power co	ntrol, yaw control, stall and pitch. Generator control; MPPT cont	trol schei	mes,	, tu	rbin
power profile,	optimal tip speed ratio, optimal torque control. Braking; electrical	l and me	char	ica	1.
M				51	
	Wind Generator Configuration generators; soft starters, two speed variations. Variable speed	generato			our
		generau	лз,		
canacity conve	rters fill canacity converters (renerator types, synchronolis dene	erators a		hro	nou
	erters, full capacity converters. Generator types; synchronous gene why voltage generator, switched reluctance generator, and transverse		sync		
	gh voltage generator, switched reluctance generator, and transverse		sync		
generators, hig			sync nera	tor.	
generators, hig Module:3 Converter con	h voltage generator, switched reluctance generator, and transverse Power Electronic Interface and Control nfigurations; AC voltage controllers, interleaved boost conver	e flux ger	sync nera tage	tor. 8 h	our
generators, hig Module:3 Converter con converters, cu	Power Electronic Interface and Control nfigurations; AC voltage controllers, interleaved boost conver rrent source converters, and back-to-back power converters. cont	e flux ger	sync nera tage	tor. 8 h	our
generators, hig Module:3 Converter con converters, cu	h voltage generator, switched reluctance generator, and transverse Power Electronic Interface and Control nfigurations; AC voltage controllers, interleaved boost conver	e flux ger	sync nera tage	tor. 8 h	our
generators, hig Module:3 Converter con converters, cu control - decor	Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost conver rrent source converters, and back-to-back power converters. cont upled controller, real and reactive power control.	e flux ger	sync nera tage age-	tor. 8 h scorie	our ourcente
generators, hig Module:3 Converter con converters, cu control - decon Module:4	Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost conver rrent source converters, and back-to-back power converters. cont upled controller, real and reactive power control. Grid Integration and Grid Codes	e flux ger ters, vol trol: volt	sync nera tage age-	tor. 8 h sc orie 7 h	our ourcente ourcente
generators, hig Module:3 Converter conconverters, cu control - decon Module:4 Wind intercon	Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost conver rrent source converters, and back-to-back power converters. cont upled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dyna	e flux ger ters, vol trol: volta amic ope	sync nera tage age-	tor. 8 h s sc orie 7 h on,	ourcource entec ourco
generators, hig Module:3 Converter conconverters, cuncentrol - decond Module:4 Wind intercond wind intercond	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converting the converters, and back-to-back power converters. control apled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynaseries dynamic braking resistor, crowbar, dc link chopper, dynamic 	e flux ger ters, vol trol: volt amic ope mic volt	sync nera tage age- crationera	tor. 8 h so orie 7 h on, rest	ourcentee ourcentee ourcentee ourcentee ourcentee faul
generators, hig Module:3 Converter conconverters, cuc control - decon Module:4 Wind intercon ride through, ramp rate lim	Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost conver rrent source converters, and back-to-back power converters. cont upled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dyna	e flux ger ters, vol trol: volt amic ope mic volt	sync nera tage age- crationera	tor. 8 h so orie 7 h on, rest	ourcentee ourcentee ourcentee ourcentee ourcentee faul
generators, hig Module:3 Converter conconverters, cuccontrol - decond Module:4 Wind intercondride through, ramp rate lime methods.	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converters converters, and back-to-back power converters. control pled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynaseries dynamic braking resistor, crowbar, dc link chopper, dynamic itations, ancillary services for frequency and voltage control, 	e flux ger ters, vol trol: volt amic ope mic volt	sync nera tage age- eratio age chro	tor. 8 h s sc oric 7 h on, rest niz	our ourc ente our faul coren atio
generators, hig Module:3 Converter conconverters, cuc control - decond Module:4 Wind intercond ride through, ramp rate lime methods.	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converters converters, and back-to-back power converters. controlled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynaseries dynamic braking resistor, crowbar, dc link chopper, dynamitations, ancillary services for frequency and voltage control, Power Quality Issues and Standards 	e flux ger rters, vol trol: volta amic ope mic volta and syne	sync nera tage age- erationage chro	tor. 8 h s sc orie 7 h on, rest niz 6 h	our ourcentee our faul corer atio
generators, hig Module:3 Converter conconverters, cuncontrol - decondrol Module:4 Wind intercondriver ride through, ramp rate lime methods. Module:5 Power quality	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converters converters, and back-to-back power converters. control pled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynastitations, ancillary services for frequency and voltage control, Power Quality Issues and Standards affecting factors and issues; voltage variations, frequency variat 	e flux ger rters, vol trol: volta amic ope mic volta and syne	sync nera tage age- erationage chro	tor. 8 h s sc orie 7 h on, rest niz 6 h	our ourcentee our faul corer atio
generators, hig Module:3 Converter conconverters, curce control - decond Module:4 Wind intercond ride through, ramp rate lime methods. Module:5 Power quality	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converters converters, and back-to-back power converters. controlled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynaseries dynamic braking resistor, crowbar, dc link chopper, dynamitations, ancillary services for frequency and voltage control, Power Quality Issues and Standards 	e flux ger rters, vol trol: volta amic ope mic volta and syne	sync nera tage age- erationage chro	tor. 8 h s sc orie 7 h on, rest niz 6 h	our ourc ente our faul core atio
generators, hig Module:3 Converter conconverters, cuccontrol - decondition Module:4 Wind intercondride through, ramp rate lime methods. Module:5 Power quality harmonics. State	 Power Electronic Interface and Control figurations; AC voltage controllers, interleaved boost converters converters, and back-to-back power converters. control pled controller, real and reactive power control. Grid Integration and Grid Codes nection requirements and grid codes; steady state operation, dynastitations, ancillary services for frequency and voltage control, Power Quality Issues and Standards affecting factors and issues; voltage variations, frequency variat 	e flux ger rters, vol trol: volta amic ope mic volta and syne	sync nera tage age- cratic age chro	tor. 8 h s sc orice 7 h on, rest niz 6 h nce	our ourc ente our fau atio



Typical subsystems, turbine technology, transmission network; HVAC and HVDC, and Sea substation impact on power system.

Module:7 Digital Monitoring and Control of Wind Energy Systems

6 hours

Components of SCADA control systems; remote terminal unit, intelligent electronic devices and interfaces. SCADA communication; requirements, topologies and protocols. Energy management systems for WES; challenges, data flow time frames, and forecasting. Digital twin technology for WES.

Module:8	Contemporary issues:
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2 hours

45 hours

		Total Lecture hours:
1	6 F	

Mode of Evaluation: CAT / Assignment / Quiz / FAT

Text Book(s)							
1	Bin Wu, Yongqiang Lang, Navid	Zargari, Samir K	ouro, "Pov	wer Conversion and Control of			
	Wind Energy Systems", John Wile	y & Sons, 2011.					
2	Siegfried Heier, "Grid Integration of	of Wind Energy C	onversion	Systems", Wiley, 2009.			
Refe	rence Books						
1	Thomas Ackkermann, "Wind Powe	er in Power Syster	ns", John V	Wiley & Sons, Ltd, 2012.			
2	Gonzalo Abad, Jesus Lopez, Migue	el Rodriguez, Luis	s Marroyo,	Grzegorz Iwanski, Doubly Fed			
	Induction Machine: Modeling and	Control for Wind	Energy Ge	eneration, October 2011, Wiley-			
	IEEE Press						
3	Olimpo Anaya-Lara, David Camp	oos-Gaona, Edgar	Moreno-C	Boytia, Grain Adam, "Offshore			
	Wind Energy Generation: Control, Protection, and Integration to Electrical Systems", John						
	Wiley & Sons, 2014.						
4	4 Mini S. Thomas, John D. McDonald, "Power System SCADA and smart grids", CRC Press, Taylor and						
	Francis, April 2015.						
Reco	ommended by Board of Studies	09-07-2022					
Appr	roved by Academic Council	No. 67	Date	08-08-2022			



Course Code	Course Title		T	Ρ	<u>C</u>
MPED607L	Microgrid Technologies	3	0	0	3
Pre-requisite	MPED501L	Syllal			ion
			1.0)	
Course Objectiv					
	odern control technologies for microgrids in islanded and grid cor	nnecte	ed op	erat	ion.
2. Understar	nd the concepts for communication in microgrid.				
Course Outcome					
	course, the student will be able to				
	nd the microgrid types and configurations				
	ne various types of control in microgrid				
	anced knowledge on control and energy management of islanded	d and	grid		
	l operation				!1
•	he power quality problems and incorporation of protection schem	es, po	ower	qua	ity
	ent technologies	4			
5. Identify the	e application for the various communication protocols in microgrid	a			
Madula Mia	requid Configurations			<u> </u>	
	rogrid Configurations	Mior		<u>5 hc</u>	
	Microgrid; CERTS Microgrid Test Bed; DC Microgrid; HFAC				
	DC and AC Coupled Microgrid; Grid Connected Mode; Island design of power converters for integration		iode;	Bai	lery
Charging mode, c					
Module:2 Mic	rogrid Control Techniques			6 hc	lire
	odel of microgrid; Impact of load characteristics; Hierarchical	cont			
	rtiary control; Local control; Centralized Control; Decentralized C				
	ol; Droop control methods; Frequency/Voltage Control; Inverter C				
	or, broop control methods, r requency/voltage control, inverter c	Juipu	. imp	cuai	100
Module:3 Cor	ntrol and Management in Standalone Microgrid			8 hc	ours
	anded microgrid; control and optimization techniques; energy	v stor			
	wer sharing; Stability; IEEE standards; Case study	,	s.ge.	•	. 9)
J					
Module:4 Ope	eration and Energy management in Grid Connected Microgri	d		8 hc	ours
	nected microgrid; Grid synchronization; Control and optimization to		ques	: En	erav
storage; Energy n	nanagement; Power sharing; Stability; IEEE and CIGRE standard	ds; Ca	ise s	, tudy	5,
Module:5 Pov	wer Quality Assessment & Enhancement			6 hc	ours
	ssues; Impact of Power Quality on microgrid; Power Qua	ality	mpro	oven	nent
technologies; Cor	npensators and controllers for power quality issues; IEEE standa	rds	-		
Module:6 Mic	rogrid Protection			5 hc	ours
	C microgrid; Challenges in Microgrid Protection; Protection in g	rid co			
islanded mode					and
Module:7 Cor	mmunication in Microgrid			5 hc	ours
	Protocols in microgrid; architectures; standards; Local Area Netw	vork (
	AN); Wide Area Network (WAN); Basics of Web Service and Cl				
Cyber Security fo		-001	501	npu	y,
	r morogna				
Module:8 Co	ontemporary issues			2 hc	lire
					-ui 3



			Tota	al Lecture hours:	45 hours	
Tex	tbook(s)			÷		
1.	Nikos Hatziargyriou,(2014) Microgrids	: Architectures	and Cont	rol, Wiley Press		
2.	Hasan Bevrani, <u>Bruno François</u> and Wiley Press	<u>Toshifumi Ise</u>	,(2017) "N	licrogrid Dynamics a	and Control"	
Ref	erence Books					
1.	Hasan Bevrani, <u>Bruno François</u> and Wiley Press	<u>Toshifumi Ise</u>	,(2017) "N	licrogrid Dynamics	and Control"	
2.	David Wenzhong Gao, (2015) "Energy	y Storage for S	ustainable	Microgrid" Academ	ic Press	
3.						
Moo Tes	de of Evaluation: Continuous Assessme	nt Test, Digital	Assignme	ent, Quiz and Final	Assessment	
Rec	commended by Board of Studies	09-07-2022				
Δ	proved by Academic Council	No. 67	Date	08-08-2022		



Course Code Integrated Circuits for Power Conversion L T P C MPED608L I Syllabus version I 0 0 0 2 Pre-requisite NIL Syllabus version 1.0 Course Objectives 1.0 Course Objectives 1.0 Course Objectives 1.0 Course Objectives 1.0 At the end of the course, the student will be able to 1. Course Outcome X K At the end of the course, the student will be able to 1. Course Objectives K K 3. Formulate suitable carrier wave generation techniques for power converters 2. Interface sensors, ADC and DAC for closed loop power converters 3. Formulate suitable circuits for grid synchronization 4. Prepare Schematic and PCB Layout K Module:1 Switching pulse generation for power converters 6 hours 6 hours Op-Amp: Linear and Non-Linear applications; Trailing edge, leading edge, and double edge carrier wave generation; 555 Timer based application circuits; Pulse width modulation techniques: Power converters; Inverters 6 hours Module:1 Sensor interfaces 4 hours F<		-	(Deemed to be University under section 3 of UGC Act, 1956)	-		_		
Pre-requisite NIL Syllabus version Course Objectives 1.0 1. To understand and analyze PWM techniques for power converters 2. 2. To develop critical design thinking for closed loop and grid synchronization 3. 3. To design PCB schematic and layout Course Outcome At the end of the course, the student will be able to 1. 1. Compare and choose suitable carrier wave generation techniques for power converters 2. 2. Interface sensors, ADC and DAC for closed loop power converters 3. 3. Formulate suitable circuits for grid synchronization 4. 4. Prepare Schematic and PCB Layout Module:1 Switching pulse generation for power converters 6 hours 0p-Amp: Linear and Non-Linear applications; Trailing edge, leading edge, and double edge carrier wave generation; 555 Timer based application circuits; Pulse width modulation techniques: Power converters; inverters 4 hours Module:2 Sensor interfaces 4 hours Hall effect sensor: AC/DC Vollage and current sensors, signal gain design; 8 bit ADC and DACs Module:3 Module:3 Closed loop control 4 hours Power converters; Nottage regulation using analog and digital Integrated circuits, Design and tuning of PIC controller parameters; Real time interface: Rapid co		de	Integrated Circuits for Power Convers	sion		Т		
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Text Book(s)	Text Book	s)						
Robert F. Coughlin and Frederick F. Driscoll, "Operational Amplifiers and Linear Integrated	Rober		Courdelin and Frederick F. Driscoll "Operational Ar	nnlifiers and I	ine	ar Int	ear	ated
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	Reference							
o	Circui							
Circuits", PHI Learning Private Limited, Sixth Edition, 2015.	Reference	Books						



(Deemed to be University under section 3 of UGC Act, 1956)							
1	Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory", Prentice						
1.	Hall, Eleventh Edition, 2015.						
2.	Bob Dobkin, Jim Williams, "Analog Circuit Design: A Tutorial Guide to Applications and						
۷.	Solutions", Elsevier Inc, First Edition, 2011.						
3.	PCB Design with Proteus – Udemy online course						
4.	Datasheets: Devices and IC's						
Mode of Evaluation: Continuous Assessment Tests, Quizzes, Assignment, Final Assessment Test							
Recommended by Board of 09-07-2022							
Studies							
Appr	oved by Academic Council	No. 67	Date	08-08-2022			



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	rse Code	Course Title					<u> </u>	Ρ	C
	D608P		ed Circuits for I	for Power Conversion Lab) 0	2	1
Pre-	Pre-requisite Nil Sy						bus		ion
Cour	rse Objective	<u> </u>					1.0)	
	-	s Id fabricate PWM	circuits for powe	er convert	ers				
		validate the contr							
Expe	ected Course	Outcome							
		of this course the analysing variou			wer conversion				
·· ·									
Indic	cative Experin	nents					Нс	ours	
1.	Generation of	of symmetric and	asymmetric carr	ier waves					
2.	Switching pu	Ilse generation for	r non-isolated D	C to DC c	onverter				
3.	Variable frequency pulse generation using VCO								
4.	Pulse width modulation using 555 timer								
5.	PWM controlled rectifier with grid synchronization								
6.	Switching pulse generation for single phase inverter								
7.	Implementation of dual linear regulated power supply								
8.	Generation of	of phase shifted s	witching pulses						
9.	Generation of gate pulses with dead-band								
10.	Generation of overlapping gate pulses								
11.	Switching pulse generation for three phase inverter								
12.	Gate pulse generation for multilevel inverter								
13.	Preparation	of schematic and	PCB Layout						
				Total	Laboratory Hou	urs:	3	0 ho	urs
Text	Book(s)								
	Robert F. Coughlin and Frederick F. Driscoll, "Operational Amplifiers and Linear Integrated Circuits",								
PHI I	Learning Priva	ate Limited, Sixth				-			
	erence Books		holoky "Electre	nia Davier	and Circuit Th	00"" F)ro pt		
Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory", Prentice Hall, Eleventh Edition, 2015.									
Bob Dobkin, Jim Williams, "Analog Circuit Design: A Tutorial Guide to Applications and Solutions",									
Elsevier Inc, First Edition, 2011.									
Recommended by Board of 09-07-2022									
Studies Approved by Academic Council No. 67 Date 08-08-2022									



	(Deemed to be University under section 3 of UGC Act, 1956)	-	· '			
Course Code	Course Title	L	T	P	<u>C</u>	
MPED609L	Power Electronics Application in Power Systems	3	0	0	<u>3</u>	
Pre-requisite Nil			Syllabus version 1.0			
Course Objective	S		1.	0		
1. To impart in	n-depth knowledge of reactive power control, application of FAC It the importance of flexible AC transmission systems and contro		ontro	ollers		
Course Outcome						
the end of the cours 1. Apply the c 2. Operation, 3. Operating p flow control 4. Application	se the student will be able to oncept of load compensation and reactive power control to AC modelling and performance analysis of shunt and Series FACT principle, modeling and control structure of Phase angle regulator ller of FACTS controllers in transmission system nsive knowledge of line commutated and modular multilevel con	S devi and l	ices Jnifi	ed po		
	smission System Compensation Systems : importance of controllable parameters, stability Limi ompensation	ts; Th	eory		ours tatic	
Module:2 SVC				Cha		
Objectives of she	and STATCOM unt compensation ;SVC : Comparison of different SVC , aracteristics ,Dynamic compensation	Volt	age		ours trol;	
Module:3 TCS	C and SSSC			6 hc	ours	
Need for variable	series compensation ; TCSC: modelling of TCSC, operating c acteristics; SSSC: control range and VA rating	ontrol	sch			
Module:4 Phas	se angle Regulator			6 hc	ours	
Objectives of volt	tage and phase angle regulator : Thyristor controlled voltage hing converter based voltage and phase angle regulator	and	pha			
Module:5 Unif	ied Power flow controller			6 hc	ours	
	le : control structure, Performance analysis			0 110		
	· · · · · ·					
	lication of FACTS Devices resonance, Damping oscillations, Transient stability and ACTS	volta	ige		ours ility;	
	Voltage DC Transmission	_			ours	
	Converter: Line commutated converters and Modular Multi leve ntemporary Topics	l conv	erte		ours	
				2 110		
	Total Lecture hours:		4	45 ho	ours	
Textbook(s) 1. Narain Hingo	orani & Lazzlo Gyugi "Understanding FACTS. Concepts & Tech	noloa	v of	FAC	TS"	
	and a Lattic Cyage of a formation of a formation of the f		, 01	0	. ,	



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	Standard publishers & distributors, 2011				
2.	Mohan Mathur, Rajiv. K. Varma, "Thyristor Based FACTS Controllers for Electrical				
	Transmission systems" John Wiley and Sons, 2001				
Reference Books					
1.	T.J.E Miller "Reactive Power Control in Electric system" John Wiley & Sons, NY, 2010.				
2.	Enrique Acha, Claudio R. Fuerte-Esquivel, Hugo Ambriz-Pérez, "FACTS: Modelling and				
	Simulation in Power Networks", John Wiley, 2011				
3.	K.R.Padiyar, "FACTS controllers in Power transmission and disribution", New Academic				
	Science, 2011				
4.	Dragan Jovcic, "High Voltage Direct Current Transmission: Converters, Systems and				
	DC Grids", 2019, Wiley Publications				
Mode of Evaluation: Continuous Assessment Test, Digital Assignment, Quiz and Final Assessment					
Test					
Reco	Recommended by Board of Studies 09-07-2022				
Appro	Approved by Academic Council No. 67 Date 08-08-2022				