

SCHOOL OF MECHANICAL ENGINEERING

M.Tech – Mechanical specialization in Cyber Physical System

M.Tech (CPS)

Curriculum

(2019-2020 admitted students)



VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research.

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international industries & universities for productivity and economic development.

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF MECHANICAL ENGINEERING

• To be a leader in imparting world-class education in Mechanical Engineering, leading to nurturing of scientists and technologists of the highest caliber who would engage in the sustainable development of the globe.

MISSION STATEMENT OF THE SCHOOL OF MECHANICAL ENGINEERING

• The mission of the school is to create and maintain an environment for Excellence in Instruction, Learning, and Applied Research in the area of Mechanical and allied disciplines so as to equip our students with necessary knowledge and skills for higher education/employment and to meet the social demands.



PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

- 1. Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems.
- 2. Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry.
- 3. Graduates will function in their profession with social awareness and responsibility.
- 4. Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country.
- 5. Graduates will be successful in pursuing higher studies in engineering or management.
- 6. Graduates will pursue career paths in teaching or research.



PROGRAMME OUTCOMES (POs)

PO_01: Having an ability to apply mathematics and science in engineering applications

PO_02: Having an ability to design a component or a product applying all the relevant standards and with realistic constraints

PO_03: Having an ability to design and conduct experiments, as well as to analyze and interpret data

PO_04: Having an ability to use techniques, skills and modern engineering tools necessary for engineering practice

PO_05: Having problem solving ability- solving social issues and engineering problems

PO_06: Having adaptive thinking and adaptability

PO_07: Having a clear understanding of professional and ethical responsibility

PO_08: Having a good cognitive load management [discriminate and filter the available data] skills



PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of M.Tech. –Mechanical specialization in Cyber Physical system, graduates will be able to

PSO_01: Design and analyze overall specifications of Cyber Physical System and translate it to the different sub-systems design requirements.

PSO_02: Adopt a multidisciplinary approach to design overall Cyber Physical System using Hybrid system and other approaches and validate the model.

PSO_03: Independently carry out research / investigation to solve practical problems and write / present a substantial technical report/document.



CREDIT STRUCTURE

Category-wise Credit distribution

Category		Credits
University core	(UC)	27
Programme core	(PC)	19
Programme elective	(PE)	18
University elective	(UE)	06
Total credits		70



DETAILED CURRICULUM

UNIVERSITY CORE

Sl. No.	COURSE CODE	COURSE TITLE	L	Т	Р	J	С
1.	MAT5005	Advanced Mathematical Methods	3	0	0	0	3
	ENG5001	Fundamentals of Communication skills	0	0	2	0	1
	&	&					
	ENG5002	Professional and Communication Skills	0	0	2	0	1
2.	(or)						
	FRE5001	Francais Fonctionnel	2	0	0	0	2
	(or)						
	GER5001	Deutsch fuer Anfänger	2	0	0	0	2
	STS5001	Essentials of Business Etiquette and Problem Solving	3	0	0	0	1
3.	&	&					
	STS5002	Preparing for Industry	3	0	0	0	1
4.	SET5001 & SET5002	SET Projects	-	-	-	-	4
5.	MEE6099	Master's Thesis	-	-	-	-	16

PROGRAMME CORE

S.No	COURSE	COURSE TITLE	L	Т	Р	J	С
	CODE						
1.	MEE5028	Mechatronics and Cyber-Physical Systems	3	0	2	0	4
2.	MEE5029	System Modeling and Simulation	2	0	2	0	3
3.	MEE5030	Smart Mobility and Intelligent Vehicles	3	0	0	4	4
4.	MEE5031	Digital Manufacturing and Factory Automation	3	0	2	0	4
5.	MEE5032	Artificial Intelligence and Machine learning	3	0	0	4	4



PROGRAMME ELECTIVES

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COURSE	COURSE	COURSE TITLE		T	Р	J	С
	CODE						
1.	MEE6061	IIoT and Cloud Computing	2	0	2	0	3
2.	MEE6062	Virtual Reality & Augmented Reality	2	0	2	0	3
3.	MEE6063	MEMS in Cyber Physical Systems	2	0	0	4	3
4.	MEE6064	Applied Robotics and Programming	2	0	2	0	3
5.	MEE6065	Hybrid and Electric Automotive Vehicle systems	3	0	0	4	4
6.	MEE6066	Cyber-Security in Design and Manufacturing	3	0	0	0	3
7.	MEE6067	Transportation Cyber Physical Systems	3	0	0	0	3
8.	MEE6068	Smart Health Technology	2	0	0	4	3
9.	MEE6069	Digital Systems Design and Architecture	3	0	0	0	3
10.	MEE6070	Data Science and Analytics	2	0	0	4	3
11.	MEE6071	Wireless Networking of Embedded Systems	2	0	0	4	3
12.	MEE6072	Multi-Agent System	3	0	0	4	4
13.	MEE6073	Control System Analysis and Design	3	0	2	0	4



University Core



		Course Title		T	P	J	C
MAT5005		Advanced Mathematical Metho	ods 3	0	0	0	3
Pre-requisit	e		Sylla	abus ve	ersion		
•					2.0		
Course Obje	ectives(CoB):	!				
		de the students with sufficient ex	xposure to	advar	nced n	nather	natica
		and tools that are relevant to engin					
		g the computational skills of stude			fficien	t knov	wledge
		ical and numerical techniques use					
		cal Engineering.		01			0
		g the knowledge of real time app	lications	of Aut	onomo	ous sy	stems
		ar systems of ordinary differentia					
	quation	5	1		1		
	1						
Course Outo	come(C	O):					
	,	analyse a variety of tools for s	olving lin	ear sv	stems	and f	finding
		hese systems.		Jul Oyi			
0		se the numerical techniques nee	ded for t	he sol	ution	ofa	giver
engineer		-	aca ioi i	.110 501	ation	or u	81701
0	01	correlate the analytical and numeri	cal metho	ds			
		5					
		mathematical proofs and scu	entitic ar	giimen	ts	neec	led to
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systems - Phase Plane Phenomena - for linear systems.

Critical Points - Stability

ical Follits - Stability

6 hours

6 hours

Module:5 Nonlinear systems

Simple critical points of nonlinear systems-Stability by Liapunov's method –

Non- Linear Mechanics: Conservative systems.

Module:6	Partial Differential	5 hours
	Equations	

Classification of Second-Order Partial Differential Equations, Significance of characteristic curves, Canonical Form, Sturm–Liouville problems and Eigen function expansions.

Module:7	Wave ec	uation					
	_		-	_	_	-	_

Displacements in a long string – a long string under its weight – a bar with prescribed force on one end – free vibrations of a string. Method of Separation of variables, Solution by method of Laplace transforms

Module:8	Contemporary Issues	2 hours
Industry Expe	ert Lecture	

	Total Lecture hours:45 hour	rs
Text	Book(s)	
1	Differential Equations: Theory, Technique and Practice, G.F. Simmons, S.	G.
	Krantz, Tata McGrawHill Publishing, 2007. (Topics from Chapters 10, 11)	
2	Elements of Partial differential equations, Ian N. Sneddon, Dover Publication	ns,
	New York, 2006. (Topics from Chapters 3, 5)	
3	Numerical Methods for Scientific and Engineering Computation, M. K. Jain, S.	R.
	K. Iyengar, R. K. Jain, New Age International publishers, 7thedition, New Dell	hi,
	2019. (Topics from Chapter 3, 7)	
4	Introductory Methods of Numerical Analysis, S. S. Sastry, PHI Pvt. Ltd., 5	5th
	Edition, New Delhi, 2015. (Topics from Chapter 11)	
5	The Calculus of Variations, Bruce van Brunt, Springer, 2004. (Topics fro	m
	Chapters 2, 4, 5)	
Refe	ence Books	
1	Differential Equations and Dynamical Systems, Lawrence Perko, 3rd ed., Springe	er-
	Verlag, 2001.	
2	An introduction to Ordinary Differential Equations, James C. Robinson, Cambridge	ge
	University Press, New York, 2008 (4th print).	
3	Elementary Applied Partial Differential Equations, Richard Haberman, Prenti	ce
	Hall International, 1998.	



4	Numerical Analysis, R. L.	Burden and J. D. Faires,					
	10 th Edition, Cengage Learning, India edition, 2015.						
Mode	e of Evaluation: Continuous Ass	sessment '	Tests, Fir	al Assessment Test, Digital			
Assig	nments, Quizzes.						
Mode	e of evaluation:						
Reco	mmended by Board of Studies	3 03-06-2019					
Appr	oved by Academic Council	No. 55	Date	13-06-2019			

Course code	Course title	L	Т	Р	J	C
ENG5001	Fundamentals of Communication Skills	0	0	2	0	1



Pre-req	uisite	As per the	academic	Syllabus version
		regulations		
0	01.1			v. 1.0
	Objectives			1. 1547.44
			n skills - Listening, Speaking, Re	
2. To he	lp learners	apply effective communicati	on in social and academic contex	Kt
3. To ma	ike student	s comprehend complex Engl	ish language through listening ar	nd reading
	Outcome(
		unicate effectively in social a	and academic contexts	
	-	e writing skills		
		r understanding the commun	ication Skills	
Module		istening		8 hours
	inding Cor			
•	g to Speec			
		fic Information		
Module:		peaking		4 hours
0	ing Inform	es, Events and Quantity		
Module:		leading		6 hours
	ng Inform	0		0 11001 5
5	Meaning			
Interpret				
Module		Vriting: Sentence		8hours
Basic Se	ntence Str	0	I	
Connect	ives			
Transfor	mation of	Sentences		
Synthesi	s of Senter	ices		
Module	:5 V	Vriting: Discourse		4hours
Instructi				
Paragrap				
Transco	ling			
			Total Lecture hou	rs: 30 hours
			Total Lecture nou	
Text Bo	ok(s)			
		Chris Theresa Clementson	, and Gillie Cunningham. <i>Fa</i>	ce2face Unner
		ate Student's Book. 2013, Car	6	confider opper
	ce Books			
1		viak .Stepping Stones: A auid	led approach to writing sentence	s and Paraaraphs
		dition), 2012, Library of Con		- J - F - G
2.			comb, Effective Interpersonal an	d Team
-			013, John Wiley & Sons, Inc., H	
			=	
3.	Jersey.			

	VIT Vellore Institute of Technology Obmult to be University under section 3 of UCC Act, 1959	
4.	Engineers and IT Professionals,2012	, IGI Global,
5.	Hershey PA.	
	Judi Brownell, Listening: Attitudes, Principles and Skills, 2016	5, 5 th Edition,
	Routledge:USA John Langan, Ten Steps to Improving College Reading Skills, 202	14 6 th Edition
	Townsend Press:USA	14, 0 Euluoli,
	Redston, Chris, Theresa Clementson, and Gillie Cunningham. <i>Fa</i>	ce2face Upper
	Intermediate Teacher's Book. 2013, Cambridge University Press.	
	Authors, book title, year of publication, edition number, press, place	
Mod	e of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar	
	List of Challenging Experiments (Indicative)	
1.	Familiarizing students to adjectives through brainstorming adjectives with	2 hours
	all letters of the English alphabet and asking them to add an adjective that	
	starts with the first letter of their name as a prefix.	
2.	Making students identify their peer who lack Pace, Clarity and Volume	4 hours
	during presentation and respond using Symbols.	
3.	Using Picture as a tool to enhance learners speaking and writing skills	2 hours
4.	Using Music and Songs as tools to enhance pronunciation in the target language / Activities through VIT Community Radio	2 hours
_		
5. 6.	Making students upload their Self- introduction videos in Vimeo.com	4 hours
0.	Brainstorming idiomatic expressions and making them use those in to their	4 hours
7.	writings and day to day conversation Making students Narrate events by adding more descriptive adjectives and	4 hours
	add flavor to their language / Activities through VIT Community Radio	4 110013
8	Identifying the root cause of stage fear in learners and providing remedies	4 hours
	to make their presentation better	
9	Identifying common Spelling & Sentence errors in Letter Writing and other	2 hours
	day to day conversations	
10.	Discussing FAQ's in interviews with answers so that the learner gets a	2 hours
	better insight in to interviews / Activities through VIT Community Radio	
	Total Laboratory Hours	30 hours
Mod	e of evaluation: Online Quizzes, Presentation, Role play, Group Discussions, A	Assignments,
	i Project	
	ommended by Board of Studies 22-07-2017	
App	roved by Academic Council No. 46 Date 24-8-2017	



Course code	Course title		LI		JC
ENG5002	Professional and Communication Skills		0 0	2	0 1
Pre-requisite	ENG5001	Sy	llabu	ıs ve	rsio
					v. 1.
Course Objective	es(CoB):				
1. To enable stude	ents to develop effective Language and Communication Skills)			
2. To enhance stu	dents' Personal and Professional skills				
3. To equip the stu	dents to create an active digital footprint				
Course Outcome	(CO):				
Students will be a	ble to apply the acquired skills and excel in a professional env	vironi	nent		
Module:1	Personal Interaction			2ŀ	iour
Introducing Oneself	f- one's career goals				
A attaction CMIOT A	- alvaia				
Activity: SWOT A Module:2	Interpersonal Interaction			<u></u>	iour
	nunication with the team leader and colleagues at the workplace			<u> </u>	iour
interpersonal Collin	numeation with the team reader and confedgues at the wolkplace				
Activity: Role Plays					
Module:3	Social Interaction			2 ł	iour
Use of Social Media	a, Social Networking, gender challenges				
Activity: Creating I	.inkedIn profile, blogs				
Module:4	Résumé Writing			41	10ur
	irement and key skills				
	n Electronic Résumé				
Module:5	Interview Skills			_4 ł	iour
	view, Group Discussions				
0	rview and mock group discussion				
Module:6	Report Writing			4 r	iour
Language and Mech	nanics of Writing				
A attraction Adviting a	Depert				
Activity: Writing a Module:7	Study Skills: Note making				iour
Iviouuic./	Study Skills. Note making				ioui
Summarizing the re	port				
Activity: Abstract	Executive Summary, Synopsis				
Module:8	Interpreting skills			2 ł	iour
Interpret data in tab				<u> </u>	Jui
-					
Activity: Transcodi	0				
Module:9	Presentation Skills			4 ł	iour
Oral Presentation us	sing Digital Tools				
Activity: Oral prese	ntation on the given topic using appropriate non-verbal cues				
Module:10	Problem Solving Skills			4 ł	iour

		Vellore Institute of Techno (Deemed to be University under section 3 of UGC Au	logy tt, 1956)		
Prol	olem Solving & Conflict Resolution				
Acti	ivity: Case Analysis of a Challenging Sce	nario			
	T	otal Lecture hou	rs:		30hours
	tt Book(s)		- 11		1
1	BhatnagarNitin and MamtaBhatnag		0		
	Engineers And Professionals, 2010	, Dorling Kindersl	ey (India	a) Pvt. Ltd.	
	erence Books		-		
1	Jon Kirkman and Christopher Turk,		: Improv	ving Scientific,	Technical and
_	Business Communication, 2015, Ro	0			
2	Diana Bairaktarova and Michele E	odice, Creative W	ays of h	Knowing in Eng	gineering, 2017,
_	Springer International Publishing	E Whiteemb	Effecti	La Internerse	nal and Toam
3	Clifford A Whitcomb & Lesli Communication Skills for Engineer				
_	ArunPatil, Henk Eijkman &Ena				
4	Engineers and IT Professionals,201	-			
Mo	de of Evaluation: CAT / Assignment /				
		-	, 		
	t of Challenging Experiments (Indic			1.	21
1.	SWOT Analysis – Focus specially	on describing two	strength	is and two	2 hours
	weaknesses				
2.	Role Plays/Mime/Skit Workplace	Situations			4 hours
3.	Liss of Social Modia Croste a Lin	radin Drafila and) hours
з.	Use of Social Media – Create a Lin		also with	e a page or	2 hours
	two on areas of interest				
4.	Prepare an Electronic Résumé and	pload the same in	ı vimeo		2 hours
	Crown disquesion on latest tonies				1 hours
<u>5.</u>	Group discussion on latest topics				4 hours
6 7	Report Writing – Real-time reports	mary on chart coi	optific o	r rocoarch	2 hours
/	Writing an Abstract, Executive Sun articles	initiary on short set	enunc o	rresearch	4 hours
,	anneres				
		raph chart or diag	1000		2 hours
8	Transcoding – Interpret the given g	U		rbal cuos	2 hours
8 9	Transcoding – Interpret the given g Oral presentation on the given topic	using appropriate	e non-ve	rbal cues	4 hours
8 9	Transcoding – Interpret the given g	using appropriate	e non-ve	rbal cues	4 hours 4 hours
8 9	Transcoding – Interpret the given g Oral presentation on the given topic	t using appropriate of a Challenging S	e non-vei cenario	rbal cues ratory Hours	4 hours
8 9 10	Transcoding – Interpret the given g Oral presentation on the given topic	e using appropriate f a Challenging S Tot	e non-ve cenario a l Labo	ratory Hours	4 hours 4 hours 30 hours
8 9 10 Mo	Transcoding – Interpret the given g Oral presentation on the given topic Problem Solving Case Analysis c de of evaluation: : Online Quizzes, Pr	e using appropriate f a Challenging S Tot	e non-ve cenario a l Labo	ratory Hours	4 hours 4 hours 30 hours
8 9 10 Mo Mir	Transcoding – Interpret the given g Oral presentation on the given topic Problem Solving Case Analysis c de of evaluation: : Online Quizzes, Pr ni Project	e using appropriate f a Challenging S Tot	e non-ve cenario a l Labo	ratory Hours	4 hours 4 hours 30 hours

Course code	Deutsch für Anfänger	L T P J C
GER5001		2 0 0 2
Pre-requisite		Syllabus version



				V.
Course Object	· · · · ·			
The course give	es students the necessa	ry background to:		
1. Enable stude	nts to read and comm	unicate in German in th	eir day to day l	ife
2. Become indu	stry-ready			
3. Make them	inderstand the usage c	of grammar in the Germ	an Language.	
Course Outco	· · · ·			
The students w	ll be able to			
1. To greet	neonle introduce onese	lf and understand basic ex	voressions in Cer	חברתי
0	· ·	l skills to use these in a	•	inan
-	n beginner's level voca		incaning way	
	0	s with significant precis	ion and in detai	1
		nension of written disco		
	Subdute Bood compres			special interests
Module:1				3 hour
Einleitung, Be	rüssungsformen, Lan	deskunde, Alphabet, P	ersonalpronom	
0	, 0	itze, Nomen – Singular	-	, 10
Lernziel:	,,			
		anus Artikolusörtor		
	tändnisvon Deutsch, Ge			
Liementares ver	ständnisvon Deutsch, Ge	enus- Antikerworter		
Module:2 Konjugation de	r Verben (regelmässig	g /unregelmässig) die M		0
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel :	r Verben (regelmässig	g /unregelmässig) die M (Hundert bis eine Millio		hentage, Hobbys,
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i	r Verben (regelmässig eiten, Artikel, Zahlen	g /unregelmässig) die M (Hundert bis eine Millio		hentage, Hobbys, Trage, Imperativ mit
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw.	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kası	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, t Module:3 Possessivprono trennnbareverb	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kası	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw.	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kası	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel :	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, t Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit UnbestimmterArtikel hlzeiten, Lebensmitte
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, t Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit <u>4 hour</u> unbestimmterArtikel hlzeiten, Lebensmitte
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kası en, Modalverben, A Modalverben, Verv	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv gbeschreiben.	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv gbeschreiben.	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen Lernziel :	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv gbeschreiben. : (Deutsch – Englisch	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, t Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen Lernziel :	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv gbeschreiben.	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen Lernziel : Grammatik – V	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, A Modalverben, Verv gbeschreiben. : (Deutsch – Englisch	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher 6 hour
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen Lernziel : Grammatik – V	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, Kasu Modalverben, Verv gbeschreiben. : (Deutsch – Englisch /ortschatz - Übung	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü / Englisch – Deutsch)	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher 6 hour 5 hour
Module:2 Konjugation de Berufe, Jahresz Sie Lernziel : Sätzeschreiben, i Module:3 Possessivprono trennnbareverb Getränke Lernziel : Sätze mit übereineWohnur Module:4 Übersetzungen Lernziel : Grammatik – V	r Verben (regelmässig eiten, Artikel, Zahlen iber Hobbys erzählen, ü men, Negation, Kasu en, Modalverben, Kasu Modalverben, Verv gbeschreiben. : (Deutsch – Englisch /ortschatz - Übung	g /unregelmässig) die M (Hundert bis eine Millio berBerufesprechenusw. 1s- AkkusatitvundDativ djektive, Uhrzeit, Präp vendungvonArtikel, ü	on), Ja-/Nein- F	hentage, Hobbys, Frage, Imperativ mit 4 hour unbestimmterArtikel hlzeiten, Lebensmitte undSprachensprecher 6 hour 5 hour



3 hours

4 hours

WortschatzbildungundaktiverSprachgebrauch

Module:6

Aufsätze :

MeineUniversität, Das Essen, mein Freund odermeineFreundin, meineFamilie, einFest in Deutschlandusw

Module:7

Dialoge:

- a) Gespräche mit Familienmitgliedern, Am Bahnhof,
- **b)** GesprächebeimEinkaufen ; in einemSupermarkt ; in einerBuchhandlung ;
- **c)** in einemHotel an der Rezeption ;einTerminbeimArzt.

TreffenimCafe

Mo	dule:8						2 ho	urs
Gue	est Lectures	/Native Speakers / Fei	nheiten der deutso	chen Spr	ache, Basis	information	über	die
deu	tschsprachige	en Länder						
			Total Lecture he	ours: 3	30 hours			
Tex	t Book(s)					•		
1.	1. Studio d A1 Deutsch alsFremdsprache, Hermann Funk, Christina Kuhn, SilkeDemme : 2012							
Ref	Reference Books							
1	Netzwerk	Deutsch alsFremdsprach	ne A1, Stefanie De	ngler, Pa	aul Rusch, H	lelen Schmt	iz, Ta	nja
	Sieber, 20	13						
2		artmutAufderstrasse, Ju	tta Müller Thoma	s Storz (0010			
3	<u> </u>	Sprachlehrefür AUslände						
3	Deutsche	SprachienierurAOsianue		li, Dula s	5CHUIZ, 2011	-		
4	ThemenAl	ktuell 1, HartmurtAufde	rstrasse, Heiko Bo	ck, Mecl	nthildGerdes	s, Jutta Müll	er und	1
	Helmut M	üller, 2010						
	www.goet	he.de						
	wirtschafts	sdeutsch.de						
	hueber.de							
	klett-sprac	hen.de						
	www.deut	schtraning.org						
Mo	de of Evalua	ation: CAT / Assignmer	nt / Ouiz / FAT					
		by Board of Studies	22-07-2017					
		cademic Council	No: 47	Date	05-10-20	17		

Course code	FRANCAIS FONCTIONNEL	L T P J C				
FRE5001		2 0 0 2				
Pre-requisite		Syllabus version				
		v.1				
Course Objectives(CoB):						



The course gives students the

necessary background to:

9 hours

- **1.** Demonstrate competence in reading, writing, and speaking basic French, including knowledge of vocabulary (related to profession, emotions, food, workplace, sports/hobbies, classroom and family).
- **2.** Achieve proficiency in French culture oriented view point.

Course Outcome(CO):

The students will be able to

- 1 To Identify in French language the daily life communicative situations via personal pronouns, emphatic pronouns, salutations, negations, interrogations etc
- 2 To communicate effectively in French language via regular / irregular verbs
- 3 To demonstrate comprehension of the spoken / written language in translating simple sentences
- 4 To understand and demonstrate the comprehension of some particular new range of unseen written materials
- 5 To demonstrate a clear understanding of the French culture through the language studied

Module:1Saluer, Se présenter, Etablir des contacts

Les Salutations, Les nombres (1-100), Les jours de la semaine, Les mois de l'année, Les Pronoms Sujets, Les Pronoms Toniques, La conjugaison des verbes réguliers, La conjugaison des verbes irréguliers- avoir / être / aller / venir / faire etc.

Modu	lle:2	Présenter correspond d'une pers	lant(e), Der	n, Chercher nander des no						
La	conj	ugaison	des	verbes	Pronom	ninaux,	La	Négation,		

L'interrogation avec 'Est-ce que ou sans Est-ce que'.

	1	
Module:3	Situer un objet ou un lieu, Poser des	9 hours
	questions	
L'article (défin	ni/ indéfini), Les prépositions (à/en/au/aux/sur/o	lans/avec etc.), L'article contracté,
Les heures en	n français, La Nationalité du Pays, L'adjectif	(La Couleur, l'adjectif possessif,
l'adjectif dém	onstratif/ l'adjectif interrogatif (quel/qu	elles/quelle/quelles), L'accord des
adjectifs avec l	le nom, L'interrogation avec Comment/ Combier	n / Où etc.,
Module:4	Faire des achats, Comprendre un texte	8 hours
	court, Demander et indiquer le chemin.	
La traduction s	simple :(français-anglais / anglais –français)	

Module:5	Trouver les questions, Répondre aux	7 hours
	questions générales en français.	
L'article Parti	tif, Mettez les phrases aux pluriels, Faites une phrase avec les mots	donnés,



	Vellore Institute of Techn (Deemed to be University under section 3 of UGO	1010gy (7 Act, 1956)		
Exprimez les phrases données au		I	Masculin ou F	éminin, Associez les
phrases.				
Module:6 Comment ecrire un	passage			9 hours
Décrivez :				
La Famille /La Maison, /L'université	/Les Loisirs/ La Vie	quotic	lienne etc.	
Module:7 Comment ecrire un	dialogue			7 hours
Dialogue:				
d) Réserver un billet de train				
e) Entre deux amis qui se rencon				
f) Parmi les membres de la famil	le			
g) Entre le client et le médecin				
Module:8 Invited Talk: Nativ	e speakers			2 hours
	Total Lecture ho	urs:	30 hours	
Text Book(s)				
1. Echo-1, Méthode de français, J. C	Girardet, J. Pécheur, I	Publis	her CLE Inter	national, Paris 2010.
2 Echo-1, Cahier d'exercices, J. Gi				
Reference Books				
1. CONNEXIONS 1, Méthode de fi	rançais, Régine Méri	eux, Y	ves Loiseau,l	Les Éditions Didier,
2004.				
2 CONNEXIONS 1, Le cahier d'e	xercices, Régine Mé	rieux,	Yves Loiseau	ı, Les Éditions
Didier, 2004.				
3 ALTER EGO 1, Méthode de fra			0	-
Kizirian, Béatrix Sampsonis, Mo		, Hacl	hette livre 200)6.
Mode of Evaluation: CAT / Assignme				
Recommended by Board of Studies	22-07-2017			
Approved by Academic Council	No. 47	Date	05-10-20	17

Course code	Course title		L	Т	Р	J	С
STS5001	Essentials of Business Etiquette and problem solving		3	0	0	0	1
Pre-requisite		Syllabus ver			ers	sion	



Course Objectives(CoB):

- 1 To develop the students' logical thinking skills
- 2 To learn the strategies of solving quantitative ability problems
- **3** To enrich the verbal ability of the students
- 4 To enhance critical thinking and innovative skills

Course Outcome(CO):

- 1 To enable students to use relevant aptitude and appropriate language to express themselves
- 2 To communicate the message to the target audience clearly

Module:1Business Etiquette: Social and Cultural Etiquette and
Writing Company Blogs and Internal Communications and
Planning and Writing press release and meeting notes

Value, Manners, Customs, Language, Tradition, Building a blog, Developing brand message, FAQs', Assessing Competition, Open and objective Communication, Two way dialogue, Understanding the audience, Identifying, Gathering Information, Analysis, Determining, selecting plan, Progress check, Types of planning, Write a short, catchy headline, Get to the Point – summarize your subject in the first paragraph., Body – Make it relevant to your audience,

Module:2	Study skills – Time management skills	3 hours
Prioritization, Pr	ocrastination, Scheduling, Multitasking, Moni	toring, working under pressure and
adhering to dead	lines	

Module:3	Presentation skills – Preparing	7 hours
	presentation and Organizing materials	
	and Maintaining and preparing visual	
	aids and Dealing with questions	

10 Tips to prepare PowerPoint presentation, Outlining the content, Passing the Elevator Test, Blue sky thinking, Introduction , body and conclusion, Use of Font, Use of Color, Strategic presentation, Importance and types of visual aids, Animation to captivate your audience, Design of posters, Setting out the ground rules, Dealing with interruptions, Staying in control of the questions, Handling difficult questions

Module:4	Quantitative Ability -L1 – Number	11 hours
	properties and Averages and	
	Progressions and Percentages and Ratios	
Number of fa	actors, Factorials, Remainder Theorem, Unit d	ligit position. Tens digit position.

Number of factors, Factorials, Remainder Theorem, Unit digit position, Tens digit position, Averages, Weighted Average, Arithmetic Progression, Geometric Progression, Harmonic Progression, Increase & Decrease or successive increase, Types of ratios and proportions



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WIO	ule:5	Reasoning Ability-L1 – Analytical Reasoning	8 hours
Data	Arrangen	nent (Linear and circular & Cross Variable Relationsh	ip), Blood Relations,
Orde	ring/ranki	ng/grouping, Puzzle test, Selection Decision table	
Mod	ule:6	Verbal Ability-L1 – Vocabulary Building	7 hours
	5	Antonyms, One-word substitutes, Word Pairs, Spellin	ngs, Idioms, Sentence
соп	pletion, A	malogies	
		Total Lecture hours:	45 hours
Refe	rence Boo	 Dks	
1.	Conver	Patterson, Joseph Grenny, Ron McMillan, AlSwitzler (sations: Tools for Talking When Stakes are High. Bar w-Hill Contemporary	
2.		arnegie, (1936) How to Win Friends and Influence I	People. New York. Gallery
3.	Scott P	eck. M (1978) Road Less Travelled. New York City. I	M. Scott Peck.
4.	FACE ((2016) Aptipedia Aptitude Encyclopedia. Delhi. Wiley	y publications
5.	ETHNU	JS (2013) Aptimithra. Bangalore. McGraw-Hill Educ	ation Pvt. Ltd.
Web	sites:		
1.	www.c	halkstreet.com	
2.	www.sl	killsyouneed.com	
	www.n	<u>iindtools.com</u>	
3.			
3. 4.	www.th	<u>nebalance.com</u>	
		<u>nebalance.com</u> guru.ooo	



Course code	Course title		L T P J C
STS5002	Preparing for Industry	/	3 0 0 1
Pre-requisite			Syllabus version
			1
Course	1 To challenge students to explore th	eir problem-solv	ing skills
Objectives:	2 To enhance the essential skills to ta	-	-
J	verbal ability questions	1	
	3 To improve working knowledge of	communicating	in English
	· · · · · · · · · · · · · · · · · · ·	<u> </u>	<u>×</u>
Course	Enabling students to simplify, evaluate	, analyze and use	e functions and
Outcome:	expressions to simulate real situations	to be industry rea	ndy.
			-
Module:1	Interview skills – Types of interview		3 hours
	and Techniques to face remote		
	interviews and Mock Interview		
Structured and unst	ructured interview orientation, Closed quest	ions and hypothe	etical questions,
Interviewers' persp	ective, Questions to ask/not ask during an ir	terview, Video i	nterview
Recorded feedback	, Phone interview preparation, Tips to custo	nize preparation	for personal
interview, Practice		1 1	1
Module:2	Resume skills – Resume Template and		2 hours
	-		
	Use of power verbs and Types of resume and Customizing resume		
	Use of power verbs and Types of resume and Customizing resume	tion to Device w	when and Mirian up
Structure of a stand	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc		
Structure of a stand Quiz on types of	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing		
Structure of a stand Quiz on types of	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc		
Structure of a stand Quiz on types of different company's	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio		it - Understanding
Structure of a stand Quiz on types of	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 –		it - Understanding
Structure of a stand Quiz on types of different company's	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain		it - Understanding
Structure of a stand Quiz on types of different company's	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis		it - Understanding
Structure of a stand Quiz on types of different company's Module:3	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving	; resume, Layou	it - Understanding
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I	, resume, Layou ndividual Brain	nt - Understanding 12 hours nstorming, Group
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta Personality Test, M	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round fore than one answer, Unique ways	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse ming, Skill Test,
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round fore than one answer, Unique ways	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse ming, Skill Test,
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Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta Personality Test, M	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round fore than one answer, Unique ways Quantitative Ability-L3 – Permutation-Combinations and Probability and Geometry and	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse ming, Skill Test,
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta Personality Test, M	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round fore than one answer, Unique ways Quantitative Ability-L3 – Permutation-Combinations and Probability and Geometry and mensuration and Trigonometry and	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse
Structure of a stand Quiz on types of different company's Module:3 Introduction, Con Brainstorming, Ste brainstorming, Sta Personality Test, M	Use of power verbs and Types of resume and Customizing resume dard resume, Content, color, font, Introduc resume, Frequent mistakes in customizing requirement, Digitizing career portfolio Emotional Intelligence - L1 – Transactional Analysis and Brain storming and Psychometric Analysis and Rebus Puzzles/Problem Solving tracting, ego states, Life positions, I pladder Technique, Brain writing, Crawfor r bursting, Charlette procedure, Round fore than one answer, Unique ways Quantitative Ability-L3 – Permutation-Combinations and Probability and Geometry and	; resume, Layou ndividual Brain d's Slip writing	nt - Understanding 12 hours nstorming, Group approach, Reverse ming, Skill Test,

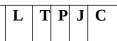


Independent and Dependent Events, Properties of Polygon, 2D & 3D Figures, Area & Volumes, Heights and distances, Simple trigonometric functions, Introduction to logarithms, Basic rules of logarithms, Introduction to functions, Basic rules of functions, Understanding Quadratic Equations, Rules & probabilities of Quadratic Equations, Basic concepts of Venn Diagram Module:5 **Reasoning ability-L3 – Logical** 7 hours reasoning and Data Analysis and Interpretation Syllogisms, Binary logic, Sequential output tracing, Crypto arithmetic, Data Sufficiency, Data interpretation-Advanced, Interpretation tables, pie charts & bar chats Module:6 Verbal Ability-L3 – Comprehension 7 hours and Logic Reading comprehension, Para Jumbles, Critical Reasoning (a) Premise and Conclusion, (b) Assumption & Inference, (c) Strengthening & Weakening an Argument 45 hours **Total Lecture hours:** References Michael Farra and JIST Editors(2011) Quick Resume & Cover Letter Book: Write and Use an Effective Resume in Just One Day. Saint Paul, Minnesota.Jist Works Daniel FlagePh.D(2003) The Art of Questioning: An Introduction to Critical Thinking. London. Pearson FACE(2016) Aptipedia Aptitude Encyclopedia. Delhi. Wiley publications **Mode of Evaluation**: FAT, Assignments, Projects, Case studies, Role plays, 3 Assessments with Term End FAT (Computer Based Test)



Cours	e code	SCIENCE, EN	GINEERING AN	ID TECH	INOLOGY		T	P J	J (
			PROJECT-	Ι					
SET 5									2
	equisite					Syllab	us '	Vers	ion
	equisite								1.1
Cours	e Objectives	· · · ·							
	-	opportunity to involv		to science	e / engineerin	g / tech	nolo	ogy	
		e research culture and							
•	To enhance	the rational and inno	vative thinking ca	pabilities					
Cours	e Outcome(CO):							
	,	his course, the studen	t should be able to):					
	1								
1.		dependent research i		rest					
2.		e scientific results and							
3.		he peer reviewed jour			nces				
4.	Understand	the ethical aspects of	research and plag	iarism					
Moda	lities / Requi	irements							
	A	or group projects can	be taken up						
		iterature survey in the	-						
		e/Engineering princip		ied issues	5				
4.		ant and well-defined				specifie	o be	biect	ive
5.	-	of scientific report ir		•		-		Sjeet	
0.	0.00111001011	or scientific report if	r a specifica forma	it (unter pr	a Starioni che	city.			
	nt Assessme	nt : Periodical review	vs, oral/poster pres	entation					
		Board of Studies	17-08-2017						

SCIENCE, ENGINEERING AND TECHNOLOGY PROJECT– II





			(Deemed to be University und	er section 3 of UGC Act, 1956)					
SET 5002									2
Pre-requisit	e -					Syllab	us Vo	ersio	n
Anti-requisi	te							1	1.10
Course Obj	ectives(C	CoB):							
То рі	ovide op	portunity to involv	e in research relate	ed to scien	ce / enginee	ring /teo	hnol	ogy	
 To in 	culcate r	esearch culture and	l applied learning						
 To er 	hance th	e rational and inno	vative thinking ca	pabilities					
			0	<u> </u>					
		<u></u>							
Course Out	· · · · ·	/	t should be able to						
On complete	on or unis	s course, the studen	it should be able to):					
1. Carry	out inde	ependent research in	n the areas of inter	est					
2. Inter	oret the so	cientific results and	l test hypothesis						
3. Publi	sh in the	peer reviewed jour	nals / Internationa	l Conferen	ices				
4. Unde	rstand th	e ethical aspects of	research and plag	iarism					
Modalities /	Require	ments							
		group projects can	be taken up						-
		rature survey in the	=						
		Engineering princip		ied issues					
		t and well-defined			o fulfill the	specifie	d obi	ectiv	ve
-		f scientific report in		0		-	a 00j		
5. 5451	1001011 01	belentine report in	i u opeenieu ioniiu	t (unter pie	igitarioini ene	city			
Student Ass	essment	: Periodical review	/s, oral/poster pres	entation					
Recommend	ed by Bo	ard of Studies	17-08-2017						
Approved by	Academ	nic Council	No. 47	Date	05-10-201	7			

Course code	Master Thesis	L	Т	Р	J	С
MEE6099		0	0	0	0	16
Pre-requisite	As per the academic regulations	Sy	llab	us v	vers	sion
						1.0



Course Objectives(CoB):

To provide sufficient hands-on learning experience related to the design, development and analysis of suitable product / process so as to enhance the technical skill sets in the chosen field and also to give research orientation.

Course Outcome(CO):

At the end of the course the student will be able to

- 1. Acquire in-depth knowledge of the major subject/field of study, including deeper insight into current research and development work
- 2. Use holistic view to critically, independently and creatively identify, formulate and deal with complex issues
- 3. Understand the ethical aspects of research and development work
- 4. Apply modern scientific software tools and underlying concepts for solving industrial and societal problems

Modalities / Requirements

- **1.** Master thesisshould be individual work, it may be a theoretical analysis, modeling & simulation, experimentation & analysis, prototype design, fabrication of new equipment, correlation and analysis of data, software development, applied research.
- **2.** Project can be for two semesters based on the completion of required number of credits as per the academic regulations.
- **3.** Master thesis can be carried out inside or outside the university, in any relevant industry or research institution.
- **4.** Publications in the peer reviewed journals / International Conferences will be an added advantage

Mode of Evaluation: Periodic revi	ews, Presentatio	n, Final o	ral viva, Poster submission
Recommended by Board of	10.06.2016		
Studies			
Approved by Academic Council	41 st AC	Date	17.06.2016



Programme Core



Course code	Mechatronics And Cyber-Physical S	ystems L T P J C
MEE5028		
Pre-requisite		Syllabus version
•		1.0
Course Objectiv	es(CoB):	
The main objectiv	ves of the course are to:	
Physical S 2. Develop a	nowledge and skills on various hardware and so Systems (CPS) - modeling, analysis, and design In exposition of the challenges in implementing onal perspective, but based equally on the princ	a cyber-physical system from a
Expected Course	e Outcome(CO):	
	course, a student will be able to:	
archite 2. Categ 3. Select 4. Under 5. Elabo	n CPS for meeting the requirements based on ecture constraints. orize the essential modeling formalisms of Cybe actuators and its associated drivers for several w stand architecture and working principles of actu- rate processors, Networking, Communication pr op CPS, security, safety aspects and its impleme	er-Physical Systems (CPS). Forking conditions uators and drives otocols and programming
Module:1 Intr syste	oduction to Mechatronic systems and cyber p	hysical 5 hours
Architecture of n Drives and Actu	nechatronics and Cyber physical systems- Key ators, Controller, Electronics devices-Commu or ABS, ACC, Lane Departure Warning,	
Module:2 Basi	cs of Drives and Actuators:	6 hours
Construction, Prin AC motors, step	nciple of Operation, Basic Equations and Applic oper motor, servo motor. Pneumatic and hy FilterApplications in Automation.	cations of electrical motors-DC,
Madula 2 Das	as of Distingly location	C hours
	cs of Digital electronics- /stem – logic gates – Boolean algebra – half	6 hours
	ters –Rectifiers – Voltage Regulation- A/D and I	
Module:4 Sens	ors and signal conditioning circuits:	6 hours
	nciples of peizo, resistive, capacitive, ultrasonic	r, IR sensors-Examples-Thermo
couples, strain g circuits	auge, pressure sensor-Analog to Digital conv	version, Data acquisition-Filter
Module:5 Proc	cessors and programming:	9 hours
Basics in Microc	ontroller - 8051 Architecture: Memory map -	Addressing modes, I/O Ports -



(1		Ventore institute of reciminology (Demet to be University inder section 3 of UGC Ad. 1956)	T , , ! ,
		d Timers – Serial data - I/ O – Interrupts –	
		ples of operation – PLC Architecture– PLC hardware components A	
		s, CPU & memory module –PLC ladder diagram. PLC programming-	-Interfacing with
sens	ors and	actuators.	
Moo	dule:6	Networking and Communication protocals:	5 hours
Pri	nciples	of Modulation and Demodulation: Principles of Amplitude a	and Frequency
Mo	odulatio	ns- CPS Network - WirelessHart, CAN, Ethernet, CPS Sw st	tack – RTOS,
Sch	heduling	Real Time control tasks CPS.	
Moo	dule:7	Systems Engineering for design of mechatronic system and	6 hours
371	M - J - J -	CPS:	
		nd its variants - System boundary definition- Multi-view and multi-l	
		l modeling- Semantic interoperability modeling- Multi-age	6
		on modeling- internal block diagrams- multi-agent developme	_
		ools-Java, Modelica. Case Study: Suspension Control, Healthca	
		nfusion Pump/Pacemaker, Green Buildings : automated lighting	, AC control,
Dig	gital Tw	in system	
		Contemporary Issues	2 hours
Inc	lustrial l	Expert Guest Lecture and Seminars	
Tota	al Lectı	re hours:	45 hours
# M	ode: Fli	pped Class Room, [Lecture to be videotaped], Use of physical and	
com	iputer m	odels to lecture, Visit to Industry, Min of 2 lectures by industry	
expe	erts		
Tex	t Book(5)	
1.	Devdas Edison	Shetty, Richard A. Kolk, Mechatronics System Design, Cengage L 2011	earning, Second
2.		Alu, Principles of Cyber-Physical Systems, The MIT Press, 2016	
		A. Lee and Sanjit A. Seshia, Introduction to Embedded Systems: A	Cyber-Physical
U .		s Approach, Second edition, MIT press, 2011	
Refe	erence	Sooks	
	erence]		vsical systems:
Ref 1.	Song,	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-ph	nysical systems:
1.	Song, founda	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-ph ions, principles and applications. Morgan Kaufmann, 2016	
	Song, founda Rodrig	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-ph ions, principles and applications. Morgan Kaufmann, 2016 ues, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phy	
1.	Song, founda Rodrig	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-ph ions, principles and applications. Morgan Kaufmann, 2016	
1. 2.	Song, founda Rodrig from th	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-phions, principles and applications. Morgan Kaufmann, 2016 les, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phy eory to practice. CRC Press, 2015.	
1. 2. Mod	Song, founda Rodrig from th le of Ev	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-ph ions, principles and applications. Morgan Kaufmann, 2016 les, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phy eory to practice. CRC Press, 2015. aluation: CAT / Assignment / Quiz / FAT / Project / Seminar	ysical systems:
 1. 2. Moc List 	Song, foundar Rodrig from th le of Ev	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-philons, principles and applications. Morgan Kaufmann, 2016 Les, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phy eory to practice. CRC Press, 2015. aluation: CAT / Assignment / Quiz / FAT / Project / Seminar eriments (Indicative) CO:	ysical systems: 1,3,4
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 1. 2. Moc List 	Song, foundat Rodrig from th de of Ev of Exp Auton system	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-phions, principles and applications. Morgan Kaufmann, 2016 Les, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phyeory to practice. CRC Press, 2015. aluation: CAT / Assignment / Quiz / FAT / Project / Seminar eriments (Indicative) CO: and CO	ysical systems: 1,3,4
1. 2. Mod List 1.	Song, foundat Rodrig from th le of Ev of Exp Auton system Sensor	H., Rawat, D. B., Jeschke, S., &Brecher, C. (Eds.). Cyber-phions, principles and applications. Morgan Kaufmann, 2016 ues, Joel Jose PC, Ivan Stojmenovic, and Danda B. Rawat. Cyber-phyeory to practice. CRC Press, 2015. aluation: CAT / Assignment / Quiz / FAT / Project / Seminar eriments (Indicative) CO: ation and Electro-pneumatic / Electro-hydraulic control using PLC	ysical systems: 1,3,4 1.5 hours



5.	Study and Programming of		Inc	lustrial	1.5 hours	
	Robot.					
6.	Speed control of motor using PII).			1.5 hours	
7.	Study on Wired and wireless con	nmunication.			1.5 hours	
8.	Data acquisition using thermocou	iple, strain gauge.			1.5 hours	
9.	Modeling and simulation of med	chatronics systems	s using co	ding software	1.5 hours	
10.	10. Modeling and simulation of cyber physical systems using open software					
tools.						
	Total Laboratory Hours					
Mode of evaluation:						
Recommended by Board of Studies 07-03-2019						
App						



Course code	SYSTEM MODELLING AND SIMULATION		L	Т	P	J	С
MEE5029			2	0	2	0	3
Pre-requisite		Sy	lla	bu	s v	ers	ion
						v.	1.0

Course Objectives(CoB):

The main objectives of the course are to:

- 1. Characterize Cyber-Physical Systems (CPS) in terms of their essential elements, purpose, parameters, constraints, performance requirements, sub-systems, interconnections and environmental context.
- 2. Develop a model real world situation related to CPS development, prediction and evaluation of outcomes against design criteria and analyze the simulation results.

Expected Course Outcome (CO):

At the endofthe course, astudent will be able to:

- 1. Model deterministic systems and differentiate between nonlinear and linear models in discrete and continuous time
- 2. Acquire knowledge on numerical simulation of linear and non-linear ordinary differential equations and deterministic systems.
- 3. Analyze the results and validate a multi-domain model based upon input and output data.
- 4. Develop model based upon new input, interface and validates the output data.
- 5. Comprehend and apply advanced theory-based understanding of engineering fundamentals
- 6. Design a simple CPS system and determine the stability of system

Module:1 Modeling Discrete-time Systems –

Modeling of Physical Systems -Discrete-Time Systems Concepts - A Discrete-Time Modeling, Simulation of a Discrete-Time Model, Discrete-time Case studies – Modeling & Simulation - Temperature control in a Room, Cruise control of ground vehicle, Spring-mass-damper system

Module:2 Modeling Continuous-Time Systems -

Continuous-Time Concepts - A Continuous-Time Modeling, Simulation of a Continuous-Time Model, A Continuous-Time Model of a Linear Time-Invariant System, Continuous-time Systems Case studies – Modeling & Simulation -Temperature control in a Room, Cruise control of ground vehicle, Spring-mass-damper system, Design Optimization - Fmincon, Genetic Algorithm, Simulated Annealing, and Evolutionary Algorithm.

Module:3 Modeling Cyber Components:

Finite State Machines, Computations, Algorithms, and a First CPS Model, Simulation of a Finite State Machine, A Finite-State Machine – Control simulation. Case studies - Temperature control in a Room, A Finite State Machine Modeling a Chess Game, A CPS Model of a Thermostat, Simulation of a CPS Model of a Thermostat, Models of Computations, A General Discrete-Time Model of a Linear Time-Invariant Algorithm

5 hours

5 hours

5 hours



Module	, , , , , , , , , , , , , , , , , , ,	4 hours
	Bond Graph modeling -Different systems analogy: mechanical, electrical, hyd	
	es, Standard elements (R, L, C, gyrator, transformer), Causality- Causality	
	es, Integrative and Derivative Causality, Generation of system equations,	Case study ·
modelli	ng and simulation of spring-mass-damper system and electrical system	
Module	:5 Modeling Interfaces for Cyber-Physical Systems:	3 hours
Conve	rsion, Networks, and Complete CPS Models, Analog to Digital Conversion, A	A Model of
	log to Digital Converter, Digital to Analog Conversion, A Modeling and sime to Digital Converter,	ulation of an
Module	:6 Finite-State Machine and Digital Communication Network -	3 hours
A Mod	el of an Implemented Finite-State Machine, Simulation of an Implemented F	inite State
Machi	ne, A Digital Communication Network, Simulation of a Digital Communication	on Network,
A CPS	Model for Estimation Over a Network, Simulation of a CPS Model for Estim	ation Over
a Netw	ork, A CPS Model for Sample and Hold Control, Simulation for Sample and	Hold
Contro	1	
Module	:7 Trajectories in CPS and Simulations:	3 hours
	omains, Executions, and Complete CPS Models - Introduction to Executions	
		•
	r-Physical Systems Hybrid Time Domains Hybrid Arcs Definition of	an Execution
0	er-Physical Systems, Hybrid Time Domains, Hybrid Arcs, Definition of the Inputs) Definition of an Execution (with Inputs) Types of Executions. F	
(withou	t Inputs), Definition of an Execution (with Inputs), Types of Executions, E	xecutions for
(withou the Dig	t Inputs), Definition of an Execution (with Inputs), Types of Executions, E ital to Analog Converter, Simulations of Cyber-Physical Systems, Introduct	xecutions for
(withou	t Inputs), Definition of an Execution (with Inputs), Types of Executions, E ital to Analog Converter, Simulations of Cyber-Physical Systems, Introduct	xecutions for
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(withou the Dig Equatio Module Industri Industri Industri Industri Industri Industri Industri Industri Industri Industri Industri	t Inputs), Definition of an Execution (with Inputs), Types of Executions, E ital to Analog Converter, Simulations of Cyber-Physical Systems, Introductions Contemporary issues: al Expert Guest Lecture and Seminars Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2 lectures by industry experts N . Siddesh, G. C. Deka, K. G. Srinivasa, L. M. Patnaik, Cyber-Physical System putational Perspective, CRC press, 2016, Fritzson, Principles of Object-Oriented Modeling and Simulation with Modeli Der-Physical Approach. Wiley-IEEE Press, 2014. Inter Books er Fritzson, Cyber-Physical Systems: From Theory to Practice, Wiley, 2015. ncois E. Cellier and Ernesto Kofman, "Continuous System Simulation," Sp	xecutions for ion to Hybrid 2 hour 30 hours ems: A ca 3.3: A
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(withou the Dig Equatio Module Industri Industri Industri Industri Industri Industri Industri Industri Industri Industri Industri	 t Inputs), Definition of an Execution (with Inputs), Types of Executions, E ital to Analog Converter, Simulations of Cyber-Physical Systems, Introductions Contemporary issues: al Expert Guest Lecture and Seminars Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts Motion 1 Siddesh, G. C. Deka, K. G. Srinivasa, L. M. Patnaik, Cyber-Physical System putational Perspective, CRC press, 2016, Fritzson, Principles of Object-Oriented Modeling and Simulation with Modeli ber-Physical Approach. Wiley-IEEE Press, 2014. Ree Books er Fritzson, Cyber-Physical Systems: From Theory to Practice, Wiley, 2015. ncois E. Cellier and Ernesto Kofman, "Continuous System Simulation," Sp w York, Inc. Secaucus, NJ, USA, 2013. thors, book title, year of publication, edition number, press, place 	xecutions for ion to Hybrid 2 hours 30 hours ems: A ca 3.3: A
(withou the Dig Equatio Module Industri Industri Industri Industri Industri Industri Industri Industri Industri Industri Co 2. P. I Cy Referen 1. Pet 2. Fra Ne Au Mode o	t Inputs), Definition of an Execution (with Inputs), Types of Executions, E ital to Analog Converter, Simulations of Cyber-Physical Systems, Introductions :8 Contemporary issues: al Expert Guest Lecture and Seminars Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts bok(s) M. Siddesh, G. C. Deka, K. G. Srinivasa, L. M. Patnaik, Cyber-Physical System putational Perspective, CRC press, 2016, Fritzson, Principles of Object-Oriented Modeling and Simulation with Modeli ber-Physical Approach. Wiley-IEEE Press, 2014. ace Books er Fritzson, Cyber-Physical Systems: From Theory to Practice, Wiley, 2015. ncois E. Cellier and Ernesto Kofman, "Continuous System Simulation," Sp w York, Inc. Secaucus, NJ, USA, 2013. thors, book title, year of publication, edition number, press, place	xecutions fo ion to Hybrid 2 hour 30 hours ems: A ca 3.3: A



Chemist to be University under section 3 of UGC Act, 1950							
2.	Development of transfer spring mass damper system	1.5 hours					
3.	Simulation of quarter car model u	sing coding tools.			1.5 hours		
4.	Finite state machine model for a v	ending machine.			1.5 hours		
5.	A CPS Model of a Thermostat.				1.5 hours		
6.	Virtual instrumentation model for	data acquisition.			1.5 hours		
7.	Power Bond Graph modeling for	an electro hydraul	ic system		1.5 hours		
8.	Agent model for CPS in JADE en	vironment.			1.5 hours		
9. Modeling and simulation of an Analog to Digital Converter					1.5 hours		
10. Application of modeling and simulation methodologies to a complex					1.5 hours		
engineering system							
Total Laboratory Hours					15 hours		
Mode of evaluation: Digital Assignments /Seminars/Surprise Tests / CATs /FAT							
Recommended by Board of Studies 07-03-2019							
Approved by Academic CouncilNo. 55Date13-06-2019							

		VIIT Vellore Institute of Technology Openadule to Education 3 of UCC Akt, 1999
Course code	SMART	
		INTELLIGENT VEHICLES



	Vellore Institute of Technology (Deemed to be University under section 3 of UGC Act, 1956)				
MEE5030		3	0 () 4	4
Pre-requisite		Sylla	abus	vers	sion
					1.0
Course Objecti	ves(CoB):				
The main object	ives of the course are to:				
driver as 2. Highligh	e students to the various technologies and systems used to a sistance systems in vehicles to the transformation in various driving functions and connector sources of information that assist with a task.	-			
Expected Cour	se Outcome(CO):				
•	course, astudent will be able to:				
 Acquire known vehicle data veh	the rational for and evolution of automotive electronics; owledge on basics of how automotive ECUs function in or bus networks and sensors; the concept of cyber-physical control systems and their app nd autonomous vehicles; with the basic concepts of wireless communications and wire the fundamental principles of data networking and its roll is vehicles; e effective communication and teamwork skills through techn roduction to Automated, Connected, and Intelligent Vehic protive Electronics, Electronics Overview, History & Evolution and Power-train Electronics, Advanced Driver Assistance Elector	plication eless data in ADA ical pres c les ion, Info	a net S an senta otain	collis worł d fur tions <u>5 ho</u> men	sion (s ture 5
Madalard Ca				5 b -	
Basic Control S	nnected and Autonomous Vehicle Technology /stem Theory applied to Automobiles, Overview of the Opera System Theory and Autonomous Vehicles, Role of Surroundi				asic
Module:3 Ser	sor Technology for Smart Mobility			6 ho	ours
	r Technology and Systems, Ultrasonic Sonar Systems, Lidar amera Technology, Night Vision Technology, Other Sensors,				~
Module:4 Ov	erview of Wireless Technology&Networking			6 ho	ours
Wireless Syster Modulation/Enc	n Block Diagram and Overview of Components, Trans oding, Receiver System Concepts–Basics of Computer Netw ess Networking Fundamentals			stem	s –



Module:5	Connected Car & Autonomous	7 hours
	Vehicle Technology	
Connectivi	ity Fundamentals, Navigation and Other Applications, Vehicle-to-Vehicl	e Technology
	cations, Vehicle-to-Roadside and Vehicle-to-Infrastructure Applications,	Autonomous
Vehicles -	Driverless Car Technology, Moral, Legal, Roadblock Issues.	
Module:6	Advanced Driver Assistance System & Prognostics Technology	6 hours
	Theory of Operation, Applications, Integration of ADAS Technology into	
	s, System Examples, Role of Sensor Data Fusion. Vehicle Prognostics Te	
	Driver Assistance System Sensor Alignment and Calibration	cennology,
Tuvanccu	Diver Assistance System Sensor Anglinent and Canoration	
Module:7	Connected Car Display & Impaired Driver Technology	8 hours
	nsole Technology, Gauge Cluster Technology, Heads-Up Display Tec echnology – Driver Notification. Impaired Driver Technology -Drive	
	hnology, Sensor Technology for Driver Impairment Detection	1
Module:8	Contemporary Discussions	2 hours
Inductrial F	Expert Guest Lecture and Seminars	
muusunai E	xpert Guest Lecture and Seminars	
	Total Lecture hours:	45 hours
		45 hours
	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2	45 hours
	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of	45 hours
Text Book(Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2 lectures by industry experts (s)	
Text Book(1. Radova	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Spring	nger, 2015
Text Book(1. Radova 2. Intellig	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Transportation Systems	nger, 2015
Text Book(1. Radova 2. Intellig Resear	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Tracch Board 2016	nger, 2015
Text Book(1. Radova 2. Intellig Resear	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Tracch Board 2016 Books	nger, 2015 ansportation
Text Book(1. Radova 2. Intellig Researce 1. Osseira	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Tracch Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile	nger, 2015 ansportation
Text Book(1. Radova 2. Intellig Researce Reference 1. Osseira commu	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016.	nger, 2015 ansportation and wireless
Text Book(1.Radova2.IntelligReseardReference1.Osseiracommu2.Benevo	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016. olo, Clara, Renata Paola Dameri, and Beatrice D'Auria. "Smart mobility	nger, 2015 ansportation and wireless
Text Book(1. Radova 2. Intellig Researd 1. Osseira 1. Osseira 2. Benevo 1. In Emp	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016. olo, Clara, Renata Paola Dameri, and Beatrice D'Auria. "Smart mobility powering Organizations, pp. 13-28. Springer, Cham, 2016.	nger, 2015 ansportation and wireless
Text Book(1. Radova 2. Intellig Researd 1. Osseira 1. Osseira 2. Benevo 1. In Emp	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016. olo, Clara, Renata Paola Dameri, and Beatrice D'Auria. "Smart mobility	nger, 2015 ansportation and wireless
Text Book(1. Radova 2. Intellig Researce Reference 1. Osseira commu 2. Benevo In Emp Mode of Ev	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016. olo, Clara, Renata Paola Dameri, and Beatrice D'Auria. "Smart mobility powering Organizations, pp. 13-28. Springer, Cham, 2016. valuation: CAT / Assignment / Quiz / FAT / Project / Seminar	nger, 2015 ansportation and wireless
Text Book(1. Radova 2. Intellig Researce Reference 1. Osseira commu 2. Benevo In Emp Mode of Ev	Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry , Min of 2 lectures by industry experts (s) an Miucic, Connected Vehicles: Intelligent Transportation Systems, Springent Transportation Systems and Connected and Automated Vehicles, Trach Board 2016 Books an, Afif, Jose F. Monserrat, and Patrick Marsch, eds. 5G mobile unications technology. Cambridge University Press, 2016. olo, Clara, Renata Paola Dameri, and Beatrice D'Auria. "Smart mobility powering Organizations, pp. 13-28. Springer, Cham, 2016. valuation: CAT / Assignment / Quiz / FAT / Project / Seminar	nger, 2015 ansportation and wireless



Course code		Digital Manufacturing and factory automation	L T P J C
MEE5031			3 0 2 0 4
Pre-requisite	2		Syllabus version
			v. 1.0
Course Objec	ctives	(CoB):	
The main obje	ectives	s of the course are to:	
2. Demoi approp	nstrate oriate	facets of manufacturing "Fourth Revolution", Industry 4.0 st e proficiency in the use of digital manufacturing tools a technologies for a digital enterprise.	
		Dutcome(CO):	
At the endofth	ne cou	rse,astudent will be able to:	
 Demon Analyz Analyz Illustra and pro Impler 	nstrate ze and ate asp otoco ment c rate vi	ligital and IT techniques for manufacturing planning and qua rtual reality and augmented reality applications, safety aspec	ng. y control. 1stry 4.0 standards llity control
		luction to Digital Manufacturing:	5 hours
		nt cycle-stages- Product Lifecycle Management- Role of con	
		Digital thread- Connected enterprise- architecture of digital	
Module:2 C		CAM Tools for Digital Manufacturing	5 hours
		C AM Tools for Digital Manufacturing: d Function representations, Voxel representations, File form	
data exchange	e Para G code	metric, Topology optimization. Numerical control technolog es and M codes, programming for milling and lathe operation	y- CNC machines-
Module:3 I	Digita	Additive Manufacturing Processes:	6 hours
		nanufacturing in product development– process chain	
		ing and post processing. Hardware basics - Contact and nor	
		dditive manufacturing data formats -Applications.	
		pts of Industry 4.0 and Connected Machines:	8 hours
-		lustrial internet of things-Reference Architecture Model	5
-		Connected machines - Standards and protocols- M2M Serval Style - UART (Universal Asynchronous Receiver/	
Module:5 F	Factor	ry Automation:	6 hours



		(Dermsel to be University under section 3 of UGC Act, 1959)	
		l material handling systems- AS/RS- F	
		ring cell- Automation pyramid in modern production systems- Supervi	
an	d Data A	Acquisition (SCADA) control system, Robotics, Human Machine interf	ace.
Ма	dule:6	Computer Aided Shep Elece Control	7 hours
		Computer Aided Shop Floor Control:	
	-	aided production planning and control, computer aided material require factory data collection system, computer process monitoring, IT suppor	
-	0	S-SAP- Fundamental of Networking- computer aided quality control.	t-Sultwale
10	UIS-IVIES	-SAP- Fundamental of Networking- computer alled quality control.	
Mo	dule:7	Smart Maintenance:	6 hours
		ity and Augmented reality applications in manufacturing- Smart mainted	
		in manufacturing -Decision support system-Prognosis and control-Dat	
Mo	dule:8	Contemporary issues:	2 hours
Ind	ustrial E	xpert Guest Lecture and Seminars	
-		Total Lecture hours:	45 hours
		# Mode: Flipped Class Room, [Lecture to be videotaped], Use of	
		physical and computer models to lecture, Visit to Industry, Min.	
		of 2 lectures by industry experts.	
		modular automation systems and additive manufacturing.	
Tex	kt Book		
1.	Andrey	w Kusiak, Smart Manufacturing, Publisher, Taylor & Francis, 2018	
Re	ference		
1.	Williar	n MacDougall, Industrie 4.0: Smart Manufacturing for the Future, Gen	many Trade &
	Invest,		2
2.	Alasda	ir Gilchrist, Industry 4.0: The Industrial Internet of Things, Apress, 201	16.
3.	Frank	Lamb, Industrial Automation: Hands On, McGraw Hill Professional, 20)13.
	Tien-C	hein Chang, Richard A. Wysk, Hsu-Pin (Ben) Wang, Computer Aideo	d Manufacturing
	(2016)	, Pearson Education.	_
Mo	de of Ev	valuation: CAT / Assignment / Quiz / FAT / Project / Seminar	
Lis	t of Exp	eriments (Indicative)	
1.		n of 3D model and automated process plan generation.	1.5 hours
2.	Devel	opment of an automated production system with simulation package.	1.5 hours
3.		opment of a 3D model and production with additive manufacturing	1.5 hours
	<u>`</u>	rinting).	
4.	Simu	late and analyse production system using material flow simulation.	1.5 hours
5.	PLC I	Data capture with and Open Platform Communication and analysis.	1.5 hours
6.	Data o	capture with Bar code/ QR code systems.	1.5 hours
7.	Data o	capture with RFID systems.	1.5 hours
8.	CAD	model development and visualization in VR environment.	1.5 hours
	1	ing with AR for engineering components assembly.	1.5 hours



10.	Basic IIoT system		deve	elopment	1.5 hours
			Total Lab	oratory Hours	15 hours
Digi	tal Assignments /Seminars/Surpris	e Tests / CATs /FA	ΑT		
Reco	ommended by Board of Studies	07-03-2019			
App	roved by Academic Council	No. 55	Date	13-06-2019	



Course code	Artificial Intelligence and Machine learning	L T P J C
MEE5032		3 0 0 4 4
Pre-requisite		Syllabus version
		1.0
Course Objectives	S(CoB):	
The main objective	es of the course are to:	
1. Provide a stror	ng foundation of fundamental concepts in Artificial Intelliger	nce
2. Elobarate diffe	erent AI and machine learning techniques for design of AI sy	stems.
Expected Course	Outcome(CO):	
· · · · · · · · · · · · · · · · · · ·	he course students will be able to	
 Apply AI and I Comprehend h Acquire the kn Analyze a real Deep learning 	-	ning. Neural Network
6. Use different r	nachine learning techniques to design AI based systems.	
	dations of data science- Statistical learning:	5 hours
	cs, Inferential Statistics, Probability & Conditional Probabili es of distribution – Binomial, Poisson & Normal distributior	
Module:2 Fuzzy	v Set Theory and Fuzzy Logic Control	5 hours
	fuzzy sets – Operations on fuzzy sets –Fuzzy relation equa	
	cation – Defuzzification – Knowledge base – Decision	
Module:3 Artifi	cial Neural Networks:	6 hours
	ory of neural networks – multilayer perceptrons –Back pro	
	Different types of learning, examples	pagauon argonum
	Marine Darama Caratanan	C h array
•	tive Neuro Fuzzy Systems:	6 hours
simultaneous mod	 Modification of rule base – Modification of memberification of rule base and membership functions – Generation-Neuro fuzzy systems 	1
Module:5 Com	outer vision and Deep learning:	7 hours
Introduction to Co CNNs, Convolution	onvolutional Neural Networks, Forward propagation & Back on, Pooling, Padding & its mechanisms, CNN architecture - <i>A</i> sNet, Transfer Learning, Semantic segmentation, YOLO, Sia	AlexNet, VGGNet,



coding tool programming

Module:6 Machine learning algorithms-1:

Multiple Variable Linear regression, Multiple regression, Logistic regression, K-NN classification, Naive Bayes classifiers, and Support vector machines.

Module:7Machine learning algorithms-2:8 hoursK-means clustering, Hierarchical clustering, High-dimensional clustering, Dimension Reduction-
PCA, Ensemble techniques Decision Trees, Random Forests, Bagging, Boosting-Value based
methods Q-learning.8 hours

Module:8 Contemporary issues:

2 hours

6 hours

Industrial Expert Guest Lecture and Seminars

Total Lecture hours:	45 hours
Total Lecture nours:	45 nours

Text Book(s)

- 1. Chandra S.S.V Artificial Intelligence and Machine Learning, Prentice Hall India Learning Private Limited; 4 edition (2018)
- 2. Janet Finlay and Alan Dix, An Introduction To Artificial Intelligence, CRC Press; 1 edition ,2017

Reference Books

- 1. Yager, Ronald R., and Lotfi A. Zadeh, eds. An introduction to fuzzy logic applications in intelligent systems. Vol. 165. Springer Science & Business Media, 2012.
- Abe, Shigeo. Neural networks and fuzzy systems: theory and applications. Springer Science & Business Media, 2012.

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

Mode of evaluation:

Recommended by Board of Studies	07-03-2019		
Approved by Academic Council	No. 55	Date	13-06-2019



Programme Electives



Course code	IIOT AND CLOUD COMPUTING	L	T P J C
MEE6061			0 2 0 3
Pre-requisite		Sylla	bus version
			v. 1.0
Course Objective			
The main objective	es of course are to:		
1 Design &	evelop IIOT Devices.		
0	the cloud concepts, capabilities across the various cloud set	rvice mo	dels
Expected Course			
	ourse,astudent will be able to:		
	the drivers and enablers of Industry 4.0		
	the Smart Factories, Smart cities, smart products and smart	services	
	the opportunities, challenges brought about by Industry 4.0		
	he concepts, key technologies, strengths and limitations of c		nputing.
	ey and enabling technologies that help in the development o		1 0
6. Understand	the architecture of computing and storage cloud, service an	ıd deliver	y models.
Module:1 Intro	duction to the Industrial Internet		3 hours
Industrial Internet	Use Cases-The Technical and Business Innovators of the In	dustrial I	nternet-IIoT
Reference Archite	cture		
Module:2 Desig	ning Industrial Internet Systems		4 hours
_	cess Network Technology and protocols-Examining the M	liddlewar	e Transport
protocols -middlev	vare Software Patterns		
	are design concepts		4 hours
	trial Internet of things platforms-IIoT WAN Technolog	ies and	Protocols -
Securing the Indus	trial Internet-Introducing Industry 4.0-Smart Factories		
	1		41
	l computing		4 hours
	and Architecture, Business Drivers, Main players in the	Field, C	Overview of
Security Issues, Xa	aaS Cloud Based Service Offerings.		
Module:5 Cloud	Anchitastura Samisas And Starage		5 hours
	I Architecture, Services And Storage	rebitectu	
	chitecture Design – NIST Cloud Computing Reference A d Clouds – laaS – PaaS – SaaS – Architectural Design		
Storage - Storage-	as-a-Service – Advantages of Cloud Storage – Cloud Storag	, e FIUVIU	eis – 33.
Module:6 Resou	urce Management And Security In Cloud		4 hours
	Irce Management And Security In Cloud rce Management – Resource Provisioning and Resource Pro	wisioning	
	of Cloud Resources – Security Overview – Cloud Se		
0	vice Security – Security Governance – Virtual Machine		
Jon ware-as-a-Jerv	see seemity – seemity Governance – vintual Machine	Security	y <u>1711</u> 11 —



Security Standards.

Modı	ule:7	Cloud technologies and advancements	4 hour
Goog	le Ap	MapReduce – Virtual Box — Google App Engine – Programming E p Engine — Open Stack – Federation in the Cloud – Four Levels o ervices and Applications – Future of Federation.	
Modu	ule:8	Contemporary Issues	2 hours
Indu	strial	Expert Guest Lecture and Seminars	
Total	Loct	ire hours:	30 hours
# Mo	ode: Fl outer m	ipped Class Room, [Lecture to be videotaped], Use of physical and nodels to lecture, Visit to Industry, Min of 2 lectures by industry	50 11001
	Book(s)	
1. 0	Gilchri	st, Alasdair: Industry 4.0: The Industrial Internet of Things. Apress, N	ew York, 2016
, ,		vang, Geoffrey C. Fox, Jack G. Dongarra, "Distributed and Cloud Co l Processing to the Internet of Things", Morgan Kaufmann Publishers, 2	
	0	house, John W., and James F. Ransome, —Cloud Computing: I ement and Security, CRC Press, 2017.	mplementation
Refer	rence]	Books	
		narBuyya, Christian Vecchiola, S. ThamaraiSelvi, —Mastering Cloud C v Hill, 2013	Computing, Tat
		/elte, Anthony Velte, Robert Elsenpeter, "Cloud Computing – A Prac cgraw Hill, 2009.	tical Approach
	0	Reese, "Cloud Application Architectures: Building Applications and I ud: Transactional Systems for EC2 and Beyond (Theory in Practice), O	
Mode	e of Ev	aluation: CAT / Assignment / Quiz / FAT / Project / Seminar	
List o	of Exp	eriments (Indicative)	
1.	Sett	ng up of Raspberry Pi and connect to a network	1.5 Hr
2.	. Fam	iliarization with GPIO pins and control hardware through GPIO pins.	1.5 Hr
3.	Spee	ed Control of motors using PWM with coding programming.	1.5 Hr
4.	Use	sensors to measure temperature, humidity, light and distance.	1.5 Hr
5.	Web	based hardware control	1.5 Hr
6.		nect IOT devices through cloud using IoT protocol such as MQTT.	1.5 Hr
7.		trolling IoT devices using Arduino.	1.5 Hr
8.		te Wireless network of sensors using Zigbee.	1.5 Hr
		elopment of ERP level of Automation	1.5 Hr
1(0. Dev	elopment of MES system	1.5 Hr
		Total Hours	15 Hr



Course code	Virtual Reality and Augmented Reality	L	T P J	C
MEE6062		2	020	3
Pre-requisite		Syllab	ous versio	n
		1.0.0		
Course Objecti	ves(CoB):			
The main object	tives of course are to:			
VR/AR app			-	
	wledge on hardware and software aspects of virtual reality a	nd augn	nented rea	ality
	g, analysis and design of engineering systems.	1.		
	cises aiming to design and develop simple prototype AR/VR	applicat	tions usin	g
state-of-the-				
A	se Outcome(CO):			
	course,astudent will be able to: and the overview of AR/VR systems and realize the differenc 5.	es in A	R/VR	
3. Cognize	hend the functions and select the appropriate hardware for VI Geometric modeling and dynamics of 3D models for VR sin	-		IS.
	and prototype effective AR/VR applications	1	C ,	
-	and match VR/AR technology to human needs and use with			
6. Demons	trate the trends and trajectories in current and future AR/VR	system	S	
Module: 1 II	ntroduction to Virtual Reality and Augmented Reality	3 hou	rs	
Virtual reality,	Augmented reality and Mixed Reality concepts - Virtual	world	space an	d real
world – Interfac	te to virtual world (inputs and outputs) – Types of interactio – Benefits and Applications of VR and AR.			
Module: 2 V	R/AR Hardware Technologies	5 hou	rs	
Displays and A	filtering & tracking, Output devices-Visual Displays, Aud ugmenting displays. Augmented Reality (AR) hardware, sp v VR - Haptic assembly architecture - Haptic Interface.			
Module: 3 G	eometric modeling and dynamics	5 hou	rs	
	leling, transforming rigid bodies, yaw, pitch, roll, axis			tation
	D rotation inverses and conversions, homogeneous trans	-	-	
	t and eye transforms, canonical view and viewport transfor			
	on, collision detection, avatar motion and vection.			in caur
	,			
Module: 4 V	isual perception and rendering	5 hou	rs	
	perception on VR -Depth perception, motion perception and			
-	ering, ray tracing, shading, BRDFs, rasterization, baryce	-	-	



(time warp)	, panoramic rendering.		
Module: 5	Tracking and Interaction	4 hours	
integration, fusion, eye	vstems – sensors for tracking position, orientation and r drift errors, tilt and yaw correction. Devices for na e tracking and map building.Remapping, locomot mechanisms.Sound propagation and auditory perception	vigation and interact	tion -senso
Module: 6	Evaluating VR/AR Systems and Experiences	3 hours	
Human Fac	tors in Virtual Reality, Perceptual training, best practice volving human subjects.		erimental
Module: 7	Case Studies in VR/AR:	3 hours	
Entertainme	and emerging VR/AR applications in Engineering, Ar ent, Science, and Training Implementation. Touch, e and Brain-machine interfaces.		
Module: 8	Contemporary Discussions	2 hours	
Industrial E	xpert Guest Lecture and Seminars	I	
and comput by industry Text Book(1. GrigoreB		ectures	
	Factors for AR and VR (Usability)(2017), ISBN-13: 9		iicatioiis,
Reference			
	nce, Virtual Reality Systems (2007), Pearson Education	•	
	Aiheli, Jonezpodobnik, Haptics for virtual reality and te		Springer.
Industry	orey and John Tinnell, Augmented Reality: Innovative 7, and Academia (2016), ISBN-13: 978-1602355569.	Perspectives across A	Art,
	valuation: CAT / Assignment / Quiz / Seminar / FAT		
	eriments (challenging Experiments) uction to virtual reality hardware and software.	<u>ר</u>	hours
	ersion of CAD models into VR models.		hours hours
	on of assemblies of products and digital mockup IN VF		hours
	on of AR environment for product / systems		hours
	uter graphics of 3D scene by OpenGL / VRML /UNITY		hours
	R for ergonomic and aesthetic studies		hours
	ratory Hours		5 hours
I ofal Lanor) IIIIII \
	valuation: Lab Experiments / FAT		



Approved by Ac		No. 56		Date	24-09-2019	
Course code		MEMS in Cyber Pl	nysical Systems			C C
MEE6063					2 0 0 4	4 3
Pre-requisite					Syllabus ver	sion
-					V	r. 1.0
Course Objectiv	ves(CoB):					
The main objecti	ves of course are	to:				
1 Undo	rstanding the con	cent of MEMS				
	0	e technological/fund	ctional approac	hes and an	nlications	
		micro sensors, actu			prications	
) mulaics.		
	e Outcome(CO)					
1		students will be abl	e to			
	nd about the basic					
		ro fabrication techr	-			
		ition for industrial	11			
		anufacturing proce	0		tabrication	
5. Design a	Micro System wi	ithPackaging at dev	vice and system	level.		
Definition – hi microelectronics disciplinary natu	storical develop , working princij re of MEMS- Su	oment – propertie ple, applications ar rvey of materials c	nd advantages	of micro s	on micro-sys system. The m	tem ulti-
Definition – hi microelectronics disciplinary natu	storical develop , working princij re of MEMS- Su	ple, applications a	nd advantages	of micro s	on micro-sys system. The m	tem ulti-
Definition – hi microelectronics disciplinary natu MEMS in cyber	storical develop , working princij re of MEMS- Su	ple, applications an rvey of materials c	nd advantages	of micro s	on micro-sys system. The m ng- Applicatior	tem, iulti- is of
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to	istorical develop , working princij re of MEMS- Su physical system ling Laws for M Scaling Issues, S	ple, applications an rvey of materials c iniaturization Scaling effects on	nd advantages entral to micro a cantilever be	of micro s engineerin eam, Scalin	on micro-sys system. The m ng- Application 4 h ng of electros	tem nulti- ns of ours tatic
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalir	storical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal ac	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of	nd advantages entral to micro a cantilever be	of micro s engineerin eam, Scalin	on micro-sys system. The m ng- Application 4 h ng of electros	tem nulti- ns of ours tatic
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalir	istorical develop , working princij re of MEMS- Su physical system ling Laws for M Scaling Issues, S	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of	nd advantages entral to micro a cantilever be	of micro s engineerin eam, Scalin	on micro-sys system. The m ng- Application 4 h ng of electros	tem nulti- ns of ours tatic
microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S of thermal ac of scaling on ma	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of tterial properties.	nd advantages entral to micro a cantilever be	of micro s engineerin eam, Scalin	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec	tem, nulti- ns of ours tatic
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalir statics. Influence Module:3 Ma	storical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S og of thermal ac of scaling on ma terials for MEM	ple, applications an rvey of materials c iniaturization Scaling effects on ctuator, Scaling of aterial properties.	nd advantages entral to micro a cantilever be Thermal Sens	of micro s engineerin eam, Scali ors, mech	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h	tem, nulti- ns of ours tatic ctro- ours
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S of thermal ac of scaling on ma terials for MEM rafers, silicon as s	ple, applications an rvey of materials c iniaturization Scaling effects on ctuator, Scaling of aterial properties. Substrate material, 1	nd advantages entral to micro a cantilever be Thermal Sens mechanical prop	of micro s engineerin eam, Scalit ors, mech	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structu	tem, nulti- ns of ours tatic ctro- ours re of
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S of thermal ac of scaling on ma terials for MEM rafers, silicon as s	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of tterial properties. Substrate material, n n Compounds - sili	nd advantages entral to micro a cantilever be Thermal Sens mechanical prop	of micro s engineerin eam, Scalit ors, mech	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structu	tem nulti- ns of ours tatic ctro- ours re of
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S g of thermal ac of scaling on ma terials for MEM rafers, silicon as s materials, Silicon	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of tterial properties. Substrate material, n n Compounds - sili	nd advantages entral to micro a cantilever be Thermal Sens mechanical prop	of micro s engineerin eam, Scalit ors, mech	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structu	tem, nulti- ns of ours tatic ctro- ours re of
Definition – himicroelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Mar Substrates and w silicon and other polymers for ME Module:4 Mic	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal act of scaling on ma terials for MEM rafers, silicon as s materials, Silicon CMS, conductive pro-Fabrication I	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes	nd advantages entral to micro a cantilever be Thermal Sens mechanical proj con piezo resist	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h	tem, nulti- ns of ours tatic ctro- ours ours ours
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal ac of scaling on ma terials for MEM rafers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I r, photo resist a	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s	nd advantages entral to micro a cantilever be Thermal Sens mechanical pro- con piezo resist	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit	tem, nulti- ns of ours tatic ctro- ours re of artz, ours
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor	storical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S of thermal ac of scaling on ma terials for MEM rafers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I deposition- Etchi	ple, applications an rvey of materials c iniaturization Scaling effects on ituator, Scaling of iterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s ing Processes, bulk	nd advantages entral to micro a cantilever be Thermal Sens mechanical proj con piezo resist	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation, nachining	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit	tem, nulti- ns of ours tatic ctro- ours re of artz, ours
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor	storical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S of thermal ac of scaling on ma terials for MEM rafers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I deposition- Etchi	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s	nd advantages entral to micro a cantilever be Thermal Sens mechanical proj con piezo resist	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation, nachining	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit	tem nulti- ns of ours tatic ctro- ours re of artz; ours
Definition – hi microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Ma Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor LASER, Electron	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal acterials for MEM rafers, silicon as se materials, Silicon CMS, conductive ro-Fabrication I 7, photo resist ap deposition- Etchi n beam, Ion beam	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s ing Processes, bulk n processes – Mask	nd advantages entral to micro a cantilever be Thermal Sens mechanical proj con piezo resist	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation, nachining	on micro-sys system. The m ag- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit – LIGA proce	tem, nulti- ns of ours tatic ctro- ours re of artz, ours tion- ess –
Definition – himicroelectronics microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scaling statics. Influence Module:3 Mar Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor LASER, Electron Module:5 Mic	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal ac of scaling on ma terials for MEM afers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I a, photo resist ap deposition- Etchi n beam, Ion beam	ple, applications an rvey of materials c iniaturization Scaling effects on ituator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s ing Processes, bulk n processes – Mask gn and Packaging	nd advantages entral to micro a cantilever be Thermal Sens mechanical proj con piezo resist cources, ion im a and surface n less lithograph	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation, nachining	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structus m arsenide, qu 4 h , Film deposit – LIGA proce	ours ours tatic ctro- ours tion- ess – ours
Definition – himicroelectronics microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scaling statics. Influence Module:3 Ma Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor LASER, Electron Module:5 Mic	istorical develop , working princip re of MEMS- Su physical system ing Laws for M Scaling Issues, S of thermal act of scaling on ma terials for MEM afers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I 7, photo resist ap deposition- Etchi n beam, Ion beam ro System Desig ations-Mechanica	ple, applications an rvey of materials c iniaturization Scaling effects on tuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s ing Processes, bulk n processes – Mask	nd advantages entral to micro a cantilever be Thermal Sens mechanical prop con piezo resist ources, ion im a and surface n less lithograph design, Realiza	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation nachining y.	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit – LIGA proce 5 h IEMS compon	tem, nulti- ns of ours tatic ctro- ours re of artz, ours tion- ess – ours
Definition – himicroelectronics microelectronics disciplinary natu MEMS in cyber Module:2 Sca Introduction to actuators, Scalin statics. Influence Module:3 Mar Substrates and w silicon and other polymers for ME Module:4 Mic Photolithography chemical vapor LASER, Electron Module:5 Mic Design consider using Software.	istorical develop , working princip re of MEMS- Su physical system ling Laws for M Scaling Issues, S ag of thermal act of scaling on ma terials for MEM rafers, silicon as s materials, Silicon CMS, conductive ro-Fabrication I 7, photo resist ap deposition- Etchi n beam, Ion beam ro System Desig ations-Mechanica Micro system pace e level and syste	ple, applications an rvey of materials c iniaturization Scaling effects on ctuator, Scaling of aterial properties. Substrate material, n n Compounds - sili polymers. Processes pplications, light s ing Processes, bulk n processes – Mask gn and Packaging al Design, Process	a cantilever be Thermal Sens nechanical proj con piezo resist ources, ion im a and surface n less lithograph design, Realiza design– levels	of micro s engineerin eam, Scali ors, mech perties of s cors, Galiun plantation nachining y.	on micro-sys system. The m ng- Application 4 h ng of electros anics and elec 4 h silicon, structur m arsenide, qu 4 h , Film deposit – LIGA proce 5 h IEMS compon system packagi	tem, nulti- ns of ours tatic ctro- ours tion- ess - ours ing -



Module:6 MEMS components				4 hours
Micro sensors - Basic principles and v	vorking of micro s	ensors - B	io-medical n	nicro sensors- Bio-
sensors- Chemical micro sensors - Op	otical Sensors – Pr	essure mic	ro sensors	acceleration micro
sensors; Micro actuators - Basic prine	1	0		
actuators- Piezoelectric micro actuator	rs- SMA micro ac	tuators- El	ectromagnet	ic micro actuators,
micro valves, micro pumps.				
Module:7 CPS applications of ME				4 hours
CPSApplications –Biomedical, Lab	1,		0	ms, RF-MEMS-
based circuits, PZT-based piezoelect	ric MEMS, MEMS	S energy h	arvester	
				21
Module:8 Contemporary Issues				2 hours
Industrial Expert Guest Lecture and S	Seminars			
Total Lecture hours:				45 hours
# Mode: Flipped Class Room, [Lectu	1		1 0	
and computer models to lecture, Vis	sit to Industry , 1	Min of 2	lectures by	
industry experts				
Text Book(s)				
1. Tai-Ran Hsu, MEMS and Microsyste				Hill 2011
2. Mohamed Gad – el – Hak , " MEMS				
3. Vijay Varadan, Xiaoning Jiang Fabrication techniques for 3D MEM		aradan, Mi	icrostereolitho	ography and other
Reference Books				
1. Trimmer William S "Micromachanic	cs and MEMS", IEE	EE Press Ne	w York 1997	
2. Francis E.H Tay and W. O. Choo New York 1997	ng "Micro fluidics	s and bio N	AEMS applic	cation" IEEE Press
Mode of Evaluation: CAT / Assignme	ent / Quiz / FAT /]	Project / S	eminar	
	•	5		
Mode of evaluation:	00.00.0010			
	06-09-2019 No. 56	Date	24-09-2019	



Course coo	e Applied Robotics and programming	L T P J C
MEE6064		2 0 2 0 3
Pre-requis	te	Syllabus versior
		v. 1.0
Course Ob	jectives(CoB):	
The main o	bjectives of course are to:	
	Acquire knowledge about the various types of robotic system and formulation.	d its mathematica
	Develop application with the acquired knowledge to solve indu	ustrial and conviou
	bevelop application with the acquired knowledge to solve mat	
	Course Outcome(CO):	
	ne endofthe course, astudent will be able to:	
	Ability to categorize the various types of industrial robots with its a	applications
	Analyze the kinematics and dynamics for various types	
	configurations.	or manipulato
	Solve the trajectory planning problem for robotic application.	
	Realize the role of mobile robot in industries and service sectors.	
	Develop knowledge on SLAM, path planning and navigation.	
	Realize the importance of bio-inspired robotic system	
	Introduction to Industrial robotic system	3 hour
	s of Industrial robotic system, workspace, work-cell, types of indu	
effector, ap		,
Module:2	Kinematic and Dynamics	4 hour
	ion of frame and transformations, Forward and inverse kinem	atics, DH matrix
Dynamics of	f two link planer.	
	Trajectory planning	
Basics of	Path and trajectory, joint space trajectory, Third order polyno	
Basics of		
Basics of polynomial	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory.	omial, Fifth orde
Basics of polynomial Module:4	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots	bmial, Fifth orde
Basics of polynomial Module:4 Introduction	Path and trajectory, joint space trajectory, Third order polyno Cartesian space trajectory. Mobile robots In to autonomous robotic system, wheeled mobile robots and its ty	bmial, Fifth orde
Basics of polynomial Module:4 Introduction	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots	bmial, Fifth orde
Basics of polynomial Module:4 Introduction differential	Path and trajectory, joint space trajectory, Third order polyno Cartesian space trajectory. Mobile robots In to autonomous robotic system, wheeled mobile robots and its ty	bmial, Fifth orde 4 hour pes, kinematics o vice applications.
Basics of polynomial Module:4 Introduction differential Module:5	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots to autonomous robotic system, wheeled mobile robots and its ty and car link mobile robot, legged mobile robot, Industries and serv	4 hour pes, kinematics o vice applications. 5 hour
Basics of polynomial Module:4 Introduction differential Module:5 Map based	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots to autonomous robotic system, wheeled mobile robots and its ty and car link mobile robot, legged mobile robot, Industries and serv SLAM	omial, Fifth orde 4 hour pes, kinematics o vice applications. 5 hour
Basics of polynomial Module:4 Introduction differential Module:5 Map based	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots n to autonomous robotic system, wheeled mobile robots and its ty and car link mobile robot, legged mobile robot, Industries and served SLAM localization, Simultaneous Localization and mapping, Challed	omial, Fifth orde 4 hour pes, kinematics o vice applications. 5 hour
Basics of polynomial Module:4 Introduction differential Module:5 Map based	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots n to autonomous robotic system, wheeled mobile robots and its ty and car link mobile robot, legged mobile robot, Industries and served SLAM localization, Simultaneous Localization and mapping, Challed	omial, Fifth orde 4 hour pes, kinematics o vice applications. 5 hour
Basics of polynomial Module:4 Introduction differential Module:5 Map based localization Module:6	Path and trajectory, joint space trajectory, Third order polyno, Cartesian space trajectory. Mobile robots n to autonomous robotic system, wheeled mobile robots and its ty and car link mobile robot, legged mobile robot, Industries and served by the served served served served by the served ser	bmial, Fifth order 4 hour pes, kinematics o vice applications. 5 hour enges, Local GP 4 hour



Μ	odule:7	Special Purpose robots				4 hours
M	ulti robot	tic system, collaborative ro	obots, Redundant ma	nipulat	ors, soft robot	ts, Nano robots,
me	edical rot	oots, origami robots.				
		1				
		Contemporary Issues				2 hours
Ir	ndustrial	Expert Guest Lecture and	Seminars			
To	tal Lect	ure hours:				30 hours
		lipped Class Room, [Lect	ure to be videotaped	ll. Use	of physical	oo nouro
		ter models to lecture, Vi	1		1 0	
	lustry ex		0 - 1		5	
Te	xt Book	(s)			·	
1.	Craig, Hall.	John J., Introduction to R	obotics: Mechanics	and Co	ontrol (2005),	Pearson/Prentice
2.		l Siegwart, Illah Reza Nou e Robots, (2011), MIT pres		ramuzz	a, Introductior	n to Autonomous
Re	ference					
1.		Saeed B (2005), Introduct n Education, New Delhi.	ion to Robotics: Me	chanics	and Control,	Second Edition,
2.	Farboo	lFahimi, Autonomous Rob	ots Modelling, Path I	Plannin	g and Control	(2008), Springer
2.		lFahimi, Autonomous Rob e and Business Media.	ots Modelling, Path I	Plannin	g and Control	(2008), Springer
2.			ots Modelling, Path I	Plannin	g and Control	(2008), Springer
	Scienc	e and Business Media.		Plannin	g and Control	(2008), Springer
	Scienc	e and Business Media. Deriments (challenging Ex	xperiments)	Plannin	g and Control	(2008), Springer
	Scienc	e and Business Media.	xperiments)	Plannin	g and Control	
	Scienc st of Exp 1. For	e and Business Media. Deriments (challenging Ex ward and inverse kinematio	xperiments) cs of two link planar	Plannin	g and Control	(2008), Springer
	Scienc st of Exp 1. For	e and Business Media. Deriments (challenging Ex	xperiments) cs of two link planar	Plannin	g and Control	2 hours
	Scienc st of Exp 1. For 2. Traj	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly	xperiments) cs of two link planar ynomial equation	Plannin	g and Control	
	Scienc st of Exp 1. For 2. Traj	e and Business Media. Deriments (challenging Ex ward and inverse kinematio	xperiments) cs of two link planar ynomial equation	Plannin	g and Control	2 hours 2 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic	xperiments) cs of two link planar ynomial equation)	Plannin	g and Control	2 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly	xperiments) cs of two link planar ynomial equation)	Plannin	g and Control	2 hours 2 hours 3 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan	e and Business Media. Deriments (challenging Ex- ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec	xperiments) cs of two link planar ynomial equation) ial functions)		g and Control	2 hours 2 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic	xperiments) cs of two link planar ynomial equation) ial functions)		g and Control	2 hours 2 hours 3 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo	e and Business Media. Deriments (challenging Ex- ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software		g and Control	2 hours 2 hours 3 hours 3 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec rk-cell development using	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software		g and Control	2 hours 2 hours 3 hours 3 hours 3 hours 3 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo 6. Prog	e and Business Media. Deriments (challenging Ex ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec rk-cell development using	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software		g and Control	2 hours 2 hours 3 hours 3 hours
	Scienc st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo 6. Prop stal Labo	e and Business Media. Deriments (challenging Ex- ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec rk-cell development using gramming differential whe	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software el mobile robot	2		2 hours 2 hours 3 hours 3 hours 3 hours 2 hours 2 hours
Lis To Mo	Science st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo 6. Prog stal Labor ode of Exp stal Labor ode of Exp	e and Business Media. periments (challenging Ex- ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spect rk-cell development using gramming differential whe pratory Hours valuation: CAT / Assignment	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software el mobile robot	2		2 hours 2 hours 3 hours 3 hours 3 hours 2 hours 2 hours
Lis	Science st of Exp 1. For 2. Traj 3. Fan 4. Fan 5. Wo 6. Prog tal Labo ode of Ev ode of ev	e and Business Media. Deriments (challenging Ex- ward and inverse kinematic jectory planning using poly uc robot Program 1 (Basic uc robot Program 2 (Spec rk-cell development using gramming differential whe pratory Hours	xperiments) cs of two link planar ynomial equation) ial functions) Robo-guide software el mobile robot	2		2 hours 2 hours 3 hours 3 hours 3 hours 2 hours 2 hours



	ode	Hybrid and Electric Automotive Vehicle Systems	L	Т	P J	I C
MEE606	5		3	0	0 4	4
Pre-requ	isite		Sylla	bus	ver	sio
1						. 1.
Course C	bjective	(CoB):				
The main	objective	s of course are to:				
	troduce tl hicles.	e fundamental concepts, principles, analysis and design of	hybrid	anc	l ele	ctri
ba	sed on tl	the mechatronic system and component design of hybrid and ne requirements to power flow management, power conv amics and energy/fuel efficiency.				
		Outcome(CO):				-
The stude	ents will b	e able to				
	noose a s sources	uitable drive scheme for developing an electric hybrid veh	nicle de	pei	ıdin	30
		develop basic schemes of electric vehicles and hybrid elect	ric vehi	icle	c	
	0	per energy storage systems for vehicle applications	iic vein	CIC	5.	
		ious communication protocols and technologies used in veh	niclo no	tx	vrke	
	5	orking of different configurations of electric vehicles and its				
		brid vehicle configuration, performance analysis and En				no
	ategies	bild venicle configuration, performance analysis and En	icigy iv	Iun	agei	IIC.
str						
Module:1					5 h	
Module: Convention transmiss of hybrid	onal Vehi ion chara l and ele	luction cles - Basics of vehicle performance, vehicle power sourc cteristics, and mathematical models to describe vehicle pe ctric vehicles, social and environmental importance of h modern drive-trains on energy supplies (include IC engine	rforman tybrid a	nce and	eriza . His ele	tio stoi ctr
Module: Convention transmiss of hybrid vehicles,	onal Vehi ion chara l and ele impact of	cles - Basics of vehicle performance, vehicle power source cteristics, and mathematical models to describe vehicle per ctric vehicles, social and environmental importance of h modern drive-trains on energy supplies (include IC engine	rforman tybrid a	nce and	eriza . His ele ated	tio stor ctr .)
Module: Convention transmiss of hybrid vehicles, Module:	onal Vehi ion chara I and ele impact of 2 Hybri	cles - Basics of vehicle performance, vehicle power source cteristics, and mathematical models to describe vehicle per ctric vehicles, social and environmental importance of h modern drive-trains on energy supplies (include IC engine d and Electric Drive-trains	rforman nybrid a CPS	nce and rel	eriza . His ele ated 6 h	tio stor ctr .)
Module:1 Convention transmiss of hybrid vehicles, Module:2 Basic con drive-train	onal Vehi ion chara l and ele impact of 2 Hybri cept of h n topolog	cles - Basics of vehicle performance, vehicle power source cteristics, and mathematical models to describe vehicle per ctric vehicles, social and environmental importance of h modern drive-trains on energy supplies (include IC engine d and Electric Drive-trains ybrid and electric vehicle traction, introduction to various ies, power flow control in hybrid and electric drive-train	rforman nybrid a CPS	nce and rel	eriza His ele ated 6 h l ele	tio stor ctr: .) ou
Module:1 Convention transmiss of hybrid vehicles, Module:2 Basic con drive-train	onal Vehi ion chara l and ele impact of 2 Hybr acept of h n topolog uel efficio	cles - Basics of vehicle performance, vehicle power source cteristics, and mathematical models to describe vehicle per ctric vehicles, social and environmental importance of h modern drive-trains on energy supplies (include IC engine d and Electric Drive-trains ybrid and electric vehicle traction, introduction to various	rforman nybrid a CPS	nce and rel	eriza His ele ated 6 h l ele	tio stor ctr: .) ou



vehicles Motor o	ction to electric components , Configuration and control of lrives, configuration and contro of Switch Reluctance Motor du	ol of Permanent	s, Configur Magnet M	ation and otor drives	
Madal					7 h
Module		· · · · · · · · · · · · · · · · · · ·	• 1 1 1 1 1 1		7 hours
energy based	ction to Energy Storage Requ storage and its analysis, Fuel C energy storage and its analy zation of different energy stora	Cell based energy ysis, Flywheel b	storage an	d its analy	sis, Super Capacitor
Module	:5 Sizing the drive system				5 hours
Matchir motor, s	g the electric machine and the sizing the power electronics, sing subsystems				izing the propulsion
Module	:6 Energy Management St	ratogias			9 hours
Introdue of diffe	ction to energy management st erent energy management st es, implementation issues of en	rategies used in h trategies, compar	rison of d	lifferent e	hicles, classification
Module	:7 Case studies				7 hours
	of an Electric and Hybrid El		EV) –Para	llel and Se	eries configuration,
Module					2 hours
Indust	ial Expert Guest Lecture and S	Seminars			
	ecture hours: : Flipped Class Room, [Lectur	-	ed], Use of	physical	45 hours
and con	nputer models to lecture, Visit	it to Industry , M	fin of 2 leo	ctures by	
and con	experts	it to Industry , N	fin of 2 leo	ctures by	
and con industry Text Bo 1. Iqb	experts	ehicles: CRC Press	; 2 nd edition	, 2010.	ns, 2 nd edition, 2015
and con industry Text Bo 1. Iqb 2. Jan	experts pok(s) al Hussein, Electric and Hybrid V	ehicles: CRC Press	; 2 nd edition	, 2010.	s, 2 nd edition, 2015
and con ind⊍stry Text Bo 1. Iqb 2. Jan Ref ren 1. Me Ve	experts bok(s) al Hussein, Electric and Hybrid V les Larminie, " Electric Vehicle T Ice Books hrdadEhsani, YiminGao, Ali nicles: Fundamentals", CRC P	Vehicles: CRC Press Sechnology Explain Emadi, "Modern ress, 2010.	;; 2 nd edition ed", John W Electric, F	, 2010. 7iley & Son 1ybrid Ele	ectric, and Fuel Cell
and con ind⊍stry Text Bo 1. Iqb 2. Jan Ref Ref 2. Me Ve 2. Em CR	experts pok(s) al Hussein, Electric and Hybrid V tes Larminie, "Electric Vehicle T ace Books hrdadEhsani, YiminGao, Ali nicles: Fundamentals", CRC Pr adi, A. (Ed.), Miller, J., Ehsa C Press, 2003.	Zehicles: CRC Press Sechnology Explain Emadi, "Modern ress, 2010. ni, M., "Vehicula	; 2 nd edition ed", John W Electric, F ar Electric	, 2010. 7iley & Son 1ybrid Ele Power Sy	ectric, and Fuel Cell
and con ind⊍stry Text Bo 1. Iqb 2. Jan Ref ren 1. Me Ve 2. Em CR	experts ok(s) al Hussein, Electric and Hybrid V tes Larminie, "Electric Vehicle T ice Books hrdadEhsani, YiminGao, Ali nicles: Fundamentals", CRC Pi adi, A. (Ed.), Miller, J., Ehsa	Zehicles: CRC Press Sechnology Explain Emadi, "Modern ress, 2010. ni, M., "Vehicula	; 2 nd edition ed", John W Electric, F ar Electric	, 2010. 7iley & Son 1ybrid Ele Power Sy	ectric, and Fuel Cell
and con ind⊍stry Text Bo 1. Iqb 2. Jan Referen 1. Me Ve 2. Em CR Mode o	experts pok(s) al Hussein, Electric and Hybrid V les Larminie, "Electric Vehicle T ice Books hrdadEhsani, YiminGao, Ali nicles: Fundamentals", CRC Pr adi, A. (Ed.), Miller, J., Ehsa C Press, 2003. f Evaluation: CAT / Assignme	Zehicles: CRC Press Sechnology Explain Emadi, "Modern ress, 2010. ni, M., "Vehicula	; 2 nd edition ed", John W Electric, F ar Electric	, 2010. 7iley & Son 1ybrid Ele Power Sy	ectric, and Fuel Cell
and con industry Text Ba2. JanReference1. MeVe2. EmCRMode o	experts pok(s) al Hussein, Electric and Hybrid V tes Larminie, " Electric Vehicle T ace Books hrdadEhsani, YiminGao, Ali nicles: Fundamentals", CRC Pr adi, A. (Ed.), Miller, J., Ehsa C Press, 2003.	Zehicles: CRC Press Sechnology Explain Emadi, "Modern ress, 2010. ni, M., "Vehicula	; 2 nd edition ed", John W Electric, F ar Electric	, 2010. 7iley & Son 1ybrid Ele Power Sy	ectric, and Fuel Cell



Course code	Cyber Security in Design and Manufacturing	L T P J C
MEE6066		3 0 0 3
Pre-requisite		Syllabus version
		v. 1.0
Course Object	tives(CoB):	
The main object	ctives of course are to:	
risks a necessa 2. Provide threats 3. Enable attacks systems Expected Cou On completion 1. Develop 2. Categon 3. Propose 4. Assess 5. Analyze 6. Create	fundamental knowledge on cloud based manufacturing, secur ssociated with different cloud deployment models along ry to protect manufacturing systems. working knowledge of using different data mining technique to a manufacturing system. students to detect and prevent system intrusion, improve defen and incident response, master modern technologies for securit and cyber-physical systems. rse Outcome(CO): of the course, the students will be able to o technical expertise in security of cyber-physical systems. ries intrusion and security breaches to cyber-physical systems. e security solutions for cyber-physical systems. the cost of security solutions for cyber-physical systems. e and solve cyber security and system safety issues in cyber-phy security metrics from the vulnerabilities, threats, risks and so	with technologies s to identify cyber se against targeted ty of machine tool
	l systems. dustrial control systems:	6 hours
	f an industrial control system-the industrial control system archi	
model for ind	ustrial control systems- industrial control system communi	
protocols		
Module 2 In	secure by inheritance	5 hours
	ol system history-modbus and modbus TCP / IP – Profinet-Cor	
	ICS- Anatomy ICS attack scenario –Attacks-consequences	
in the		



Backend protocols-advanced grid-Industrial protocol simulators

metering infrastructure and smart

6 hours

45 hours

Module:3	The Purdue model and a converged plant-wide Ethernet:	6 hours
The conver	ged plant wide Enterprise-The safety zone-the manufacturing zon	e-the enterprise
zone-the C	PwE industrial network security framework- Physical ICS securit	ty-ICS network
security-IC	S computer security-ICS Application security-ICS Device security -	The ICS cyber
security pro	gram development process.	

Module:4 Industrial Network design and architecture

Introduction to industrial networking- common topologies- network segmentation-network services- Wireless networks-Remote access -performance considerations-safety instrumented systems-special considerations

Module:5 | Hacking Industrial control systems |

6 hours Consequences of successful cyber incident-cyber security and safety-common industrial targetscommon attack methods- Attack trends-industrial application layer attacks

Module:6 Risk and vulnerability assessments

9 hours Cyber security and risk management-methodologies for accessing risk within industrial control system-system characterization-threat identification-vulnerability identification-risk classification and ranking-risk reduction and mitigation

Module:7 | Security of Machine Tool Systems- Standards and regulations: 5 hours Cyber physical systems - Safety and security of cyber physical systems- Cyber-attacks and measures in cyber-physical systems - Cyber risks in industrial control systems - Costing security solutions -NERC CIP-CFATS-ISA/ IEC62443-mapping Industrial network security to compliance –common criteria and FIPS standards-standards organizations-NIST security guidelines

Module:8 C	ontemporary Issues	2 hours
Industrial Exp	pert Guest Lecture and Seminars	

Total Lecture hours:

Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2 lectures by industry experts

Text Book(s)

- Pascal Ackerman, "Industrial Cyber security-Efficiently secure critical infrastructure 1. systems", Packt Publishing Ltd., Bringham, 2017.
- 2. Eric D.Knapp and Joel Thomas Langill, "Industrial Network Security- Securing Critical



	Infrastructure Networks for		cm	art Grid, SCADA, and other				
	Industrial Control Systems" Syngress is an Imprint of Elsevier, 2015.							
Ref	Reference Books							
1.	Lihui Wang, Xi Vincent Wang, "	Cloud-Based Cyb	er –Physio	cal systems in Manufacturing",				
	Springer Nature, 2018							
2.	Edward J.M. Colbert and Alexan	der Kott, "Cyber-S	Security an	d SCADA and other Industrial				
	control Systems" Springer Interna	ational Publishing	AG Switz	erland,2016				
Mo	de of Evaluation: CAT / Assignme	ent / Quiz / FAT / I	Project / Se	eminar				
Mo	de of evaluation:							
Rec	commended by Board of Studies	06-09-2019						
Ар	proved by Academic Council	No. 56	Date	24-09-2019				
	· · · · · ·	-						



MEE6067	Transportation Cyber Physical Systems	L	T	P J	J
		3	0	0 (D 3
Pre-requisite		Sylla	ibus	vers	ion
-		v. 1.0	0		
Course Obje	ctives(CoB):				
	ectives of course are to:				
 Under in des Devel Devel Expected Co At the endof tion Assess trans Select appoint Analyze da Infer hum Plan and ir Realize en Module: 1 Introduction 	be the concepts of transportation cyber physical system architected stand the capability of transportation technologies and important of an and implementation. The provided the component of the course, astudent will be able to: asportation system user services in real world. The course, astudent will be able to: asportation system user services in real world. The course in intelligent transportation cyber physical system monophysical system monophysical system monophysical system monophysical system for transportation cyber physical systems and control modes for transportation cyber physical systems to transportation cyber physical systems, Components of the transportation cyber physical systems of the tyber physical systems of the tyber physical systems of the tyber ph	specific ber pl odels. l syste ration 5 ho	huma pility. c cond hysic ms. s. urs ortati	an fa	ns. //sten
			ay bei		
	ironmental and societal benefits. Infrastructure for Transportation Cyber Physical	5 ho			
Module: 2	Infrastructure for Transportation Cyber Physical Systems	5 ho	urs		-
Module: 2 Information Systems. Date	Infrastructure for Transportation Cyber Physical	5 ho rres in ensor	urs the tech	trar	nspo
Module: 2 Information T systems. Da Transponders Module: 3	Infrastructure for Transportation Cyber Physical Systems Management. Importance of networking among data structu a processing engines and serving layer, Traffic flow s and Communication systems. Real time control in autonomous Data management in Transportation Cyber Physical Systems	5 hor res in ensor vehic 6 hor	urs the tech cles. urs	trar	nspo ogie
Module: 2 Information T systems. Da Transponders Module: 3 Data Manage Transport sy Identification	Infrastructure for Transportation Cyber Physical Systems Management. Importance of networking among data structu a processing engines and serving layer, Traffic flow s and Communication systems. Real time control in autonomous Data management in Transportation Cyber Physical	5 ho rres in ensor vehice 6 hor er Phyehicle	urs tech cles. urs vsical Loco	trar mole Sys	nspo ogie stem
Module: 2 Information T systems. Dat Transponders Module: 3 Data Manage Transport sy Identification	Infrastructure for Transportation Cyber Physical Systems Management. Importance of networking among data structu a processing engines and serving layer, Traffic flow s and Communication systems. Real time control in autonomous Data management in Transportation Cyber Physical Systems ment Issues; Data Base Systems and Data Analytics for Cyber stem data collection techniques – Detectors, Automatic Ver GIS, video data collection. Route Navigation and Guidance control	5 ho rres in ensor vehice 6 hor er Phyehicle	urs tech cles. urs vsical Loco ts; D	trar mole Sys	nspo ogie stem

NUT VIT	VIT [*]
	Vellore Institute of Technology (Deemed to be University under section 3 of UGC Act, 1956)

		Land	(Deemed to be University under section 3 of UGC Act, 1956)	1
Module: 5	Intelligent Transportation C	yber Physic	al System	7 hours
0	ansportation Syst	em Models	and Evaluation Methods; Conc ing and co-simulation.	ept of transportation
Module: 6	Transportation control	Cyber Phy	sical Systems security and	6 hours
	ansportation Cyber		ystem design and operation; Safe ystem. Applied security control ir	
Module: 7	Transportation	System Ap	plications	8 hours
Traffic and	incident manage	ement syste	vices in smart city construction, ra ems; sustainable mobility, Tra g, Integration of Automated Trans	nsportation network
Module: 8	Contemporary I	Discussions		2 hours
Industrial Ex	pert Guest Lecture	and Semina	ars	1
and computer by industry e	ped Class Room, [models to lecture xperts		oe videotaped], Use of physical dustry, Minimum of 2 lectures	45 hours
Text Book(s) 1. Lipika			Transportation Cyber-Physical 42960	Systems, Publisher
Wiley	aZuazola, Intellige & Sons, 2015. IS	BN:111889	ort Systems: Technologies and	l Applications, John
			lishers, London. 2014. ISBN: 978	
Reference B	ooks			
Sons,	2011.		n, Modelling Transport, 4th Editi	
Hall c	of India Pvt. Ltd.		iples of Transportation Engineer	
	on Education India	•	N: 9332587647.	
Mode	ling, Butterworth-	Heinemann	Transportation Engineering: Tl, 2016. ISBN:0128038896	neory, Practice and
		_ <u> </u>	Quiz / Seminar / FAT	
Studies	ed by Board of	06-09-201	.9	1
Approved by Council	Academic	No. 56	Date	24-09-2019



Course code	Smart Health Technology]	LΤ	Ρ	JC
MEE6068				2 0	0	4 3
Pre-requisit	<u> </u>		Svll	abu	s ve	rsin
TTC TCquisit	-		Oyn	uvu		v. 1.
Course Obje	ctives(CoB):					
	ectives of course are to:					
1 Introduc	e leading technology trends in the field of smart healthcare.					
	application of acquired theoretical and technological knowled	lao in	tho	fiold	lof	e ma
healthca		ige in	i uie i	lieit	1013	Silla
licaluica	ς.					
	urse Outcome(CO):					
At the endot	the course,astudent will be able to:					
1. Familiar	ze with health system organization and basic concepts of sma	art he	althc	are		
	eir knowledge successfully, design, and develop mobile appli				alth	
	skills in major architectures and technologies of IoT in health					
	knowledge on cloud computing technologies and infrastructu					
-	technologies and infrastructure needed for development of w		ole sc	luti	ons	
-	ntation of smart health services in smart cities					
Module:1	Introduction to eHealth				31	nour
	to health system concepts. Basic concepts of Smart health	care.	Mul	tidis		
	art healthcare				- r	
Module:2	nHealth - Mobile technologies				4 h	our
Mobile techn	ologies and health services. Mobile networking fundamentals	s. Bo	dy A	rea	Netv	vorl
Mobile devic	es and applications in eHealth. Examples of mobile healthcar	e imj	olemo	enta	tions	5.
			1			
	Implementation of IoT in eHealth					iour
	chnological trends in healthcare and their implementation in , protocols and infrastructures needed for developing IoT solu					
Technologies		ution	5 111 1	lean	IICal	e
Module:4	Wearable computing				4 h	our
	wearable computing. Examples of applications of wearable	arabl	es ir	ı h	ealth	care
•	and infrastructure needed for development of wearable so	lutio	ns. E	xan	ples	s an
case studies i	n smart healthcare					
N/- J-1					- 1	
	Smart healthcare services in smart cities art city infrastructure and services. Implementation of smart h		 1 COPT	vico		iour mai
	ve healthcare in smart cities. Examples of health services in s) III S	SIIId



Module:6 Gamification in Healthcare and applications	4 hours
Introduction to gamification. Application of gamification in healthcare. Learn	
in healthcare. Technologies for healthcare games development. Example	
healthcare applications. Healthcare services suitable for smart healthcare impl	ementation.
Module:7 Cloud computing and big data	4 hours
Basic concepts of cloud computing. Basic concepts of cloud services and c	
Technologies and infrastructure necessary for cloud computing in	
implementation. Big data infrastructure, services and analytics in smart he	ealthcare. (content
robotics application in medical – surgical applications)	
Module:8 Contemporary Issues	2 hours
Industrial Expert Guest Lecture and Seminars	
Total Lecture hours:	30 hours
# Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and	
computer models to lecture, Visit to Industry, Min of 2 lectures by industry	7
experts	
Text Book(s)	
1. AdwitiyaSinha, MeghaRathi, "Smart Healthcare Systems", CRC Press, 20	
2. Bruno Bouchard, "Smart Technologies in Healthcare", CRC Press, 2017.	
Reference Books	
1. Andreas Holzinger, CarstenRöcker, "Smart Health: Open Problems and I	Future Challenges",
CRC Press, 2015.	
2. Thomas F. Heston "eHealth: Making Health Care Smarter" Boca Raton, I	Intech Open, 2013.
Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar	
Mode of evaluation:	
Recommended by Board of Studies 06-09-2019	
Approved by Academic Council No. 56 Date 24-09-201	9



Course codeDigital Systems Design and ArchitectureLTPJCMEE606930003Pre-requisiteSyllabus versionv. 1.0

Course Objectives(CoB):

The main objectives of course are to:

- 1. Acquire basic knowledge in digital systems design and architecture
- 2. Understand the steps in designing of digital circuits and systems.
- 3. Develop an digital electronic control system for general engineering applications

Expected Course Outcome(CO):

At the endof the course, astudent will be able to:

- 1. Understand basics of digital devices and architecture.
- 2. Provide specifications of digital circuit using hardware description language.
- 3. Analyze the building blocks and designing of digital system.
- 4. Distinguish architecture of various processors and memory device.
- 5. Develop program using interfacing peripherals and communications in a digital circuit.
- 6. Design the digital circuits for various types of processors.

Module:1 Digital Devices

4 hours

7 hours

Digital circuit-Device technologies- IC, classification of ASIC-FPGA-Development cycle-Electronic Design Automation

Module:2 Hardware Description Languages

Introduction to reconfigurable computing, circuit specification using hardware description languages, use of HDL packages

Module:3 RTL based System Design

Introduction to RTL based design, data paths and controllers

Module:4 RISC architecture

Features of RISC architecture, pipelining, register windows, register renaming Vector processing, Multithreading, Multiprocessing.

Module:5 Processor design

Instruction set architecture, hardwired and micro programming approaches to processor design

Module:6 Memory design

RAM, ROM, EPROM, SRAM, DRAM, memory cells and memory organization, cache memory design, memory interfacing **-Virtual memories**.

7 hours

9 hours

5 hours

6 hours



Modu	10.7	Δενη	chronous seque		(Deemed to be University of	nder section 3 of UGC Act		mc			5 hours
	uction	-			ial avatama	20.00	syste conditio		stability		
			asynchronous	sequent	ial systems,	race	Conditio	JIIS,	Stability	issues,	state
reduct	lon tec	cnniqu	es-finite state n	lacinne							
N 7 1	1 0	6	. T							r	. 1
Modu			temporary Iss		1	1 1 .		. 1			2 hours
			iques in digital	system	design-Digit	al elect	ronic coi	ntrol	system-	application	ons
and c	ase st	udies									
Total										45	5 hours
			Class Room, [I			-	-	-			
compu	iter m	odels	to lecture, Vis	sit to In	dustry ,Min	of 2 le	ectures b	y ino	dustry		
expert	S										
Text E	Book(s)									
1. D	avid I	Harris	, Sarah Harris,	Digital	Design and (Compu	ter Archi	tecti	ıre, MK	Publishe	rs,
Se	econd	Ediso	on, 2012								
2. A	rrozG	uiher	me, Monteiro J	ose, Oli	veira Arlind	o, Com	puter Ar	chite	ecture: D	igital Cir	cuits
to	Micr	oproc	essors, World S	Scientifi	c Publishing	, 2018	-			-	
3. M	Iorris	Mano	, Computer Sy	stem Ar	chitecture , T	hrid ed	lition, Pe	arso	n, 2007		
Refere	ence I	Books									
1. M	Iorris	Mano	, Digital Logic	and Co	nputer Desig	n. Moi	gan Kau	fmai	nn, 2016		
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			inguage. Spring	0	0				r · · ·		
		<u> </u>	on: CAT / Assi			[/ Proj	ect / Sem	ninar	4		
Mode	of eva	aluatio	on:								
Recon	nmend	led by	Board of Stud	lies	06-09-2019						
			demic Council		No. 56	D	ate 2	24-0	9-2019		
		<i>v</i>					I				



Course code	Data Science & Analytics	L T P J C
MEE6070		2 0 0 4 3
Pre-requisite		Syllabus versior
		v. 1.0
Course Objective	s(CoB):	
The main objective		
1. Introduc	e data analytics software tools for processing, extracting and	analysing data for
	ring applications.	unaryoning data io
	ata mining techniques to realistic data sets in which they can rec	ognize the demands
	neir area of specialization.	0
3. Learn to	implement the solutions for data analytics problems in a program	uming language and
	structured and systematic approach to data processing.	
Expected Course		
On completion of th	e course, the students will be able to	
	basic statistical concepts and techniques (like the mean, median	n, mode, percentile
	ge, variance, confidence intervals, p-value, correlation, and t-test).	
	lyze and model data (linear regression, clustering, decision tree	mining, association
	s learning).	
	lyze the interpret database schemes and write simple queries to a d	
	tify and apply data transformations (normalization, aggregation), discretion.	data reduction, and
	ly suitable visualization techniques (like line graphs, bar chart	e scattor plots pi
	ts, box plots, violin plots, and heat maps).	s, scatter piots, pie
	ign data analytics problems in a programming language and app	olv a structured and
	ematic approach to data processing	
	s of Data science	3 hours
	ng-Data preparation- Data transformation- Mathemati	
	vectors, matrices- Geometric view - vectors, distance, proje	
	atistics for decision making- Descriptive statistics, notic	
distributions.		
M. 1.1		
	s in Data analytics	4hours
5	me work- General software Tools for Data Analysis-Ba	asic programming
environmentDat	a extraction- Data visualization- Big Data.	
Module:3 Softw	vare tools for data analytics	4 hour
	e, scripting Language (coding tools), Statistical Language	(R, SAS, SPSS)
and Open source s		
Module:4 Type	s of Data analytics	4 hours
Tribuule.4 Type		- 4 HUU IS
Decision making	process-Descriptive-Diagnostic-Predictive-Prescriptive	types- Advanced



techniques in data analytics

Module:5 Data analytics techniques - 1

Regression-Prediction- Simple linear regression Multivariate linear regression, model assessment, assessing importance of different variables, subset selection

Module:6Data analytics techniques - 24 hoursClassification using kNN and k-means clustering- Naive Bayes -Ensemble technique-Bagging &
Boosting, Random Forest, AdaBoost& Gradient boosting- Decision tree4 hours

Module:7Data analytics techniques - Applications4 hoursDeep learning and natural language processing- Engineering applications of Data analytics- Case
studies- Autonomous driving- Manufacturing-Supply chain-E commerce, Banking, Super market

Module:8 Contemporary Issues

Industrial Expert Guest Lecture and Seminars

Total Lecture hours: # Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical and computer models to lecture, Visit to Industry, Min of 2 lectures by industry experts

Text Book(s)

- 1. João Moreira, Andre Carvalho, TomásHorvathm, A General Introduction to Data Analytics, Wily, 2019
- 2. Edward L. Robinson Data Analysis for Scientists and Engineers, Princeton University Press, 2016.
- 3. Thomas A. Runkler Data Analytics: Models and Algorithms for Intelligent Data Analysis, Springer Verlog, 2016

Reference Books

1. **Runkler**, Thomas A. Models and Algorithms for Intelligent Data Analysis, Springer, 2012

2. **Edward L. Robinson,** Data Analysis for Scientists and Engineers, press Princeton, 2017

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

Mode of evaluation:

Recommended by Board of Studies	06-09-2019				
Approved by Academic Council	No. 56	Date	24-09-2019		

30 hours

2 hours

5 hours



Course code	Wireless Networking of Embedded Systems	L T P J C
MEE6071		3 0 0 4 4
Pre-requisite		Syllabus version
		v. 1.0

Course Objectives(CoB):

The main objectives of course are to:

- 1. Develop an embedded system that requires the understanding of the physical world with the system that has to interact via wireless network.
- 2. Understand the suitable principles and standards (e.g. IEEE 802.15.1 and ZigBee) in design and evaluation of sensor networks and wireless communication protocols for small digital transmitters.
- 3. Teach the basic and advanced concepts in wireless networking architectures and protocols.
- 4. Study the application of WSN Environment Monitoring and Health Care applications.

Expected Course Outcome(CO):

At the endof the course, astudent will be able to:

- 1. Acquire knowledge about the architecture of various embedded devices.
- 2. Ability to get knowledge about real time system and communications.
- 3. Understand the embedded system in the application of CPS.
- 4. Design wireless sensor network based on applications
- 5. Develop and compute the routing protocol
- 6. Demonstrate the protocols for maximizing lifetime of wireless sensor networks

Module:1Embedded Systems:4 hoursIntroduction: Definition, history and applications of Embedded System - Concept of Real timeSystems - Embedded System Design - Components of Embedded Systems

Module:2	Embedded Processor and Memory:	7 hours				
Embedded	Embedded system design flow - Embedded processors - Microcontrollers (PIC and ARM					
architecture	architectures) – DSP, ASICs and SoC – Memory interface – Memory Technologies –					
Heterogene	Heterogeneous memory system					
Module:3	Embedded Communication Protocols:	9 hours				
Embedded	Networking: Introduction-Serial/Parallel Communication -Serial/Parallel	ial communication				
protocols –	protocols – RS232 standard – RS485 Synchronous Serial Protocols – Serial Peripheral Interface					
(SPI) – Inter Integrated Circuits (I2C) – PC Parallel port programming – ISA/PCI Bus protocols						
– Firewire.		Ŧ				

Module:4 Wireless Communication:

4 hours



	v-power RF modules – W		EEE 802.1	1) – Bluetooth
(IEI	EE 802.15.1) – Zigbee (IEEE	802.15.4) – 6LoWPAN		
	dule:5 Wireless Embedded			9 hours
		oduction – Applications – Netw		
		efficient MAC protocols – SMA	C – Energy e	efficient and robust
rout	ing – Data Centric routing			
Mo	dule:6 Routing protocols:			5 hours
Ge	ssiping and agent-based uni	cast forwarding – Energy-effic	ient unicast	– Broadcast and
	ılticast – Geographic routing -			
				1
		ssion on Specific Applications		5 hours
		Environment Monitoring – G		
		ance analysis of energy effici	ient clusteri	ng protocols for
ma	iximizing lifetime of wireless	sensor networks		
Mo	dule:8 Contemporary Issu	95		2 hours
	lustrial Expert Guest Lecture			2 11001 5
1110	iustriui Expert Guest Decture (
	•			45 hours
Tot	al Lecture hours:		hysical and	45 hours
Tot # M	al Lecture hours: Iode: Flipped Classroom, [Lec	cture to be videotaped], Use of p		45 hours
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Tot # M con exp	al Lecture hours: lode: Flipped Classroom, [Lec uputer models to lecture, Visit erts e rts	cture to be videotaped], Use of p t to Industry, Min of 2 lectures	by industry	
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Course code	Multi Agent System	LTP	JC
MEE6072		3 0 0	4 4
Pre-requisite		Syllabus v	ersio
			v. 1.0
Course Objective	s(CoB):		
The main objective	es of course are to:		
1. Introduce t	he conceptual framework of multi agent systems and its fu	Indamental co	ncepts
	ation, cooperation, dynamics in multi agent systems		1
	he different programming approaches for multi agent sys	stems and stue	dv the
	ent languages and programming platforms		
	l develop the multi agent system for different industrial app	olications	
Expected Course			
	ourse,astudent will be able to:		
1. Understand	l the fundamental concepts and metal models of multi agen	t systems.	
	e various programming approaches for multi agent systems		
	erent agent languages and platform for the development of		stems
		าd web platfor	ms
4. Gain insigh	nts of integrating multi agent systems, mobile computing an		ms
 Gain insight 5. Explore incomplete 	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system.	•	
4. Gain insigh 5. Explore inc Module:1 Multi	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system	. 6	hours
4. Gain insigh 5. Explore inc Module:1 Multi Conceptual frame	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system.	. 6	hour
4. Gain insigh 5. Explore inc Module:1 Multi	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system	. 6	hour
4. Gain insigh 5. Explore inc Module:1 Multi Conceptual frame dynamics.	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization-	. 6 - Coordinatio	hours n and
 4. Gain insight 5. Explore incomplete Module:1 Multi Conceptual frame dynamics. Module:2 Program 	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming	. 6 - Coordinatio	hours n and hours
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 4. Gain insight 5. Explore incomplete to the second s	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming Programming, Environment Oriented Programming, Ir ganisation Oriented Programming- Multi-Agent Oriented ap	. 6 - Coordination 5 nteraction Or oproach 7	hours n and hours ientec
4. Gain insigh 5. Explore inc Module:1 Multi Conceptual frame dynamics. Module:2 Progr Agent Oriented Programming, Org Module:3 Hybri Agent meta-mode	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming Programming, Environment Oriented Programming, Ir ganisation Oriented Programming- Multi-Agent Oriented ap id and Embedded Models l- Agent & Agent Interaction meta-model- Agent's dyna	. 6 - Coordination 5 nteraction Or oproach 7 amics- Enviro	hours n and hours iented
4. Gain insigh 5. Explore inc Module:1 Multi Conceptual frame dynamics. Module:2 Progr Agent Oriented Programming, Org Module:3 Hybri Agent meta-mode	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming Programming, Environment Oriented Programming, Ir ganisation Oriented Programming- Multi-Agent Oriented ap	. 6 - Coordination 5 nteraction Or oproach 7 amics- Enviro	hours n and hours iented
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 4. Gain insight 5. Explore incomplete to the second state of the sec	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming Programming, Environment Oriented Programming, Ir ganisation Oriented Programming- Multi-Agent Oriented ap id and Embedded Models l- Agent & Agent Interaction meta-model- Agent's dyna at & Environment Interaction meta-model Environment's dy nization meta-model a-model - organisational artifacts: Organisation's dynami organisation	. 6 - Coordinatio	hours n and hours iented hours nmen hours sation
4. Gain insight 5. Explore ind Module:1 Multi Conceptual frame dynamics. Module:2 Program Agent Oriented Programming, Org Module:3 Hybri Agent meta-mode meta-model- Agen Organisation meta adaptation of the o Module:5 Agen	nts of integrating multi agent systems, mobile computing an dustrial case studies and applications of multi agent system. i agent system work, Agent – Environment- Interaction- Organization- ramming Programming, Environment Oriented Programming, Ir ganisation Oriented Programming- Multi-Agent Oriented ap id and Embedded Models l- Agent & Agent Interaction meta-model- Agent's dyna at & Environment Interaction meta-model Environment's dyna mization meta-model a-model - organisational artifacts: Organisation's dynami organisation	. 6 - Coordination - Coordination 5 nteraction Or oproach 7 amics- Environ ynamics 6 ics- Reorganis 9	hour n and hour iented hour sation hour
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Mo	odule:6	Multi agent architecture	e for cyber physic	al system	S	5 hours
	0	architecture for cyber phy	Đ	0	0 1	0
		Physical System- Practica	l application-orie	nted syste	m design f	for Cyber Physical
Sys	stem					
Mo	dule:7	CPS with Embedded Ap	plication			5 hours
Inte	egration	with technologies- Web	2.0 applications-	mobile	computing	applications- Web
Ser	vices ap	plications- "Web of Things	" Applications- Se	emanticall	y Aware Ag	gents
Ap	plication	s of multi agent system	s-manufacturing,	factory a	utomation,	smart factory- E
con	nmerce-	supply chain, mobile	computing- hea	lth care	-Automotiv	e-Aerospace-Home
aut	omation					
						1
		Contemporary Issues				2 hours
In	dustrial	Expert Guest Lecture and S	eminars			
	_					
		ire hours:				45 hours
		ipped Class Room, [Lectu	1		1 0	
	-	er models to lecture, Visit	to Industry, Minii	num of 2	lectures by	
	ustry ex					
	xt Book		T 1 . • 1 A		· • 1·	
1.		Leitão StamatisKarnouskos		its: Emerg	ing Applica	ations of Software
2	Agents	in Industry, Elsevier, 2015	•			
2.	Bordin	i, R.H., Dastani, M., Diz	x, J., El Fallah	Seghrouch	ini, A. (E	Eds.) Multi-Agent
	Program	nming, Languages, Platfor	ms and Applicatio	ns, Spring	er 2009.	
Re	ference	Books				
1.		hoham , Kevin Leyton-Br	own. Multiagent	Systems-	Algorithmic	. Game-Theoretic.
		gical Foundations, Cambrid				, came meerede,
		0		,		
Mo	de of Ev	valuation: CAT / Assignment	nt / Quiz / FAT / H	Project / Se	eminar	
Mo	de of ev	aluation:				
Ree	commen	ded by Board of Studies	06-09-2019			
Ap	proved t	y Academic Council	No. 56	Date	24-09-201	9



Course cod	e Control System Analysis and Design	L T P J C
MEE6073		3 0 2 0 4
Pre-requisi	te	Syllabus version
		v. 1.
Course Obj	ectives (CoB):	
The main ol	pjectives of course are to:	
	ntroduce the concept of model based controller and performance	measures in time and
	requency domain.	
	Provide control system design procedures for Single Input Single (Dutput system and identification of dynamic models of plants	Julput and Two Input Two
	Jnderstand the basic concepts of control systems for online and of	fline identification of
	process dynamics	mile identification of
•	ourse Outcome(CO):	
	ne endof the course, astudent will be able to:	·
	nulate the mathematical of model based controller and unders	stand the performance
	sures in time and frequency domain.	rand the performance
	yze the effect of measurement noise and load on control syst	em performance in time
	frequency domain.	I I I I I I I I I I I I I I I I I I I
	gn the model based controllers for Single Input Single Outpu	it and Two Input Two
	but system	1
-	ly state space analysis techniques for the identification of dyr	namic models of plants
	y the basic concepts in Nonlinear and optimal control system	
	gn of advanced control systems for real time applications.	
	Introduction to Control system	5 hour
I		I
Introduction	, Model Based Controller Design-Control structures and per	formance measures,
	quency domain performance measures, Control system desig	
	Basics in Design of Controller	6 hour
	ontroller for Single Input Single Output system-PI-PD contro	oller for SISO system-
	easurement noise and load- Identification of dynamic model	
Module:3	State variable analysis and Design	6 hour
	state, state variable and state model, state equations, Contro	
1	y, Observer system, Pole placement by state feed back	indoning and
	,, , , , , , , , , , , , , , , , , , ,	
Module:4	Control System identification:	6 hour
	n and Frequency domain approaches for system identification	
	ynamics- On-line identification of plant dynamics	
<u>or process u</u>	Junites on me identification of plant dynamics	
Module:5	Nonlinear control systems	9 hour
Physical no	ı linearities-Phase plane method – Singular points – Stability	y of nonlinear systems-
Lianunov cr	iterion- Phase trajectories- Function method- Stability analy	sis
Liupunov ci		



Vellore Institute of Technology (Deemed to be University under section 3 of UGC Act. 1956)	
Parameter optimization- Servomechanisms- C	Optimal
control approach using transfer functions-state variables.	-
Module:7 Advances in control systems	6 hours
Adaptive and robust control system design, LQR, Back stepping, Model predictive of	control,
Sliding mode, Adaptive neuro fuzzy inference systems-Motion control applications	
Module:8 Contemporary Issues	2 hours
Industrial Expert Guest Lecture and Seminars	
Total Lecture hours:	45 hours
# Mode: Flipped Class Room, [Lecture to be videotaped], Use of physical	
and computer models to lecture, Visit to Industry, Min of 2 lectures by	
industry experts	
Text Book(s)	o Acio/India
1. S. Majhi, Advanced Control Theory-Relay Feedback Approach, Cengag Pvt.Ltd, 2009. A. Johnson and H.	e Asid/IIIuid
 Moradi, New Identifications and Design Methods, Springer - Verlag, 2005. Nor 	man S. Niso
Control Systems Engineering, John Wiley & Sons, 2008.	
Reference Books	
1. A. NagoorKani , Advanced Control Theory, RBA Publications, 2009	
2. Varmah, K R. Control Systems, McGraw Hill Education, 2010	
Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar	
List of Experiments (challenging Experiments)	
1. State space models and simulation of physical systems	1.5 Hr
2. System design and identification of control system	1.5 Hr
3. Time, Frequency response analysis of LEAD -LAG compensating network	1.5 Hr
4. Gain selection PID controller for stability and damped response	1.5 Hr
5. Bode, Nyquist and Root locus plots for system analysis	1.5 Hr
6. Design of Temperature control system using PID controller	1.5 Hr
7. Study on Speed-torque control of a servo drive	1.5 Hr
8. Study on control system characteristics of inverted pendulum.	1.5 Hr
9. Study on control system characteristics of automotive steer by wire system	1.5 Hr
10. Study on motion control of an electro hydraulic actuator	1.5 Hr
Total Hrs	15 Hr
Mode of evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar	
Recommended by Board of Studies 06-09-2019	
Approved by Academic Council No. 56 Date 24-09-2019	