

SCHOOL OF ELECTRICAL ENGINEERING

B. Tech Electronics and Instrumentation Engineering

(B.Tech EIE)

Curriculum (2019)



VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international industries & universities for productivity and economic development

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

To be a leader for academic excellence in the field of electrical, instrumentation and control engineering imparting high quality education and research leading to global competence for the societal and industrial developments.

MISSION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

M1: Impart high quality education and interdisciplinary research by providing conducive teaching learning environment and team spirit resulting in innovation and product development.

M2: Enhance the core competency of the students to cater to the needs of the industries and society by providing solutions in the field of electrical, electronics, instrumentation, and automation engineering.

M3: Develop interpersonal skills, leadership quality and societal responsibility through ethical value-added education.



PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

The school of Electrical Engineering has established and sustained a welldefined set of educational objectives and preferred program outcomes. Educational objectives of the program satisfy to the requirements of the stakeholders such as students, parents, employers, alumni, faculty etc. The Program Educational Objectives (PEOs) are as follows.

PEO-1: Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems in electrical engineering and allied disciplines.

PEO-2: Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry.

PEO-3: Graduates will function in their profession with social awareness and responsibility.

PEO-4: Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country.

PEO-5: Graduates will be successful in pursuing higher studies leading to careers in engineering, management, teaching, and research.



PROGRAMME OUTCOMES (POs)

POs are statements that describe what students are expected to know and be able to do upon graduating from the program. These relate to the skills, knowledge, analytical ability attitude and behaviour that students acquire through the program.

NBA has defined the following twelve POs for an engineering graduate. These are in line with the Graduate Attributes as defined by the Washington Accord: PO_01: Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.

PO_02: Problem Analysis: Identify, formulate, review research literature, and analyse complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences and engineering sciences.

PO_03: Design / Development of Solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.

PO_04: Conduct Investigations of Complex Problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions for complex problems:

• that cannot be solved by straightforward application of knowledge, theories and techniques applicable to the engineering discipline as against problems given at the end of chapters in a typical text book that can be solved using simple engineering theories and techniques

• that may not have a unique solution. For example, a design problem can be solved in many ways and lead to multiple possible solutions that require consideration of appropriate constraints / requirements not explicitly given in



the problem statement such as cost, power requirement, durability, product life, etc.

• which need to be defined (modelled) within appropriate mathematical framework

• that often require use of modern computational concepts and tools, for example, in the design of an antenna or a DSP filter.

PO_05: Modern Tool Usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.

PO_06: The Engineer and Society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

PO_07: Environment and Sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

PO_08: Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.

PO_09: Individual and Team Work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings. PO_10: Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.

PO_11: Project Management and Finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

PO_12: Life-long Learning: Recognize the need for, and have the preparation and ability to engage in independent and lifelong learning in the broadest context of technological change.



PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of B. Tech. (Electronics and Instrumentation Engineering) programme, graduates will be able to

- PSO1: Design and develop electronics and instrumentation systems for fulfilling socio-economic and environmental requirements.
- PSO2: Analyze and design signal conditioning circuits for sensors, measurement, instrumentation system, process control and automation techniques by considering economic and environmental constraints.
- PSO3: Apply and implement intelligent systems using modern tools for instrumentation engineering.



CREDIT STRUCTURE

| Distribution | Credits |
|--------------------------|---------|
| University Core (UC) | 53 |
| University Elective (UE) | 12 |
| Programme Core (PC) | 59 |
| Programme Elective (PE) | 36 |
| Total | 160 |

Category-wise Credit distribution



DETAILED CURRICULUM

University Core

| University Core (53 Credits) | | | | | | | | | |
|------------------------------|-------------|---|-------|-------|-------|-------|----|--|--|
| S. No. | Course Code | Course Title | L | Т | Р | J | С | | |
| 1. | CHY1701 | Engineering Chemistry | 3 | 0 | 2 | 0 | 4 | | |
| 2. | CHY1002 | Environmental Sciences | 3 | 0 | 0 | 0 | 3 | | |
| 3. | CSE1001 | Problem Solving and Programming | 0 | 0 | 6 | 0 | 3 | | |
| 4. | CSE1002 | Problem Solving and Object Oriented Programming | 0 | 0 | 6 | 0 | 3 | | |
| 5. | EEE1901 | Technical Answers for Real World Problems (TARP) | 1 | 0 | 0 | 4 | 2 | | |
| 6. | EEE4098 | Comprehensive Examination | 0 | 0 | 0 | 0 | 1 | | |
| 7. | EEE4099 | Co-op /Capstone Project | 0 | 0 | 0 | 0 | 12 | | |
| 8. | ENG1901/ | Technical English I | | | | | | | |
| | ENG1902/ | Technical English II | 0/0/0 | 0/0/0 | 4/4/2 | 0/0/4 | 2 | | |
| | ENG1903 | Advanced Technical English | | | | | | | |
| 9. | ENG 1000/ | Foundation English I | 0 | 0 | 4 | 0 | 2 | | |
| | ENG 2000 | Foundation English II | | | | | | | |
| 10. | HUM1021 | Ethics and Values | 2 | 0 | 0 | 0 | 2 | | |
| 11. | MAT1011 | Calculus for Engineers | 3 | 0 | 2 | 0 | 4 | | |
| 12. | MAT2001 | Statistics for Engineers | 3 | 0 | 2 | 0 | 4 | | |
| 13. | MGT1022 | Lean Start-up Management | 1 | 0 | 0 | 4 | 2 | | |
| 14. | PHY1701 | Engineering Physics | 3 | 0 | 2 | 0 | 4 | | |
| 15. | PHY1901 | Introduction to Innovative Projects | 1 | 0 | 0 | 0 | 1 | | |
| 16. | EXC4097 | Extra & Co- Curricular Activities | 0 | 0 | 0 | 0 | 2 | | |
| 17. | EEE1902 | Industrial Internship | 0 | 0 | 0 | 0 | 1 | | |
| 18. | FLC4097 | Foreign Language Courses Basket | 2 | 0 | 0 | 0 | 2 | | |
| 19. | STS4097 | Soft Skills | _ | _ | _ | _ | 6 | | |



Programme Core

| | Programme Core (59 Credits) | | | | | | | | | |
|--------|-----------------------------|--|---|---|---|---|---|--|--|--|
| S. No. | Course Code | Course Title | L | T | Р | J | C | | | |
| 1. | EEE1002 | Electric Circuits | 3 | 0 | 0 | 0 | 3 | | | |
| 2. | EEE1004 | Engineering Electromagnetics | 3 | 0 | 2 | 0 | 4 | | | |
| 3. | EEE1005 | Signals and Systems | 3 | 0 | 0 | 0 | 3 | | | |
| 4. | EEE2001 | Network Theory | 3 | 0 | 0 | 0 | 3 | | | |
| 5. | EEE2002 | Semiconductor Devices and Circuits | 2 | 0 | 2 | 4 | 4 | | | |
| 6. | EEE2005 | Digital Signal Processing | 2 | 0 | 2 | 0 | 3 | | | |
| 7. | EEE3001 | Control Systems | 3 | 0 | 2 | 0 | 4 | | | |
| 8. | EEE3002 | Analog and Digital Circuits | 3 | 0 | 2 | 0 | 4 | | | |
| 9. | EEE4001 | Microprocessor and Microcontroller | 2 | 0 | 2 | 0 | 3 | | | |
| 10. | EEE4021 | Sensors and Signal Conditioning | 3 | 0 | 2 | 0 | 4 | | | |
| 11. | EEE4031 | Electrical and Electronic Instrumentation | 3 | 0 | 2 | 0 | 4 | | | |
| 12. | EEE4032 | Process Automation and Control | 3 | 0 | 2 | 0 | 4 | | | |
| 13. | EEE4033 | Industrial Instrumentation | 3 | 0 | 0 | 4 | 4 | | | |
| 14. | MAT2002 | Applications of Differential and Difference Equations | 3 | 0 | 2 | 0 | 4 | | | |
| 15. | MAT3003 | Complex Variables and Partial Differential Equations | 3 | 1 | 0 | 0 | 4 | | | |
| 16. | MAT3005 | Applied Numerical Methods | 3 | 1 | 0 | 0 | 4 | | | |



Programme Elective

| S. No. | Course Code | Course Title | L | Т | Р | J | C |
|--------|----------------|---|---|---|---|---|---|
| 1. | EEE1007 | Neural Network and Fuzzy Control | 2 | 0 | 0 | 4 | 3 |
| 2. | EEE1008 | Bio-Medical Instrumentation | 3 | 0 | 0 | 4 | 4 |
| 3. | EEE1011 | Automated Test Engineering | 2 | 0 | 2 | 0 | 3 |
| 4. | EEE1012 | Optoelectronic Instrumentation | 3 | 0 | 0 | 0 | 3 |
| 5. | EEE1013 | Analytical Instrumentation | 3 | 0 | 0 | 0 | 3 |
| 6. | EEE1014 | Fiber Optic Sensors | 3 | 0 | 0 | 0 | 3 |
| 7. | EEE1015 | Micro Electromechanical Systems | 3 | 0 | 0 | 4 | 4 |
| 8. | EEE1016 | Non-Destructive Testing | 3 | 0 | 0 | 0 | 3 |
| 9. | EEE1018 | Nanotechnology Fundamentals and its Applications | 3 | 0 | 0 | 0 | 3 |
| 10. | EEE1020 | Engineering Optimization | 2 | 1 | 0 | 4 | 4 |
| 11. | EEE2006 | Communication Engineering | 3 | 0 | 2 | 0 | 4 |
| 12. | EEE2008 | Electrical Technology | 3 | 0 | 2 | 0 | 4 |
| 13. | EEE3008 | Data Communication Network | 3 | 0 | 0 | 0 | 3 |
| 14. | EEE3009 | Digital Image Processing | 3 | 0 | 0 | 4 | 4 |
| 15. | EEE4018 | Advanced Control Theory | 3 | 0 | 0 | 4 | 4 |
| 16. | EEE4019 | Advanced Digital System Design With FPGAs | 2 | 0 | 0 | 4 | 3 |
| 17. | EEE4020 | Embedded System Design | 2 | 0 | 0 | 4 | 3 |
| 18. | EEE4022 | Analog VLSI Design | 3 | 0 | 0 | 0 | 3 |
| 19. | EEE4024 | Computer Architecture and Organization | 3 | 0 | 0 | 0 | 3 |
| 20. | EEE4026 | Digital Control Systems | 2 | 0 | 0 | 4 | 3 |
| 21. | EEE4027 | Robotics and Control | 2 | 0 | 0 | 4 | 3 |
| 22. | EEE4028 | VLSI Design | 3 | 0 | 2 | 0 | 4 |
| 23. | EEE4029 | Advanced Microcontrollers | 2 | 0 | 0 | 4 | 3 |



| 24. | EEE4030 | System on Chip Design | 3 | 0 | 0 | 4 | 4 |
|-----|---------|---|---|---|---|---|---|
| 25. | EEE4034 | Wireless Sensor Networks | 3 | 0 | 0 | 4 | 4 |
| 26. | EEE4035 | Virtual Instrumentation | 0 | 0 | 2 | 4 | 2 |
| 27. | EEE4037 | Rapid Prototyping with FPGAs | 0 | 0 | 4 | 0 | 2 |
| 28. | EEE4038 | Testing and Calibration Systems | 0 | 0 | 2 | 0 | 1 |
| 29. | MEE1006 | Applied Mechanics and Thermal Engineering | 2 | 0 | 2 | 0 | 3 |
| 30. | ECE3501 | IoT Fundamentals | 2 | 0 | 2 | 4 | 4 |
| 31. | ECE3502 | IoT Domain Analyst | 2 | 0 | 2 | 4 | 4 |

University Elective Baskets

Management courses

| Sl.No | Code | Title | L | T | Р | J | C |
|-------|---------|---|---|---|---|---|---|
| 1 | MGT1001 | Basic Accounting | 3 | 0 | 0 | 0 | 3 |
| 2 | MGT1002 | Principles of Management | 2 | 0 | 0 | 4 | 3 |
| 3 | MGT1003 | Economics for Engineers | 2 | 0 | 0 | 4 | 3 |
| 4 | MGT1004 | Resource Management | 2 | 0 | 0 | 4 | 3 |
| 5 | MGT1005 | Design, Systems and Society | 2 | 0 | 0 | 4 | 3 |
| 6 | MGT1006 | Environmental and Sustainability Assessment | 2 | 0 | 0 | 4 | 3 |
| 7 | MGT1007 | Gender, Culture and Technology | 2 | 0 | 0 | 4 | 3 |
| 8 | MGT1008 | Impact of Information Systems on Society | 2 | 0 | 0 | 4 | 3 |
| 9 | MGT1009 | Technological Change and Entrepreneurship | 2 | 0 | 0 | 4 | 3 |
| 10 | MGT1010 | Total Quality Management | 2 | 2 | 0 | 0 | 3 |
| 11 | MGT1014 | Supply Chain Management | 3 | 0 | 0 | 0 | 3 |
| 12 | MGT1015 | Business Mathematics | 3 | 0 | 0 | 0 | 3 |
| 13 | MGT1016 | Intellectual Property Rights | 3 | 0 | 0 | 0 | 3 |
| 14 | MGT1017 | Business Regulatory Framework For Start- ups | 3 | 0 | 0 | 0 | 3 |
| 15 | MGT1018 | Consumer Behaviour | 3 | 0 | 0 | 0 | 3 |



| | (Deemed to be University under section 3 of UGC Act, 1956) | | | | | |
|---------|---|--|--|--|---|--|
| MGT1019 | Services Marketing | 3 | 0 | 0 | 0 | 3 |
| MGT1020 | Marketing Analytics | 2 | 0 | 2 | 0 | 3 |
| MGT1021 | Digital and Social Media Marketing | 3 | 0 | 0 | 0 | 3 |
| MGT1022 | Lean Start-up Management | 1 | 0 | 0 | 4 | 2 |
| MGT1023 | Fundamentals of Human Resource Management | 3 | 0 | 0 | 4 | 4 |
| MGT1024 | Organizational Behaviour | 3 | 0 | 0 | 4 | 4 |
| MGT1025 | Foundations of Management And Organizational Behaviour | 3 | 0 | 0 | 4 | 4 |
| MGT1026 | Information Assurance and Auditing | 2 | 0 | 0 | 4 | 3 |
| MGT1028 | Accounting and Financial Management | 2 | 2 | 0 | 4 | 4 |
| MGT1029 | Financial Management | 2 | 1 | 0 | 4 | 4 |
| MGT1030 | Entrepreneurship Development | 3 | 0 | 0 | 4 | 4 |
| MGT1031 | International Business | 3 | 0 | 0 | 4 | 4 |
| MGT1032 | Managing Asian Business | 3 | 0 | 0 | 4 | 4 |
| MGT1033 | Research Methods in Management | 2 | 1 | 0 | 4 | 4 |
| MGT1034 | Project Management | 3 | 0 | 0 | 4 | 4 |
| MGT1035 | Operations Management | 3 | 0 | 0 | 0 | 3 |
| MGT1036 | Principles of Marketing | 3 | 0 | 0 | 4 | 4 |
| MGT1037 | Financial Accounting and Analysis | 2 | 1 | 0 | 4 | 4 |
| MGT1038 | Financial Econometrics | 2 | 0 | 0 | 4 | 3 |
| MGT1039 | Financial Markets and Institutions | 2 | 0 | 0 | 4 | 3 |
| MGT1040 | Personal Financial Planning | 2 | 0 | 0 | 4 | 3 |
| MGT1041 | Financial Derivatives | 2 | 1 | 0 | 4 | 4 |
| MGT1042 | Investment Analysis and Portfolio Management | 2 | 0 | 0 | 4 | 3 |
| MGT1043 | Applications in Neuro Marketing | 3 | 0 | 0 | 4 | 4 |
| MGT1044 | Global Brand Marketing Strategies | 3 | 0 | 0 | 4 | 4 |
| MGT1045 | Industrial Marketing | 3 | 0 | 0 | 4 | 4 |
| MGT1046 | Sales and Distribution Management | 3 | 0 | 0 | 4 | 4 |
| | MGT1020 MGT1021 MGT1022 MGT1023 MGT1024 MGT1025 MGT1026 MGT1027 MGT1028 MGT1029 MGT1030 MGT1031 MGT1032 MGT1033 MGT1034 MGT1035 MGT1035 MGT1036 MGT1037 MGT1038 MGT1039 MGT1040 MGT1041 MGT1041 MGT1043 | MGT1019Services MarketingMGT1020Marketing AnalyticsMGT1021Digital and Social Media MarketingMGT1022Lean Start-up ManagementMGT1023Fundamentals of Human Resource ManagementMGT1024Organizational BehaviourMGT1025Foundations of Management And Organizational BehaviourMGT1026Information Assurance and AuditingMGT1028Accounting and Financial ManagementMGT1029Financial ManagementMGT1030Entrepreneurship DevelopmentMGT1031International BusinessMGT1032Managing Asian BusinessMGT1033Research Methods in ManagementMGT1034Project ManagementMGT1035Operations ManagementMGT1036Financial Accounting and AnalysisMGT1037Financial EconometricsMGT1038Financial EconometricsMGT1040Personal Financial PlanningMGT1041Financial DerivativesMGT1042Investment Analysis and Portfolio ManagementMGT1043Applications in Neuro MarketingMGT1044Global Brand Marketing StrategiesMGT1045Industrial Marketing | MGT1019Services Marketing3MGT1020Marketing Analytics2MGT1021Digital and Social Media Marketing3MGT1022Lean Start-up Management1MGT1023Fundamentals of Human Resource Management3MGT1024Organizational Behaviour3MGT1025Foundations of Management And Organizational Behaviour3MGT1026Information Assurance and Auditing2MGT1029Financial Management2MGT1030Entrepreneurship Development3MGT1031International Business3MGT1032Managing Asian Business3MGT1034Project Management2MGT1035Operations Management3MGT1036Principles of Marketing3MGT1037Financial Accounting and Analysis2MGT1038Financial Econometrics2MGT1040Personal Financial Planning2MGT1041Financial Derivatives2MGT1043Applications in Neuro Marketing3MGT1044Global Brand Marketing Strategies3MGT1045Industrial Marketing3 | MGT1019Services Marketing30MGT1020Marketing Analytics20MGT1021Digital and Social Media Marketing30MGT1022Lean Start-up Management10MGT1023Fundamentals of Human Resource Management30MGT1024Organizational Behaviour30MGT1025Foundations of Management And Organizational Behaviour30MGT1026Information Assurance and Auditing20MGT1028Accounting and Financial Management22MGT1030Entrepreneurship Development30MGT1031International Business30MGT1032Managing Asian Business30MGT1033Research Methods in Management21MGT1034Project Management30MGT1035Operations Management30MGT1036Principles of Marketing30MGT1037Financial Accounting and Analysis21MGT1038Financial Planning20MGT1040Personal Financial Planning20MGT1041Financial Derivatives21MGT1042Investment Analysis and Portfolio Management20MGT1044Global Brand Marketing Strategies30MGT1045Industrial Marketing30 | MGT1019Services Marketing300MGT1020Marketing Analytics202MGT1021Digital and Social Media Marketing300MGT1022Lean Start-up Management100MGT1023Fundamentals of Human Resource Management300MGT1024Organizational Behaviour300MGT1025Foundations of Management And Organizational Behaviour300MGT1026Information Assurance and Auditing200MGT1028Accounting and Financial Management210MGT1030Entrepreneurship Development300MGT1031International Business300MGT1032Managing Asian Business300MGT1033Research Methods in Management210MGT1034Project Management300MGT1035Operations Management300MGT1036Principles of Marketing300MGT1037Financial Accounting and Analysis210MGT1040Personal Financial Planning200MGT1041Financial Derivatives210MGT1044Global Brand Marketing Strategies300MGT1045Industrial Marketing Strategies300 | MGT1019Services Marketing3000MGT1020Marketing Analytics2020MGT1021Digital and Social Media Marketing3000MGT1022Lean Start-up Management1004MGT1023Fundamentals of Human Resource Management3004MGT1024Organizational Behaviour3004MGT1025Foundations of Management And Organizational Behaviour3004MGT1026Information Assurance and Auditing2004MGT1028Accounting and Financial Management2104MGT1030Entrepreneurship Development3004MGT1031International Business3004MGT1032Managing Asian Business3004MGT1033Research Methods in Management2104MGT1034Project Management3004MGT1035Operations Management3004MGT1036Principles of Marketing3004MGT1037Financial Accounting and Analysis2104MGT1038Financial Markets and Institutions2004MGT1039Financial Markets and Institutions2004MGT1040Personal Financial Planning20 |



| 43 | MGT1047 | Social Marketing | 3 | 0 | 0 | 4 | 4 |
|----|---------|---|---|---|---|---|---|
| 44 | MGT1048 | Political Economy of Globalization | 3 | 0 | 0 | 4 | 4 |
| 45 | MGT1049 | Sustainable Business Models | 3 | 0 | 0 | 4 | 4 |
| 46 | MGT1050 | Software Engineering Management | 2 | 0 | 0 | 4 | 3 |
| 47 | MGT1051 | Business Analytics for Engineers | 2 | 2 | 0 | 0 | 3 |
| 48 | MGT1052 | Bottom of the Pyramid Operations | 3 | 0 | 0 | 0 | 3 |
| 49 | MGT1053 | Entrepreneurship Development, Business Communication and IPR | 1 | 0 | 2 | 0 | 2 |
| 50 | MGT1054 | Product Planning and Strategy | 2 | 2 | 0 | 0 | 3 |
| 51 | MGT1055 | Design Management | 2 | 2 | 0 | 0 | 3 |
| 52 | MGT1056 | Accounting and Financial Management | 3 | 0 | 0 | 4 | 4 |
| 53 | MGT6001 | Organizational Behaviour | 2 | 0 | 0 | 4 | 3 |

Humanities courses

| Sl.No | Code | Title | L | T | P | J | C |
|-------|---------|---|---|---|---|---|---|
| 1 | HUM1001 | Fundamentals of Cyber Laws | 3 | 0 | 0 | 0 | 3 |
| 2 | HUM1002 | Business Laws | 3 | 0 | 0 | 0 | 3 |
| 3 | HUM1003 | Basic Taxation for Engineers | 3 | 0 | 0 | 0 | 3 |
| 4 | HUM1004 | Corporate Law for Engineers | 3 | 0 | 0 | 0 | 3 |
| 5 | HUM1005 | Cost Accounting for Engineers | 3 | 0 | 0 | 0 | 3 |
| 6 | HUM1006 | Business Accounting for Engineers | 3 | 0 | 0 | 0 | 3 |
| 7 | HUM1007 | Contemporary Legal Framework for Business | 3 | 0 | 0 | 0 | 3 |
| 8 | HUM1009 | International Business | 3 | 0 | 0 | 0 | 3 |
| 9 | HUM1010 | Foreign Trade Environment | 3 | 0 | 0 | 0 | 3 |
| 10 | HUM1011 | Export Business | 3 | 0 | 0 | 0 | 3 |
| 11 | HUM1012 | Introduction to Sociology | 3 | 0 | 0 | 0 | 3 |
| 12 | HUM1013 | Population Studies | 3 | 0 | 0 | 0 | 3 |
| 13 | HUM1021 | Ethics and Values | 2 | 0 | 0 | 0 | 2 |



| 1 | 5 | | | - | - | |
|---------|---|---|--|---|--|---|
| HUM1022 | Psychology in Everyday Life | 2 | 0 | 0 | 4 | 2 |
| HUM1023 | Indian Heritage and Culture | 2 | 0 | 0 | 4 | 2 |
| HUM1024 | India and Contemporary World | 2 | 0 | 0 | 4 | 2 |
| HUM1025 | Indian Classical Music | 1 | 0 | 2 | 4 | 1 |
| HUM1033 | Micro Economics | 3 | 0 | 0 | 0 | 3 |
| HUM1034 | Macro Economics | 3 | 0 | 0 | 0 | 3 |
| HUM1035 | Introductory Econometrics | 2 | 0 | 2 | 0 | 2 |
| HUM1036 | Engineering Economics and Decision Analysis | 2 | 0 | 0 | 4 | 2 |
| HUM1037 | Applied Game Theory | 2 | 0 | 0 | 4 | 2 |
| HUM1038 | International Economics | 3 | 0 | 0 | 0 | 3 |
| HUM1039 | Community Development in India | 2 | 0 | 0 | 4 | 2 |
| HUM1040 | Indian Social Problems | 3 | 0 | 0 | 0 | 3 |
| HUM1041 | Indian Society Structure and Change | 3 | 0 | 0 | 0 | 3 |
| HUM1042 | Industrial Relations and Labour Welfare in India | 3 | 0 | 0 | 0 | 3 |
| HUM1043 | Mass Media and Society | 2 | 0 | 0 | 4 | 2 |
| HUM1044 | Network Society | 3 | 0 | 0 | 0 | 3 |
| HUM1045 | Introduction to Psychology | 2 | 0 | 2 | 0 | 2 |
| HUM1706 | Business Accounting for Engineers | 3 | 0 | 0 | 0 | 3 |
| | HUM1024 HUM1025 HUM1033 HUM1034 HUM1035 HUM1036 HUM1037 HUM1038 HUM1039 HUM1040 HUM1041 HUM1042 HUM1043 HUM1044 HUM1045 | HUM1023Indian Heritage and CultureHUM1024India and Contemporary WorldHUM1025Indian Classical MusicHUM1033Micro EconomicsHUM1034Macro EconomicsHUM1035Introductory EconometricsHUM1036Engineering Economics and Decision AnalysisHUM1037Applied Game TheoryHUM1038International EconomicsHUM1039Community Development in IndiaHUM1040Indian Social ProblemsHUM1041Indian Society Structure and ChangeHUM1042Industrial Relations and Labour Welfare in IndiaHUM1043Mass Media and SocietyHUM1044Network SocietyHUM1045Introduction to Psychology | HUM1023Indian Heritage and Culture2HUM1024Indian Acontemporary World2HUM1025Indian Classical Music1HUM1033Micro Economics3HUM1034Macro Economics3HUM1035Introductory Econometrics2HUM1036Engineering Economics and Decision Analysis2HUM1037Applied Game Theory2HUM1038International Economics3HUM1039Community Development in India2HUM1040Indian Societly Structure and Change3HUM1042Industrial Relations and Labour Welfare in India3HUM1043Mass Media and Society2HUM1044Network Society3HUM1045Introduction to Psychology2 | HUM1023Indian Heritage and Culture20HUM1024India and Contemporary World20HUM1025Indian Classical Music10HUM1033Micro Economics30HUM1034Macro Economics30HUM1035Introductory Econometrics20HUM1036Engineering Economics and Decision Analysis20HUM1037Applied Game Theory20HUM1038International Economics30HUM1039Community Development in India20HUM1040Indian Social Problems30HUM1041Industrial Relations and Labour Welfare in India30HUM1043Mass Media and Society20HUM1044Network Society30HUM1045Introduction to Psychology20 | HUM1023Indian Heritage and Culture200HUM1024India and Contemporary World200HUM1025Indian Classical Music102HUM1033Micro Economics300HUM1034Macro Economics300HUM1035Introductory Econometrics202HUM1036Engineering Economics and Decision Analysis200HUM1037Applied Game Theory200HUM1038International Economics300HUM1039Community Development in India200HUM1040Indian Social Problems300HUM1041Industrial Relations and Labour Welfare in India300HUM1043Mass Media and Society200HUM1044Network Society300HUM1045Introduction to Psychology202 | HUM1023Indian Heritage and Culture2004HUM1024India and Contemporary World2004HUM1025Indian Classical Music1024HUM1033Micro Economics3000HUM1034Macro Economics3000HUM1035Introductory Econometrics2020HUM1036Engineering Economics and Decision Analysis2004HUM1037Applied Game Theory2004HUM1038International Economics3000HUM1039Community Development in India2004HUM1041Indian Society Structure and Change3000HUM1042Industrial Relations and Labour Welfare in India3000HUM1043Mass Media and Society2004HUM1044Network Society3000 |



| | | 500 800 | | | | |
|---------------|------------------------|---------|--------|----------|-----|-------|
| CHY1002 | Environmental Sciences | I | Т | P | J | С |
| | | 3 | 0 | 0 | 0 | 3 |
| Pre-requisite | NIL | S | yllabı | is versi | ion | |
| | | | | | | v:1.1 |

Course Objectives:

1. To make students understand and appreciate the unity of life in all its forms, the implications of life style on the environment.

- 2. To understand the various causes for environmental degradation.
- 3. To understand individuals contribution in the environmental pollution.

4. To understand the impact of pollution at the global level and also in the local environment.

Expected Course Outcome:

- 1. Students will recognize the environmental issues from a problem-oriented interdisciplinary perspective.
- 2. Students will understand the key environmental issues, the science behind those problems, and potential solutions.
- 3. Students will demonstrate the significance of biodiversity and its preservation.
- 4. Students will identify various environmental hazards.
- 5. Students will design various methods for the conservation of resources.
- 6. Students will formulate action plans for sustainable alternatives that incorporate science, humanity, and social aspects.
- 7. Students will have foundational knowledge enabling them to make sound life decisions as well as enter a career in an environmental profession or higher education.
- 8. Understand the need for eco-balance
- 9. Acquire basic knowledge about global climate change with a particular reference to the Indian context.
- 10. Find ways to protect the environment and play pro-active roles

| Module:1 | Environment and Ecosystem | 7 hours |
|----------|---------------------------|---------|
| | | |

Key environmental problems, their basic causes and sustainable solutions. IPAT equation. Ecosystem, earth – life support system and ecosystem components; Food chain, food web, Energy flow in ecosystem; Ecological succession- stages involved, Primary and secondary succession, Hydrarch, mesarch, xerarch; Nutrient, water, carbon, nitrogen, cycles; Effect of human activities

on these cycles.

| Module:2 | Biodiversity | 6 hours |
|----------|--------------|---------|
| | | |

Importance, types, mega-biodiversity; Species interaction - Extinct, endemic, endangered and rare species; Hot-spots; GM crops- Advantages and disadvantages; Terrestrial biodiversity and Aquatic

biodiversity – Significance, Threats due to natural and anthropogenic activities and Conservation methods.



| Chemical hazards- BPA | Sustaining Natural | 1 hours |
|-------------------------|---|-------------------------------|
| Chemical hazards- BPA | Resources and Environmental | 7 hours |
| Chemical hazards- BPA | Quality | |
| Chemical hazards- BPA | s – causes and solutions. Biological ha | azards – AIDS. Malaria |
| | A, PCB, Phthalates, Mercury, Nuclear haz | |
| of hazards. Water foot | print; virtual water, blue revolution. Water | |
| ts conservation. Solid | | 4 |
| | s and waste management methods. | |
| JF JF | | |
| Module:4 | Energy Resources | 6 hours |
| Panawahla Non ranav | vable energy resources- Advantages and dis | sadvantagas oil Natural |
| | ••••••• | |
| | rgy. Energy efficiency and renewable energy | gy. Solar energy, |
| Hydroelectric | waves Wind and as the meal an every Free | an fuan hianaaa aalan |
| | energy, Wind and geothermal energy. Ener | gy from biomass, solar- |
| Hydrogen revolution. | | |
| Module:5 | Environmental Impact Assessment | 6 hours |
| | Environmental Impact Assessment | |
| | mental impact analysis. EIA guidelines, No | |
| | ll Protection Act – Air, water, forest and wi | ild life). Impact |
| assessment | | - |
| nethodologies. Public a | awareness. Environmental priorities in Indi | la. |
| | | |
| Module:6 | Human Population Change and | 6 hours |
| | Environment | |
| - | roblems; Consumerism and waste products | |
| | of population age structure – Women and c | |
| | ing human societies: Economics, environm | ent, policies and |
| education. | | |
| | Clobal Climatic Change and | 5 h |
| Module:7 | Global Climatic Change and | 5 hours |
| | Mitigation | |
| 1 | een house effect, Ozone layer depletion and | Acid rain. Kyoto |
| protocol, | | |
| | sequestration methods and Montreal Proto | col. Role of Information |
| echnology in environm | nent-Case Studies. | |
| Module:8 | Contemporary issues | 2 hours |
| viouuic.o | | 2 110015 |
| Lecture by Industry F | | 451 |
| Lecture by Industry I | Total Lecture hours: | 45 hours |
| Lecture by Industry I | | 1 |
| Lecture by Industry I | | |
| | | |
| Гext Books | G Tyler Miller and Scott F. Spoolman | (2016) Environmental |
| | G. Tyler Miller and Scott E. Spoolman | |
| Fext Books | Science, 15 th Edition, Cengage learning | g. |
| Гext Books | Science, 15 th Edition, Cengage learning George Tyler Miller, Jr. and Scott Spo | g. olman (2012), Living in |
| Fext Books | Science, 15 th Edition, Cengage learning | g. olman (2012), Living in |



| Reference Books | | | | | | | | | |
|---------------------------------|-------------------------------------|---|-------------------|--|--|--|--|--|--|
| 1. | | senzahl,Mary Catherine | Hager, Linda | | | | | | |
| | | R.Berg (2011), Visualizing Environmental Science, | | | | | | | |
| | 4thEdition, John Wiley & Sons, USA. | | | | | | | | |
| Mode of evaluation: Interr | nal Assessment | (CAT, Quizzes, Digital A | ssignments) & FAT | | | | | | |
| Recommended by Board of Studies | 12.08.2017 | | | | | | | | |
| Approved by Academic Council | 46 th AC | Date | 24.08.2017 | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CHY1002.1 | 2 | 1 | - | - | - | 3 | 3 | - | 1 | 1 | - | 2 | - | - | - |
| CHY1002.2 | 2 | 1 | _ | _ | _ | 2 | 2 | _ | - | _ | | 2 | _ | _ | _ |
| CHY1002.3 | 2 | 1 | _ | _ | | 2 | 2 | _ | _ | _ | _ | 2 | _ | | _ |
| CHY1002.4 | 2 | 1 | - | - | - | 3 | 3 | - | - | - | - | 2 | - | - | - |
| CHY1002.5 | 2 | 1 | - | - | - | 3 | 3 | - | - | - | - | 2 | - | - | - |
| CHY1002.6 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | 3 | 3 | - | 1 | 1 | - | 2 | - | - | - |
| CHY1002.7 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | 2 | 2 | - | 1 | 1 | - | 2 | - | - | - |
| CHY1002.8 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| CHY1002.9 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| CHY1002.10 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| | 2 | 1 | - | - | - | 3 | 3 | - | 1 | 1 | - | 2 | - | - | - |



| CHY1701 | (Deemed to be University under section 3 of UGC Act, 1956) Engineering Chemistry | |
|---|---|--|
| | Engineering Chemistry | |
| Pre-requisite | NIL | Syllabus version |
| | | v.1 |
| Course Objectives | : | |
| * | echnological aspects of applied chemistry | |
| | dation for practical application of chemistry in engineerir | ng aspects |
| Expected Course | Dutcomes (CO): Students will be able to | |
| | Il and analyze the issues related to impurities in water and their | |
| | y recent methodologies in water treatment for domestic and inc | ě – – – – – – – – – – – – – – – – – – – |
| 2. Eval meta | uate the causes of metallic corrosion and apply the methods for ls | r corrosion protection of |
| | uate the electrochemical energy storage systems such as lithiur cells, and design for usage in electrical and electronic applicate | |
| 4. Asse | ss the quality of different fossil fuels and create an awareness t | |
| fuels 5. Anal | yze the properties of different polymers and distinguish the po | lymers which can be |
| degra | aded and demonstrate their usefulness | |
| cons | ly the theoretical aspects: (a) in assessing the water quality truction and working of electrochemical cells; (c) analyzing me umental methods; (d) evaluating the viscosity and water ab | · · · · · |
| Module:1 Water | · Technology | 5 hours |
| problems in hardnes | ard water - hardness, DO, TDS in water and their deterns s determination by EDTA; Modern techniques of water of hard water in industries. | |
| Module:2 Water | Treatment | 8 hours |
| Specifications of wa treatment for munici Domestic water puri | hods: - Lime-soda, Zeolite and ion exchange processes an ater for domestic use (ICMR and WHO); Unit process pal supply - Sedimentation with coagulant- Sand Filtratio fication – Candle filtration- activated carbon filtration; D reatment, Ozonolysis, Reverse Osmosis; Electro dialysis. | es involved in water on - chlorination; |
| Module:3 Corro | osion | 6 hours |
| emphasizing Differe | on - detrimental effects to buildings, machines, devices & ential aeration, Pitting, Galvanic and Stress corrosion on nd choice of parameters to mitigate corrosion. | , |
| Module:4 Corre | osion Control | 4 hours |
| methods; Advanced Alloying for corrosic | n - cathodic protection – sacrificial anodic and impress protective coatings: electroplating and electroless plating on protection – Basic concepts of Eutectic composition an Ferrous and non-ferrous alloys. | sed current protection, PVD and CVD. |
| ` | rochemical Energy Systems | 6 hours |
| Brief introduction to energy systems: Li applications. | o conventional primary and secondary batteries; High e thium batteries – Primary and secondary, its Chemi r membrane fuel cells, Solid-oxide fuel cells- working p | istry, advantages and |



| | 11 | (Deemed to be University under section 3 of UGC Ac | | | | | | | | |
|---|-----------------------|--|-------------------|---------------------------------|--|--|--|--|--|--|
| | | Types – Importance of silicon single crystal, poly | | | | | | | | |
| solar cells, dye sensitized solar cells - working principles, characteristics and applications. | | | | | | | | | | |
| Module:6Fuels and Combustion8 hours | | | | | | | | | | |
| | | ue - Definition of LCV, HCV. Measurement of calo | orific value usin | ng bomb calorimeter | | | | | | |
| | • | lorimeter including numerical problems. | | | | | | | | |
| Contr | rolled co | ombustion of fuels - Air fuel ratio – minimum quanti | ity of air by vol | ume and by weight- | | | | | | |
| Num | erical pi | oblems-three way catalytic converter- selective cat | alytic reduction | n of NO _X ; Knocking | | | | | | |
| in IC | engines | -Octane and Cetane number - Antiknocking agents. | | | | | | | | |
| Moo | dule:7 | Polymers | | 6 hours | | | | | | |
| Diffe | rence be | etween thermoplastics and thermosetting plastics; E | Engineering app | olication of plastics - | | | | | | |
| ABS | , PVC, I | PTFE and Bakelite; Compounding of plastics: mould | ding of plastics | for Car parts, bottle | | | | | | |
| | | on moulding), Pipes, Hoses (Extrusion moulding), N | | | | | | | | |
| - | - | n moulding), Fibre reinforced polymers, Composite | | | | | | | | |
| | v mould | | × · | | | | | | | |
| ` | | olymers- Polyacetylene- Mechanism of conduction | – applications (| polymers in sensors, | | | | | | |
| | | windows) | 11 | | | | | | | |
| | dule:8 | Contemporary issues: | | 2 hours | | | | | | |
| | | Industry Experts | | | | | | | | |
| | <u> </u> | Total Lecture hours: | 45 hours | | | | | | | |
| | | | ie nouis | | | | | | | |
| Tex | t Book(| s) | I | | | | | | | |
| 1. | | hawla, A Text book of Engineering Chemistry, Dha | annat Rai Publi | shing Co., Pyt. Ltd. | | | | | | |
| | | ional and Technical Publishers, New Delhi, 3rd Edit | 1 | shing col, i vi Etal, | | | | | | |
| 2. | | alanna, McGraw Hill Education (India) Private Limi | | t 2015 | | | | | | |
| 3. | | sankar, Engineering Chemistry 1 st Edition, Mc Gra | | | | | | | | |
| 4. | | | | | | | | | | |
| 4. | | voltaic solar energy : From fundamentals to Appl Verlinden, Wilfried van Sark, Alexandre Freundlich | - | | | | | | | |
| Ref | erence l | Books | | | | | | | | |
| 1. | O.V. F | Roussak and H.D. Gesser, Applied Chemistry-A | Text Book | for Engineers and | | | | | | |
| | | ologists, Springer Science Business Media, New Yo | | - | | | | | | |
| 2. | S. S. D | Para, A Text book of Engineering Chemistry, S. C | | | | | | | | |
| | Edition | , 2013. | | | | | | | | |
| Mod | de of Ev | aluation: Internal Assessment (CAT, Quizzes, Digit | al Assignments | s) & FAT | | | | | | |
| List | of Exp | eriments | | · | | | | | | |
| | | | | | | | | | | |
| | Experi | ment title | | Hours | | | | | | |
| 1. | 1 | Purification: Estimation of water hardness by EDTA | A method and i | | | | | | | |
| 1. | | al by ion-exchange resin | i incence and i | | | | | | | |
| | | | n in different | 2 11 | | | | | | |
| 2. | water s | Quality Monitoring: Assessment of total dissolved oxyge amples by Winkler's method | en in different | 3 Hours | | | | | | |
| | Estima | ation of sulphate/chloride in drinking water by condu | uctivity method | 1 3 Hours | | | | | | |
| 3. | | | - | | | | | | | |
| J. | | | | | | | | | | |
| | | | | | | | | | | |
| 4/5 | | • | | ing | | | | | | |
| | metal | ions of Ni/Fe/Cu using conventional and smart phor | | ing | | | | | | |
| 4/5 | metal metho | ions of Ni/Fe/Cu using conventional and smart phoreds | | | | | | | | |
| | metal metho Analys | ions of Ni/Fe/Cu using conventional and smart phor | ne digital-imag | 3 Hours | | | | | | |



| 8. | Determination of viscosity-average | erent | 3 Hours | | | | | | | |
|-----|---|-----------------------------------|---------|--|--|--|--|--|--|--|
| | natural/synthetic polymers | | | | | | | | | |
| 9. | 9. Arduino microcontroller based sensor for monitoring | | | | | | | | | |
| | pH/temperature/conductivity in samples. | | | | | | | | | |
| | Total Laboratory Hours | | | | | | | | | |
| | Mode of Evaluation: Viva-voce and Lab performance & FAT | | | | | | | | | |
| Mod | le of Evaluation: Viva-voce and La | b performance & | FAT | | | | | | | |
| - | de of Evaluation: Viva-voce and La ommended by Board of Studies | b performance & 31-05-2019 | FAT | | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CHY1701.1 | 2 | 1 | - | - | - | 2 | 2 | - | 1 | 1 | - | 1 | - | - | - |
| CHY1701.2 | 3 | 2 | - | - | - | 2 | 2 | - | 1 | 1 | - | - | - | - | - |
| CHY1701.3 | 3 | 2 | - | - | - | 1 | 1 | - | 1 | 1 | _ | - | - | - | - |
| CHY1701.4 | 3 | 2 | - | - | - | 1 | - | - | 1 | 1 | - | - | - | - | - |
| CHY1701.5 | 3 | 2 | _ | _ | _ | 2 | 2 | _ | 2 | 2 | _ | - | - | - | - |
| CHY1701.6 | 3 | 2 | _ | - | 1 | 2 | 1 | _ | 2 | 2 | - | 1 | - | - | - |
| | 3 | 2 | - | - | 1 | 2 | 2 | - | 2 | 2 | - | 1 | - | - | - |



| CSE1001 | Problem Solving and Programming | L | Τ | P | J C |
|---|---|-------|---------------|--------|------------|
| | | 0 | 0 | 6 | 0 3 |
| Pre-requisite | NIL | S | yllat | ous v | ersion |
| ~ | | | | | v.1 |
| Course Objec | | | | | |
| | develop broad understanding of computers, programming lan | guag | ges a | ind t | heir |
| 0 | nerations | | | | |
| | roduce the essential skills for a logical thinking for problem solvi | 0 | ~_ 1 - | | maina |
| | gain expertise in essential skills in programming for prob | lem | SOL | ving | using |
| Expected Cou | nputer | | | | |
| <u> </u> | derstand the working principle of a computer and identify the put | mog | of | | oputor |
| | gramming language. | pose | | | iiputei |
| - | arn various problem solving approaches and ability to iden | tify | on | onnr | onriata |
| | proach to solve the problem | ury | an | аррг | opriate |
| | ferentiate the programming Language constructs appropriately to | col | ia ar | NV Dr | oblam |
| | ve various engineering problems using different data structures | 501 | | iy pro | JUICIII |
| | le to modulate the given problem using structural approach of pro- | arai | nmir | ıα | |
| | iciently handle data using flat files to process and store data for the | | | | lem |
| 0. En | letentry handle data using hat mes to process and store data for h | ic gi | ven | pioo | |
| List of Challe | nging Experiments (Indicative) | | | | |
| | in Problem Solving Drawing flowchart using yEd tool/Raptor To | പ | | Δ | Hours |
| _ | luction to Python, Demo on IDE, Keywords, Identifiers, I/O | 01 | | | Hours |
| Staten | • | | | | nouis |
| | e Program to display Hello world in Python. | | | Δ | Hours |
| | tors and Expressions in Python | | | | Hours |
| | ithmic Approach 1: Sequential | | | | Hours |
| U | ithmic Approach 2: Selection (if, elif, if else, nested if else | | | | Hours |
| - | rithmic Approach 3: Iteration (while and for) | | | 6 | Hours |
| - | gs and its Operations | | | 6 | Hours |
| 9 Regu | lar Expressions | | | 6 | Hours |
| 10 List a | nd its operations. | | | 6 | Hours |
| 11 Diction | onaries: operations | | | 6 | Hours |
| 12 Tuple | s and its operations | | | 6 | Hours |
| 13 Set an | nd its operations | | | 6 | Hours |
| | ions, Recursions | | | | Hours |
| | g Techniques (Bubble/Selection/Insertion) | | | | Hours |
| 16 Searc | hing Techniques : Sequential Search and Binary Search | | | 6 | Hours |
| | and its Operations | | | | Hours |
| Total | Lecture hours: | | | 45 | 5 hours |
| | | | 1 | | |



| Text Book(s) | | | | | | | | | |
|---------------------|--|-------------------|-------------------------------|--|--|--|--|--|--|
| 1. | John V. Guttag., 201 | 6. Introduction t | to computation and | | | | | | |
| | programming using python: with applications to understanding data. | | | | | | | | |
| | PHI Publisher. | PHI Publisher. | | | | | | | |
| Reference Books | | | | | | | | | |
| 1. | Charles Severance.2016.Python for everybody: exploring data in | | | | | | | | |
| | Python 3, Charles Severance. | | | | | | | | |
| 2. | Charles Dierbach.20 | 013.Introduction | n to computer science using | | | | | | |
| | python: a computation | onal problem-sol | ving focus. Wiley Publishers. | | | | | | |
| Mode of Evaluation: | PAT/CAT/FAT | | | | | | | | |
| Recommended by | 04-04-2014 | | | | | | | | |
| Board of Studies | | | | | | | | | |
| Approved by | 38th AC Date 23-10-2015 | | | | | | | | |
| Academic Council | | | | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CSE1001.1 | 2 | 1 | - | - | 1 | - | - | - | 1 | 1 | - | 2 | - | - | - |
| CSE1001.2 | 2 | 1 | - | - | 1 | - | - | - | 1 | 1 | - | 2 | - | - | - |
| CSE1001.3 | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1001.4 | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1001.5 | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1001.6 | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |



| CSE1002 | (Deemed to be University under section 3 of UGC Act, 1956) | |
|-------------------------|---|-----------------------|
| CSE1002 | Problem Solving and Object Oriented Programming | 0 0 6 0 3 |
| Pre-requisite | NIL | Syllabus version |
| 110-10quisite | | v.1.0 |
| Course Objective | s. | ۷.1.0 |
| • | the benefits of object oriented concepts | |
| 1 | students to solve the real time applications using object orient | ted programming |
| features. | students to solve the real time appreadons using object offen | ieu programming |
| | e skills of a logical thinking and to solve the problems using a | any processing |
| elements | | |
| | | |
| Expected Course | Outcome: | |
| | he basics of procedural programming and to represent the rea | l world |
| | gramming constructs | |
| | ject oriented concepts and translate real-world applications in | to graphical |
| representation | | |
| | he usage of classes and objects of the real world entities in ap | - |
| | he reusability and multiple interfaces with same functionality | based features to |
| | c computing problems ible error handling constructs for unanticipated states or input | ts and to use generic |
| | constructs to accommodate different data types. | is and to use generic |
| | rogram against file inputs towards solving the problem | |
| - | | |
| List of Challengi | ng Experiments (Indicative) | |
| 1. Postman Pro | blem | |
| A postman ne | eds to walk down every street in his area in order to deliver the | e mail. Assume that |
| | between the streets along the roads are given. The postman sta | |
| | ck to the post office after delivering all the mails. Implement a | an algorithm to help |
| | to walk minimum distance for the purpose. | |
| | ation for Marketing Campaign | |
| | ufacturing company has got several marketing options such a | |
| | campaign, TV non peak hours campaign, City top pap | |
| - | mpaign, Web advertising. From their previous experience, t paybacks for each marketing option. Given the marketing b | |
| | e current year and details of paybacks for each option, imple | - · - |
| | he amount that shall spent on each marketing option so that the | - |
| the maximum | | |
| | and Cannibals | |
| | naries and three cannibals are on one side of a river, along v | with a boat that can |
| | vo people. Implement an algorithm to find a way to get every | |
| of the river, v | vithout ever leaving a group of missionaries in one place o | utnumbered by the |
| cannibals in the | | |
| U | cation Problem | |
| - | component of a computer processor that can hold any type o | |
| | r. As registers are faster to access, it is desirable to use them t | |
| | e execution is faster. For each code submitted to the pro- | |
| - | raph (RIG) is constructed. In a RIG, a node represents a temp ded between two nodes (variables) t1 and t2 if they are live | • |
| U | the program. During register allocation, two temporaries can | • |
| | the program. During register anocation, two temporaries can | |



| | Land Asid (De | emed to be University under section | | 4 |
|-----|--|--|---|---|
| | same register if there is no edge co between variables in a code, imple required to store the variables and | ment an algorithn | n to detern | nine the number of registers |
| 5. | Selective Job Scheduling Probler | | | |
| | A server is a machine that waits fo purpose of a server is to share hard submit the jobs to the server for ex In such a situation, the server sch logic. Each job contains two value that there are two servers that scl named as Time_Schedule_Server a model and implement the time_Sch Time_Schedule_Server arranges jo whereas memory_Schedule_Server ascending order. | r requests from of lware and softwar ecution and the so redule the jobs su s namely time and hedules jobs base and memory_Sche hedule_Server and obs based on time | e resource erver may bmitted to d memory : d on time edule_Serv d memory_ required f | s among clients. All the clients get multiple requests at a time. o it based on some criteria and required for execution. Assume and memory. The servers are ver respectively. Design a OOP _Schedule_Server. The for execution in ascending order |
| 6. | Fragment Assembly in DNA Seq DNA, or deoxyribonucleic acid, is organisms. The information in DN adenine (A), guanine (G), cytosine sheared into millions of small frag sequence ("superstring"). Each rea of reads, the objective is to determ example, given a set of strings, superstring is 0001110100. Given superstring that contains all the given | the hereditary match is stored as a contract of (C), and thymine ments (reads) white d is a small string ine the shortest su {000, 001, 010, 0 a set of reads, in | ode made ((T). In Dl ch assemb . In such a perstring (011, 100, | up of four chemical bases: NA sequencing, each DNA is ble to form a single genomic fragment assembly, given a set that contains all the reads. For 101, 110, 111} the shortest |
| _ | superstring that contains all the giv | ven reads. | | |
| 7. | House Wiring An electrician is wiring a house wild different locations. Given a set of p algorithm to find the minimum cal | power points and t | | |
| | | | To | otal Laboratory Hours: 90 Hours |
| Tex | xt Book(s) | | | |
| 1. | Stanley B Lippman, Josee Lajoie, Wesley, 2012. | | | |
| 2. | Ali Bahrami, Object oriented Syste | ems development, | Tata McC | Graw - Hill Education, 1999 |
| 3. | Brian W. Kernighan, Dennis M. I Prentice Hall Inc., 1988. | Ritchie, The "C" | program | ning Language, 2nd edition, |
| Ref | ference Books | | | |
| 1. | Bjarne stroustrup, The C++ progra | 0 0 0 | | • |
| 2. | Harvey M. Deitel and Paul J. Deite | | - | |
| 3. | Maureen Sprankle and Jim Hub edition, Pearson Eduction, 2014 | | _ | |
| | de of Evaluation: CAT / Assignmen | | roject / Se | minar |
| | commended by Board of Studies | 29-10-2015 | | |
| App | proved by Academic Council | 39 th AC | Date | 17-12-2015 |
| | | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CSE1002.1 | | | | | | | | | | | - | - | | | |
| | 2 | 1 | - | - | 1 | - | - | - | 1 | 1 | - | 2 | - | - | - |
| CSE1002.2 | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1002.3 | 2 | 1 | - | - | 1 | - | - | - | 1 | 1 | - | 2 | - | - | - |
| CSE1002.4 | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1002.5 | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| CSE1002.6 | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 2 | - | - | - |



| EEE1901 | Technical Ans | swers for Real Wo | orld Prob | ems (TARP) | L T P J C |
|---|---|--|--|--|--|
| | | | | | 1 0 0 4 2 |
| Pre-requisite | PHY1901 and 11 | 15 Credits Earned | | | Syllabus version |
| | | | | | v. 1.0 |
| Course Objectives | | | | | |
| needs | - | | | - | industrial / societal |
| | | nplement relevant | technolog | y for the deve | lopment of the |
| prototypes / pro | | | | | |
| To make the str prototypes / pro | | use the methodolog | gies availa | ble to assess t | he developed |
| Expected Course | Outcome: | | | | |
| | ne course, the stude | | | | |
| • | ife problems related | • | | | |
| 11 * 11 1 | | s) to address the ide | entified pr | oblems using | engineering |
| principles and | arrive at innovative | e solutions | | | |
| Minimum of Appropriate Solution sh design/relet Consolidate Participation will be used Project outo political an Contribution | of eight hours on se e scientific method ould be in the form vant scientific meth ed report to be subr n, involvement and d as the modalities come to be evaluated d demographic feas n of each group me | nitted for assessme l contribution in gro for the continuous ed in terms of techn | ctivity ed to solve ng/model nt oup discus assessmer ical, econ d | e the identified ing/product d ssions during at of the theor omical, socia | esign/process the contact hours y component I, environmental, |
| | | e unce reviews wit | ii the welg | mage 01 20:5 | 0.50 |
| | | nuous Assessment | | | k weightage of |
| · | - | tted, presentation a | nd project | reviews | |
| Recommended by | | 05/03/2016 | | | |
| Approved by Acad | | 40 th AC | Date | 18/03/2016 | - |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1901.1 | 3 | 2 | 1 | 1 | - | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 2 | - |
| EEE1901.2 | 3 | 2 | 1 | 1 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 2 | 3 |
| | 3 | 2 | 1 | 1 | 3 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 2 | 3 |



| EEE4098 | Comprehensive Examination | L T P J C |
|--|--|---|
| LLL+070 | | |
| Pre-requisite | NIL | Syllabus version |
| Tre requisite | | v.1.0 |
| | | |
| Module:1 Elect | rical Circuits | |
| resistor, inductor, excitation. Kirchho power transfer and active and reactive resonance, locus d | nt sources: independent, dependent, ideal and practical; V mutual inductor and capacitor; transient analysis of RL0 off's laws, mesh and nodal analysis, superposition, Thevenin's reciprocity theorems. Peak, average and rms values of ac q we powers; phasor analysis, impedance and admittance; iagrams, realization of basic filters with R, L and C elements orks, driving point impedance and admittance, open-, and show | C circuits with dc s, Norton, maximum quantities; apparent, series and parallel s. One-port |
| | | |
| 0 | Is and Systems | |
| frequency response systems; convolution | c and impulse signals; Laplace, Fourier and z-transforms e of first and second order linear time invariant systems, in on, correlation. Discrete time system: impulse response, fi- tion; DFT and FFT; basics of IIR and FIR filters | mpulse response of |
| Module:3 Contr | rol Systems | |
| | elling and representation of systems, Feedback principle, trans | sfer function. Block |
| | nal flow graphs, Transient and Steady-state analysis of lin | |
| | arwitz and Nyquist criteria, Bode plots, Root loci, Stability | |
| Lag, Lead and Le | ead-Lag compensators; P, PI and PID controllers; State s | space model, State |
| transition matrix | | |
| | | |
| | og and Digital Circuits | 11 |
| transistor circuits, opamps: difference amplifier, precision controlled oscillato functions. IC family vibrators, sequentic circuit, multiplexen and digital-to-ana Characteristics of time); basics of multiplexentic time); | applications of diode, Zener diode, BJT and MOSFET; sma feedback amplifiers. Characteristics of operational amplifier e amplifier, adder, sub tractor, integrator, differentiated n rectifier, active filters and other circuits. Oscillators, signal ors and phase locked loop. Combinational logic circuits, minin lies: TTL and CMOS. Arithmetic circuits, comparators, Sch al circuits, flip-flops, shift registers, timers and counters; analog-to-digital (successive approximation, integrating, fla log converters (weighted R, R-2R ladder and curren ADC and DAC (resolution, quantization, significant bits, umber systems, microcontroller: applications, memory and acing; basics of data acquisition systems. | ers; applications of or, instrumentation generators, voltage mization of Boolean mitt trigger, multi- ; sample- and-hold ish and sigma-delta) t steering logic). |
| 1 1 | rical and Electronic Instrumentation | |
| precision index, potentiometer; bri and power in sing current scaling, measurements, di | ic and random errors in measurement, expression of uncerta propagation of errors. PMMC, MI and dynamometer typ dges for measurement of R, L and C, Q-meter. Measurement le and three phase circuits; ac and dc current probes; true rms instrument transformers, timer/counter, time, phase an gital voltmeter, digital multimeter; oscilloscope, shielding an strial Instrumentation | pe instruments; dc t of voltage, current meters, voltage and nd frequency |



Resistive-, capacitive-, inductive-, piezoelectric-, Hall effect sensors and associated signal conditioning circuits; transducers for industrial instrumentation: displacement (linear and angular), velocity, acceleration, force, torque, vibration, shock, pressure (including low pressure), flow (differential pressure, variable area, electromagnetic, ultrasonic, turbine and open channel flow meters) temperature (thermocouple, bolometer, RTD (3/4 wire), thermistor, pyrometer and semiconductor); liquid level, pH, conductivity and viscosity measurement

Module:7 Optoelectronic Instrumentation

Optical sources and detectors: LED, laser, photo-diode, light dependent resistor and their characteristics; interferometer: applications in metrology; basics of fiber optic sensing.

Module:8 Communication Engineering

Amplitude- and frequency modulation and demodulation; Shannon's sampling theorem, pulse code modulation; frequency and time division multiplexing, amplitude-, phase-, frequency-, pulse shift keying for digital modulation.

Mode of Evaluation: Witten Exam

| Recommended by Board of Studies | 05.06.2015 | | |
|---------------------------------|---------------------|------|------------|
| Approved by Academic Council | 37 th AC | Date | 16.06.2015 |



| | (Deemed to be University under section 3 of UGC Act, 1956) | | | | - ' | ~ |
|----------------------|--|---------------------------------------|--------|-------|-------|----------|
| ENG1901 | Technical English - I | L | T | P | J | <u>C</u> |
| | | 0 | 0 | 4 | 0 | 2 |
| Pre-requisite | Foundation English-II | S | yllat | ous V | | |
| | | | | | v. | 1.1 |
| Course Objective | | | | | | |
| | e students' knowledge of grammar and vocabulary to read and | d wri | te eri | ror-f | ree | |
| | n real life situations. | | | | | |
| | e students' practice the most common areas of written and sp | oken | 1 | | | |
| | ations skills. | | | | | |
| | e students' communicative competency through listening and | spea | aking | acti | vitie | S |
| in the class | | | | | | |
| Expected Course | | | | | | |
| | p a better understanding of advanced grammar rules and write | e gra | mma | tical | ly | |
| | sentences. | innt | ~ ** | | | |
| 1 | e wide vocabulary and learn strategies for error-free commun | | | ntor | ta | |
| 1 | ehend language and improve speaking skills in academic and e listening skills so as to understand complex business comm | | | | | |
| | of global English accents through proper pronunciation. | unica | auon | m a | | |
| 5 | et texts, diagrams and improve both reading and writing skills | whi | ch w | ould | helr |) |
| | their academic as well as professional career. | , , , , , , , , , , , , , , , , , , , | | ouiu | non | , |
| | | | | | | |
| Module:1 Adv | anced Grammar | | | 4 | hou | irs |
| | voice and Prepositions | | | | | |
| | ets on Impersonal Passive Voice, Exercises from the prescrib | oed te | ext | | | |
| | | | | | | |
| Module:2 Voc | abulary Building I | | | 4 | 4 ho | urs |
| Idioms and Phrase | s, Homonyms, Homophones and Homographs | | | | | |
| Activity: Jigsaw P | uzzles; Vocabulary Activities through Web tools | | | | | |
| | | | | | | |
| | ening for Specific Purposes | | | 4 | 4 ho | urs |
| U | short conversations, announcements, briefings and discussion | ns | | | | |
| Activity: Gap fillin | ig; interpretations | | | | | |
| Module:4 Spe | aking for Expression | | | 6 | ho | ire |
| I | f and others, Making Requests & responses, Inviting and Acc | enti | ισ/Π | | | 41.9 |
| Invitations | i and services, making requests & responses, inviting and Acc | opui | 16/17 | | mg | |
| | oductions; Role-Play; Skit. | | | | | |
| | | | | | | |
| Module:5 Rea | ding for Information | | | 4 | 4 ho | urs |
| | sages, News Articles, Technical Papers and Short Stories | | | - 1 | | |
| U | specific news paper articles; blogs | | | | | |
| | | | | | | |
| Module:6 Wri | ting Strategies | | | 4 | ho | urs |
| | ces, word order, sequencing the ideas, introduction and conclu | usion | 1 | | | |
| | agraphs; Describing familiar events; story writing | | • | | | |
| - | abulary Building II | | | 4 | ho | urs |
| | v 0 | | | - 1 | | |

| | (Deemed to be University under section 3 of UGC Act, 1956) | |
|--|--|--|
| Enrich | the domain specific vocabulary by describing Objects, Charts, Food, Sports and | |
| Employ | /ment. | |
| Activity | y: Describing Objects, Charts, Food, Sports and Employment | |
| | | |
| Module | 8 | 4 hours |
| | ng for statistical information, Short extracts, Radio broadcasts and TV interviews | |
| Activity | y: Taking notes and Summarizing | |
| Module | e:9 Expressing Ideas and Opinions | 6 hours |
| | onic conversations, Interpretation of Visuals and describing products and processes. | |
| | y: Role-Play (Telephonic); Describing Products and Processes | |
| | | |
| Modul | e: 10 Comprehensive Reading | 4 hours |
| Reading | g Comprehension, Making inferences, Reading Graphics, Note-making, and Critica | 1 |
| Reading | g. | |
| Activity | y: Sentence Completion; Cloze Tests | |
| | | |
| Modul | | 4 hours |
| | g narrative short story, Personal milestones, official letters and E-mails. | |
| Activity | y: Writing an E-mail; Improving vocabulary and writing skills. | |
| Module | e:12 Pronunciation | 4 hours |
| WUUU | | |
| | Sounds Word Stress Intension Various accents | 4 Hours |
| Speech | Sounds, Word Stress, Intonation, Various accents y: Practicing Pronunciation through web tools: Listening to various accents of Engli | |
| Speech | Sounds, Word Stress, Intonation, Various accents y: Practicing Pronunciation through web tools; Listening to various accents of Engli | |
| Speech Activity | | |
| Speech Activity Modul | y: Practicing Pronunciation through web tools; Listening to various accents of Engli | ish 4 hours |
| Speech Activity Modul Simple, | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, | ish 4 hours |
| Speech Activity Modul Simple, Punctua | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity Modul | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity Modul "The B | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity Modul "The B | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity Modul "The B | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. | ish 4 hours 4 hours |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours | ish 4 hours |
| Speech Activity Modul Simple, Punctua Activity "The B Activity Text B | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook | 4 hours 4 hours 60 hours |
| Speech Activity Modul Simple, Punctua Activity "The B Activity Text B | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English (| 4 hours 4 hours 60 hours |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity Text B 1. | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English (& Composition. New Delhi: Sultan Chand Publishers. | ish 4 hours 4 hours 60 hours Grammar |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity Text B 1. | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English G & Composition. New Delhi: Sultan Chand Publishers. Kumar, Sanjay,; Pushp Latha. (2018) English Language and Communication Skill | ish 4 hours 4 hours 60 hours Grammar |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity Text B 1. 2 | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English (& Composition. New Delhi: Sultan Chand Publishers. | ish 4 hours 4 hours 60 hours Grammar |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity Text B 1. 2 Referen | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English G & Composition. New Delhi: Sultan Chand Publishers. Kumar, Sanjay,; Pushp Latha. (2018) English Language and Communication Skill Engineers, India: Oxford University Press. nce Books | 4 hours 4 hours 60 hours Grammar s for |
| Speech Activity Modul Simple, Punctua Activity "The B Activity Text B 1. 2 | y: Practicing Pronunciation through web tools; Listening to various accents of Engli e:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English G & Composition. New Delhi: Sultan Chand Publishers. Kumar, Sanjay,; Pushp Latha. (2018) English Language and Communication Skill Engineers, India: Oxford University Press. nce Books Guptha S C, (2012) Practical English Grammar & Composition, 1st Edition, India: Arih | 4 hours 4 hours 60 hours Grammar s for |
| Speech Activity Modul Simple, Punctua Activity Modul "The B Activity Text B 1. 2 Referen | y: Practicing Pronunciation through web tools; Listening to various accents of Engli le:13 Editing , Complex & Compound Sentences, Direct & Indirect Speech, Correction of Errors, ations. y: Practicing Grammar le:14 Short Story Analysis oundary" by Jhumpa Lahiri y: Reading and analyzing the theme of the short story. Total Lecture hours ook / Workbook Wren, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English G & Composition. New Delhi: Sultan Chand Publishers. Kumar, Sanjay,; Pushp Latha. (2018) English Language and Communication Skill Engineers, India: Oxford University Press. nce Books | ish 4 hours 4 hours 60 hours Grammar s for ant |

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| | | eemed to be University under section | 5 01 0 GC AG, 1950) | |
|---------|---|--------------------------------------|-----------------------------|------------------|
| 3. | Liz Hamp-Lyons, Ben Heasley | v, (2010) Study Wr | iting, 2nd Edition, UK: C | ambridge |
| | University Pres. | | | |
| 4. | Kenneth Anderson, Joan Macle Cambridge, University Press. | ean, (2013) Tony I | Lynch, Study Speaking, 21 | nd Edition, UK: |
| 5. | Eric H. Glendinning, Beverly I Cambridge University Press. | Holmstrom, (2012) | Study Reading, 2nd Edit | ion, UK: |
| 6. | Michael Swan, (2017) Practica Oxford University Press. | ll English Usage (F | Practical English Usage), 4 | 4th edition, UK: |
| 7. | Michael McCarthy, Felicity O Asian Edition), UK: Cambridg | · · · · | • | vanced (South |
| 8. | Michael Swan, Catherine Walt 4th Edition, UK: Oxford Unive | | English Grammar Course | Advanced, Feb, |
| 9. | Watkins, Peter. (2018) Teachir for Language teachers, UK: Ca | | | ge Handbooks |
| 10. | (The Boundary by Jhumpa Lah https://www.newyorker.com/ma | | /the-boundary?intcid=inline | _amp |
| Mode of | of evaluation: Quizzes, Presenta | ation, Discussion, | Role play, Assignments a | nd FAT |
| List of | Challenging Experiments (Ind | licative) | | |
| 1. S | elf-Introduction | , | | 12 hours |
| 2. S | equencing Ideas and Writing a H | Paragraph | | 12 hours |
| | eading and Analyzing Technica | | | 8 hours |
| | istening for Specificity in Interv | | cific) | 12 hours |
| 5. Id | lentifying Errors in a Sentence of | or Paragraph | | 8 hours |
| 6. W | Vriting an E-mail by narrating lit | fe events | | 8 hours |
| | | Т | otal Laboratory Hours | 60 hours |
| | of evaluation: Quizzes, Presentat | tion, Discussion, R | ole play, Assignments an | d FAT |
| Recom | mended by Board of Studies | 08.06.2019 | | |
| Approv | ed by Academic Council | 55 th AC | Date: 13-06-2019 | |
| | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ENG1901.1 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG1901.2 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG1901.3 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG1901.4 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG1901.5 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |



| | 8 | L | Τ | P | J | С |
|--|---|-------------|--------------|---------------------|---------------------------------------|--------------------|
| | | 0 | 0 | 4 | 0 | 2 |
| Pre-requisite | 71% to 90% EPT score | Sy | llab | us ' | Vers | |
| ~ ~ ~ ~ ~ ~ | | | | | v. | 1.1 |
| Course Objective | | | | | | |
| | proficiency levels in LSRW skills on par with the requirements | for | plac | em | ent | |
| | of high-end companies / competitive exams. | | c | | | |
| | e complex arguments and to articulate their own positions on a ra | ang | e of | tec | hnica | al |
| and general | - | 1 | | . 1 . | | |
| - | grammatical and acceptable English with minimal MTI, as wel | 1 as | saev | elo | ра | |
| Expected Course | tive vocabulary. | | | | | |
| * | ate proficiently in high-end interviews and exam situations and a | <u></u> | nonio | 1 | | |
| situations | are proficiently in high-end interviews and exam situations and a | an | SUCIA | u | | |
| | nd academic articles and draw inferences | | | | | |
| - | fferent perspectives on a topic | | | | | |
| | ly and convincingly in academic as well as general contexts | | | | | |
| | complex concepts and present them in speech and writing | | | | | |
| | | | | | | |
| Module:1 List | ening for Clear Pronunciation | | | | 4 ho | irc |
| | duction to vowels, consonants, diphthongs. | | | | T 110 | uis |
| - | l conversations in British and American accents (BBC and CNN | 1) a | | 11 | a oth | or |
| 'native' accents | r conversations in Diffish and American accents (DDC and Civit | () a | s we | n a | s our | CI |
| | nd interpretive exercises; note-making in a variety of global Eng | alia | haa | oon | ta | |
| | | gns | | | 4 ho | |
| Speaking: Individu | oducing Oneself | | | | 4 110 | urs |
| | lai Presentanons | | | | | |
| | | | | | | |
| Activity: Self-Intro | oductions, Extempore speech | | | Г | 6 ho | 116 |
| Activity: Self-Intro Module:3 Effe | oductions, Extempore speech ective Writing | | | | 6 ho | urs |
| Activity: Self-Intro Module:3 Effe Writing: Business | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos | cin | σan | <u> </u> | | urs |
| Activity: Self-Intro Module:3 Effe Writing: Business Structure/ template | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla | cin | g an | <u> </u> | | urs |
| Activity: Self-Intro Module:3 Effe Writing: Business Structure/ template Formats of Minute | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos | cin | g an | <u> </u> | | urs |
| Activity: Self-Intro Module:3 Effe Writing: Business Structure/ template Formats of Minute Activity: Students | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo | cin | g an | ord | ler; | |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4Con | oductions, Extempore speech ective Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo aprehensive Reading | | | ord | ler; 4 ho | urs |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: Reading | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo nprehensive Reading Comprehension Passages, Sentence Completion (Technical and | | | ord | ler; 4 ho | urs |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: ReadingVocabulary and W | eductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo aprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy | | | ord | ler; 4 ho | urs |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: ReadingVocabulary and WActivities: Cloze te | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo nprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy ests, Logical reasoning, Advanced grammar exercises | | | ord 1 In | ler; 4 hor teres | u rs t), |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: Reading:Vocabulary and WActivities: Cloze teModule:5List | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo aprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy ests, Logical reasoning, Advanced grammar exercises ening to Narratives | Ge | nera | ord | ler; 4 ho teres 4 ho | urs t), urs |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: ReadingVocabulary and WActivities: Cloze teModule:5ListListening: Listening: | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo nprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy ests, Logical reasoning, Advanced grammar exercises ening to Narratives ng to audio files of short stories, News, TV Clips/ Documentarie | Ge | nera | ord | ler; 4 ho teres 4 ho | urs t), urs |
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| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: Reading:Vocabulary and WActivities: Cloze teModule:5ListListening: ListeningSpeeches in UK/ UActivity: Note-malModule:6Aca | aductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo aprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy ests, Logical reasoning, Advanced grammar exercises ening to Narratives Ing to audio files of short stories, News, TV Clips/ Documentarie US/ global English accents. king and Interpretive exercises demic Writing and Editing | Ge | nera | ord I In | ler; 4 ho teres 4 ho | urs t), urs |
| Activity: Self-IntroModule:3EffeWriting: BusinessStructure/ templateFormats of MinuteActivity: StudentsModule:4ConReading: Reading:Vocabulary and WActivities: Cloze teModule:5ListListening: ListeningSpeeches in UK/ UActivity: Note-malModule:6Aca | oductions, Extempore speech ctive Writing letters and Emails, Minutes and Memos e of common business letters and emails: inquiry/ complaint/ pla s and Memos write a business letter and Minutes/ Memo nprehensive Reading Comprehension Passages, Sentence Completion (Technical and ford Analogy ests, Logical reasoning, Advanced grammar exercises ening to Narratives ng to audio files of short stories, News, TV Clips/ Documentarie US/ global English accents. king and Interpretive exercises | Ge | nera | ord I In | ler; 4 ho teres 4 ho onal | urs t), urs |
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| Discu | king: Group Discussions and Debates on complex/ contemporary topics | |
|--|--|---|
| | | |
| Activ | ssion evaluation parameters, using logic in debates | |
| | ity: Group Discussions on general topics | |
| Modu | 0 | 4 hours |
| | ing: Resumes and Job Application Letters, SOP | |
| | ity: Writing resumes and SOPs | |
| Modu | 5 | 4 hours |
| | ing: Reading short stories | |
| | ity: Classroom discussion and note-making, critical appreciation of the short story | |
| | ule: 10 Creative Writing | 4 hours |
| | ing: Imaginative, narrative and descriptive prose | |
| Activ | ity: Writing about personal experiences, unforgettable incidents, travelogues | |
| Modu | ale: 11 Academic Listening | 4 hours |
| Liste | ning: Listening in academic contexts | |
| Activ | ity: Listening to lectures, Academic Discussions, Debates, Review Presentations, R | esearch |
| Talks | , Project Review Meetings | |
| Modu | ıle:12 Reading Nature-based Narratives | 4 hours |
| Narra | atives on Climate Change, Nature and Environment | |
| Activ | ity: Classroom discussions, student presentations | |
| Mod | ule:13 Technical Proposals | 4 hours |
| Writi | ing: Technical Proposals | |
| | ities: Writing a technical proposal | |
| | ule:14 Presentation Skills | 4 hours |
| | asive and Content-Specific Presentations | |
| | ity: Technical Presentations | |
| | | |
| | Total Lecture hours: | 60 hours |
| Text | Total Lecture hours: Book / Workbook | 60 hours |
| | Book / Workbook | |
| Text 1. | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud | |
| 1. | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud Paperback. Oxford University Press, UK, 2017. | |
| 1. 2 | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud Paperback. Oxford University Press, UK, 2017. Rizvi, Ashraf. Effective Technical Communication. McGraw-Hill India, 2017. | |
| 1. 2 | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud Paperback. Oxford University Press, UK, 2017. | |
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| 1. 2 Refer 1. 2. 3. 4. 5. | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud Paperback. Oxford University Press, UK, 2017. Rizvi, Ashraf. Effective Technical Communication. McGraw-Hill India, 2017. rence Books Oxenden, Clive and Christina Latham-Koenig, New English File: Advanced: Tead with Test and Assessment. CD-ROM: Six-level General English Course for Adult Paperback. Oxford University Press, UK, 2013. Balasubramanian, T. English Phonetics for the Indian Students: A Workbook. Lax Publications, 2016. Philip Seargeant and Bill Greenwell, From Language to Creative Writing. Blooms Academic, 2013. Krishnaswamy, N. Eco-English. Bloomsbury India, 2015. Manto, Saadat Hasan. Selected Short Stories. Trans. Aatish Taseer. Random Hous 2012. Ghosh, Amitav. The Hungry Tide. Harper Collins, 2016. Ghosh, Amitav. The Great Derangement: Climate Change and the Unthinkable. P Books, 2016. | ents Book. cher's Book ts. kmi sbury se India, |
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| 1. 2 Refer 1. 2. 3. 4. 5. 6. 7. | Book / Workbook Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stud Paperback. Oxford University Press, UK, 2017. Rizvi, Ashraf. Effective Technical Communication. McGraw-Hill India, 2017. rence Books Oxenden, Clive and Christina Latham-Koenig, New English File: Advanced: Tead with Test and Assessment. CD-ROM: Six-level General English Course for Adult Paperback. Oxford University Press, UK, 2013. Balasubramanian, T. English Phonetics for the Indian Students: A Workbook. Lax Publications, 2016. Philip Seargeant and Bill Greenwell, From Language to Creative Writing. Blooms Academic, 2013. Krishnaswamy, N. Eco-English. Bloomsbury India, 2015. Manto, Saadat Hasan. Selected Short Stories. Trans. Aatish Taseer. Random Hous 2012. Ghosh, Amitav. The Hungry Tide. Harper Collins, 2016. Ghosh, Amitav. The Great Derangement: Climate Change and the Unthinkable. P Books, 2016. | ents Book. cher's Book ts. kmi sbury se India, |



 https://americanliterature.com/short-short-stories. (75 short short stories)

 http://www.eco-ction.org/dt/thinking.html (Leopold, Aldo. "Thinking like a Mountain")

 /www.esl-lab.com/;

 www.bbc.co.uk/learningenglish/;

 /www.bbc.com/news;

 /learningenglish.voanews.com/a/using-voa-learning-english-to-improve-listening

 skills/3815547.html

Mode of evaluation: Quizzes, Presentation, Discussion, Role play, Assignments and FAT

| | | | 1 0 0 | |
|------|-------------------------------------|---------------------|---------------------------------|----------|
| | List of Challenging | Experiments (| Indicative) | |
| 1. | Self-Introduction using SWOT | | | 12 hours |
| 2. | | 10 hours | | |
| 3. | Writing an abstract | | | 10 hours |
| 4. | ation | 10 hours | | |
| 5. | Cloze Test | | | 6 hours |
| 6. | Writing a proposal | | | 12 hours |
| | | | Total Laboratory Hours | 60 hours |
| Mod | le of evaluation: Quizzes, Presenta | ation, Discussion | n, Role play, Assignments and I | FAT |
| Reco | ommended by Board of Studies | 08.06.2019 | | |
| App | roved by Academic Council | 55 th AC | Date: 13-06-2019 | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|--------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ENG | | | | | | | | | | | | | | | |
| 1902.1 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG | | | | | | | | | | | | | | | |
| 1902.2 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG | | | | | | | | | | | | | | | |
| 1902.3 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG | | | | | | | | | | | | | | | |
| 1902.4 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| ENG | | | | | | | | | | | | | | | |
| 1902.5 | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |
| | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |



| | (Deemed to be University under section 3 of UGC Act, 1956) | T | | D | T | | | | |
|---|--|--------------------|-------|----------|-------|-------|--|--|--|
| ENG1903 | Advanced Technical English | L | T | <u>Р</u> | J | C | | | |
| D | | 0024 Syllabus V | | 4 | 2 | | | | |
| Pre-requisite | re-requisite Greater than 90 % EPT score | | | | | | | | |
| | | | | | | | | | |
| Course Objective | | | | | | | | | |
| | literature in any form or any technical article | | | | | | | | |
| | ntent in social media and respond accordingly | ham | | and | | | | | |
| | 3. To communicate with people across the globe overcoming trans-cultural barriers and negotiate successfully | | | | | | | | |
| | • | | | | | | | | |
| Expected Course | | | | | | | | | |
| - | itically and write good reviews | | | | | | | | |
| | research papers, project proposals and reports | | | | | | | | |
| | ate effectively in a trans-cultural environment | | | | | | | | |
| 0 | and lead teams towards success | | | | | | | | |
| 5. Present ide | as in an effective manner using web tools | | | | | | | | |
| Module:1 Neg | otiation and Decision Making Skills through Literary An | alysi | s | | 5 ho | urs | | | |
| Concepts of Negot | iation and Decision Making Skills | | | | | | | | |
| Activity: Analysis | of excerpts from Shakespeare's "The Merchant of Venice" (c | court | scer | ie) ai | nd | | | | |
| discussion on nego | otiation skills. | | | | | | | | |
| Critical evaluation | of excerpts from Shakespeare's "Hamlet" (Monologue by Ha | mlet |) and | d dis | cussi | on | | | |
| on decision makin | | | | | | | | | |
| | ting reviews and abstracts through movie interpretations | | | 5 | hou | rs | | | |
| Review writing an | d abstract writing with competency | | | | | | | | |
| Activity: Watching | g Charles Dickens "Great Expectations" and writing a movie | revie | ew | | | | | | |
| Watching William | F. Nolan's "Logan's Run" and analyzing it in tune with the p | orese | nt sc | enar | io of | • | | | |
| depletion of resour | ces and writing an abstract | | | | | | | | |
| Module:3 Tec | hnical Writing | | | | 4 ho | urs | | | |
| Stimulate effective | e linguistics for writing: content and style | | | | | | | | |
| Activity: Proofread | 0 | | | | | | | | |
| Statement of Purpo | | | | | | | | | |
| | Module:4 Trans-Cultural Communication | | | | | urs | | | |
| | cultural communication | | | | | | | | |
| • • | cussion and case studies on trans-cultural communication. | | | | | | | | |
| | Itural communication. | | | - | | | | | |
| | ort Writing and Content Writing | | | | 4 ho | urs | | | |
| Enhancing reportage on relevant audio-visuals | | | | | | | | | |
| Activity: Watch a documentary on social issues and draft a report | | | | | | | | | |
| - | any social issue and interpret | | | | | | | | |
| | fting project proposals and article writing | | | 4 | 1 ho | urs | | | |
| | ing project proposals and research articles | | | | | | | | |
| | a project proposal., Writing a research article. | | | | 1 | 1114~ | | | |
| | hnical Presentations | | | 4 | 1 ho | urs | | | |
| - | tation skills and strategies | | | | | | | | |
| Activity: Technica | l presentations using PPT and Web tools | | | | 01 | | | | |
| Tort D 1- / 337 | Total Lectu | ire f | ours | <u> </u> | 0 ho | urs | | | |
| Text Book / Work | (DOOK | | | | | | | | |



| 1. | Raman, Meenakshi & Sangeeta Shar 3rd edition, Oxford University Press | | cal Communication: Principles and | Practice, | | | | |
|------|---|--------------------|--|-----------|--|--|--|--|
| Ref | erence Books | , 2013. | | | | | | |
| 1 | Basu B.N. Technical Writing, 2011 | Kindle editi | on | | | | | |
| 2 | Arathoon, Anita. Shakespeare's The Publishers, 2015. | | | vergreen | | | | |
| 3 | Kumar, Sanjay and Pushp Lata. English Language and Communication Skills for Engineers, Oxford University Press, India, 2018. | | | | | | | |
| 4 | Frantisek, Burda. On Transcultural Communication, 2015, LAP Lambert Academic Publishing, UK. | | | | | | | |
| 5 | Geever, C. Jane. The Foundation Ce Reprint 2012 The Foundation Center | , USA. | | | | | | |
| 6 | Young, Milena. Hacking Your States 2014 Kindle Edition. | | | Your SOP, | | | | |
| 7 | Ray, Ratri, William Shakespeare's Hamlet, The Atlantic Publishers, 2011. | | | | | | | |
| 8 | C Muralikrishna & Sunitha Mishra, Pearson, 2011. | Communica | tion Skills for Engineers, 2nd edition | on, NY: | | | | |
| Mo | de of Evaluation: Quizzes, Presentation | on, Discussi | on, Role Play, Assignments | | | | | |
| List | t of Challenging Experiments (Indica | ntive) | | | | | | |
| 1. | Enacting a court scene - Speaking | | | 6 hours | | | | |
| 2. | Watching a movie and writing a review | | | | | | | |
| 3. | Trans-cultural – case studies | | | 2 hours | | | | |
| 4. | Drafting a report on any social issue | | | 6 hours | | | | |
| 5. | Technical Presentation using web too | ols | | 6 hours | | | | |
| 6. | Writing a research paper | | | | | | | |
| J- (| Component Sample Projects | | | | | | | |
| | 1. Short Films | | | | | | | |
| | 2. Field Visits and Reporting | | | | | | | |
| | 3. Case studies | | | | | | | |
| | 4. Writing blogs | | | | | | | |
| | 5. Vlogging | | | | | | | |
| | - | | Total Hours (J-Component) | 60 hours | | | | |
| Mo | de of evaluation: Quizzes, Presentation | , Discussio | n, Role play, Assignments and FAT | | | | | |
| | 2 | 8.06.2019 | | | | | | |
| An | broved by Academic Council 55 | 5 th AC | Date: 13-06-2019 | | | | | |



| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ENG1903.1 | - | _ | - | _ | _ | _ | - | _ | 2 | 3 | - | 2 | - | - | - |
| ENG1903.2 | - | - | - | _ | _ | - | _ | - | 2 | 3 | - | 2 | _ | _ | - |
| ENG1903.3 | - | - | - | - | _ | - | - | - | 2 | 3 | - | 2 | - | _ | - |
| ENG1903.4 | - | - | - | - | _ | - | - | - | 2 | 3 | - | 2 | - | _ | - |
| ENG1903.5 | - | - | - | - | _ | - | - | - | 2 | 3 | - | 2 | - | - | - |
| | - | - | - | - | - | - | - | - | 2 | 3 | - | 2 | - | - | - |



| | (Deemed to be University under section 3 of UGC Act, 1956) | - | - | _ | |
|-----------------------|--|--------|-------|------------|-------|
| ENG1000 | Foundation English - I | L | T | P J | |
| | | 0 | 0 | 4 0 | |
| Pre-requisite | Less than 50% EPT score | Syl | abu | s Ver | |
| | | | | V | . 1.1 |
| Course Objectiv | | | | | |
| 1 1 | learners with English grammar and its application. | | | | |
| | e learners to comprehend simple text and train them to speak a | nd w | rite | | |
| flawlessly | | | | | |
| 3. To famili | arize learners with MTI and ways to overcome them. | | | | |
| Expected Cours | se Outcome: | | | | |
| 1. Develop | the skills to communicate clearly through effective grammar, | pronu | incia | tion a | nd |
| writing. | | _ | | | |
| 2. Understa | nd everyday conversations in English | | | | |
| | icate and respond to simple questions about oneself. | | | | |
| | vocabulary and expressions. | | | | |
| - | ATI (Mother Tongue Influence) during usual conversation. | | | | |
| | | | | | |
| Module:1 Es | montials of anomy | | | 3 H | |
| | ssentials of grammar | | | 3 П | Jurs |
| | c grammar-Parts of Speech ar worksheets on parts of speech | | | | |
| - | | | | 2 11 | |
| | bcabulary Building Plopment; One word substitution | | | 3 H | JULS |
| • | ntary vocabulary exercises | | | | |
| | | | | 4 H | |
| Types of sentence | pplied grammar and usage | | | 4 П | Jurs |
| • • | har worksheets on types of sentences; tenses | | | | |
| | | | | 4 H | nure |
| | ectifying common errors in everyday conversation | | | 7 11 | Juis |
| | y common mistakes in everyday conversation | | | | |
| • | on errors in prepositions, tenses, punctuation, spelling and oth | er pai | ts of | spee | ch; |
| Colloquialism | | | - T | | |
| Module :5 | Jumbled sentences | | | 2 He | ours |
| Sentence structur | re; Jumbled words to form sentences; Jumbled sentences to for | rm pa | ragr | aph/ | |
| short story | | | | | |
| Activity: Unscra | mble a paragraph / short story | | | | |
| Module:6 | Text-based Analysis | | | 4 H | ours |
| | utobiography of APJ Abdul Kalam (Excerpts) | | | | |
| Activity: Enrich | vocabulary by reading and analyzing the text | | | | |
| Module:7 | Correspondence | | | 3 He | ours |
| Letter, Email, Ap | oplication Writing | | | | |
| Activity: Compo | se letters; Emails, Leave applications | | | | |
| Module:8 | Listening for Understanding | | | 4 He | ours |
| | | | | - | |
| Listening to simp | ple conversations & gap fill exercises | | | | |



| Modu | ıle:9 | Speaking to Convey | 6 Hours |
|--------|---------------|--|-------------|
| | | ; role-plays; Everyday conversations | 0 110 01 15 |
| | | and communicate characteristic attitudes, values, and talents; Worki | ing and |
| | cting within | | C |
| Modu | ıle:10 | Reading for developing pronunciation | 6 Hours |
| Loud | reading wit | h focus on pronunciation by watching relevant video materials | |
| | • | e pronunciation by reading aloud simple texts; Detecting syllables; Vi words shown in relevant videos | sually |
| | ile:11 | Reading to Contemplate | 4 Hours |
| WIUUU | 110.11 | Reading to Contemplate | 4 110015 |
| Readi | ing short sto | ories and passages | |
| Activ | ity: Reading | g and analyzing the author's point of view; Identifying the central ide | a. |
| Modu | ıle:12 | Writing to Communicate | 6 Hours |
| Parag | raph Writin | g; Essay Writing; Short Story Writing | |
| Activ | ity: Writing | paragraphs, essays and short- stories | |
| Modu | ıle:13 | Interpreting Graphical Data | 6 Hours |
| Descr | ribing graph | ical illustrations; interpreting basic charts, tables, and formats | |
| Activ | ity: Interpre | eting and presenting simple graphical representations/charts in the for | m of PPTs |
| Modu | ıle:14 | Overcoming Mother Tongue Influence (MTI) in | 5 Hours |
| | | Pronunciation | |
| Practi | cing comm | on variants in pronunciation | |
| | - | ving and overcoming mother tongue influence. | |
| | | Total Laboratory Hours | 60 Hours |
| Text | Book / Wo | | 00 110415 |
| 1. | | C., & Martin, H. (2018).High School English Grammar & Compositio | n N D V |
| 1. | | ao (Ed.). NewDelhi: S. Chand & Company Ltd. | II IN.D.V. |
| 2. | McCarthy | , M. O'Dell, F.,& Bunting, J.D. (2010). Vocabulary in Use(High Inte | ermediate |
| ۷. | students b | ook with answers). Cambridge University Press | |
| Refer | ence Book | S | |
| 1. | | P.(2018). Teaching and Developing Reading Skills: Cambridge Handl teachers. Cambridge University Press. | books for |
| 2. | | ., &Muralikrishna, C. (2014).Communication Skills for Engineers. Pe | earson |
| | Education | | |
| 3 | Lewis, N. | (2011).Word Power Made Easy. Goyal Publisher | |
| 4 | | ericanliterature.com/short-short-stories | |
| | - | ., &Kalam, A. (1999).Wings of Fire - An Autobiography of Abdul K | alam. |
| 5 | | es Press (India) Private Limited. | |
| Mode | | ion: Quizzes, Presentation, Discussion, Role Play, Assignments | |
| | | | |



| List of | Challenging Experiments (In | dicative) | | | |
|---------|----------------------------------|---------------------|-----------------|------------|----------|
| 1. | Rearranging scrambled senter | nces | | | 8 hours |
| 2. | Identifying errors in oral and | written communi | cation | | 12 hours |
| 3. | Critically analyzing the text | | | | 8 hours |
| 4. | Developing passages from him | nt words | | | 8 hours |
| 5. | Role-plays | | | | 12 hours |
| 6. | Listening to a short story and | analyzing it | | | 12 hours |
| | | T | otal Laborat | ory Hours | 60 hours |
| Mode of | of Evaluation: Quizzes, Presenta | ation, Discussion, | , Role Play, As | signments | |
| Recom | mended by Board of Studies | 08-06-2019 | | | |
| Approv | ved by Academic Council | 55 th AC | Date | 13-06-2019 | |



| | Foundation English - II | L T P J C |
|---|--|---|
| ENG2000 | | |
| Pre-requisite | 51% - 70% EPT Score / Foundation English I | Syllabus version |
| • | C | v.1.1 |
| Course Objectiv | ves: | |
| • | ce grammar and vocabulary effectively | |
| 2. To acquir | re proficiency levels in LSRW skills in diverse social situations. | |
| 3. To analy | ze information and converse effectively in technical communicat | ion. |
| Expected Cours | se Outcome: | |
| 1. Accompl | ish a deliberate reading and writing process with proper gramma | r and vocabulary. |
| 2. Compreh | end sentence structures while Listening and Reading. | |
| 3. Commun | nicate effectively and share ideas in formal and informal situation | S. |
| 4. Understa | nd specialized articles and technical instructions and write clear t | echnical |
| correspon | ndence. | |
| 5. Critically | think and analyze with verbal ability. | |
| Module:1 | Grammatical Aspects | 4 hours |
| Sentence Pattern | , Modal Verbs, Concord (SVA), Conditionals, Connectives | |
| Activity : Works | | |
| Module:2 | Vocabulary Enrichment | 4 hours |
| | | |
| Active & Passive | e Vocabulary, Prefix and Suffix, High Frequency Words | |
| Active & Passive Activity : Works | | |
| | | 4 Hours |
| Activity : Works Module:3 | sheets, Exercises | |
| Activity : Works Module:3 | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- | |
| Activity : Works Module:3 Speech Sounds - | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er | |
| Activity : Works Module:3 Speech Sounds - and Plural Marke | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er | |
| Activity : Works Module:3 Speech Sounds - and Plural Marke Activity : Works Module:4 | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises | Past Tense Marker |
| Activity : Works Module:3 Speech Sounds - and Plural Marke Activity : Works Module:4 | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary | Past Tense Marker |
| Activity : Works Module:3 Speech Sounds - and Plural Marko Activity : Works Module:4 Tenses /SVA/Ar | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary | Past Tense Marker |
| Activity : Works Module:3 Speech Sounds - and Plural Marko Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors | Past Tense Marker 2 Hours 2 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Bro | Past Tense Marker 2 Hours 2 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors | Past Tense Marker 2 Hours 2 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brosheets, Exercises | Past Tense Marker 2 Hours 2 Hours evity 6 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marke Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Bre sheets, Exercises Listening and Note making | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The |
| Activity : Works Module:3 Speech Sounds - and Plural Marke Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Bre sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: 0) | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ven scene in Julius C | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brasheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Conce, Disguise Scene in The Twelfth Night, Death of Desdemontary | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ven scene in Julius C | sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er sheets, Exercises Syntactic and Semantic Errors tticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brosheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Onice, Disguise Scene in The Twelfth Night, Death of Desdemont Caesar and Balcony scene from Romeo and Juliet) | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ Module:7 | Sheets, Exercises Phonics in English Vowels and Consonants – Minimal Pairs- Consonant Clusterser Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Bresheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Onice, Disguise Scene in The Twelfth Night, Death of Desdemon Caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The in Othello, Death 6 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marke Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ Module:7 Impromptu, Imp | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brosheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Chice, Disguise Scene in The Twelfth Night, Death of Desdemond Caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos Art of Public Speaking | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The in Othello, Death 6 Hours |
| Activity : Works Module:3 Speech Sounds - and Plural Marka Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ Module:7 Impromptu, Imp Presentations – I | Sheets, Exercises Phonics in English - Vowels and Consonants – Minimal Pairs- Consonant Clusters- er Sheets, Exercises Syntactic and Semantic Errors tricles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brosheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Onice, Disguise Scene in The Twelfth Night, Death of Desdemont Caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos Art of Public Speaking ortance of Non-verbal Communication, Technical Talks, Dynam | Past Tense Marker 2 Hours 2 Hours evity 6 Hours Court scene in The ta in Othello, Death ta in Othello, Death 6 Hours 1000000000000000000000000000000000000 |



| Skimming, | scanning, comprehensive reading, guessing words from context, underst | anding text |
|-------------|--|--------------|
| organizatio | n, recognizing argument and counter-argument; distinguishing between main | information |
| and suppor | ting detail, fact and opinion, hypothesis versus evidence; summarizing and | note-taking, |
| Critical Re | asoning Questions – Reading and Discussion | |
| Activity: R | eading of Newspapers Articles and Worksheets on Critical Reasoning from w | eb |
| resources | | |
| Module: 9 | Creative Writing | 4 Hours |
| Structure o | f an essay, Developing ideas on analytical/ abstract topics | |
| Activity: N | lovie Review, Essay Writing on suggested Topics, Picture Descriptions | |
| Module: 1 | 0 Verbal Aptitude | 6 hours |
| Word Anal | ogy, Sentence Completion using Appropriate words, Sentence Correction | |
| | racticing the use of appropriate words and sentences through web tools. | |
| Module: 1 | | 4 hours |
| Formal Let | ters- Format and purpose: Business Letters - Sales and complaint letter | |
| | etter writing- request for Internship, Industrial Visit and Recommendation | |
| Module: 1 | | 6 hours |
| Telephone | Etiquette, Resume Preparation, Video Profile | |
| - | Preparation of Video Profile | |
| Module: 1 | - | 4 hours |
| Technical I | nstructions, Process and Functional Description | |
| | Vriting Technical Instructions | |
| Module: 1 | | 4 hours |
| Format of a | Report and Proposal | |
| | Fechnical Report Writing, Technical Proposal | |
| • | | |
| | Total Lecture hours: | 60 hours |
| Text Book | / Workbook | |
| 1. Sanja | y Kumar & Pushp Lata, Communication Skills, 2nd Edition, OUP, 2015 | |
| 2 Wren | & Martin, High School English Grammar & Composition, Regular ed., ND: I | Blackie |
| ELT | 300ks, 2018 | |
| Reference | Books | |
| 1 Peter | Watkins, Teaching and Developing Reading Skills: Cambridge Handbooks fo | r Language |
| Teach | ers, Cambridge, 2018 | |
| 2 Aruna | a Koneru, Professional Speaking Skills, OUP, 2015. | |
| 3 J.C.N | esfield, English Grammar English Grammar Composition and Usage, Macmil | lan. 2019. |
| 4 Richa | rd Johnson-Sheehan, Technical Communication Today, 6th edition, ND: Pear | son, 2017. |
| 5 Balas | ubramaniam, Textbook of English Phonetics For Indian Students, 3rd Edition | , S. Chand |
| | shers, 2013. | |
| | · | |



| Web Re | esources | | | | |
|---------|---|---------------------|----------------|-------------|----------|
| | //www.hitbullseye.com/Sentend | | | | |
| - | <pre>//hitbullseye.com/Critical-Reas of Evaluation: Presentation, D</pre> | Ŭ ¹ | 1 1 | ate EAT | |
| wioue | of Evaluation. Fleschation, L | | iay, Assignmen | | |
| List of | Challenging Experiments (In | dicative) | | | |
| 1. | Reading and Analyzing Crit | ical Reasoning qu | estions | | 8 hours |
| 2. | Listening and Interpretation | of Videos | | | 12 hours |
| 3. | Letter to the Editor | | | | 6 hours |
| 4. | Developing structured Tech | nical Talk | | | 12 hours |
| 5. | Drafting SOP (Statement of | Purpose) | | | 10 hours |
| 6. | Video Profile | | | | 12 hours |
| | | | Total Labora | atory Hours | 60 hours |
| Mode of | f Evaluation: Presentation, Dis | cussion, Role Play | , Assignments | , FAT | |
| Recomm | nended by Board of Studies | 08.06.2019 | | | |
| Approv | ed by Academic Council | 55 th AC | Date | 13-06-2019 | |
| | | | | | |



| EEE1904 Ca Pre-requisite As per the academic reg Pre-requisite As per the academic reg Course Objectives: Image: Course Objective sufficient hands-on learning expansion of suitable product / process so as Expected Course Outcome: Course the student will be ab | perience related to the | ne design, develop | |
|---|-------------------------|------------------------|--|
| Course Objectives: 1. To provide sufficient hands-on learning expansion of suitable product / process so as Expected Course Outcome: | perience related to the | ne design, develop | villabus version v. 1.0 ment and |
| Course Objectives: 1. To provide sufficient hands-on learning expansion of suitable product / process so as Expected Course Outcome: | perience related to the | ne design, develop | v. 1.0 ment and |
| To provide sufficient hands-on learning expansion of suitable product / process so as Expected Course Outcome: | | | ment and |
| To provide sufficient hands-on learning expansion of suitable product / process so as Expected Course Outcome: | | | |
| analysis of suitable product / process so as Expected Course Outcome: | | | |
| Expected Course Outcome: | o enhance the techn | nical skill sets in th | e chosen field |
| A | | | |
| - | | | |
| At the end of the course the student will be ab | | | |
| | le to | | |
| 1. Formulate specific problem statement | for ill-defined real | life problems with | reasonable |
| assumptions and constraints. | | | |
| 2. Perform literature search and / or pate | | | |
| 3. Conduct experiments / Design and An | | ations and docume | nt the results. |
| 4. Perform error analysis / benchmarking | | | |
| 5. Synthesise the results and arrive at sci | | | n |
| 6. Document the results in the form of te | chnical report / pres | entation | |
| ~ | | | |
| Contents | | | |
| 1. Capstone Project may be a theoretical | | - | |
| analysis, prototype design, fabrication | | | nalysis of data, |
| software development, applied researc | • | | |
| 2. Project can be for one or two semester | 1 | pletion of required | number of |
| credits as per the academic regulations | | | |
| 3. Can be individual work or a group pro | | | |
| 4. In case of group projects, the individu | | ach student should | l specify the |
| individual's contribution to the group | | | |
| 5. Carried out inside or outside the unive | | • | |
| 6. Publications in the peer reviewed jour advantage | als / International C | Conferences will be | e an added |
| Mode of Evaluation: Periodic reviews, Preser | tation, Final oral viv | va, Poster submissi | ion |
| Recommended by Board of Studies 10.06 | .2015 | | |
| Approved by Academic Council 37 th | | 16.06.2015 | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1904.1 | 3 | 2 | 1 | 1 | | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 2 | |
| EEE1904.1 | 3 | Z | 1 | 1 | - | 3 | 3 | 3 | 3 | 3 | 3 | | 3 | Z | - |
| EEE1904.2 | 2 | 1 | - | - | 1 | - | - | 2 | 3 | 2 | 2 | 2 | - | - | 1 |
| EEE1904.3 | 3 | 3 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 |
| EEE1904.4 | 3 | 3 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 |
| EEE1904.5 | 3 | 3 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 |
| EEE1904.6 | 2 | 1 | - | - | 2 | - | - | 2 | 3 | 2 | 2 | 2 | - | - | 2 |
| | 3 | 3 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 | 2 | 3 | 3 | 2 |



| EEE1902 | Indu | ustrial Interns | ship | | | L | Т | Р | J | C |
|---|---|--|------------|--------|---------|--------|-------|------|----------|----|
| | | | | | | 0 | 0 | 0 | 0 | 1 |
| Pre-requisite | Completion of mi | nimum of Two | o semeste | ers | | S | yllab | us v | ersi | or |
| - | | | | | | | · | | v. | |
| Course Object | ives: | | | | | | | | | |
| 1. The course is | designed so as to e | xpose the stud | ents to in | ndust | ry en | vironi | nent | and | to | |
| take up on-si | ite assignment as tra | ainees or interr | ıs. | | | | | | | |
| Free a stad Carry | an Outroom of | | | | | | | | | |
| Expected Cour | | 1 / 1 111 | 11 / | | | | | | | |
| At the end of th | is internship the stu | dent should be | e able to: | | | | | | | |
| 1. Have an | exposure to industr | rial practices a | nd to wo | ork in | team | s | | | | |
| | nicate effectively | r | | | | - | | | | |
| Δ . Commu | | | | | | | | | | |
| | 5 | igineering solu | tions in | a glo | bal, e | conor | nic. | | | |
| 3. Underst | and the impact of er mental and societal | | tions in | a glo | bal, e | conor | nic, | | | |
| 3. Underst environ | and the impact of er mental and societal | context | | _ | | | | rnin | g | |
| Underst environ Develop | and the impact of er mental and societal the ability to engage | context ge in research a | | _ | | | | rnin | g | |
| Underst environi Develop Compre | and the impact of er mental and societal | context ge in research a issues | and to in | _ | | | | rnin | an | |
| Underst environi Develop Compre | and the impact of er mental and societal the ability to engage hend contemporary | context ge in research a issues | and to in | _ | | | | rnin | g | |
| Underst environi Develop Compre | and the impact of er mental and societal the ability to engage hend contemporary | context ge in research a issues | and to in | _ | | | | | g Wee | |
| Underst environi Develop Compre Engage Contents | and the impact of er mental and societal the ability to engag hend contemporary in establishing his/h | context ge in research a issues her digital foot | and to in | _ | | fe-lon | | | _ | k |
| Underst environi Develop Compre Engage Contents | and the impact of er mental and societal the ability to engage hend contemporary | context ge in research a issues her digital foot | and to in | _ | | fe-lon | | | _ | k |
| Understienvironi Develop Compre Engage Contents | and the impact of er mental and societal o the ability to engag hend contemporary in establishing his/h | context ge in research a issues her digital foot | and to in | _ | | fe-lon | | | _ | ek |
| Understienvironi Develop Compre Engage Contents | and the impact of er mental and societal the ability to engag hend contemporary in establishing his/h | context ge in research a issues her digital foot | and to in | _ | | fe-lon | | | _ | k |
| Understienvironi Develop Compre Engage Contents Four weeks of value | and the impact of er mental and societal o the ability to engag hend contemporary in establishing his/r work at industry site | context ge in research a issues her digital foot | and to in | volve | e in li | fe-lon | | | _ | k |
| Understienvironi Develop Compre Engage Contents Four weeks of value | and the impact of er mental and societal o the ability to engag hend contemporary in establishing his/h | context ge in research a issues her digital foot | and to in | volve | e in li | fe-lon | | | _ | |
| 3. Understienvironi 4. Develop 5. Comprei 6. Engage Contents Four weeks of vironi Supervised by a Mode of Evaluation | and the impact of er mental and societal o the ability to engag hend contemporary in establishing his/h work at industry site un expert at the indu | context ge in research a issues her digital foot | and to in | volve | e in li | fe-lon | | | _ | |
| Understienvironi Develop Compre Engage Contents Four weeks of value | and the impact of er mental and societal o the ability to engag hend contemporary in establishing his/h work at industry site un expert at the indu | context ge in research a issues her digital foot stry. | and to in | volve | e in li | fe-lon | | | _ | |

| со | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1902.1 | 2 | 1 | - | - | - | - | - | 2 | 3 | 2 | - | 1 | - | - | - |
| EEE1902.2 | 2 | 1 | - | - | - | - | - | - | 3 | 3 | - | 1 | - | - | - |
| EEE1902.3 | | | | | | | | | | | | | | | |
| | 2 | 1 | 2 | - | - | 2 | 2 | - | - | - | - | 1 | - | - | - |
| EEE1902.4 | 3 | 2 | 1 | 1 | - | - | 3 | 3 | 3 | 3 | - | 1 | 2 | - | - |
| EEE1902.5 | 2 | 1 | - | - | - | - | 2 | - | - | - | - | 1 | - | - | - |
| EEE1902.6 | 2 | 1 | - | - | 2 | - | 2 | 2 | 3 | 2 | - | 1 | - | - | 2 |
| | 3 | 2 | 2 | 1 | 2 | 2 | 3 | 3 | 3 | 3 | - | 1 | 2 | - | 2 |



| MAT1011 | Calculus for Engineers | | LI | | J | C |
|--------------------|---|---------------------|---------|--------|-------|------|
| | | | 3 0 | 2 | 0 | 4 |
| Pre-requisite | MAT1001 | | yllabı | is V | ersi | on |
| Course Objectiv | | | v.1.0 | | | |
| <u> </u> | le the requisite and relevant background ne | aggery to under | tand t | ha at | hor | |
| - | t engineering mathematics courses offered | - | | | | |
| - | 0 0 | 0 | | nusu | 5. | |
| | uce important topics of applied mathematic | cs, namely Single | and | | | |
| | able Calculus and Vector Calculus etc. | | , . | • | c | |
| - | t the knowledge of Laplace transform, an in | mportant transfor | m tec | nniqu | ue ic | r |
| | s which requires knowledge of integration | | | | | |
| Expected Cours | s course the students should be able to | | | | | |
| | ferentiation to solve max/min problems an | d compute volun | nes of | revo | lutic | n |
| | ce areas of revolution using Integration. | a compute volum | 105 01 | 10.00 | iun | /11 |
| | e concepts of Laplace Transforms and solve | e problems with | neriod | ic fu | nctio | าทร |
| | tions, impulse functions and convolution. | e problems with | period | ie iu | neur | 5115 |
| - | partial derivatives, limits, total differential | s Iacobians Tay | lor se | ies a | nd | |
| | ion problems involving several variables. | s, sacoblans, ray | 101 301 | 105 0 | inu | |
| 1 | multiple integrals in Cartesian, Polar, Cylin | ndrical and Spher | rical c | oord | inate | 26 |
| | he concepts of gradient, directional derivat | - | | | | |
| - | and the circulation, work done, conservative | - | | | | |
| | the theorem. | | 15, 510 | ксs, | Uau | 55 |
| - | programming tools for engineering probler | ne and visualize | solutio | me | | |
| | gle variable differentiation and integration | | | | in | |
| | ng and find the maxima and minima of fun | | proor | | 111 | |
| 8 | | | | | | |
| Module:1 Ap | plication of Single Variable Calculus | 9 h | ours | | | |
| Differentiation-I | Extrema on an Interval-Rolle's Theorem ar | nd the Mean Valu | ie The | oren | 1- | |
| U | ecreasing functions and First derivative tes | | | | | |
| | cavity. Integration-Average function value | | curve | s - V | olun | nes |
| of solids of revol | ution - Beta and Gamma functions-interrel | ation | | | | |
| Madula 2 La | | 71 | | | | |
| | place transforms | | hours | i a ma | Lon | 100 |
| | place transform-Properties-Laplace transf step function, Impulse function-Inverse La | - | | | - | Tac |
| | step function, impulse function-inverse La | | COIIV | Jun | л. | |
| Module:3 Mu | ltivariable Calculus | 41 | nours | | | |
| | variables-limits and continuity-partial der | ivatives –total dif | fferent | ial-J | acot | oiar |
| and its properties | | | | | | |
| Module:4 Ap | plication of Multivariable Calculus | 51 | nours | | | |
| 1 | on for two variables-maxima and minima- | | | nd m | inim | ia- |
| | plier method. | | | | | |



| | (Deemed to be University under section 3 of) | |
|-----------|---|---|
| Mod | ile:5 Multiple integrals | 8 hours |
| | Evaluation of double integrals-change of order | 0 |
| | en Cartesian and polar co-ordinates - Evaluation of | |
| | een Cartesian and cylindrical and spherical co-ordina | tes- evaluation of multiple integrals |
| using | gamma and beta functions. | |
| Mod | ile:6 Vector Differentiation | 5 hours |
| | r and vector valued functions – gradient, tangent plan | |
| | url-scalar and vector potentials-Statement of vector i | |
| Mod | Ile:7 Vector Integration | 5 hours |
| | surface and volume integrals - Statement of Green | |
| | ems -verification and evaluation of vector integrals us | • |
| | | |
| Mod | | 2 hours |
| Ind | ustry Expert Lecture | |
| | Total Lecture hours: | 45 hours |
| | | |
| Text | Book(s) | |
| 1. | Thomas' Calculus, George B.Thomas, D.Weir and | J. Hass, 13 th edition, Pearson, 2014. |
| 2. | Advanced Engineering Mathematics, Erwin Kreysz | tig, 10 th Edition, Wiley India, 2015. |
| Refe | rence Books | |
| 1. | Higher Engineering Mathematics, B.S. Grewal, 43 ^r | ^d Edition ,Khanna Publishers, 2015 |
| 2. | Higher Engineering Mathematics, John Bird, 6 th Ed | |
| 3. | Calculus: Early Transcendentals, James Stewart, 8 th | ¹ edition, Cengage Learning, 2017. |
| 4. | Engineering Mathematics, K.A.Stroud and Dexter. Macmillan (2013) | |
| Mode | e of Evaluation: Digital Assignments, Quiz, Continue | us Assessments, Final Assessment |
| Test | · · · · · · · · · · · · · · · · · · · | |
| List | of Challenging Experiments (Indicative) | |
| 1. | Introduction to MATLAB through matrices, and gen | eral Syntax 2 hours |
| 2 | Plotting and visualizing curves and surfaces in MAT Symbolic computations using MATLAB | LAB – 2 hours |
| 3. | Evaluating Extremum of a single variable function | 2 hours |
| 4. | Understanding integration as Area under the curve | 2 hours |
| 5. | Evaluation of Volume by Integrals (Solids of Revolu | |
| 6. | Evaluating maxima and minima of functions of seven | |
| 7. | Applying Lagrange multiplier optimization method | 2 hours |
| 8. | Evaluating Volume under surfaces | 2 hours |
| 9. 10. | Evaluating triple integrals Evaluating gradient, curl and divergence | 2 hours 2 hours |
| 10. | Evaluating line integrals in vectors | 2 hours |
| | | - 10015 |



| 12 | Applying Green's theorem to real worl | 2 hours | | | | |
|-----|---------------------------------------|---------------------|----------|------------|--|--|
| | | 24 hours | | | | |
| Mod | de of Assessment: Weekly assessmen | nt, Final Assessme | ent Test | | | |
| Rec | ommended by Board of Studies | 12-06-2015 | | | | |
| App | proved by Academic Council | 37 th AC | Date | 16-06-2015 | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| MAT1011.1 | 3 | 2 | - | - | - | - | - | - | - | 1 | - | 2 | - | - | - |
| MAT1011.2 | 2 | 1 | - | - | _ | _ | - | - | - | 1 | - | 2 | - | _ | _ |
| MAT1011.3 | 3 | 2 | | | | | | | 1 | | | 2 | | | |
| | | | - | - | - | - | - | - | 1 | 1 | - | | - | - | - |
| MAT1011.4 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 2 | - | - | - |
| MAT1011.5 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 2 | - | - | - |
| MAT1011.6 | 3 | 2 | - | - | 2 | - | - | - | 1 | 2 | - | 3 | - | - | - |
| MAT1011.7 | - 3 | - 2 | - | - | - 2 | - | - | - | - 1 | - 2 | - | - 3 | - | - | - |



| N. 4 (50001 | Vellore Institute of Tec (Deemed to be University under section 3 of | UGC Act, 1956) | T | _ D | | 0 |
|-------------------------------------|---|----------------|--------------|------------|--------|----------|
| MAT2001 | Statistics for Engineers | L | Т | P | J | C |
| | | 3 | 0 | 2 | 0 | 4 |
| Prerequisites | MAT1011 | Syll | abus V | Versio | on: | v.1.0 |
| Course Objectives : | | I | | | | |
| 1. To provide s | students with a framework that will | help them of | choose | the | appro | opriate |
| _ | nethods in various data analysis situati | | | | | |
| - | stributions and relationship of real-tin | | | | | |
| | mation and testing methods to make in | nference and | l mode | lling | techr | nques |
| for decision 1 Expected Course O | <u> </u> | | | | | |
| - | urse the student should be able to: | | | | | |
| | stical data using measures of central to | endency and | disne | rsion | | |
| • | apply the concepts of random variable | • | - | | | to |
| | nts and characteristic functions. | | Jution | Tunet | 10115 | .0 |
| | experimental data using correlation an | d regression | analv | sis an | d inte | erpret |
| the results. | | 8 | , | | | r |
| 4. Apply the co | ncepts of inferential statistics and inte | rpret the rest | ults. | | | |
| | tistical methodology in solving reliab | - | | roblei | ns. | |
| 6. Develop prog | gramming tools for engineering proble | ms and visu | alize s | olutio | ons. | |
| 7. Compute and | l interpret descriptive statistics using n | umerical an | d grap | hical | techr | niques |
| 8. Understand t | he basic concepts of random variables | and find an | appro | priate | dist | ributio |
| for analysing | data specific to an experiment | | | | | |
| | ical methods like correlation, regression | on analysis i | n analy | ysing, | | |
| | experimental data. | | | | | |
| | riate decisions using statistical inferer | nce that is th | e centi | al to | | |
| experimental | | | | | | |
| | l methodology and tools in reliability | engineering | proble | ems | | |
| 12. demonstrate | R programming for statistical data | | | | | |
| Module: 1 | Introduction to Statistics | | 6 ho | ours | | |
| Introduction to stat | istics and data analysis-Measures o | f central te | ndenc | у – М | leasu | res of |
| | s-Skewness-Kurtosis (Concepts only) | | | - | | |
| Module: 2 | Random variables | | 8 h o | ours | | |
| Introduction -random | n variables-Probability mass Function | , distributio | n and | densi | ty fur | nctions |
| - joint Probability di | stribution and joint density functions | - Marginal, | condit | ional | distr | ibution |
| and density function | ns- Mathematical expectation, and it | s properties | Cova | rianc | e,n | noment |
| generating function - | - characteristic function. | | | | | |
| Module: 3 | Correlation and regression | | 4 h o | ours | | |
| Correlation and Reg regression. | ression – Rank Correlation- Partial | and Multipl | e corre | elatio | n- M | ultiple |
| Module: 4 | Drobability Distributions | | 7 ho | | | |
| wiouuie: 4 | Probability Distributions | | / 110 | Jul S | | |



| Binomial and P | Oberned to be University under section | | on – | | |
|---|---|-----------------------|-----------------|--|--|
| | stribution – Weibull distribution. | | | | |
| Module: 5 | Hypothesis Testing I | 4 ho | ours | | |
| U I | othesis – Introduction-Types of errors, ge sample tests- Z test for Single Propor of means. | 0 1 | Ũ | | |
| Module: 6 | Hypothesis Testing II | 9 ho | ours | | |
| - | ests- Student's t-test, F-test- chi-square to gn of Experiments - Analysis of varianc D. | 0 | - | | |
| Module: 7 | Reliability | 5 ho | ours | | |
| 1 | s- Hazard function-Reliabilities of ser | 1 2 | • | | |
| Module: 8 | Contemporary Issues | 2 ho | ours | | |
| Industry Expert | tLecture | | | | |
| | Total Lecture hours | 45 h | ours | | |
| Text book(s) | | | | | |
| S.L.May | lity and Statistics for engineers and scient yers and K.Ye, 9 th Edition, Pearson Educa | ation (2012). | - | | |
| | Statistics and Probability for Engineers, 6 th Edition, John Wiley & Sons (2016). | Douglas C. Montgon | nery, George C. | | |
| Reference bool | | | | | |
| 1. Reliabil | ity Engineering, E.Balagurusamy, Tata N | AcGraw Hill, Tenth r | eprint 2017. | | |
| | lity and Statistics, J.L.Devore, 8th Edition | | - | | |
| | lity and Statistics for Engineers, R.A.Joh | nson, Miller Freund's | s, 8th edition, | | |
| | e Hall India (2011). Lity, Statiatics and Baliability for Enginee | m and Scientista Dil | al M. Armub | | |
| and Ric | lity, Statistics and Reliability for Enginee hard H. McCuen, 3 rd edition, CRC press | (2011). | | | |
| Mode of Evalua Assessment Tes | ation: Digital Assignments, Continuous A | Assessment Tests, Qu | iiz, Final | | |
| | nents (Indicative) | | | | |
| 1. Introdu | uction: Understanding Data types; impor | ting/exporting data. | 2 hours | | |
| 2. Computing Summary Statistics /plotting and visualizing data using Tabulation and Graphical Representations. 2 hours | | | | | |



| 3. | Applying correlation and simple dataset; computing and interpreti determination. | 0 | | l 2 hours | | | | | |
|--------|---|--|----------------|---------------|--|--|--|--|--|
| 4. | Applying multiple linear regressi computing and interpreting the m determination. | | | 2 hours | | | | | |
| 5. | Fitting the following probability | Fitting the following probability distributions: Binomial distribution | | | | | | | |
| 6. | Normal distribution, Poisson dist | 2 hours | | | | | | | |
| 7. | Testing of hypothesis for One sar real-time problems. | m 2 hours | | | | | | | |
| 8. | Testing of hypothesis for Two sat real-time problems | om 2 hours | | | | | | | |
| 9. | Applying the t test for independe | nt and depende | ent samples | 2 hours | | | | | |
| 10. | Applying Chi-square test for goo test to real dataset | dness of fit test | and Continger | acy 2 hours | | | | | |
| 11. | Performing ANOVA for real data design, Randomized Block desig | - | • | ed 2 hours | | | | | |
| | L | Tota | l laboratory h | ours 22 hours | | | | | |
| Mode o | f Evaluation: Weekly Assessment, | , Final Assessn | nent Test | I | | | | | |
| Recom | nended by Board of Studies | 25-02-2017 | | | | | | | |
| Approv | 0-2017 | | | | | | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| MAT2001.1 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 2 | - | - | - |
| | | | | | | | | | | | | | | | |
| MAT2001.2 | 2 | 1 | - | - | - | - | - | - | - | - | - | 2 | - | - | - |
| MAT2001.3 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 2 | - | - | - |
| MAT2001.4 | 3 | 2 | - | - | - | - | - | - | - | 1 | - | 2 | - | - | - |
| MAT2001.5 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 2 | - | - | - |
| MAT2001.6 | 3 | 2 | - | - | 2 | - | - | - | 1 | 2 | - | 2 | - | - | - |
| MAT2001.7 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| | | | | | | | | | | | | | | | |
| MAT2001.8 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| MAT2001.9 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| MAT2001.10 | - | - | - | - | - | - | - | - | - | - | I | - | - | - | _ |
| MAT2001.11 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| MAT2001.12 | - | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| | 3 | 2 | - | - | 2 | - | - | - | 1 | 2 | - | 2 | - | - | - |



| MGT1022 | Lean Start up Manageme | ent | L T P J C | | | | | |
|---|--|-------------------|---------------------|--|--|--|--|--|
| | | | | | | | | |
| Pre-requisite | NIL | | Syllabus version | | | | | |
| | | | v.1.0 | | | | | |
| • | : To develop the ability to | | | | | | | |
| | ods of company formation and management. | | and collection of | | | | | |
| business ide | cal skills in and experience of stating of be | Isiness using pi | re-set conection of | | | | | |
| | s of entrepreneurial skills. | | | | | | | |
| | * | | | | | | | |
| Expected Course Outcome: On the completion of this course the student will be able to: | | | | | | | | |
| | developing business models and growth driv | | | | | | | |
| | iness model canvas to map out key compone | | e | | | | | |
| | rket size, cost structure, revenue streams, an build-measure-learn principles | u value cham | | | | | | |
| | and quantifying business and financial risks | | | | | | | |
| | | | | | | | | |
| Module:1 | | | 2 Hours | | | | | |
| | gn Thinking (identify the vertical for busine | ess opportunity, | understand your | | | | | |
| customers, accurate | ely assess market opportunity) | | | | | | | |
| Module:2 | | | 3 Hours | | | | | |
| | roduct (Value Proposition, Customer Segme | nts, Build- meas | | | | | | |
| | | | · · · | | | | | |
| Module:3 | | | 3 Hours | | | | | |
| | Development(Channels and Partners, Reve | | | | | | | |
| | es and Costs, Customer Relationships and avas –the lean model- templates) | Customer Deve | lopment Processes, | | | | | |
| | | | | | | | | |
| Module:4 | | | 3 Hours | | | | | |
| | Access to Funding(visioning your ventu | | | | | | | |
| · 1 | an including Digital & Viral Marketing, st Angel/VC,/Bank Loans and Key elements of | 1 | - Costs/Profits & | | | | | |
| | Angel, VC, Dank Loans and Key clements of | raising money) | | | | | | |
| Module:5 | | | 3 Hours | | | | | |
| Legal, Regulatory, | CSR, Standards, Taxes | | | | | | | |
| Module:6 | | | 2 Hours | | | | | |
| | | | 2 Hours | | | | | |
| Lectures by Entrep | reneurs | | | | | | | |
| | Total Lecture | | 15 hours | | | | | |
| Text Book(s) | | | | | | | | |
| - | vner's Manual: The Step-By-Step Guide for Bu Ranch; 1 st edition (March 1, 2012) | uilding a Great C | Company, Steve | | | | | |
| , | s to the Epiphany, Steve Blank, K&S Ranch; | 2nd edition (Jul | y 17, 2013) | | | | | |
| - me rour steps | s to the Epiphany, steve Diank, Kas Kallell, | | y 17, 2013) | | | | | |



| 3 | The Lean Startup: How Today's Ent Successful Businesses, Eric Ries, G | | | | eate Radically |
|-----|--|---------------------------------|-------------|----------------------|----------------|
| Ref | ference Books | / | 1 | , | |
| 1. | Holding a Cat by the Tail, Steve Bla | ank, K&S Ranch l | Publishing | LLC (August 1 | 4, 2014) |
| 2 | Product Design and Development, | | - | | |
| 3 | Zero to One: Notes on Startups, or I | How to Build the F | uture, Pete | er Thiel, Crown | Business(2014) |
| 4 | Lean Analytics: Use Data to Build a | Better Startup Fas | ter (Lean S | eries), Alistair C | Croll& |
| | Benjamin Yoskovitz, O'Reilly Med | lia; 1 st Edition (N | Iarch 21, 2 | 013) | |
| 5 | Inspired: How To Create Products C | | | | 1st edition |
| | (June 18, 2008) | | | | |
| 6 | Website References: | | | | |
| | 1. http://theleanstartup.com/ | | | | |
| | 2. https://www.kickstarter.com/pro | ojects/881308232/0 | only-on-kie | ckstarter-the-lea | ders-guide- |
| | by-eric-ries | | | | |
| | 3. http://businessmodelgeneration | | | | |
| | 4. https://www.leanstartupmachine | | | | |
| | 5. https://www.youtube.com/watch | | | | |
| | http://thenextweb.com/entreprent methodology/#gref | neur/2015/07/05/w | hats-wrong | g-with-the-lean- | startup- |
| | 7. http://www.businessinsider.in/W | /hats-Lean-about- | Lean-Start | up/articleshow/ | 53615661.cms |
| | 8. https://steveblank.com/tools-and | l-blogs-for-entrepi | eneurs/ | - | |
| | 9. https://hbr.org/2013/05/why-the- | -lean-start-up-chai | nges-every | thing | |
| | 10. chventures.blogspot.in/ platform | sandnetworks.blc | gspot.in/p | /saas-model.htn | nl |
| | | | | | |
| | de of Evaluation: Assignments; H | Field Trips, Case | e Studies; | e-learning; Le | arning through |
| | earch, TED Talks | | | | |
| | oject | | | | |
| 1. | Project | | | | 60 hours |
| | | | | Total Project | 60 hours |
| | commended by Board of Studies | 08-06-2015 | _ | | |
| Ap | proved by Academic Council | 37 th AC | Date | 16-06-2015 | |
| | | | | | |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| MGT1022.1 | 2 | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| MGT1022.2 | | | | 3 | | | 3 | | 3 | | | | | | |
| MG11022.2 | - | - | - | 3 | - | - | 3 | - | 3 | - | - | - | - | - | - |
| MGT1022.3 | - | 3 | - | - | - | - | - | - | - | - | 3 | - | - | - | - |
| MGT1022.4 | - | - | - | - | - | - | - | - | - | 2 | - | 2 | - | - | - |
| MGT1022.5 | - | - | - | - | - | - | - | - | - | - | 2 | - | - | - | - |
| | 2 | 3 | - | 3 | - | - | 3 | - | 3 | 2 | 3 | 2 | - | - | - |



| | Engineering Physics | |
|--|---|--|
| | | 3 0 2 0 4 |
| Pre-requisite | NIL | Syllabus version |
| | | v.1. |
| Course Object | | |
| Having Having | g an ability to apply mathematics and science in enging g a clear understanding of the subject related concept g Sense-Making Skills of creating unique insights in v er level thinking skills which cannot be codified) | s and of contemporary issues |
| Expected Cou | urse Outcome: | |
| constant of the second s | acquire the necessary knowledge about modern physicering and technology disciplines. This course meets the Comprehend the dual nature of radiation and matter. Compute Schrodinger equations to solve finite and in Analyze quantum ideas at the nanoscale Apply quantum ideas for understanding the operation electronic devices To analyze the Maxwell equations in differential and To classify the optical fiber for different Engineering Apply the various types of optoelectronic devices for nunication system. To demonstrate the quantum mechanical ideas Introduction to Modern Physics | the following student outcomes infinite potential problems. In and working principle of I integral form. I applications. I designing a typical optical fibe |
| lanck's conc | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V | |
| Planck's conce Davisson Gerr | ept (hypothesis), Compton Effect, Particle properties | of wave: Matter Waves, |
| Planck's conce Davisson Gerre equation (time | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). | o of wave: Matter Waves, Vave function, and Schrodinger |
| Planck's conce Davisson Gerr quation (time Module:2 | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). Applications of Quantum Physics | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours |
| Planck's conce Davisson Gerr equation (time Module:2 Particle in a 1- | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling |
| Planck's conce Davisson Gerr equation (time Module:2 Particle in a 1- Effect (Qualita | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). Applications of Quantum Physics -D box (Eigen Value and Eigen Function), 3-D Analy ative) (AB 205), Scanning Tunneling Microscope (S | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). |
| Planck's conce Davisson Gerri equation (time Module:2 Particle in a 1- Effect (Qualita Module:3 Introduction to confinement, (| ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). Applications of Quantum Physics -D box (Eigen Value and Eigen Function), 3-D Analy | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). 5 hour naterials, Quantum |
| Planck's conce Davisson Gerre equation (time Module:2 Particle in a 1- Effect (Qualita Module:3 Introduction to confinement, Quanta to confinement to confin | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). Applications of Quantum Physics -D box (Eigen Value and Eigen Function), 3-D Analy ative) (AB 205), Scanning Tunneling Microscope (S' Nanophysics o Nano-materials, Moore's law, Properties of Nano-n Quantum well, wire & dot, Carbon Nano-tubes (CNT | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). 5 hour naterials, Quantum |
| Planck's concerned Davisson Gerra equation (time Module:2 Particle in a 1- Effect (Qualita Module:3 Introduction to confinement, Quantion nanotechnolog Module:4 Laser Characte Population inv | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, V e dependent & independent). Applications of Quantum Physics -D box (Eigen Value and Eigen Function), 3-D Analy ative) (AB 205), Scanning Tunneling Microscope (S' Nanophysics D Nano-materials, Moore's law, Properties of Nano-n Quantum well, wire & dot, Carbon Nano-tubes (CNT gy in industry. | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). 5 hour naterials, Quantum T), Applications of 6 hours oefficient & its significance, chemes, Threshold gain |
| Planck's concerned Davisson Gerra equation (time Module:2 Particle in a 1- Effect (Qualita Module:3 Introduction to confinement, Qualita Module:4 Laser Characte Population investigations. | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, We dependent & independent). Applications of Quantum Physics -D box (Eigen Value and Eigen Function), 3-D Analy ative) (AB 205), Scanning Tunneling Microscope (S' Nanophysics D Nano-materials, Moore's law, Properties of Nano-n Quantum well, wire & dot, Carbon Nano-tubes (CNT gy in industry. Laser Principles and Engineering Application eristics, Spatial and Temporal Coherence, Einstein Coversion, Two, three & four level systems, Pumping sc pumponents of laser, Nd-YAG, He-Ne, CO2 and Dye | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). 5 hour naterials, Quantum T), Applications of 6 hours oefficient & its significance, chemes, Threshold gain |
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| Planck's conce Davisson Gerri equation (time Module:2 Particle in a 1- Effect (Qualita Module:3 Ntroduction to confinement, Qualita Module:4 Laser Characto Population invector coefficient, Complications. | ept (hypothesis), Compton Effect, Particle properties mer Experiment, Heisenberg Uncertainty Principle, We dependent & independent). Applications of Quantum Physics Dox (Eigen Value and Eigen Function), 3-D Analy ative) (AB 205), Scanning Tunneling Microscope (S' Nanophysics Do Nano-materials, Moore's law, Properties of Nano-n Quantum well, wire & dot, Carbon Nano-tubes (CNT gy in industry. Laser Principles and Engineering Application eristics, Spatial and Temporal Coherence, Einstein Coversion, Two, three & four level systems, Pumping sc pumponents of laser, Nd-YAG, He-Ne, CO2 and Dye Electromagnetic Theory and its application Divergence, Gradient and Curl, Qualitative understand | s of wave: Matter Waves, Vave function, and Schrodinger 5 hours ysis (Qualitative), Tunneling TM). 5 hour naterials, Quantum '), Applications of 6 hours oefficient & its significance, chemes, Threshold gain laser and their engineering 6 hours ding of surface and volume vation), EM Waves, Phase |
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Sources-LED & Laser Diode, Detectors-Photodetectors- PN & PIN - Applications of fiber optics in communication- Endoscopy.

Special Theory of Relativity:

Frame of reference, Galilean relativity, Postulate of special theory of relativity, Simultaneity, length contraction and time dilation.

| | dule:8 Contemporary issues: | 2 hours |
|------|---|-------------------|
| Lec | ture by Industry Experts | |
| | | |
| | Total Lecture hours: 45 hours | |
| | t Book(s) | |
| 1. | Arthur Beiser et al., Concepts of Modern Physics, 2013, Sixth Edition, Tata M | AcGraw Hill. |
| 2. | William Silfvast, Laser Fundamentals, 2008, Cambridge University Press. | |
| 3. | D. J. Griffith, Introduction to Electrodynamics, 2014, 4th Edition, Pearson. | |
| 4. | Djafar K. Mynbaev and Lowell L.Scheiner, Fiber Optic Communication Tech Pearson. | nnology, 2011, |
| Ref | erence Books | |
| 1. | Raymond A. Serway, Clement J. Mosses, Curt A. Moyer Modern Physics, 2 Edition Cengage learning. | 2010, 3rd Indian |
| 2. | John R. Taylor, Chris D. Zafiratos and Michael A. Dubson, Modern Physics | sfor |
| 2. | Scientists and Engineers, 2011, PHI Learning Private Ltd. | |
| 3. | Kenneth Krane Modern Physics, 2010, Wiley Indian Edition. | |
| 4. | Nityanand Choudhary and Richa Verma, Laser Systems and Applications, 2 Learning Private Ltd. | 2011, PHI |
| 6. | S. Nagabhushana and B. Sathyanarayana, Lasers and Optical Instrumentation 2010, I.K. International Publishing House Pvt. Ltd., | on, |
| 7. | R. Shevgaonkar, Electromagnetic Waves, 2005, 1st Edition, Tata McGraw | Hill |
| 8. | Principles of Electromagnetics, Matthew N.O. Sadiku, 2010, Fourth Edition | n, Oxford. |
| 9. | Ajoy Ghatak and K. Thyagarajan, Introduction to Fiber Optics, 2010, Camb Press. | oridge University |
| Mo | de of Evaluation: Quizzes, Digital Assignments, CAT-I and II and FAT | |
| List | t of Challenging Experiments (Indicative) | |
| 1. | Determination of Planck's constant using electroluminescence process (Module 1) | 2 hours |
| 2. | Electron diffraction (Module 1) | 2 hours |
| 3. | Determination of wavelength of laser source (He -Ne laser and diode lasers of different wavelengths) using diffraction technique (Module 4) | 2 hours |
| 4. | Dispersive power of prism (Module 6) | 2 hours |
| 5. | Optical Fiber communication (source + optical fiber + detector) (Modules 7+8) | 2 hours |
| б. | Determination of size of fine particle using laser diffraction (Module 3) | 2 hours |
| 7. | Determination of the track width (periodicity) in a written CD (Module 4) | 2 hours |



| 8. | PIN diode characteristics (Module | e 8) | | | 2 hours |
|------|---|---------------------|-----------------|----------------|----------|
| 9. | Black body Radiation (Module 1- | | 2 hours | | |
| 10. | Optical Fiber communication (sou + 8) | urce + optical fi | ber + detecto | or) (Modules 7 | 2 hours |
| 11. | Analysis of crystallite size and str diffraction (Module 3) | rain in a nano -c | rystalline fili | m using X-ray | 2 hours |
| 12. | Numerical solutions of Schröding (Module 2) (can be given as an as | a box problem) | 2 hours | | |
| 13. | Laser coherence length measurem | nent (Module 4) | | | 2 hours |
| 14. | Proof for transverse nature of E.M | I. waves (Modu | ıle 6) | | 2 hours |
| 15. | Quantum confinement and Heiser 3) | berg's uncertai | nty principle | (Module 1 + | 2 hours |
| | | | Total Lab | oratory Hours | 30 hours |
| Reco | ommended by Board of Studies | 11.08.2017 | | | |
| Appr | roved by Academic Council | 46 th AC | Date | 24.08.2017 | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| PHY1701.1 | 2 | 1 | - | - | - | - | - | - | 2 | 2 | - | 1 | - | - | - |
| | | | | | | | | | | | | | | | |
| PHY1701.2 | 2 | 1 | - | - | - | - | - | - | 1 | 1 | - | - | - | - | - |
| PHY1701.3 | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 1 | - | - | - |
| PHY1701.4 | 3 | 2 | I | - | - | - | - | I | 2 | 2 | - | 1 | - | - | - |
| PHY1701.5 | 2 | 1 | - | - | - | - | - | - | - | - | - | - | - | - | - |
| PHY1701.6 | 3 | 2 | - | - | - | - | - | - | - | - | - | - | - | - | - |
| PHY1701.7 | 3 | 2 | - | - | - | - | - | - | - | - | - | - | - | - | - |
| PHY1701.8 | 2 | 1 | - | - | 2 | - | - | - | 1 | 1 | - | 1 | - | - | - |
| | 3 | 2 | - | - | 2 | - | - | - | 2 | 2 | - | 1 | - | - | - |



| | (Deemed to be University under section 3 of UGC) | Act, 1956) | |
|------------------------------|--|-------------------------|----------------------|
| PHY1901 | Introduction to Innovative P | Projects | L T P J C |
| | | | 1 0 0 4 2 |
| Pre-requisite | NIL | 8 | yllabus version |
| | | | v.1.0 |
| Course Objective | | • • • • • • • • • | |
| | ered to the students in the 1 Year of B.Tech | . in order to orient th | iem towards |
| | emic thinking and be innovative. | | |
| | ents confident enough to handle the day to day e "Thinking Skill" of the students, especially | | 12:110 |
| 1 | udents to be innovative in all their activities | Creative Thinking S | okiiis |
| | project report on a socially relevant theme as a | a solution to the exis | ting issues |
| | e Outcome: Students will be able to | a solution to the exis | |
| | ovative thinking skills | | |
| 1 | and techniques for generating innovative idea | s | |
| | vative solutions for societal/technical problem | | |
| | | | |
| Module:1 A Se | lf Confidence | 1 ho | ur |
| Understanding se | elf – Johari Window –SWOT Analysis – Self | Esteem – Being a co | ontributor – |
| Case Study | | _ | |
| Project : Explor | ing self, understanding surrounding, thinking | g about how s(he) ca | n be a |
| | e society, Creating a big picture of being an in | | |
| | ography of self – Topic "Mr X – the great inn | novator of 2015" and | l upload. (4 |
| non- contact hou | rs) | | |
| Module:1 B Th | inking Skill | 1 ho | r |
| | haviour – Types of thinking– Concrete – Abs | | |
| | ical, Sequential and Holistic thinking – Chun | | |
| Examples – Case | | King mungle Con | ient ond |
| | g at least 50 people belonging to various stra | ta of life and talk to | them / make |
| | ntify a min of 100 society related issues, prob | | |
| | em and upload along with details of people n | | |
| contact hours) | | | |
| | | | |
| | iteral Thinking Skill | | |
| | ny – HOTS – Outof the box thinking – deBor | no lateral thinking m | odel – |
| Examples Project : Lest w | aska incomplete portion to be done and uple | adad | |
| Froject : Last w | eeks - incomplete portion to be done and uplo | Jaueu | |
| Module:2 A Cr | reativity | 1 ho | ur |
| | ls – Walla – Barrons – Koberg & Begnall – | | |
| | ing 5 out of 100 issues identified for futur | | ased approach |
| | n, use of statistical tools & upload . (4 non- | | 11 |
| | <u>-</u> | | |
| | ainstorming | 1 ho | ur |
| | g techniques and examples | | <i>-</i> - • |
| Project : Brainst | torm and come out with as many solutions as | possible for the top | 5 issues |
| | oad . (4 non- contact hours) ind Mapping | 1 ho | ur |
| | techniques and guidelines. Drawing a mind | | 'u1 |
| wind widpping | configues and guidefines. Drawing a lilling | map | |



| Project : Using Mind Maps get another set of solutions | s forthe next 5 issues (issue $6 - 10$). (4 |
|---|---|
| non- contact hours) | |
| Module:4 A Systems thinking | 1 hour |
| Systems Thinking essentials – examples – Counter Intuitiv | |
| Project : Select 1 issue / problem for which the pos | |
| Apply Systems Thinking process and pick up one solution | |
| other possible solutions have been left out]. Go back to the | |
| and upload (4 non- contact hours) | |
| · · · · · · · · · · · · · · · · · · · | |
| Module:4 B Design Thinking | 1 hour |
| Design thinking process – Human element of design think | |
| Project : Apply design thinking to the selected solution, ap | |
| to it. Participate in "design week" celebrations upload the | weeks learning out come. |
| Module:5 A Innovation | 1 hour |
| | 1 hour |
| Difference between Creativity and Innovation – Examples | of innovation –Being innovative. |
| Project: A literature searches on prototyping of your solution model or process and unload (4 page context hours) | ation infanzed. Prepare a prototype |
| model or process and upload (4 non- contact hours) | |
| Module:5 B Blocks for Innovation | 1 hour |
| Identify Blocks for creativity and innovation – overcomi | |
| Project : Project presentation on problem identificati | on, solution, innovations-expected |
| results – Interim review with PPT presentation (4 non- | |
| | • contact hours) |
| results meetin review while it i presentation (4 non | • contact hours) |
| Module:5 C Innovation Process | contact hours) 1 hour |
| Module:5 C Innovation Process | |
| | 1 hour |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation | 1 hour |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours) | 1 hour and uploading the text (4 non- |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in India | 1 hour |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations | 1 hour and uploading the text (4 non- 1 hour |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations | 1 hour and uploading the text (4 non- 1 hour |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- contact hours) | 1 hour and uploading the text (4 non- 1 hour contact hours) |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- c Module:6 BJUGAADInnovation | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- contact hours) Module:6 B JUGAAD Innovation Frugal and flexible approach to innovation - doing more | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- contact hours) Module:6 B JUGAAD Innovation Frugal and flexible approach to innovation - doing more Project: Fine tuning the innovation project with JUGA | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- contact hours) Module:6 B JUGAAD Innovation Frugal and flexible approach to innovation - doing more Project: Fine tuning the innovation project with JUGA | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- cModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing mor Project: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- conModule:7 AInnovation Project Proposal | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- cModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing mor Project: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- conModule:7 AInnovation Project Proposal Presentation | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading ntact hours) 1 hour 1 hour |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- cModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing mor Project: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- conModule:7 AInnovation Project Proposal PresentationProject proposal contents, economic input, ROI – Template | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading 1 hour e |
| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- cModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing mor Project: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- conModule:7 AInnovation Project Proposal Presentation | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading 1 hour e |
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| Module:5 CInnovation ProcessSteps for Innovation – right climate for innovationProject: Refining the project, based on the review report a contact hours)Module:6 AInnovation in IndiaStories of 10 Indian innovationsProject: Making the project better with add ons (4 non- cModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing morProject: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- conModule:7 AInnovation Project Proposal PresentationProject: proposal contents, economic input, ROI – Template Project: Presentation of the innovative project proposalModule:8 AContemporary issue in Innovation | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour contact hours) 1 hour re with less Indian Examples AAD principles and uploading ntact hours) 1 hour e and upload . (4 non- contact hours) |
| Module:5 C Innovation Process Steps for Innovation – right climate for innovation Project: Refining the project, based on the review report a contact hours) Module:6 A Innovation in India Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- contact hours) Module:6 B JUGAAD Innovation Frugal and flexible approach to innovation - doing mort Project: Fine tuning the innovation project with JUGA (Credit for JUGAAD implementation) . (4 non- contact for JUGAAD implementation) . (5 non- contact for JUGAAD implementation) . (6 non- contact for JUGAAD implementation) . (7 non- contact for JUGAAD implementation) . (7 non- contact for JUGAAD implementation) . (7 non- contact for JUGAAD implementation) . (8 non- contact for JUGAAD implementation) . (9 non- contact for JUGAAD implementatic for JUGAAD imple | 1 hour and uploading the text (4 non- 1 hour contact hours) 1 hour contact hours) 1 hour and upload . (4 non- contact hours) |
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| | (Deemed to be University under section 3 of UGC Act, 1956) | | | | | | | | |
|------------|---|--------------------|-------------|--------------------------|--|--|--|--|--|
| 1. | How to have Creative Ideas, Edward debone, Vermilon publication, UK, 2007 | | | | | | | | |
| 2. | The Art of Innovation, Tom Kelley & Jonathan Littman, Profile Books Ltd, UK, 2008 | | | | | | | | |
| Ref | erence Books | | | | | | | | |
| 1. | Creating Confidence, Meribeth Bo | onct, Kogan Page | e India Ltd | , New Delhi, 2000 | | | | | |
| 2. | Lateral Thinking Skills, Paul Sloar | ie, Keogan Page I | ndia Ltd, I | New Delhi, 2008 | | | | | |
| 3. | Indian Innovators, Akhat Agrawal | , Jaico Books, Mu | mbai, 201 | 5 | | | | | |
| 4. | JUGAAD Innovation, Navi Radjou | ı, Jaideep Prabhu, | Simone A | huja Random house India, | | | | | |
| | Noida, 2012. | | | | | | | | |
| | Nolua, 2012. | | | | | | | | |
| | · | | | | | | | | |
| Mo | de of Evaluation: CAT / Assignmen | t / Quiz / FAT / P | roject / Se | minar | | | | | |
| | de of Evaluation: CAT / Assignmen | | 5 | minar | | | | | |
| | · | | 5 | minar | | | | | |
| Thr | de of Evaluation: CAT / Assignmen | | 5 | minar | | | | | |
| Thr Rec | de of Evaluation: CAT / Assignmen ee reviews with weightage of 25 : 2 | 5 : 50 along with | 5 | minar 17-12-2015 | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| PHY1901.1 | - | - | - | - | 1 | 1 | - | - | 1 | 1 | - | 2 | - | - | - |
| PHY1901.2 | - | - | - | - | 1 | 1 | - | - | 2 | 2 | - | 2 | - | - | - |
| | | | | | | | | | | | | | | | |
| PHY1901.3 | 2 | 1 | - | - | 2 | 2 | - | - | 2 | 2 | - | 2 | - | - | - |
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| HUM1021 | | | | | Ethics | s and Va | alues | | L | Т | Р | J | 0 |
|--|---|--|--|---|--|--|--|------------|---|---|---|--|---|
| | | | | | | | | | 2 | 0 | 0 | 0 | 2 |
| Pre-requisit | e | NIL | | | | | | | | Syll | abus | versi | 01 |
| | | | | | | | | | | | v. 1. | 2 | |
| Course Obj | | | | | | | | | | | | | |
| To under polity To under To apprece | stand th | ne neg | ative h | nealth i | impacts | of certa | in unhea | althy beha | viors | | | ety a | nc |
| Expected Co | ourse C | Jutcoi | me: | | | | | | | | | | |
| Students will | | | | | | | | | | | | | |
| 1. Compr | ehend e | ethical | l and m | noral v | values. | | | | | | | | |
| 2. Unders | | | | | | | | | | | | | |
| 3. Unders | | | | | | | | | | | | | |
| 4. Identif | | | | | | | | texts, inc | | | | | , |
| subject | | JI UI S | ources | s, the C | Jojective | - present | iation of | uata, allu | i ine nea | u1110111 (| n nun | .1411 | |
| 5. Identif | | ain ty | pologi | es, cha | aracteris | stics, act | ivities, a | ctors and | forms of | of cyber | crime | • | |
| | - | | 1 0 | | | | , | | | | | | |
| | Reing | A 1 | | | | | | | | | | | |
| | | | and R | | | | | | | | | 5 ho | u |
| | lues suc | ch as t | truth ar | nd non | n-violenc | | | e analysis | | | ast ar | nd | u |
| present – So | lues suc ciety's i | ch as t intere | truth ar sts vers | nd non sus sel | n-violenc lf-interes | | | | | | ast ar | nd | u |
| present – So | lues suc ciety's i | ch as t intere | truth ar sts vers | nd non sus sel | n-violenc lf-interes | | | | | | ast ar | nd | u 1 |
| present – So needy, charit | lues suc ciety's i ty and s | ch as t interes erving | truth ar sts vers g the so | nd non sus sel | n-violenc lf-interes | | | | | | oast ar oing th | nd ne | |
| present – Soo needy, charit Module:2 | lues succiety's ity and s | ch as t interes erving Issue | truth ar sts vers g the so s 1 | nd non sus sel ociety | 1-violence lf-interes | sts - Per | sonal So | ocial Resp | onsibili | | oast ar oing th | nd | |
| present – So needy, charit | lues succiety's ity and s | ch as t interes erving Issue | truth ar sts vers g the so s 1 | nd non sus sel ociety | 1-violence lf-interes | sts - Per | sonal So | ocial Resp | onsibili | | oast ar oing th | nd ne | |
| present – So needy, charit Module:2 Harassment | lues succiety's ity and s | ch as t interes erving Issue es - Pr | truth ar sts vers g the so s 1 reventio | nd non sus sel ociety | 1-violence lf-interes | sts - Per | sonal So | ocial Resp | onsibili | | bast ar | nd ne | u |
| present – So needy, charit Module:2 Harassment Module:3 Corruption: 1 | lues succiety's i ty and s Social t – Type Social Ethical | ch as t interes serving Issue es - Pr Issue values | truth ar sts vers g the so s 1 revention s 2 s, cause | nd non sus sel ociety on of l es, im | harassmo | sts - Persenter - Pers | sonal So lence an ention – | ocial Resp | oonsibili sm | ty: Help | bast ar | nd ne 4 hor | u |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar | lues succiety's i ty and s Social t – Type Social Ethical | ch as t interes erving Issue es - Pr Issue values - Tax | truth ar sts vers g the so s 1 evention s 2 s, cause evasion | nd non sus sel ociety on of l es, imj ons – U | harassmo | sts - Persenter - Pers | sonal So lence an ention – | ocial Resp | oonsibili sm | ty: Help | past ar bing th | nd ne 4 hor | u |
| present – So needy, charit Module:2 Harassment Module:3 Corruption: I White collar Module:4 | lues succiety's i ty and s Social t – Type Social Ethical crimes | ch as t interest erving Issue es - Pr Issue values - Tax tion a | truth ar sts vers g the so s 1 revention s, causo evasion nd He | nd non sus sel ociety on of l es, imj ons – U alth | h-violend lf-interes harassmo pact, lav Unfair tr | sts - Persenters ent, Vio ws, preve rade prac | sonal So lence an ention – ctices | ecial Resp | onsibili sm malprae | ty: Help | past ar ping th | nd ne 4 ho 4 ho 5 ho | u |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar Module:4 Peer pressure - Prevention | lues suc ciety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic | ch as t interest serving Issue es - Pr Issue values - Tax tion a pholist cides; | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions mt Hee | nd non sus sel ociety on of l es, imj ons – U alth ical va | harassmo pact, law Unfair tr | sts - Pers ent, Vio vs, preve rade prac | sonal So lence an ention – ctices | ecial Resp | sm malprae | ty: Help ctices; | past ar bing th | 4 ho 4 ho 5 ho | u u in |
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| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar White collar Module:4 Peer pressure - Prevention Sexual Healt | lues suc ciety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev | ch as t interes serving Issue es - Pr Issue values - Tax tion a pholisi des; entior | truth ar sts vers g the so s 1 revention s 2 s, causon $revasion nd Hestimesm: Ethimping and in revent in and in$ | nd non sus sel ociety on of l es, imj ons – U alth ical va | harassmo pact, law Unfair tr | sts - Pers ent, Vio vs, preve rade prac | sonal So lence an ention – ctices | ecial Resp | sm malprae | ty: Help ctices; | bast ar bing th construction co | nd ne 4 ho 4 ho 5 ho 5 mok iseas | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure - Prevention Sexual Healt Module:5 | lues succiety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev | ch as t interest serving Issue es - Pr Issue - Tax tion a pholist cides; rentior | truth ar sts vers g the so s 1 eventions s 2 s, causo evasions mt Hea n and in | nd non sus sel ociety on of l es, imj ons – U alth ical va mpact | harassmu harassmu pact, law Unfair tr alues, ca | sts - Pers ent, Vio vs, preve rade prac usses, im marital p | sonal So lence an ention – ctices pact, lav | ecial Resp | malprae malprae | ty: Help ctices; Ill effec ransmit | bast ar bing th construction co | 1 ho 4 ho 4 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar White collar Module:4 Peer pressure - Prevention Sexual Healt | lues suc ciety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug <i>A</i> | ch as t interest serving Issue es - Pr Issue - Tax tion a pholist cides; rentior | truth ar sts vers g the so s 1 eventions s 2 s, causo evasions mt Hea n and in | nd non sus sel ociety on of l es, imj ons – U alth ical va mpact | harassmu harassmu pact, law Unfair tr alues, ca | sts - Pers ent, Vio vs, preve rade prac usses, im marital p | sonal So lence an ention – ctices pact, lav | ecial Resp | malprae malprae | ty: Help ctices; Ill effec ransmit | bast ar bing th construction co | 1 ho 4 ho 4 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention | lues succiety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug A | ch as t interest serving Issue es - Pr Issue values - Tax tion a pholist des; rentior Abuse t types | truth ar sts vers g the so s 1 evention s 2 s, cause r cause $r causer causer$ | nd non sus sel ociety on of l es, imj ons – U alth ical va mpact gal and | harassmu harassmu pact, lav Unfair tr alues, ca of pre-r d illegal | sts - Pers ent, Vio ws, preve rade prac uses, im marital p drugs: H | sonal So lence an ention – ctices pact, lav | ecial Resp | malprae malprae | ty: Help ctices; Ill effec ransmit | bast ar bing th construction ts of s ted D ted D ts and | 4 ho 4 ho 5 ho 5 ho 5 ho 3 ho 1 | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention Module:6 | lues succiety's i ty and s social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug A lifferent | ch as t interest serving Issue es - Pr Issue values - Tax tion a pholist cides; rentior Abuse t type | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions m: Ethin n and in s of leg | nd non sus sel ociety on of l es, impons – U alth ical va mpact gal and | harassmo harassmo pact, lav Unfair tr alues, ca of pre-r d illegal | sts - Pera ent, Vio ws, preve rade prac uses, im marital p drugs: F | sonal So lence an ention – ctices pact, lav pregnanc Ethical v | ecial Resp | malprae malprae | ty: Help ctices; Ill effec ransmit | bast ar bing th construction ts of s ted D ted D ts and | 1 ho 4 ho 4 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho 5 ho | u u u u i i r u u |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention | lues succiety's i ty and s social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug A lifferent | ch as t interest serving Issue es - Pr Issue values - Tax tion a pholist cides; rentior Abuse t type | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions m: Ethin n and in s of leg | nd non sus sel ociety on of l es, impons – U alth ical va mpact gal and | harassmo harassmo pact, lav Unfair tr alues, ca of pre-r d illegal | sts - Pera ent, Vio ws, preve rade prac uses, im marital p drugs: F | sonal So lence an ention – ctices pact, lav pregnanc Ethical v | ecial Resp | malprae malprae | ty: Help ctices; Ill effec ransmit | bast ar bing th construction ts of s ted D ted D ts and | 4 ho 4 ho 5 ho 5 ho 5 ho 3 ho 1 | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention Module:6 Dishonesty | lues suc ciety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug Hifferent Person y - Steal | ch as t interest serving Issue es - Pr Issue values - Tax tion a oholist cides; rentior Abuse t types t types nal an ling - of Te | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions nd Hea m: Ethin n and in s of leg d Prof Malpra | nd non sus sel ociety on of l es, imj ons – U alth ical va mpact gal and fession actices | harassmo harassmo pact, lav Unfair tr alues, ca of pre-r d illegal nal Ethio s in Exan | sts - Pera ent, Vio ws, preve rade prac uses, im marital p drugs: F cs mination | sonal So lence an ention – ctices pact, lav pregnanc Ethical v | cial Resp | malprae malprae ntion – 1 sually T uses, im | ty: Help ctices; Ill effec ransmit pact, la | bast ar bing th construction ts of s ted D ts of s ted D | 4 ho 4 ho 5 ho 5 ho 5 ho 3 ho 1 | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: I White collar Module:4 Peer pressure - Prevention Sexual Healt Module:5 Abuse of c prevention Module:6 Dishonest Module:7 Hacking and | lues suc ciety's i ty and s Social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug Hifferent Person y - Steal | ch as t interest serving Issue es - Pr Issue values - Tax tion a oholist cides; rentior Abuse t types t types nal an ling - of Te | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions nd Hea m: Ethin n and in s of leg d Prof Malpra | nd non sus sel ociety on of l es, imj ons – U alth ical va mpact gal and fession actices | harassmo harassmo pact, lav Unfair tr alues, ca of pre-r d illegal nal Ethio s in Exan | sts - Pera ent, Vio ws, preve rade prac uses, im marital p drugs: F cs mination | sonal So lence an ention – ctices pact, lav pregnanc Ethical v | cial Resp | malprae malprae ntion – 1 sually T uses, im | ty: Help ctices; Ill effec ransmit pact, la | bast ar bing th construction ts of s ted D ts of s ted D | 4 ho 4 ho 5 ho 5 ho 5 ho 5 ho 1 4 ho | |
| present – Soo needy, charit Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention Module:6 Dishonesty | lues succiety's i ty and s social t – Type Social Ethical crimes Addict e - Alco of Suic th: Prev Drug A lifferent y - Steal Abuse other c | ch as t interest serving Issue es - Pr Issue values - Tax tion a oholist ides; rention Abuse t type: nal an ling - of Te | truth ar sts vers g the so s 1 eventions s 2 s, cause evasions nd Hea m: Ethin n and in s of leg d Prof Malpra | nd non sus sel ociety on of I es, imp ons – U alth ical va mpact gal and fession actices , Addi | harassmo harassmo pact, law Unfair tr alues, ca of pre-r d illegal nal Ethio s in Exan | sts - Pera ent, Vio ws, preve rade prac uses, im marital p drugs: F cs mination | sonal So lence an ention – ctices pact, lav pregnanc Ethical v | cial Resp | malprae malprae ntion – 1 sually T uses, im | ty: Help ctices; Ill effec ransmit pact, la | bast ar bing th coing th coing th coing th coing the coing the coi | 4 ho 4 ho 5 ho 5 ho 5 ho 5 ho 1 4 ho | |



| | | Total Lecture hours: | 30 hours | |
|---------|--|----------------------------|-----------------|--------------------|
| Referer | nce Books | | - | |
| 1. | 2 | | | |
| | Presupposition and Precept | s,2016, Writers Choice, Ne | w Delhi, India. | |
| | Vittal, N, "Ending Corrupti | on? - How to Clean up Indi | a?", 2012, Pen | guin Publishers, |
| 2. | UK. Pagliaro, L.A. and Pag | liaro, A.M, "Handbook of G | Child and Adol | escent Drug and |
| | Substance | | | |
| | Abuse: Pharmacological, I | Developmental and Clinical | Consideration | s", 2012Wiley |
| 3. | Publishers, U.S.A. | | | |
| 4. | Pandey, P. K (2012), "Sexu Germany. | al Harassment and Law in | India", 2012, L | ambert Publishers, |
| | | | | |
| Aode of | f Evaluation: CAT, Assignm | ent, Quiz, FAT and Semina | r | |
| | | | | |
| | nended by Board of Studies | 26-07-2017 | | |
| | ed by Academic Council | 46 th AC Date | e 24-08-20 |)17 |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| HUM1021.1 | - | - | - | - | - | 3 | 2 | 3 | 1 | 2 | - | 2 | - | - | - |
| HUM1021.2 | - | - | - | - | - | 3 | 2 | 3 | 2 | 2 | - | 2 | - | - | - |
| HUM1021.3 | - | - | - | - | - | 3 | 2 | 3 | 1 | 2 | - | 2 | - | - | - |
| | | | | | | | | | | | | | | | |
| HUM1021.4 | - | - | - | - | - | 3 | 2 | 3 | 2 | 2 | - | 2 | - | - | - |
| HUM1021.5 | - | - | - | - | - | 3 | 2 | 3 | 1 | 2 | - | 2 | - | - | - |
| | - | - | - | - | - | 3 | 2 | 3 | 2 | 2 | - | 2 | - | - | - |



| EE1002 | Electric circuits | | L T P J C |
|---|---|-----------------------|-----------------------|
| | - | | 3 0 0 0 3 |
| Pre-requisite | NIL | | Syllabus version |
| Anti-requisite | NIL | | v. 1. |
| Course Objective | | | |
| | mathematical model of the electric circui | | |
| | network theorems to solve the electric ci | | |
| | analyze the steady state and transient resp | oonses of DC and AC c | ricuits |
| Expected Course | | | |
| | of this course the student will be able to | | |
| | equations of the electric circuits using ba | | |
| | response of DC circuits using basic analy | | |
| | esponse of DC circuits using network the ansient behavior of electric circuits with a | | 0 |
| • | lements of AC circuits and the phasor con | • • | |
| | nce circuits, and solve three phase ac circ | 1 | |
| | nagnetic circuits | | |
| L | | | |
| | | | |
| | damentals of Electric Circuits | | 5 Hour |
| | ircuit Elements, Ohms Law and Kirchh rmation and Source Transformation. | off's Laws. Voltage a | and Current Division |
| Star-Dena Transic | mation and Source Transformation. | | |
| Module:2 Line | ear Circuit Analysis | | 5 Hours |
| | analysis of Linear Network with Independent | dent and Dependent D | C sources. |
| Module:3 Net | work Theorems | | 7 Hour |
| Thevenin's Theorem | rem, Norton's Theorem, Maximum Po | ower Transfer Theore | m and Superposition |
| Theorem for circu | its with independent and dependent source | ces. | |
| Module:4 Tra | nsient Circuit Analysis | | 7 Hour |
| | Elements – L and C. Analysis of Source | Free RC RI and RI(| |
| - | esponse of RC, RL and RLC Circuits. | THE RC, RE and REA | circuits, Singularity |
| | | | |
| Module:5 Intr | oduction to Phasors | | 7 Hours |
| | nusoids and Phasors, Impedance and Adm | | - |
| | ues of Sinusoids, Instantaneous and Av | - | omplex Power - Rea |
| Power, Reactive P | ower and Apparent Power Calculations a | and Power Factor. | |
| Madulas (| Circuits and Resonance | | 7 11.000 |
| | | demendent sources Er | 7 Hour |
| • | State Analysis for AC circuits with in L and C Combinations. Resonance in S | - | |
| A DECEMBER OF A | its, Power in a Balanced System, Three F | | |
| | | | |
| | <u>,</u> | | |
| Three Phase Circu | · · · · · · · · · · · · · · · · · · · | | Hours |
| Three Phase Circu Module:7 Mag | gnetic Circuits pled Circuits, Self and Mutual Inducta | ance, Dot Convention | |



| Module:8 | Contemporary issues: | 2 hours |
|----------|----------------------|----------|
| | Total Lecture hours: | 45 Hours |

| Г | Text Book(s) | | | |
|---------|----------------------------------|---------------------|--------------|-----------------------------------|
| 1. | Charles K Alexander, Mathew N | NO Sadiku, 'Fui | ndamentals | of Electric Circuits, Tata McGraw |
| | Hill, 2012. | | | |
| Referen | nce Books | | | |
| 1. | . | Engineering-Pri | nciples & | Applications', Pearson Education |
| | Limited, 7/e, 2017. | | | |
| 2. | Robert L Boylestad, 'Introductor | ry Circuit Analys | is', Pearson | n Education Limited, 13/e, 2016. |
| 3. | W. H. Hayt, J.E. Kemmerly and | S. M. Durbin, ' | Engineerin | g Circuit Analysis', McGraw Hill, |
| | New York, 8/e, 2012. | | | |
| 4. | Abhijit Chakrabarti, 'Circuit T | heory : Analysis | s and Synt | hesis', Dhanpat Rai & Co., New |
| | Delhi, 6/e, 2014 | | | |
| 5. | Mahmood Nahvi; Joseph A Edm | inister, 'Electric | Circuits', I | McGraw Hill Education, 6/e, 2015. |
| Mode o | f Evaluation: CAT / Assignment / | / Quiz / FAT / Pr | oject / Sem | inar |
| Recom | mended by Board of Studies | 29/05/2015 | | |
| Approv | ed by Academic Council | 37 th AC | Date | 16/06/2015 |

| | DO1 | DOA | DOG | DOI | D05 | DOC | D07 | DOO | DOG | DO 10 | D011 | D010 | DOOL | DGGG | DGOO |
|-----------|------------|-----|-----|-----|-----|-----|-----|-----|-----|-------|------|------|------|------|------|
| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE1002.1 | 3 | 2 | 1 | 1 | 1 | - | - | - | - | - | - | 1 | 2 | 1 | 1 |
| EEE1002.2 | | | | | | | | | | | | | | | |
| | 3 | 2 | 1 | 1 | 1 | - | - | 2 | 2 | 1 | - | 1 | 2 | 1 | 1 |
| EEE1002.3 | 3 | 2 | 1 | 1 | 1 | - | - | 2 | 2 | 1 | - | 1 | 2 | 1 | 1 |
| EEE1002.4 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 1 | - | - | - | - | - | - | 1 | 2 | 2 | 1 |
| EEE1002.5 | 2 | 1 | - | - | - | - | - | - | - | - | - | 1 | - | - | - |
| EEE1002.6 | 3 | 2 | 1 | 1 | 1 | - | - | 2 | 2 | 1 | I | 1 | 2 | 1 | 1 |
| EEE1002.7 | 3 | 2 | 1 | 1 | 1 | - | - | - | - | - | - | 1 | 2 | 1 | 1 |
| | 3 | 2 | 2 | 2 | 1 | - | - | 2 | 2 | 1 | - | 1 | 2 | 2 | 1 |



| | (Defined to be University under section 5 of UGC Act, 1956) | |
|--------------------|--|------------------------|
| EEE1004 | Engineering Electromagnetics | L T P J C |
| | | 3 0 2 0 4 |
| Pre-requisite | MAT1011 | Syllabus version |
| Anti-requisite | NIL | v. 1.1 |
| Course Objectives | S: | |
| 1. To convey the b | basic physical concepts that lie behind all electrical enginee | ring, the interactions |

between charged particles, whether stationary or in motion.

2. To examine the electric and magnetic forces between stationary and steadily moving charged particles.

3. To study the various electric & magnetic field concepts both in static and time varying condition.

Expected Course Outcome:

On the completion of this course the student will be able to:

- 1. Explore different coordinate systems related to magnetic fields.
- 2. Define the electric flux density, field intensity and different charge distributions.
- 3. Demonstrate the boundary conditions and method of images.
- 4. Compare the electric and magnetic boundary conditions, calculate the capacitance and inductance.
- 5. Analyze Maxwell equations.
- 6. Summarise the electric magnetic waves and wave propagation in different medium.
- 7. Apply the electric and magnetic field concepts
- 8. Design and Conduct experiments, as well as analyze and interpret data

Review of Scalar and Vector Fields Module:1

Different Co-ordinate Systems: Cartesian, Cylindrical and Spherical –Differential elements in different coordinate systems - Del Operator: Divergence, Curl and Gradient, Divergence Theorem -Stoke's Theorem - Helmholtz's Decomposition.

Module:2 **Electrostatics: Charges**

Coulomb's law - Electric Field Intensity - Electric Flux - Gauss's Law - Potential due to Point, Line and Surface Charge Distributions.

Module:3 **Electric Fields in Dielectrics and Conductors**

Different current flow mechanisms – Continuity equation and relaxation time - Boundary conditions - Laplace and Poisson's equations - Solutions - Analytical Methods - Variables separable methods -Method of images - Numerical Techniques - Finite Difference Method - Electrostatic Energy -**Capacitance Calculations**

Module:4 **Magneto statics**

Magnetic Fields - Magnetic Flux - Biot Savart's Law - Ampere's Law - Magnetic Torque and Moment - Forces due to Magnetic Fields - Vector Potential - Magnetic Boundary Conditions -Inductors and Inductances – Calculations - Magnetic Energy

Module:5 **Electromagnetic Fields** Faraday's law – Lenz's Law – Maxwell's equations – Displacement current – Maxwell's Equations in Final Forms – Time Varying Fields - Relation between field theory and circuit theory

8 Hours

8 Hours

8 Hours

5 Hours

6 Hours



| Mod | ule:6 | Electromagnetic Waves Generation | | 8 Hours |
|------|--------------------|---|---------------------|--------------------|
| | | of waves in lossy dielectrics, conductors and from | e space – Skin e | |
| - | - | Power and Poynting Vector. | ee space Skin e | liteet complex |
| | 5 | , , | | |
| | lule: 7 | Application | | 2 hours |
| Sour | ces, Effe | ects and application of Electromagnetic fields | | |
| Mod | ule:8 | Contemporary issues: | | 2 Hours |
| wiou | ule.o | Total Lecture hours: | | 45 Hours |
| N 1 | f F | | N i | 45 110015 |
| | | luation: CAT / Assignment / Quiz / FAT / Project / S | Seminar | |
| | | enging Experiments (Indicative) | | 2.1 |
| 1. | | magnetic concepts using Matlab tool functions Representation ,Coordinate Systems and conversion | | 2 hours |
| 2. | | | 2 hours | |
| 3. | | e and surface integration (Vectorial) | - abarras and line- | 2 hours |
| 4. | Determ charge | ining electric field distribution for an infinite sheet | charges and line | 2 hours |
| 5. | • | ne charge | 2 hours | |
| 6. | Energy | stored in a region due to electric field | | 2 hours |
| 7. | Solving | g dielectric $(\Box r1)$ - dielectric $(\Box r2)$ boundary condition | on problem | 2 hours |
| 8. | Determ capacito | he parallel plate | 2 hours | |
| 9. | | nination of voltage and electric field distribution insi Laplace equation). | de the co-axial | 2 hours |
| 10. | | ining and plotting the magnetic field due to infinite | sheet current | 2 hours |
| 11. | Determ | ination of an inductance of a solenoid | | 2 hours |
| 12. | | ination of the mutual inductance between an infinit ngular coil | e line current and | 2 hours |
| 13. | Electro | magnetic wave propagation in good conductors. | | 2 hours |
| 14. | | ination of Electric field and Voltage profile for a s ruptured by the presents of a needle inclusion on t | | 2 hours |
| 15. | Determ | ination of static magnetic field induced by the state electric motor. | | 2 hours |
| | •••• ₽•• | | aboratory Hours | 30 hours |
| Mod | e of Eva | luation: Assignment / FAT | - J V | |
| | | | | |
| | Book(s) | | 1 6 51 | |
| 1. | | thew N. O. Sadiku & S. V. Kulkarni, 'Princi | ples of Electroma | ignetics', Oxford |
| Dofo | rence B | versity Press, New York, Sixth Edition, 2015. | | |
| 1. | | Hayt, John A. Buck, 'Engineering Electromagne | tics' McGraw-Hill | Fighth Edition |
| 1. | 2012 | | | , Eighti Euluoll, |
| 2. | | Edminister, 'Schaum's Outline of Electromagnetics' | . McGraw-Hill Pro | ofessional. Fourth |
| | | ion, 2013. | , | |
| 3. | Karl | E. Lonngren, Sava Savov, Randy J. Jost, 'Fu TLAB', 2007. | ndamental of Elec | ctomagnetic with |



| Recommended by Board of Studies | 30/11/2015 | | |
|---------------------------------|---------------------|------|------------|
| Approved by Academic Council | 39 th AC | Date | 17/12/2015 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1004.1 | 2 | 1 | - | - | - | - | - | - | - | - | - | - | - | - | - |
| EEE1004.2 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | 2 | 2 | 1 | - | 1 | - | - | - |
| EEE1004.3 | 2 | 1 | - | - | - | - | - | 2 | 2 | 1 | - | 1 | - | - | - |
| EEE1004.4 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | 2 | 2 | 1 | - | 1 | - | - | - |
| EEE1004.5 | 3 | 3 | 2 | 2 | - | - | - | - | - | - | - | 1 | 3 | 1 | 2 |
| EEE1004.6 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | - | - | - | - | 1 | - | - | - |
| EEE1004.7 | 3 | 2 | 1 | 1 | - | - | - | 2 | 2 | 1 | - | 1 | 3 | 2 | - |
| EEE1004.8 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 2 | - | - | 3 | 3 | 3 | - | 2 | 3 | 2 | 2 |
| | 3 | 2 | 2 | 2 | 2 | - | - | 3 | 3 | 2 | - | 2 | 3 | 2 | 2 |



| EEE1005 | | Signals and systems | | L | Τ | P J | C C |
|---------------|------------|--|--------------------|----------|--------|------------|----------|
| | | | | 3 | 0 | 0 0 |) 3 |
| Pre-requisite | ; | MAT2002 | | Sylla | ibus | s vers | sior |
| Anti-requisi | te | NIL | | | | V | . 1.0 |
| Course Obje | ctives: | | | | | | |
| 1. To underst | and the | mathematical representations of signals and | systems in contin | nuous a | and c | discre | ete |
| domain. | | | - | | | | |
| 2. Analyse ar | nd perfo | orm various operations with the signals. | | | | | |
| • | - | nse of linear time invariant (LTI) systems in o | | iscrete | dom | nain. | |
| | | ing theorem and represent signals in the frequ | uency domain. | | | | |
| Expected Co | | | | | | | |
| - | | f this course the student will be able to: | | | | | |
| systems | | cal tools to perform operations and classify di | ••• | • | | • | |
| • | | s types of LTI systems based on their behavi | · · | | | | |
| | - | susing Fourier seriesDifferentiate the behav | iour of LTI sys | tems a | s pe | eriodi | ic |
| and aperiodi | c signa | ls using Fourier Transforms | | | | | |
| | | ehaviour of LTI systems as periodic and aper | 0 | 0 | rier | | |
| | | l the analysis to unstable systems using the L | aplace Transform | ıs | | | |
| | 0 | inal signal from samples using interpolation | | | | | |
| | | nsform to analyse continuous LTI systems | | | | | |
| | | m to analyse discrete LTI systems | | | | | |
| Module:1 | | amentals of Signals | | | | 5 Ho | |
| - | | Continuous and Discrete-time Signals, Uni | - · | • · | | - | |
| | - | plex Exponentials. Classification of signals – | - | | - | | vei |
| - | | ergy and Power Signal, Deterministic and Ra | - | ransfor | mati | on | |
| of Independe | nt Varia | ables – Time Shifting, Time Scaling and Time | e Reversal. | | | | |
| Module:2 | Funda | amentals of Systems | | | ł | 5 Ho | urs |
| Representatio | on of C | Continuous and Discrete Time Systems. Cla | assification of sy | stems | - St | tatic | and |
| Dynamic, Lii | near and | Nonlinear, Time variant and Time Invariant | , Causal and Non | –Causa | al, St | table | and |
| unstable, In | vertible | and non- invertible systems. Block I | Diagram Repres | entatio | n a | and | |
| Interconnecti | on of S | ystems | | | | | |
| Module:3 | Analy | sis of LTI System | | | | 6 Ho | our |
| Impulse Resp | onse of | f Continuous and Discrete Time LTI Systems | . Convolution, B | asic pr | oper | ties o | of |
| systems using | g impul | se response. | | - | - | | |
| | | | | | | | |
| Module:4 | and L | er Representation of Periodic Signals TI Systems | 6 Hours | | | | |
| | | sentation of Continuous Time and Discrete- | | | ope | rties | of |
| Fourier Serie | s, Pars | eval's relation, Response of LTI Systems to C | Complex Expone | ntials. | | | |
| | D · | | 7 11 | | | | |
| Module:5 | and L | er Representation of Aperiodic Signals TI Systems | 7 Hours | | | | |
| | | d Discrete Time Fourier Transforms, Propert | | | | — • | |
| | - | of LTI system. Applications: Modulation for | communications | , Filter | ng, | Time | <u>)</u> |
| Frequency re | present | ation and uncertainty principle. | | | | | |
| B.TECH (EIE) | - | | | Page | 70 | | |



| k | | | | | | | | | |
|-----------------------------------|--|---|--|---------------|-----------------------------------|--|--|--|--|
| Module | e:6 | Representation of Contin | uous time signals b | ŊУ | 5 Hours | | | | |
| | | its samples | | | | | | | |
| | | | | | of Continuous Time Signals with | | | | |
| Sample | and H | Hold, Reconstruction of Sign | al from Samples – | Interp | olation. | | | | |
| | | | | | | | | | |
| Module | e:7 | Analysis of Continuous an | nd Discrete LTI | | 9 Hours | | | | |
| | | Systems with Laplace Tra | ansform and Z- | | | | | | |
| | | Transform | | | | | | | |
| Review | of La | place Transform, Region of | Convergence, Char | racteri | zation of LTI systems with | | | | |
| | | | - | | ane, Review of Z-Transform, | | | | |
| | | | | | on expansion. Characterization of | | | | |
| - | | using Z -Transforms. | , 1 | | 1 | | | | |
| | | 0 | | | | | | | |
| Module | ::8 | Lecture by industry expe | erts. | | 2 Hours | | | | |
| | | | Total Lecture hou | irs: | 45 Hours | | | | |
| Text B | oolz(a) | | | | | | | | |
| | JUK(S | | | | | | | | |
| 1. | | | Oppenhein, Alan S | . Will | sky and S. Hamid, Pearson 2016. | | | | |
| 1. Refere | Sign | als and Systems by Alan V. | Oppenhein, Alan S | . Will | sky and S. Hamid, Pearson 2016. | | | | |
| | Sign nce B | als and Systems by Alan V. | ** | | | | | | |
| Referen | Sign nce B Sign | als and Systems by Alan V. ooks als and systems by Simon H | laykin, John Wiley, | 2016. | | | | | |
| Refere | Sign nce B Sign Fund | als and Systems by Alan V. ooks als and systems by Simon H | laykin, John Wiley, | 2016. | | | | | |
| Referen 1. 2. | Sign nce B Sign Fund S. H | als and Systems by Alan V. ooks als and systems by Simon H damentals of Signals and Sy | laykin, John Wiley, stems Usin Web an | 2016. d MA | TLAB, Edward W Kamen, Bonnie | | | | |
| Referen 1. 2. Mode o | Sign nce B Sign Fund S. H f Eva | als and Systems by Alan V. ooks als and systems by Simon H lamentals of Signals and Sy eck, Pearson, 2014. | laykin, John Wiley, stems Usin Web an | 2016. d MA | TLAB, Edward W Kamen, Bonnie | | | | |
| Referen | Sign Ice B Sign Fund S. H f Eva mendo | als and Systems by Alan V. ooks als and systems by Simon H lamentals of Signals and Sy eck, Pearson, 2014. luation: CAT / Assignment / | Iaykin, John Wiley, stems Usin Web an Quiz / FAT / Proje | 2016. d MA | TLAB, Edward W Kamen, Bonnie | | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1005.1 | 2 | | 1 | 1 | 1 | | | | | | | | 1 | 0 | 1 |
| | 3 | 2 | 1 | 1 | 1 | | | | | | | | 1 | 2 | 1 |
| EEE1005.2 | 3 | 3 | 2 | 2 | 1 | | | 2 | 2 | 2 | | 1 | 3 | 3 | 1 |
| EEE1005.3 | 2 | 1 | | | | | | | | | | | | 1 | |
| EEE1005.4 | 3 | 2 | 1 | 1 | 1 | | | | | | | 1 | | 2 | 1 |
| EEE1005.5 | 3 | 3 | 2 | 2 | 1 | | | 2 | 2 | 2 | | 1 | 2 | 3 | 1 |
| EEE1005.6 | 3 | 2 | 1 | 1 | 1 | | | 2 | 2 | 2 | | 1 | 2 | 2 | 1 |
| | 3 | 3 | 2 | 2 | 1 | - | - | 2 | 2 | 2 | - | 1 | 3 | 3 | 1 |



| | | (Deemed to be University under section 3 of UGC Act, 19. | 66) | | | <u> </u> | | |
|---|-----------------------|--|--------------------------------------|-----------|-------|--------------|------|----|
| EEE2001 | | Network theory | | L | Т | Р | J | С |
| | | | | 3 | 0 | 0 | 0 3 | 3 |
| Pre-requisite | e | EEE1002, MAT1011 | | Sylla | bu | s ve | rsio | n |
| Anti-requisit | | NIL | | · | | , | v. 1 | .0 |
| Course Obje | | | | | | | | |
| 1. Analyse th 2. Apply Lap response | e steady lace trai | y state response of circuits and discuss various nsform and Fourier transform techniques to ci- ters and analyse its frequency response. | | | | catic ete |)ns | |
| 8 1 | | | | | | | | |
| Expected Co | ourse O | utcome: | | | | | | |
| On the comp | letion of | f this course the student will be able to: | | | | | | |
| 1. Apply nod | e voltag | e and mesh current methods to analyse circui | ts in steady state. | | | | | |
| circuits ii) and identif | Derive t fy its po | ransform techniques for solving problems and he transfer function and identify its poles and les and zeros polics in nonsinusoidal inputs to circuits using | zerosDerive the tr | | | | | |
| | | sform to circuits with nonsinusoidal inputs | | | | | | |
| | | ters and analyse the frequency response. | | | | | | |
| | | e two-port network parameters. | | | | | | |
| | na reiat | e two port network parameters. | | | | | | |
| Module:1 | Sinus | oidal Steady State Analysis | | | | 6 F | Iou | rs |
| | | Nodal Analysis, Mesh Analysis, Thevenin's T | boorom Norton's | Theor | rom | | loui | 10 |
| | | ansfer Theorem and Superposition Theorem for | | | | | 1 | |
| dependent si | | 1 1 | of circuits with mu | epend | ent | anu | • | |
| dependent sn | lusoiua | sources | | | | | | |
| Module:2 | Mode | ing of Network in s-Domain | | | | 6 F | Iou | rs |
| | | L and C in s-Domain. Application of Laplace | Transforms to inte | -oro-c | liffe | | | |
| | | and RLC circuits. Transfer Function. Impuls | | | | | | |
| 1 | | other sources using convolution integral. | | und I | | 2110 | 4105 | |
| | <u> </u> | | | | | | | |
| Module:3 | Comp | lete Response of Networks | | | | 6 H | Iou | rs |
| | - | r zero and non zero initial conditions in s-dom | ain Pole-Zero M | ans 1 | Net | | | |
| Stability. | y 515 W 10 | 2010 and non 2010 initial conditions in 5 doin | | ups. 1 | 101 | 1011 | | |
| Module:4 | Netwo Excita | tion | | | | | Iou | |
| | | er Series for Non-Sinusoidal Functions. Cin | | verage | Po | wer | : an | ıd |
| RMS Values | using F | ourier Coefficients. Exponential Fourier Serie | es. | | | | | |
| | | | | | | | | |
| Module:5 | | rk Analysis using Fourier Transform | | <u>.</u> | | | Iou | |
| | | or commonly used periodic and aperiodic func- e signal using Parseval's Theorem. | ctions. Circuit Ana | lysis i | n fi | equ | enc | :y |
| Module:6 | Desig | n of Filters | | | | 4 F | Iou | r¢ |
| | 9 | cy Response of RL, RC and RLC circuits. Pas | sive Filters_Low | Pase | Hia | | | |
| | | I Stop. Magnitude and Frequency Scaling. | $5170 \text{ I mers}^{-} \text{LOW}$ | uss, 1 | ing | | , | |
| Module:7 | | Port Networks | | | | 6 F | Iou | r¢ |
| | | p-Port Networks - Impedance and Admitta | nce narameters " | Franci | nic | | | |
| masauction | 10 I W | s i or records impedance and Adminia | nee parameters, | - i anisi | 113 | 1011 | | u |



| Hybrid | Paran | neters. Relationship between | parameter, Interco | onnection | of Networks. | | | | |
|---|---|--|--------------------|-----------|---------------------------------|--|--|--|--|
| Module | e:8 | Contemporary issues: | | | 2 hours | | | | |
| | | | Total Lecture ho | ours: | 45 Hours | | | | |
| Text B | ook(s) | | | 1 | | | | | |
| 1. | | les K Alexander, Mathew Braw Hill, 2012. | N O Sadiku, "Fu | ndamenta | lls of Electric Circuits", Tata | | | | |
| Refere | nce B | ooks | | | | | | | |
| 1. | Allan R. Hambley, 'Electrical Engineering-Principles & Applications' Pearson Education, First Impression, 6/e, 2013. | | | | | | | | |
| 2. | Rob 2010 | • | y Circuit Analysis | ' Pearson | n Education Ltd, 12th Edition, | | | | |
| 3. | | Hayt, J.E. Kemmerly and S Braw Hill, New Delhi, 2011. | . M. Durbin, 'En | gineering | g Circuit Analysis', 6/e, Tata | | | | |
| Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar | | | | | | | | | |
| Recom | mende | ed by Board of Studies | 29/05/2015 | | | | | | |
| Approv | Approved by Academic Council 37th AC Date 16/06/2015 | | | | | | | | |

| | | PO | PO1 | PO1 | PO1 | PSO | PSO | PSO |
|---------------|-----|----|----|----|----|----|----|----|----|-----|-----|-----|-----|-----|-----|
| CO | PO1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 1 | 2 | 1 | 2 | 3 |
| EEE2001. 1 | 3 | 2 | 1 | 1 | | | | | | | | 1 | 1 | 2 | |
| EEE2001. 2 | 3 | 2 | 1 | 1 | | | | 2 | 2 | 2 | | 1 | 1 | 2 | |
| EEE2001. 3 | 3 | 3 | 2 | 2 | | | | | | | | 1 | 2 | 3 | |
| EEE2001. 4 | 3 | 2 | 1 | 1 | | | | | | | | 1 | 2 | 2 | |
| EEE2001. 5 | 3 | 3 | 2 | 2 | | | | 2 | 2 | 2 | | 1 | 2 | 3 | |
| EEE2001. 6 | 3 | 2 | 1 | 1 | | | | | | | | 1 | 1 | 2 | |
| | 3 | 3 | 2 | 2 | - | - | - | 2 | 2 | 2 | - | 1 | 2 | 3 | - |



| EEE2002 | (Deemed to be University under section 3 of UGC Act, 1956) Semiconductor Devices and Circuits | L | Т | ΡJ | C |
|-------------------|--|-------------|-------|-------|-----|
| | Semiconductor Devices and Circuits | 2 | | _ | |
| Pre-requisite | EEE1002 | 2 Syllat | | 2 4 | |
| Anti-requisite | NIL | Synai | Jus | | 1.0 |
| Course Objectiv | | | | ۷. | 1.0 |
| • | mowledge of solid state devices principles to analyze electronic c | | | | |
| | plifiers under different configurations and study their responses | | | | |
| | s on learning experience and software knowledge by doing practic | cal exerc | ises | and | |
| projects. | | | | | |
| Expected Cours | se Outcome: | | | | |
| On the completion | on of this course the student will be able to: | | | | |
| 1. Explain the be | haviour of semiconductor devicesAnalyze diode circuits | | | | |
| • | e circuits to determine voltages and currentsCompare the various | configur | atio | ns o | f |
| BJT | | | | | |
| , T | characteristics and biasing methods of BJTs and MOSFETs ii) C | 1 | | | |
| | figurations.iii) Compare the MOSFET amplifiers configurations. e of semiconducting devices. | Analyze | the | nıgn | |
| | high frequency response of semiconductor devices ii)Compare ar | nd contr | ast f | he | |
| | positive feedback in amplifier ii)Compare and contrast the negative | | | | |
| • • | iments, as well as analyze and interpret data | U | | | |
| 5. Design and ex | perimentally verify the circuit for the given specifications | | | | |
| 6. Design and de | velopment of an electronic circuit for engineering applications | | | | |
| | | | | | |
| | miconductor Device Physics | | | Ho | |
| | s, charge carriers, intrinsic and extrinsic semi-conductors, | | gen | erati | on, |
| | njection of carriers, Drift and diffusion, carrier mobility, conducti | ivity. | | TT | |
| | ode Circuit Analysis | Diada | | Ho | |
| | le – Formation of Junction, Junction Capacitance, characteristics, – Clipper and Clamper, rectifiers with and without filters, ot | | | | |
| | ed power supplies. | inci inui | upic | | Jue |
| encuns, regulat | power supplies. | | | | |
| Module:3 Tr | ansistor DC Analysis | | 5 | Ho | urs |
| | tics, current gains, h-parameters, MOSFET Characteristics, Load | line and | | | |
| | C analysis and biasing of BJTs and MOSFETs. | | 1 | | U |
| Module:4 B. | T Amplifiers | | 5 | Ho | urs |
| Small signal an | nalysis of BJT amplifiers, Calculation of Gain, Input Impe | dance a | nd | Out | put |
| Impedance. Basi | c BJT amplifier Configurations (CE, CC and CB). Power Amplif | iers. | | | |
| | | | | | |
| | OSFET Amplifiers | | | Ho | |
| 0 | alysis of MOSFET amplifiers. Calculation of Gain, Input Imp | | and | Out | put |
| Impedance. Basi | c MOSFET amplifier configurations - (CS, CD and CG) amplifie | ers. | | | |
| | | | | | |
| | requency response | | | Ho | |
| | uency Response, System Transfer Functions, Frequency Response | | | | |
| Transistor Circu | Circuit Capacitors, Frequency Response of the FET, High-Frequents | епсу ке | spo | use (| л |
| B TECH (EIE) | | Page | | | |



| Module:7 | Feedback Amplifiers and Oscillators | 3 Hours |
|---------------|---|------------------------------------|
| Basic concep | ts of feedback-Negative feedback advantages and ty | pes. Voltage/Current Series/Shunt, |
| Positive feed | back, Stability, Conditions for Oscillations RC and I | C oscillators. |

| Mod | lule:8 | Contemporary issues: | | | | 2 Hours | | |
|------|-----------|--|---------------------|--|-----------------|------------------|--|--|
| | | | Total Lecture h | ours: | | 30 Hours | | |
| Text | t Book(s) | | | L. L | | | | |
| 1. | | A.S.Sedra, K.C. Smith, "I | Microelectronic C | ircuits: Th | eory with Appl | ications", 6Ed, | | |
| | | Oxford University Press, 2 | 013. | | | | | |
| Refe | erence B | ooks | | | | | | |
| 1. | | D.A. Neamen, Electronic C | Circuits – Analysis | and Desig | gn, 3Ed, McGrav | v Hill, 2011. | | |
| 2. | | David A. Bell, "Electronic | Devices and Circ | uits", 5ed, | Oxford Univers | ity Press, 2008. | | |
| 3. | | Behzad Razavi, Fundamen | tals of Microelect | conics, 3Ec | l, Wiley, 2013. | | | |
| 4. | | Ben Streetman, Sanjay Bar | nerjee, Solid State | Electronic | Devices, 7ED, 1 | Pearson, 2014. | | |
| Mod | le of Eva | luation: CAT / Assignment / | / Quiz / FAT / Pro | ject / Semi | nar | | | |
| List | of Chall | enging Experiments (Indic | cative) | | | | | |
| 1. | Realiza | tion of logic gates using dio | des | | | 2 hours | | |
| 2. | Design | line and load voltage regula | tion circuits using | Zener dio | de | 2 hours | | |
| 3. | Design | a capacitor for a rectifier cir | cuit | | | 2 hours | | |
| 4. | Design | various clamping circuits us | sing diode | | | 2 hours | | |
| 5. | Design | various clipping circuits usi | ng diode | | | 2 hours | | |
| 6. | Design | the circuit using BJT as a s | witch in an alarm | system | | 2 hours | | |
| 7. | | the h-parameters for diffe characteristics | rent configuration | ns in BJT | using input – | 2 hours | | |
| 8. | Design | the circuit for a verification pair | on of BJT as a sw | vitch and a | amplifier using | 2 hours | | |
| 9. | Design | the circuit to perform DC a | nalysis of a BJT | | | 2 hours | | |
| 10. | | ng characteristics of MOSF | | | | 2 hours | | |
| 11. | | the circuit for verifying UJT | | vitch | | 2 hours | | |
| 12. | 0 | a RC coupled amplifier | | | | 2 hours | | |
| 13. | Design | a common collector amplifi | er | | | 2 hours | | |
| 14. | - | a common source FET amp | | | | 2 hours | | |
| | | 1 | | Total Lab | oratory Hours | 30 hours | | |
| Mod | le of Eva | luation: Assignment /FAT | | | - | | | |
| | | ed by Board of Studies | 29/05/2015 | | | | | |
| | | Academic Council | 37 th AC | Date | 16/06/2015 | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE2002.1 | 2 | 1 | | | | | | | | | | | | | |
| EEE2002.2 | 3 | 3 | 2 | 2 | | | | | | | | 1 | | 3 | |
| EEE2002.3 | 2 | 1 | | | | | | | | | | 1 | | 1 | |
| EEE2002.4 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 2 | | 1 | 2 | 2 | 2 |
| EEE2002.5 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 2 | | 2 | 2 | | 2 |
| EEE2002.6 | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 3 | 2 | 2 | 3 | 2 | 2 |
| | 3 | 3 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 3 | 2 | 2 | 3 | 2 | 2 |



| | | (Deemed to be University under section 3 of UG | | |
|-----------------|--------------------|---|---------------------|--|
| EEE2005 | | Digital Signal Processing | S | L T P J C |
| | | | | |
| Pre-requisite | | EEE1005 | | Syllabus version |
| Anti-requisi | | NIL | | v. 2.0 |
| Course Obje | | | | |
| U | | ar Time-Invariant (LTI) discrete-time system | | |
| - | | ers using impulse invariance & bilinear transf | ormation technic | lues |
| 0 | | ers using various window functions | | |
| | | lge and ability to use the appropriate tools lik | e digital signal p | rocessors to |
| | - | ms for real time problems | | |
| Expected Co | | | | |
| | | f this course the student will be able to: | | |
| | | echniques to analyze the discrete time system | | |
| | | lters using Chebyshev and Butterworth polyr | | |
| | | using transformation techniques iii) Design of | of FIR filters usin | ig various windowing |
| techniques | | atmustures for digital filter realization | | |
| | | structures for digital filter realization Filter and adaptive filter to remove artefacts | and interference | for signal |
| processing ap | | - | | s for signal |
| | - | ations in Fixed point and floating point digitation | al signal process | ore |
| | | rmance characteristics of filters using simular | | |
| | | ligital signal processor | | F |
| | | | | |
| Module:1 | Frequ | ency Analysis of Signals and Systems | | 6 Hours |
| Review of | discrete | e -time signals and systems – Classific | ation, Z- | transform – ROC- |
| stability/caus | ality an | alysis, DTFT- Frequency domain sampling - | DFT-Properties- | Frequency analysis of |
| signals using | DFT-F | FT Algorithm-Radix-2 FFT algorithms-Appl | ications of FFT. | |
| | | | - | |
| Module:2 | | y and Design of Analog Filters | | 4 Hours |
| | | or analog low pass filter -Butterworth and C | hebyshev approx | kimations, frequency |
| transformatio | · · · | | T | |
| Module:3 | | n of IIR Digital Filters | | 4 Hours |
| | - | linear and Impulse Invariant Transformation | techniques - Spe | ctral transformation of |
| digital filters | • | | | |
| Module:4 | Desim | n of FIR Digital Filters | | 4 Hours |
| | | Phase and group delay - Design characteris | tics of FIR filter | |
| | 0 | of linear phase FIR filters – Design of FIR | | 1 |
| | - | d Blackmann window functions. | inters using Ite | in the second se |
| Training, Du | tiett un | Didekindini window functions. | | |
| Module:5 | Realiz | ation of Digital Filters | | 4 Hours |
| Direct Forms | I and I | I, Cascade, Parallel and Lattice structures. | | |
| | T .14 | | 1 | 4 77 |
| Module:6 | Filters interfe | | | 4 Hours |
| | i interta | arence | 1 | |
| Ontimum E | | he Wiener Filter, Adaptive filters and their ap | nlications | |



| Mod | ule:7 | Digital Signal Processors | 2 Hours |
|-------|-------------------|---|-------------------|
| Gene | eral-purp | pose digital signal processors - Fixed point and floating point DSP - Fi | inite word length |
| effec | ts - M | AC, filter operation in different DSP architectures - typical implementation | nentation of DSP |
| algor | rithms. | | |
| Mod | ule:8 | Contemporary issues: | 2 Hours |
| 11100 | uiero | Total Lecture hours: | 30 Hours |
| Text | Book(s |) | |
| 1. | | John G. Proakis, D.G. Manolakis and D.Sharma, "Digital Sign Principles, Algorithms and Applications", 4th edition, Pearson Education | e |
| 2. | | Sanjit K. Mitra, Digital Signal Processing, 4th edition, TMH, 2013. | , |
| Refe | rence B | ooks | |
| 1. | | Sophocles J. Orfanidis, "Introduction to Signal Processing" 2nd ed Hall, Inc, 2010 | lition, Prentice |
| 2. | | Oppenhiem V.A.V and Schaffer R.W, "Discrete – time Signal Predition, Pearson new international edition, 2014. | rocessing", 3rd |
| 3. | | Lawrence R Rabiner and Bernard Gold, "Theory and Application of D Processing", Pearson India Education Services, 2016. | igital Signal |
| 4. | | Emmanuel C. Ifeachor, "Digital Signal Processing- A Practical A edition, Prentice Hall, 2011. | Approach" 2nd |
| Mod | e of Eva | luation: CAT / Assignment / Quiz / FAT / Project / Seminar | |
| List | of Chal | lenging Experiments (Indicative) | |
| 1. | Analy | sis of continuous time and discrete time signals. | 2 hours |
| 2. | 10-tern approx | er a symmetric square wave with frequency 100 Hz. Plot the 4-term, n and 25-term Fourier series approximations. Compare the FS imations with the actual square wave. Observe the approximation or at the points of discontinuity. | 2 hours |
| 3. | | a program to convolve two discrete time square pulse signals. Observe ects of repeated convolution with a square pulse. | 2 hours |
| 4. | - | the effects of signal length and windowing on the spectrum of a signal ted with FFT. | 2 hours |
| 5. | | e frequency response and impulse response of an ideal discrete-time ss filter. | 2 hours |
| 6. | • | the effect of the following window functions on the magnitude of quency response: Rectangular, Hamming and Blackman. | 2 hours |
| 7. | Genera frequer | te a sinusoidal signal which contains 50Hz, 70Hz, 100Hz and 120Hz ncies. Analyse the frequency components present in the signal with and t AWGN for a SNR of 0.6. Obtain the plot and comment on the | 2 hours |
| 8. | - | an IIR filter to filter out noise from the sinusoidal signal for the ing specifications. Plot the spectra. Comment and infer your results. Type of filter: Butterworth Pass band frequency: 100 Hz; Stop band frequency: 150 Hz Pass band ripple: 0.1 dB; Stop band ripple: 40 dB | 2 hours |



| 9. | Design a FIR filter and estimate | the filter coefficie | ents for th | e following | 2 hours | | |
|--|--------------------------------------|----------------------|-------------|----------------|---------|--|--|
| | specifications. Plot, comment and in | nfer your results. | | | | | |
| | Type of filter: Band stop | | | | | | |
| | Order of the filter: 10 | | | | | | |
| | Pass band frequency: 200 H | Hz. | | | | | |
| 10. | Design Chebyshev Type 1 and Typ | e 2 high pass and | band pass a | analog filters | 2 hours | | |
| | for the following specifications. | | | | | | |
| | Passband ripple =0.04dB; | | | | | | |
| | Stopband attenuation= 30dl | 3 | | | | | |
| | Passband frequency $= 400$ H | Iz ; Stopband frequ | uency = 80 | 0Hz | | | |
| | Sampling frequency $= 2000$ |)Hz | | | | | |
| | Plot their magnitude and phase chan | racteristics. | | | | | |
| 11. | Signal processing methods for Mus | ic Signals using D | SP Process | sor | 2 hours | | |
| 12. | Signal processing mechanisms for I | Bio-Signals using I | DSP proce | ssor | 2 hours | | |
| | | ratory Hours | 30 hours | | | | |
| Mod | Mode of Evaluation: Assignment /FAT | | | | | | |
| Recommended by Board of Studies 05/03/2016 | | | | | | | |
| Appi | roved by Academic Council | 40 th AC | Date | 18/03/2016 | | | |
| | | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE2005.1 | 3 | 2 | 1 | 1 | | | | | | | | 1 | | 2 | |
| EEE2005.2 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 1 | | 1 | 3 | 2 | 2 |
| EEE2005.3 | 3 | 2 | 1 | 1 | 1 | | | 1 | 1 | 1 | | 1 | 2 | 2 | 1 |
| EEE2005.4 | 3 | 3 | 2 | 2 | 1 | | | 1 | 1 | 1 | | 1 | 2 | 2 | 1 |
| EEE2005.5 | 2 | 1 | | | | | | | | | | 1 | | | |
| EEE2005.6 | 3 | 3 | 2 | 2 | 3 | | | 2 | 2 | 2 | | 2 | 2 | 3 | 3 |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 2 | - | 2 | 3 | 3 | 2 |



| FFF2 004 | | (Deemed to be University under section 3 of UGC A | | |
|-----------------|------------------|--|---------------------------|---------------------|
| EEE3001 | | Control Systems | | |
| D | 4 - | | | |
| Pre-requisi | te | EEE2001, MAT2002/EEE1001 | | Syllabus version |
| Course Oh | inativos | | | v. 1.0 |
| Course Ob | | | nol an air a arin a m | husical austam |
| | | ar exposition of the classical methods of cont ic principles of frequency and time domain d | | |
| | | ctical control system design with realistic sys | 0 1 | |
| | | whedge of state variable models and fundation | | |
| design | | when the state variable models and fund | inclutions c | i state recebuck |
| design | | | | |
| Expected C | Course | Outcome: | | |
| - | | of this course the student will be able to: | | |
| | - | ansfer function model for electrical, mechani | cal and electrome | chanical systems |
| 2. Analyze | the time | e response characteristics of given first and se | econd order system | m for various inpu |
| signals | | | | |
| | | stability of linear systems using root locus to | | |
| | | nse specifications using bode and polar plot i | ii)Determine the s | stability of linear |
| | | equency domain | | 1-4 |
| | | ators and controllers for the given specificati em using state space model | ions using bode pl | ιοι |
| | | Formance of the designed controller by condu | icting suitable exr | periments |
| 0. 1 mary 20 | une peri | ormanee of the designed controller by cond | iering surtuere exp | |
| Module:1 | Syster | ms and their Representations | | 6 hours |
| Basic eleme | ents in c | control systems - open loop & closed loop - T | Fransfer functions | of mechanical, |
| electrical an | nd analo | ogous systems. Block diagram reduction - sig | nal flow graphs. | |
| | | | | |
| Module:2 | | Response Analysis | | 6 hours |
| | | ls, Time response of first and second order s | ystem, Time doma | ain specifications, |
| Steady state | e error, e | error constants, generalized error coefficient. | | |
| Module:3 | Stabil | lity Analysis and Root Locus | | 6 hours |
| Stability - c | concept | and definition, Characteristic equation – L | ocation of poles | - Routh Hurwitz |
| criterion - R | Root loc | us techniques: construction, properties and a | pplications. | |
| | | | | |
| Module:4 | - | iency Response Analysis | | 6 hours |
| Bode plot - | Polar p | lot - Correlation between frequency domain | and time domain | specifications |
| Madula,5 | Stab: | iter in Fragman av Damain | | (have |
| Module:5 | | lity in Frequency Domain Gain margin, Phase margin, stability analysis | using fraguency | 6 hours |
| methods. N | vauist s | stability criterion. | using frequency i | response |
| | <u>, 1915t 5</u> | | | |
| Module:6 | Comp | pensator and Controller | | 7 hours |
| Realization | - | c compensators, cascade compensation in tin | ne domain and fre | quency domain, |
| | | ation - Design of lag, lead, lag-lead series cor | | |
| | | lers in frequency domain. | | |
| Module:7 | | Space Analysis | | 6 hours |
| | | variable and state model, Solution of state | | space to transfer |
| function con | nversio | n, Controllability, Observability, Pole placer | ment control | |
| | | | | Dago 01 |



| Mo | dule:8 Contemporary issues: | | 2 hours | |
|-----|--|------------------------|-------------------------------|------------------------------|
| | | | | 4.7. \ |
| | Total Lecture h | ours: | | 45 hours |
| Tex | tt Book(s) | | | |
| 1. | Norman S. Nise, "Control System Engineering", Jo | nn Wiley | & Sons, 6 th Editi | on, 2011. |
| 2. | Benjamin C Kuo "Automatic Control System" John | Wiley & | Sons, 8th Edition | n, 2007. |
| Ref | erence Books | - | | |
| 1. | K. Ogata, "Modern Control Engineering", Pearson, | 5 th Editio | n, 2010. | |
| 2. | R.C. Dorf & R.H. Bishop, "Modern Control System | s", Pearso | on Education, 11 | th Edition, 2008. |
| 3. | M. Gopal, "Control Systems-Principles And Design | ", Tata M | cGraw Hill –4 th | Edition, 2012. |
| 4. | Graham C. Goodwin, Stefan F. Graebe, Mario E. Sa Hall, 2003' | gado, " C | ontrol System D | esign", Prentice |
| 5. | J.Nagrath and M.Gopal," Control System Engineeri 4 th Edition, 2006. | ng", New | Age Internationa | al Publishers, |
| Mo | de of Evaluation: CAT / Assignment / Quiz / FAT / H | Project / S | eminar | |
| Lis | t of Challenging Experiments (Indicative) | | | |
| 1. | Block Diagram Reduction | | | 2 hours |
| 2. | Determination of Time Domain Specifications | | | 2 hours |
| 3. | Stability analysis of linear systems | | | 2 hours |
| 4. | PID Controller Design using Bode Plot | | | 2 hours |
| 5. | PID Controller Design using Root Locus | | | 2 hours |
| 6. | Compensator Design in Frequency and Time Doma | | | 2 hours |
| 7. | Transfer Function to State Space Conversion with Observability Tests | Controllal | oility and | 2 hours |
| 8. | Lag compensator design for linear servo motor for application | speed con | trol | 2 hours |
| 9. | Pole placement controller design for inverted pend | ulum | | 2 hours |
| 10. | PD controller design for position control of servo p | lant | | 2 hours |
| 11. | Cascade control design for ball and beam system | | | 2 hours |
| 12. | PID controller design for magnetic levitation system | n | | 2 hours |
| 13. | Transfer function of Separately excited DC generat | | | 2 hours |
| 14. | Transfer function of Field Controlled DC Motor | | | 2 hours |
| 15. | Study of First and Second order systems | | | 2 hours |
| | • | Total La | aboratory Hours | 30 hours |
| Mo | de of evaluation: CAM/ FAT | | - | |
| Rec | commended by Board of Studies 30/11/2015 | | | |
| App | proved by Academic Council 39th AC | Date | 17/12/2015 | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE3001.1 | 3 | 2 | 1 | 1 | | | | | | | | 1 | 2 | 2 | |
| EEE3001.2 | 3 | 3 | 2 | 2 | 1 | | | | | | | 1 | 2 | 3 | 1 |
| EEE3001.3 | 3 | 2 | 1 | 1 | 1 | | | 2 | 2 | 1 | | 1 | | 2 | 1 |
| EEE3001.4 | 3 | 3 | 2 | 2 | 2 | | | | | | | 1 | 3 | 3 | 2 |
| EEE3001.5 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 1 | | 1 | 3 | 3 | 2 |
| EEE3001.6 | 3 | 3 | 2 | 2 | 3 | | | 2 | 2 | 1 | | 2 | 3 | 3 | 3 |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 2 | 3 | 3 | 2 |



| EEE2002 | Analog and Digital Circuits | | L | T | P | J | С |
|----------------------------|---|--------------|------------|------|-------|------|------|
| EEE3002 | | | 3 | 0 | 2 | 0 | 4 |
| Pre-requisite | EEE2002 | | - | - | is ve | - | |
| Anti-requisite | NIL | | - J | | | | .2.0 |
| Course Objective | | | | | | | |
| ÷ | e functional building blocks, characteristics and appl | ications of | Analog | ICs | | | |
| | lifferent methods for design and implementation of I | | U | | | | |
| | e various applications of digital and analog ICs | e | | | | | |
| | | | | | | | |
| Expected Course | | | | | | | |
| - | n of this course the student will be able to: | | | | | | |
| | formance characteristics of Op-Amp | | | | | | |
| | p based circuits for various linear and non-linear app | | | | | | |
| - | er based multi-vibrators and fixed & variable voltage | - | | | | | |
| 4. Realization of I method | Boolean operations using De Morgan's laws, Karnau | gh map and | d Quine- | Mc | clus | ke | у |
| | binational circuit ii) Design of synchronous sequent | | | | | .:. | for |
| industrial control | equential circuit using state diagram and design of ar ol applications" | lalog/ulgita | al IC Das | eu | circi | 111 | IOF |
| | formance of linear & non-linear and sequential & contained ware experimentation | mbination | al circuit | us | ing | | |
| Module:1 Ope | erational Amplifier | | | | 61 | Ho | urs |
| - | The operational amplifier, Input resistance, Output | resistance, | Open lo | op | | | |
| | urrents, Offset voltage, Common mode rejection ratio | | - | - | - | | |
| | Differential amplifier.AC Performance - Frequency | | | | | | |
| | sation, Poles and zeros cancelation | - | | | - | | |
| | | | | | | | |
| Module:2 Opa | amp Applications | | | | 71 | Ю | urs |
| | ns of op-amp – summing, subtracting, averaging | g amplifier | r, voltag | ge t | c c | urr | ent |
| converter, curren | t to voltage converter, differentiator and integra | ator. Nonl | inear aj | opli | catio | ons | s – |
| comparator, Mult | ivibrators, Schmitt Triggers, Precision Diode, Half | wave and | full wa | ve | recti | ifie | ers, |
| Peak detector, Wa | ve form generators and Active Filters. | | | | | | |
| Module:3 Tim | ner And Power Supplies | | | | 51 | Но | urs |
| 555 Timer and i | ts applications, monostable multivibrator, Astable | multivib | ator. Li | nea | r vo | olta | age |
| regulator, 78XX a | nd 79XX family, 723 IC voltage regulator, Switching | g regulator | s. | | | | |
| Module:4 Dig | ital Techniques | | | | 61 | Но | urs |
| Dig | | | | | | | |



Number systems - Binary, octal and hexadecimal numbers. Binary codes, Logic Gates, Boolean algebra - Conversion and operations. De Morgan's laws, Truth tables, Karnaugh's map, Min term, Max term, SOP, POS, Synthesis of Boolean functions, Quine Mccluskey method.

| Module:5 | Combinational Circuit Design | 6 Hours | | | | | | | | |
|---|--|------------|--|--|--|--|--|--|--|--|
| Arithmetic circuits, Parity generator, Seven-segment display, Analysis and Design Procedure - | | | | | | | | | | |
| Multiplexer, | Decoder, Encoder, Design using programmable logi | c Devices. | | | | | | | | |
| Module:6 | Synchronous Sequential Circuit Design | 6 Hours | | | | | | | | |

Flip Flops - SR, D, T and JK Flip-flops, Master slave Flip Flops, Counters, Registers. Design using

State machines-Moore and Mealy machines, Design Examples.

| Module:7 | Asynchronous Sequential Circuit Design | 6 Hours |
|--------------|--|------------------------------------|
| Design Proc | edure- Asynchronous Sequential Circuits-State Di | agram-State assignment-implication |
| table-Design | examples. Applications: Temperature Indicator a | nd Controller, Speed control of DC |
| Motor using | Analog/Digital ICs | |

| Module:8 | Contemporary issues: | | 2 Hours | | | | | | | | |
|--------------|---|------------------------------------|----------------------------|--|--|--|--|--|--|--|--|
| - | Total Lecture hours: | | 45 Hours | | | | | | | | |
| | | | | | | | | | | | |
| Text Boo | k(s) | | | | | | | | | | |
| 1. | Op-Amps & Linear Integrated Circuits by Rama India, New Delhi, 4th edition, 2002. | kant Gayakwad, P | rentice Hall of | | | | | | | | |
| 2. | Digital Design by M. Morris Mano and Mictae Edition, 2013. | el Ciletti, Pearson | Education, 5 th | | | | | | | | |
| Reference | e Books | | | | | | | | | | |
| 1. | Operation Amplifiers & Linear Integrated Circuits | • • | hlin and Frederick | | | | | | | | |
| 2 | F. Driscoll, Prentice Hall of India, New Delhi, 6 th Edition, 2009. | | | | | | | | | | |
| 2. | Design with Operational Amplifiers & Analog Integrated Circuits by Sergio Franco, Tata McGraw Hill Education, 4 rd Edition, 2015. | | | | | | | | | | |
| 3. | Digital Fundamentals by Floyd, Madrid Pearson Ed | ducation, 11 th Edition | on, 2016. | | | | | | | | |
| 4. | Digital System Design using Verilog by Charles I | Roth, Lizy John and | l Byeong Kil Lee, | | | | | | | | |
| | Cengage Learning, 1 st Edition, 2016. | | | | | | | | | | |
| 5. | Electronic Principles by Albert Malvino, David.J. 8 th Edition, 2016. | Bates, Tata Mcgra | w Hill Education, | | | | | | | | |
| Mode of F | Evaluation: CAT / Assignment / Quiz / FAT / Project / S | Seminar | | | | | | | | | |
| 1110 00 01 1 | | | | | | | | | | | |
| List of Cl | nallenging Experiments (Indicative) | | | | | | | | | | |
| | ign and implementation of inverting and non-inverting | amplifier | 2 hours | | | | | | | | |
| | ign and implementation of precision rectifier using op-a | | 2 hours | | | | | | | | |
| 3. Des | ign and implementation of low pass and high pass filter | , | 2 hours | | | | | | | | |
| 4. Des | ign of implementation of integrator and differentiator u | sing op-amp | 2 hours | | | | | | | | |
| 5. Dest | ign and implementation of triangular wave generator us | ing op-amp | 2 hours | | | | | | | | |



| 6. | Design and implementation of summing and difference amplifier | 2 hours |
|-----|---|----------|
| 7. | Design and implementation of astable multivibrator | 2 hours |
| 8. | Design and implementation of half and full adder circuit | 2 hours |
| 9. | Design and implementation of multiplexer | 2 hours |
| 10. | Design and implementation of magnitude comparator | 2 hours |
| 11. | Design and implementation of BCD to 7 segment display | 2 hours |
| 12. | Design and implementation of code converters | 2 hours |
| 13. | Design and implementation of J,K and D flip flops | 2 hours |
| 14. | Design and implementation of shift registers | 2 hours |
| 15. | Design and implementation of synchronous decade counter | 2 hours |
| | Total Laboratory Hours | 30 hours |

| Mode of Evaluation: Assignment /FAT | | | |
|-------------------------------------|---------------------|------|------------|
| Recommended by Board of Studies | 05/03/2016 | | |
| Approved by Academic Council | 40 th AC | Date | 18/03/2016 |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE3002.1 | 2 | 1 | | | | | | | | | | | | | |
| EEE3002.2 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 1 | | 1 | 3 | 3 | 2 |
| EEE3002.3 | 3 | 2 | 1 | 1 | | | | | | | | 1 | 2 | 2 | |
| EEE3002.4 | 3 | 2 | 1 | 1 | 1 | | | | | | | 1 | 2 | 2 | 1 |
| EEE3002.5 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 1 | | 1 | 3 | 3 | 2 |
| EEE3002.6 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 1 | | 2 | 3 | 3 | 2 |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 2 | 3 | 3 | 2 |



| EEE4001 | | (Deemed to be University under section 3 of UGC Act, 1956) | Т | Т | PJ | JC |
|----------------|------------|--|---------------|------|------------|--------|
| EEE4001 | | Microprocessor and Microcontroller | | | | |
| D | | | 2 | 0 | | 0 3 |
| Pre-requisite | | EEE3002 | Sylla | bus | | |
| Anti-requisit | | NIL | | | V | 7. 2.0 |
| Course Obje | | | | | | |
| - | | he hardware functionality of Intel 8051 and ARM | | | | |
| | | ntial knowledge on operating modes of I/O ports ,Timers/Cour | nters, co | ontr | ol | |
| | | s types of interrupts. | | | | |
| | | s interfacing techniques. | | | | |
| Expected Co | | | | | | |
| On the compl | etion o | f this course the student will be able to: | | | | |
| 1 Internet th | a anahi | testure of microprocessor and classify the different modes of | | | | |
| | | tecture of microprocessor and classify the different modes of a actions and differentiate the instruction under various categorie | | | | |
| | | oblems using ARM | 63 | | | |
| | - | knowledge on the complete architecture of 8051 microcontroll | er | | | |
| - | | ictions and write simple programs using 8051 microcontroller | | | | |
| | | is interrupts and write programs to handle interrupts | - | | | |
| | | ntroller based embedded systems by interfacing external devic | ces | | | |
| - | | uct experiments, as well as analyze and interpret data | | | | |
| C | | | | | | |
| | | | | | | |
| Module:1 | Intro | luction to ARM Processor | | | 4 H | ours |
| Introduction | to RIS | SC processor – Comparison between CISC and RISC - C | Overvie | w | | |
| | | ent modes of ARM processor – Program status register | | | | |
| | | | | | | |
| Module:2 | ARM | Instruction Set | | | <u>3 H</u> | ours |
| Data transfer | instru | ction - Arithmetic instruction - Logical Instruction - Mu | ltiply in | nstr | uctio | on – |
| | | Load/Store instruction – Swap instruction. | 1 5 | | | |
| | | L L | | | | |
| Module:3 | Progr | amming using ARM Processor | | | 2 H | ours |
| | 0 | quation – generation of square wave form – Memory operation | IS | | | |
| | | | | | | |
| Module:4 | 8051 | Microcontroller Architecture | | | <u>4 H</u> | ours |
| | | 1 Micro controller – Program Status Register – Structure | of Rand | lom | | |
| | | Function Registers - Pin diagram of 8051 Microcontrolle | | | | |
| microcontrolle | - | Tunction Registers - The diagram of 6051 Wherecontrolle | <i>I</i> – 10 | 115 | 01 (| 5051 |
| Module:5 | | uction set of 8051 microcontroller | | | 2 11 | ours |
| | | | turation | 9 | | |
| | | ctions – Arithmetic and Logical Instructions – Boolean Ins | | | | |
| | | 6 – Programming using 8051 microcontroller – Demonstrat | 1011 01 | HE. | A 111 | le |
| generation and | u progi | ram execution. | | | | |
| Module:6 | 8051 M | Microcontroller Programming | | | <u>5 H</u> | ours |
| | | ports - Different modes of timer programs – Counters – Transfe | erring d | ata | ~ 11 | J MI D |
| • | U 1 | lata serially - Interrupts and Interrupt Handling – Interrupt price | 0 | uia | | |
| Module:7 | | Cacing Techniques | | | 7 H | ours |
| | | nong - company | | | , 11 | |



Interfacing of Analog to Digital Converter – Digital to Analog Converter – Sensor Interface – Keypad Interface.Display Interface: 7 segment interface – LCD.Communication Interface: GSM – Xbee – GPS – Bluetooth.

| Mod | lule:8 | Con | temporal | y issues | : | | | | 2 Hours |
|------|---------|-----------|------------|-----------|------------|-------------------------------|------------------|---------|-------------------------------|
| | | | | | Tota | l Lecture hours | s: | | 30 Hours |
| Text | t Book | (s) | | | | | | | |
| 1. | | Andre | w N Slos | s , Domi | nic Sym | es , Chris Wrigh | t, " ARM Syster | m Dev | veloper's Guide: |
| | | Desig | ning and | Optimi | zing Sys | stem Software | ", Morgan Kau | ıfman | n Publishers, 1 st |
| | | editio | n, 2009. | | | | | | |
| 2. | | | | | | | | 1 Mic | crocontroller and |
| | | | dded Sys | tems ", P | earson e | ducation, 2 nd Edi | ition, 2014. | | |
| | erence | | | | | | | | |
| 1. | | | | | | o controller", Th | | - | |
| 2. | | | runa Saga | | | | ford : Alpha Sci | | |
| 3. | | | | | | ture System on C | | ', Apre | ess, 2013. |
| Mod | le of E | valuation | : CAT / A | Assignme | ent / Quiz | z / FAT / Project | / Seminar | | |
| | | | | | | | | | |
| | | | g Experin | | |) | | | |
| 1. | - | | arithmet | - | | | | | 2 hours |
| 2. | | 1 0 | um to solv | 0 | - | | | | 2 hours |
| | ` | | + A2B + | | , , | A+B+C) | | | |
| | | | 8 & C are | | | | | | |
| 3. | Write | 1 0 | - | | following | g data transfer | | | 2 hours |
| | | | M to RA | | | | | | |
| | | | OM to RA | | | | | | |
| | | | TERNAI | | ERNAL | | | | |
| | | | M to EX | | | | | | |
| 4. | | | llowing E | | | | | | 2 hours |
| 5. | Write | | um to perf | | | | | - | 2 hours |
| | | Option | 0 | 1 | 2 | 3 | 9 | | |
| | | Task | A + B | ~B +1 | A*B | $AB + \sim A \sim B$ | ~A +1 | | |
| | | Option | 4 | 5 | 6 | 7 | 8 | | |
| | | Task | A A to | 55H | A ^ B | ~A | ~B | | |
| | | | P1 | to P1 | | | | | |
| 6. | | | - | | | g wave forms. | • • • • • | | 2 hours |
| | a. | | | quare wa | ave on PC | 0.0. use Timer 1 | in mode 1. Assu | ıme | |
| | | L = 16M | | oue ferre | on DO | | | | |
| 7 | b. | | ate step w | | | <u> </u> | | 04040 | 2 hours |
| 7. | | | | | S WIT | n 8051 microcor | nroner also gen | erate | 2 hours |
| Ŷ | | | ing LED' | |) Uz | | 1 normally 1 | Thor | 2 hours |
| 8. | | | - | | - | are wave on P1 | - | | 2 hours |
| | | - | fAL = 11 | | - | wave on P1.1. | Use unier U in I | noue | |
| | 1. A | ssume A | IAL - II | .0372 IVI | 112. | | | | |



| 9. | Write a program to display the foll | owing sequence in | 7 segmen | t display. | 2 hours | | | | | | |
|-----|--|-------------------|------------|---------------|----------|--|--|--|--|--|--|
| | 0 - 2 - 4 - 6 - 8 | | | | | | | | | | |
| 10. | | | | | | | | | | | |
| | $Ab^2 + c^2d$ where, a,b,c,d are 16 bit numbers. | | | | | | | | | | |
| | | r - | Fotal Labo | oratory Hours | 30 hours | | | | | | |
| | Mode of Evaluation: Assignment / FAT | | | | | | | | | | |
| Mod | le of Evaluation: Assignment / FAT | | | | | | | | | | |
| | le of Evaluation: Assignment / FAT prommended by Board of Studies | 05/03/2016 | | | | | | | | | |

| ~~~ | | | | | | | | | | | | | | | |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE4001.1 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | - | - | - | - | 1 | 2 | - | - |
| EEE4001.2 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | - | - | - | - | 1 | 2 | - | - |
| EEE4001.3 | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 1 | 3 | 3 | 2 |
| EEE4001.4 | | | | | | | | | | | | | | | |
| | 2 | 1 | - | - | - | - | - | - | - | - | - | - | - | - | - |
| EEE4001.5 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 1 | 3 | 3 | 2 |
| EEE4001.6 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 1 | 3 | 3 | 2 |
| EEE4001.7 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 1 | - | 1 | 3 | 3 | 2 |
| EEE4001.8 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 3 | - | - | 2 | 2 | 1 | - | 2 | 3 | 3 | 3 |
| | 3 | 3 | 2 | 2 | 3 | - | - | 2 | 2 | 1 | - | 2 | 3 | 3 | 3 |



| EEE4021 |) | | _ | | _ | |
|---|---|--|--|---|--|---|
| | | Sensors and Signal Conditioning | L | Т | ΡJ | |
| | | | 3 | 0 | 2 0 | - |
| Pre-requisite | PHY 1001, EE | CE3002 | Sylla | bus | | |
| Anti-requisite | | | | | v. | 1.0 |
| Course Object | tives: | | | | | |
| 1. To give an | nderstanding of the ge | eneral concepts and terminology of measurement | nt syste | ms | and | |
| transducer cla | sifications. | | | | | |
| 2. To introduc | e the basics of various | sensors and transducers and their construction. | | | | |
| 3. To describe | the principle of operat | tion and function of sensors. | | | | |
| 4. To teach the | design of signal cond | litioning circuits. | | | | |
| ^ | rse Outcome: | | | | | |
| 1. Explain the | static and dynamic of | characteristics of transducers, standards, calibr | ation ar | nd e | rror | |
| | neasurement system | | | | | |
| | | sensors for measurement of various physical p | | ers | | |
| | | or measurement of various physical parameters | | | | |
| | | ng circuits for resistive sensors ii)Design vario | us signa | al | | |
| | for reactance variation | | • .1 | | • | |
| | | sors and its signal conditioning circuits ii)Expl | ain the | peri | orma | ince |
| | | magnetic ,Optical and Digital Sensors | | | | |
| 6. Analyze the | performance characte | eristics of various measurement systems | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| Module:1 | | | | | 7 Ho | iire |
| | General concepts and | l terminology of measurement systems, Transd | ucers cl | | | |
| | | , Static and dynamic characteristics of a mea | | | | |
| | | ad statistical analysis in measurement systems. | | | | |
| | ata in measurement sy | | , 10450 | que | | . 01 |
| 1 | Resistive Sensors | | | | 5 Ho | urs |
| | | olumn and Ring type force, torque measuremer | nt Piezo | | | |
| | | -types and applications-linearization, Magne | | | | |
| | inclinition models | types and applications intearization, magne | to resig | stor | s Li | σni |
| dependent res | | | to resis | stor | s, Li | gnt |
| dependent resi Module:3 | stors. | | to resis | | | |
| Module:3 | stors. Reactance Variation | Sensors | | | 4 Ho | urs |
| Module:3 Capacitive set | stors. Reactance Variation sors-variable-differen | Sensors tial, Inductive sensors- variable reluctance-ed | | | 4 Ho | urs |
| Module:3 Capacitive set Synchros-reso | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag | Sensors tial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive | | rent | 4 Ho -LVI | urs DT- |
| Module:3Capacitive serSynchros-resoModule:4 | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning fo | Sensors tial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive or resistive sensors | ldy cur | rent | <mark>4 Ho</mark> -LVI 5 H o | urs DT- urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage divide | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for | Sensors Itial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive Itial sensors or resistive sensors Itial sensors voltage dividers, Wheatstone bridge- balant | ldy curr | rent | 4 Ho -LVI 5 Ho remen | urs DT- urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection me | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for sourements- sensitivity | Sensors | ldy curr | rent | 4 Ho -LVI 5 Ho remen | urs DT- urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential at | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for surements- sensitivity d Instrumentation amp | Sensors | ldy curr | rent asui | 4 Ho -LVI 5 Ho remen bridg | urs DT- urs nts- ges, |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5 | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for surements- sensitivity d Instrumentation amp Signal conditioning for | Sensors | ldy curr nce me ive sens | rent asui sor | 4 Ho -LVI 5 Ho remen bridg 5 Ho | urs DT- urs nts- ges, urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges, | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for usurements- sensitivity d Instrumentation amp Signal conditioning for Dependion Amplifier | Sensors Itial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive Itial, Inductive sensors or resistive sensors Itial, Inductive sensors voltage dividers, Wheatstone bridge- balanty, linearity, and analog linearization of resistive plifiers. Grounding and Isolation or reactance variation sensors Itial based inductance and capacitance measuring | ldy curr nce me ive sens | rent asui sor | 4 Ho -LVI 5 Ho remen bridg 5 Ho | urs DT- urs nts- ges, urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers and | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for surements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig | Sensors | ldy curr nce me ive sens | rent asun sor uits | 4 Ho -LVI 5 Ho remen bridg 5 Ho , car | urs DT- urs nts- ges, urs rier |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers andModule:6 | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for usurements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig Self-generating Sense | Sensors tial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive or resistive sensors voltage dividers, Wheatstone bridge- balan y, linearity, and analog linearization of resistive plifiers. Grounding and Isolation or reactance variation sensors based inductance and capacitance measuring gnal conditioning | ldy curr nce mea ive sens | rent asun sor uits | 4 Ho -LVI 5 Ho remen bridg 5 Ho , car | urs DT- urs nts- ges, urs rier urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers andModule:6Thermocoup | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for usurements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig Self-generating Senso e, piezoelectric senso | Sensors tial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive or resistive sensors voltage dividers, Wheatstone bridge- balan y, linearity, and analog linearization of resisti plifiers. Grounding and Isolation or reactance variation sensors based inductance and capacitance measurir gnal conditioning ors-effect-materials-applications, pyroelectric | ldy curr nce mea ive sens ng circu sensor | rent asui sor uits | 4 Ho -LVI 5 Ho remen bridg 5 Ho , car 8 Ho effect | urs DT- urs nts- res, urs rier urs |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers andModule:6Thermocoupmaterials-app | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for surements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig Self-generating Sense e, piezoelectric sense lications, and electroc | Sensors | ldy curr nce mea lve sens ng circu sensor Chopp | asun sor uits s- o er a | 4 Ho -LVI 5 Ho remen bridg 5 Ho , car 8 Ho effect nd lo | urs DT- urs nts- es, trier urs w |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers andModule:6Thermocoupmaterials-appdrift amplifier | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for usurements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig Self-generating Sense e, piezoelectric sense lications, and electroc rs, electrometer and tra | Sensors tial, Inductive sensors- variable reluctance-ed gnetoelastic- magnetostrictive or resistive sensors voltage dividers, Wheatstone bridge- balan y, linearity, and analog linearization of resistive plifiers. Grounding and Isolation or reactance variation sensors based inductance and capacitance measuring gnal conditioning ors-effect-materials-applications, pyroelectric chemical sensors. Signal conditioning circuits: ans impedance amplifiers, charge amplifiers, no | ldy curr nce mea lve sens ng circu sensor Chopp | asun sor uits s- o er a | 4 Ho -LVI 5 Ho remen bridg 5 Ho , car 8 Ho effect nd lo lifier | urs DT- urs ats- ges, urs rier urs t- w s |
| Module:3Capacitive setSynchros-resoModule:4Voltage dividdeflection meDifferential atModule:5AC bridges,amplifiers andModule:6Thermocoupmaterials-appdrift amplifierModule:7 | stors. Reactance Variation sors-variable-differen vers- inductosyn- mag Signal conditioning for ers - amplifiers for surements- sensitivity d Instrumentation amp Signal conditioning for Operation Amplifier coherent detection, sig Self-generating Sense e, piezoelectric sense lications, and electroc rs, electrometer and tra Electromagnetic, Opt | Sensors | ldy curr ace mea we sens ng circu sensor Chopp bise in a | asun sor uits, s- o er a amp | 4 Ho -LVI 5 Ho remer bridg 5 Ho 5 Ho car 8 Ho effect nd lo lifier 9 Ho | urs DT- urs tits- tes, tier urs s urs |



Optical transducer, Photo emissive cells, Photoconductive cells, Photo diodes, Photo transistors, Photovoltaic cells – Measurement of physical quantities. Position encoders-absolute position encoder-incremental position encoder, Resonant sensors- sensors based on quartz resonators- digital quartz thermometer- quartz micro balance-quartz resonators for force and pressure sensing- quartz angular rate sensor, SAW sensors.

| Module | e:8 | Contemporary issues: | | 2 Hours |
|---------|--------|--|-------------------------|---------------|
| | | Total Lecture hours: | | 45 Hours |
| Text B | ook(s) |) | | |
| 1. | Pvt. | on Pallas-Areny,John G.Webster, "Sensors and S Ltd.,NewDelhi, 2nd Edition 2013. | | |
| 2. | 2nd | .S.Murthy, "Transducers and Instrumentation", Prent edition 2012. | ice Hall of India Learn | ing Pvt. Ltd. |
| Referen | | | | |
| 1. | 2004 | | | , 5th Edition |
| 2. | Patra | anabis, "Sensors and Transducers", Prentice Hall of Ir | dia, New Delhi, 2003. | |
| 3. | | Shawney, "A course in Electrical and Electronic r. npat Rai &Company, 18th Edition, 2010. | neasurement and Instru | umentation", |
| 4. | | n P. Bentley, "Principles of Measurement Systems", 31 gman Ltd, UK 2000 | d edition Addison Wes | ley |
| 5. | | b Fraden, "Handbook of Modern Sensors: Physics, D nce + Business Media, Inc, 3rd Edition, 2004. | esigns, and Application | n", Springer |
| | | luation: CAT / Assignment / Quiz / FAT / Project / Se | minar | |
| List of | Chall | enging Experiments (Indicative) | | Hours |
| 1. | S | train gauge based torque measurement | | 2 Hours |
| 2. | Т | emperature Measurement using RTD | | 2 Hours |
| 3. | Т | emperature Measurement using Thermistor | | 2 Hours |
| 4. | Т | emperature Measurement using J and K type Thermoo | ouples | 2 Hours |
| 5. | D | isplacement Measurement using LVDT | | 2 Hours |
| 6. | S | peed measurement using magnetic sensor | | 2 Hours |
| 7. | D | isplacement Measurement using Inductive Pickup | | 2 Hours |
| 8. | P | ressure Measurement using Diaphragm pressure gauge | 2 | 2 Hours |
| 9. | V | elocity measurement using Piezo-electric Transducer | | 2 Hours |
| 10. | A | cceleration measurement using Piezo-electric Transdu | lcer | 2 Hours |
| 11. | | esign a signal conditioning circuit for thermocompensation using K-type thermocouple and analyse i | 1 0 | 2 Hours |
| 12. | | besign the linearization circuit for the 5K Ω thermistor | * | 2 Hours |
| 13. | | The signal conditioning circuit using RTD PT10 0 °C to 100 °C to get an output voltage of 0 to 4 V | | 2 Hours |



| | Power dissipation = 30 mW | and test its perfo | ormance. | 2 Hours | | | | | | |
|--------|--|---------------------|-----------------|---------------|--|--|--|--|--|--|
| 14. | Design signal conditioning circuit for strain gauge sensor to compensate 2 Hours temperature effects. | | | | | | | | | |
| 15. | Design the signal conditioning circuit for the pressure cell using Piezo 2 Hours electric sensor having the sensitivity of 10mV/g. | | | | | | | | | |
| | | Т | otal Laboratory | Hour 30 Hours | | | | | | |
| Mode o | f Evaluation: Assignment /FAT | | | | | | | | | |
| Recom | nended by Board of Studies | 25/10/2017 | | | | | | | | |
| Approv | ed by Academic Council | 37 th AC | Date | 05/10/2017 | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4021.1 | 2 | 1 | | | | | | | | 1 | | 1 | 1 | 2 | 1 |
| EEE4021.2 | 3 | 3 | 2 | 1 | | | | | | 1 | | | 1 | 2 | 1 |
| EEE4021.3 | 3 | 3 | 2 | 1 | | | | | | 1 | | 1 | 1 | 2 | 1 |
| EEE4021.4 | 3 | 2 | 2 | | | | | 2 | 2 | 1 | | | 1 | 2 | 1 |
| EEE4021.5 | 2 | 1 | | | | | | 2 | 2 | 1 | | 1 | 1 | 2 | 1 |
| EEE4021.6 | 3 | 3 | 2 | 2 | 2 | | | 2 | 2 | 2 | | 2 | 1 | 3 | 2 |
| | 3 | 2 | 2 | 2 | 2 | - | - | 2 | 2 | 2 | - | 2 | 1 | 3 | 2 |



| EEE4031 | (Deemed to be University under section 3 of UGC Act, 1956) Electrical and Electronic Instrumentation | L T P J C |
|---------------|---|----------------------------|
| | | |
| Dro requisit | | |
| Pre-requisit | | Syllabus version v. 1.0 |
| Anti-requisi | | V. 1.0 |
| Course Obj | | |
| - | e basic understanding of electrical and electronic measurement systems | |
| limitations. | horough knowledge of varieties of measuring instruments, its operation | ig principies, and |
| | e basic understanding of data acquisition systems and virtual instrumer | ntation |
| | ourse Outcome: | Itation |
| | letion of this course the student will be able to: | |
| 1 | n the construction of various types of voltmeters, ammeters and watt- | meters ii) Explain the |
| | action and working principle of energy, magnetic power factor and high | |
| instrur | | , in voltage measuring |
| | an AC and DC bridges to measure the unknown resistance, capacitan | ce and inductance ii) |
| | a DC-AC potentiometer to measure the unknown voltage and resistant | |
| | n the construction and working principle of voltmeter, signal generato | |
| - | nction generator | |
| 4. Illustra | te the working principle of various signal analysers | |
| 5. Design | A/D and D/A converters for the given specifications | |
| 6. Condu | ct the hardware experiments to measure various electrical parameters | and data acquisition |
| using 1 | LabVIEW | |
| Module:1 | Electrical Measurements - I | 8 Hours |
| | ving coils, moving iron, dynamometer type, rectifier type, and the | |
| | arement: Hall effect Wattmeter, Thermal type wattmeter, Compensate | d wattmeter, Single |
| | ase power measurement. | |
| Module:2 | Electrical Measurements - II | 6 Hours |
| | surement: energy meter - Magnetic measurements: Ballistic tests - | Maximum demand |
| | neter - High voltage measurements. | |
| Module:3 | DC & AC Bridges | 6 Hours |
| | nunt type ohmmeter – Megger - DC Bridges: Wheatstone Bridge, Kelv | |
| - | well Bridge, Wien Bridge, Anderson, Hay, Desauty, and Schering Br | - |
| Module:4 | Potentiometers | 5 Hours |
| | ratio Bridges - Detectors in Bridge measurements - Wagner Ground | d connections - DC |
| | ntiometers: Various types, Working Principle and applications. | |
| Module:5 | Electronic Measurements | 6 Hours |
| | neasurement Design and Instruments: BJT, FET and MOSFET Voltme | |
| | neter, Digital Multi-meter – DSO - Signal Generation: Audio and Rac | no frequency signal |
| generators, F | function generator. | |
| Module:6 | Signal Analyzers | 5 Hours |
| | er - Spectrum analyzer - Frequency Measurement - Measurement of p | |
| - | neasurement. | |
| - muse ungie | | |



| Mod | ule:7 | Data Acquisition & LABVIEW | 7 Hours |
|-----------------|-----------------------|--|---------------------------------------|
| board Instru | ls - D/A Imentatio | rs: Types, resolution, dynamic range, accuracy, sampling concepts a converters: Types, D/A boards - Digital I/O boards - Counter/Timer on: Components of LabView - Front panel - LOOP Behaviou n - Block diagram - SubVI- DAQ cards and accessories-Data Acquis | I/O boards. Virtual Ir and inter loop |
| Moo | lule:8 | Contemporary issues: | 2 Hours |
| | | Total Lecture hours: | 45 Hours |
| Tex | t Book(s) |) | |
| 1. | | David A. Bell, "Electronic Instrumentation and Measurements", 3 rd I university press, New Delhi, 2013. | Edition, Oxford |
| 2. | | Cooper W.D and Helfrick A.D, "Modern Electronic Instr Measurement Techniques", 4 th Edition, Pearson India Education, 201 | |
| Ref | erence B | ooks | |
| 1. | | H.S. Kalsi, "Electronic Instrumentation", 3rd Edition, Mc-Graw Hill | education, 2015. |
| 2. | | A.K. Sawhney, "A Course In Electrical And Electronic M Instrumentation", Dhanpat Rai Publications, 2012. | Measurements And |
| 3. | | Jovitha Jerome, "Virtual Instrumentation using LABVIEW", Prentic | e Hall India, 2013. |
| Mod | le of Eva | luation: CAT / Assignment / Quiz / FAT / Project / Seminar | |
| List | of Expe | riments (Indicative) | |
| 1. | - | a bridge circuit to measure a resistance in low and medium range. | 2 hours |
| 2. | Design range n | a circuit to measure high values of current and voltage using low neters. | 2 hours |
| 3. | 0 | of inductance measurement bridge circuit. | 2 hours |
| 4. | - | of capacitance measurement bridge circuit | 2 hours |
| 5. | power | | 2 hours |
| 6. | wattme | a circuit for Calibrating the single phase electro dynamometer type ter with direct loading. | 2 hours |
| 7. | Design | a circuit for Calibrating the given voltmeter and ammeter. | 2 hours |
| 8. | | ement of insulation resistance using Megger. | 2 hours |
| 9. | | VI to acquire and process a real time signals using NI DAQ cards. | 2 hours |
| 10. | and act | p a VI to check the amplitude of sinusoidal signal for a pre-set value ivate the alarm if it exceeds the limit. | 2 hours |
| 11. | respons | | 2 hours |
| 12. | Develo | p a VI diagram to calculate the monthly EMI for a loan received. | 2 hours |
| 13. | Build a number | VI that reverses the order of an array that contains 100 random rs. | 2 hours |
| 14. | Build a | VI diagram using formula node in case structure palette. | 2 hours |



| 15. Develop a VI to check the amplit | pre-set value | 2 hours | | |
|--------------------------------------|---------------------|----------|----------------|----------|
| and activate the alarm if it exceed | | | | |
| | | Total La | boratory Hours | 30 hours |
| Mode of Evaluation: Assignment / FA | АT | | | · |
| Recommended by Board of Studies | 05/03/2016 | | | |
| Approved by Academic Council | 40 th AC | Date | 18/03/2016 | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4031.1 | 2 | 1 | | | | | | 1 | 2 | 1 | | 1 | 2 | 2 | 1 |
| EEE4031.2 | 3 | 2 | 1 | 1 | | | | 1 | 2 | 1 | | 1 | 3 | 2 | 1 |
| EEE4031.3 | 2 | 1 | | | | | | 1 | | | | 1 | 2 | 1 | 1 |
| EEE4031.4 | 2 | 1 | | | | | | | | | | 1 | 2 | 1 | 1 |
| EEE4031.5 | 3 | 3 | 2 | 2 | 2 | | | | 1 | 1 | | 1 | 3 | 3 | 2 |
| EEE4031.6 | 3 | 3 | 2 | 2 | 2 | | | 1 | 3 | 2 | | 2 | 3 | 3 | 2 |
| | 3 | 2 | 2 | 2 | 2 | - | - | 1 | 2 | 2 | - | 2 | 3 | 2 | 2 |



| EEE4032 | | Commented to be University under section 3 of UGC Act, 1956) Process Automation and Control | | L | Т | ΡJ | C |
|------------------------------|----------|---|----------|-------|------|-------|-------|
| | | | | 3 | 0 | 2 0 | 4 |
| Pre-requisite | | EEE3001, EEE4021 | S | - | ÷ | - | sion |
| Anti-requisite | | NIL | 5, | 'nu' | Jub | | . 1.0 |
| Course Objec | | | | | | • | . 1.0 |
| ÷ | | er to have successful career in process industries and motivat | e for l | nigh | er s | studi | es. |
| | | undation to solve control and instrumentation problems in | | | | | |
| problems. | U | 1 | | | | | |
| 4. Impart kno | owledge | e on advanced control strategies and industrial network proto | cols. | | | | |
| Expected Cou | urse Ou | utcome: | | | | | |
| 1 | | this course the student will be able to: | | | | | |
| , 1 | | thematical model for interacting, non-interacting, continuous | | | | | |
| · · · | ON -OI | FF, analog and digital PID controller using different tuning n | nethod | ls fo | r v | arioi | 18 |
| processes 2. i)Identify a | an annr | opriate final control element for a given application ii) Selec | rt an a | dva | nce | ed co | ntrol |
| | | en industrial process | Ju all a | uva | nec | u cu | muoi |
| | | ibsystems, HMI and SCADA for process automation | | | | | |
| | | gram and configure DCS to handle local and distributed auto | omatic | on ta | sks | 5 | |
| | | network protocols for the given automation task | | | | | |
| | | act experiments to control level, pressure, temperature proces | ss and | auto | oma | ate 3 | -axis |
| positioner, | , ріск а | nd place robotic arm and conveyor control | | | | | |
| Module:1 | Proces | s Dynamics: | | | | 8 H | ours |
| Need for proce | ess con | trol – Mathematical model of Processes – Interacting and nor | n-inter | acti | ng | syst | ems |
| – Degrees of | freedo | m – Continuous and batch processes – Self regulation – S | Servo | and | re | gula | tory |
| operations – L | Lumped | and Distributed parameter models. | | | | | |
| | | ol Actions & Tuning: | | | | | ours |
| | | off, proportional, integral and derivative controllers – P+I, P+ | | | | | |
| | | ID controller – Selection of control modes for different proce | | | | | |
| | | nd ¼ decay ratio - Tuning:- Process reaction curve method | | tinu | ous | cyc | cling |
| | - | oscillation Method. Direct Digital Control - Digital forms o | f | | | | |
| PID Controller | | | | | | | |
| | | Control Elements: | | 11 | | | ours |
| | | natic and electric actuators – Valve Positioner – Control Valv | | | | | |
| | | herent and Installed characteristics – Classification of cor | | | | 0 | |
| • • | 0 | , ball valves – Valve body – Commercial valve bodies – C ng – Selection criteria. | onuoi | val | ve | SIZII | iig – |
| | | s Control Strategies: | | | | 6 Ц | ours |
| | | ol – Ratio control – Cascade control – Inferential control | 1 (| Inli | | | |
| | | variable control – Case studies from distillation column and b | | - | | - | |
| | | ratio = Control - Case studies from distination contain and oontrol - Adaptive control - Dead - time Compensation - S | | • | | | vic |
| Algorithm. | | and raupare contor Deux and compensation D | | 100 | | /1 | |
| | Autom | nation Structure: | | | | 4 H | ours |
| | | 1 - Subsystems: Instrumentation- Measurement and data | acqui | sitio | | | |
| | • | rface: Definition, need, Hardware based, Software based: Op | - | | | | |
| | | rol unit (DACU) - Network Control Systems (NCS) - Supe | | | | | |
| - | | (SCADA) systems. | | - | | | |
| 1 | | · · · · | | | | | |



| Module:6 | Logical Control Units: | 5 Hours |
|--------------|--|--|
| - | ammable Logic Controller (PLC): Ladder Logic Programm | |
| Distributed | | cations, configuration and |
| | - Performance Criteria for DCS and other automation tool | |
| Module:7 | Instrumentation Standard Protocols: | 7 Hours |
| | tocol introduction, frame structure, programming, | |
| - | and Limitations. Foundation Fieldbus H1, introduced in the second s | |
| - | on, implementation examples, Benefits, Advantage protocols MODBUS - Device net – Profibus (Proce | |
| Industrial H | • | ess rield bus) – controlliet – cAiv - |
| Module:8 | Contemporary issues: | 2 Hours |
| mouncio | Total Lecture hours: | |
| Text Book | | |
| | ephanopoulos, G., 'Chemical Process Control - An | Introduction to Theory and Practice' |
| | arson India Education Services, 2015. | introduction to Theory and Tractice, |
| | rry L. M. Bartelt, 'Industrial Automated Systems: 1 | nstrumentation and Motion Control'. |
| | ngage Learning, 2011. | |
| | ank D. Petruzella, 'Programmable logic controllers', | McGraw Hill Education, 3rd Edition, |
| | 10. | , , , |
| Reference | Books | |
| 1. Se | borg, D.E., Edgar, T.F. and Mellichamp, D.A., 'Pro | ocess Dynamics and Control', Wiley |
| Jo | nn and Sons, 3 rd Edition, 2010. | |
| | ughanowr, D.R., 'Process Systems Analysis and C ition, 2009. | ontrol", McGraw -Hill International |
| | quette, B.W., 'Process Control Modeling, Design and | Simulation', Prentice Hall, 2010. |
| | rtis D. Johnson, 'Process Control Instrumentatio | n Technology', 8th Edition, 2006. |
| | ndon: Pearson, 2014. | |
| | aart A. Boyer, SCADA: 'Supervisory control and Da | ata Acquisition', ISA Publication, 4 th |
| | ition, 2010. | ~ • |
| Mode of E | valuation: CAT / Assignment / Quiz / FAT / Project / | Seminar |
| List of Ch | Illenging Experiments (Indicative) | |
| | mentation of Level control process using SCADA | 2 hours |
| - | mentation of Temperature process using SCADA | 2 hours |
| 1 | mentation of Pressure control process using SCADA | 2 hours |
| | sis of interacting and non-interacting systems | 2 hours |
| | al tank control using LabVIEW | 2 hours |
| | g of controllers for single loop and multi loop setup | 2 hours |
| | zing inherent and installed characteristics of control | valves 2 hours |
| | and Smith predictive control strategies using MATLA | |
| 9. Anal | vsis of timer and counter functions using PLC | 2 hours |
| 10. Batch | process control and Sequential control using PLC | 2 hours |
| 11. Cont | olling a pick and place robotic arm using PLC | 2 hours |



| 12. | Controlling a gantry crane using PL | 2 hours | | | | | | | | |
|------|--|---------|----|-----------|-------------|----------|--|--|--|--|
| 13. | Controlling a 3 axis positioner usin | 2 hours | | | | | | | | |
| 14. | Multi-level conveyor control using | 2 hours | | | | | | | | |
| 15. | HMI module interface and coding v | | | 2 hours | | | | | | |
| | | | To | tal Labor | atory Hours | 30 hours | | | | |
| Mod | le of evaluation: CAM / FAT | | | | | | | | | |
| Reco | Recommended by Board of Studies 05/03/2016 | | | | | | | | | |
| Rece | | | | | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4032.1 | 3 | 2 | 1 | 1 | 1 | | | 1 | 1 | 1 | | 1 | 1 | 2 | 2 |
| EEE4032.2 | 2 | 1 | | | | | | 1 | 1 | 1 | | | 2 | 1 | 1 |
| EEE4032.3 | 3 | 2 | 1 | 1 | 2 | | | 1 | | | | | 1 | 2 | 2 |
| EEE4032.4 | 3 | 2 | 1 | 1 | 2 | | | 1 | 2 | 2 | | 1 | 2 | 2 | 2 |
| EEE4032.5 | 3 | 2 | 1 | | 2 | | | 1 | | | | | 2 | 2 | 2 |
| EEE4032.6 | 3 | 2 | 1 | 1 | 3 | | | 2 | 3 | 2 | | 2 | 1 | 2 | 3 |
| | 3 | 2 | 1 | 1 | 3 | - | - | 2 | 3 | 2 | - | 2 | 2 | 2 | 2 |



| EEE4033 | Industrial Instrumentation | on L T P | J C |
|------------------|----------------------------|-------------|--------|
| | | 3 0 0 | 4 4 |
| Pre-requisite | EEE4021 | Syllabus ve | ersion |
| Anti-requisite | NIL | | v. 1.0 |
| Course Objective | | | |

Course Objectives:

1. To develop a better understanding of various sensors & instrumentation system applications in industrial monitoring and control.

2. To provide a good design level understanding of industrial measurement systems.

3. To understand the instrumentation methods available to monitor and control process variables like temperature, pressure flow & level.

Expected Course Outcome:

On successful completion of this programme the graduate will

- 1. i)Demonstrate the working principles of various pressure measurement techniques ii)Illustrate the various methodologies for wide range of flow measurement
- 2. i)Illustrate the principles of various temperature sensor based measurement system ii)Design various level measurement systems for the given specifications
- 3. Determine the response of force and torque sensor based measurement system
- 4. Illustrate the concepts and methods pertaining to speed measurement
- 5. Design various types of accelerometer for measuring the vibration
- 6. Develop a model/prototype for measurement system by applying the relevant standards with realistic constraints

Module:1 Pressure Measurement

Elastic type pressure gauges – Bourdon tubes, bellows, diaphragms; Electrical methods – elastic elements with LVDT and strain gauges – capacitive type pressure gauge – piezo resistive pressure sensor – resonator pressure sensor ; measurement of vacuum – McLeod gauge – pirani gauge - thermal conductivity gauges – Ionization gauge cold cathode and hot cathode types.

| Module:2 | Flow Measurements: | 7 Hours | | | | | | | |
|---|--|-------------------------------------|--|--|--|--|--|--|--|
| Pressure gra | dient techniques, Positive displacement flow meter | rs, turbine flow meter; Rotameter: | | | | | | | |
| Design- Coriolis mass flow meters - thermal mass flow meter - volume flow meter; Electrical type | | | | | | | | | |
| flow meter: Electromagnetic flow meter, different types of ultrasonic flow meters – laser doppler | | | | | | | | | |
| anemometer | systems; vortex shedding flow meter - target flow me | eter – solid flow rate measurement. | | | | | | | |
| Module:3 | Temperature, Measurements: | 6 Hours | | | | | | | |
| RTDs and Thermistor characteristics; Thermocouples-Laws, Principals, cold junction compensation; | | | | | | | | | |
| Radiation methods of temperature measurement total and selective radiation pyrometers – optical | | | | | | | | | |
| pyrometer; T | hermal conductivity measurements-liquids and gases. | | | | | | | | |

| N/- J1 4 | T 1 M 4 | |
|----------------|---|---|
| Module:4 | Level Measurements: | 6 Hours |
| Gauge glass | technique coupled with photo electric readout system; | float type level indication – different |
| schemes – 1 | evel switches level measurement using displacer a | and torque tube – bubbler system; |
| differential p | pressure method; electrical types of level gauges us | ing resistance, capacitance, |
| nuclear radia | tion and ultrasonic sensors. | |
| 36 1 1 5 | | |

Module:5 Force and Torque Measurements:

8 Hours



| Modu | le:6 | Speed measurement: | | | 6 Hours |
|--------|--------|---|--------------------------|-------------|----------------------------------|
| | | - | -drag cup type tach | o – D.0 | C and A.C tacho generators – |
| Strobo | | _ | | | |
| | - | | | | |
| Modu | le:7 | Vibration Measurement: | | | 6 Hours |
| Nature | of vi | brations – Seismic transduce | er – Types of acceler | ometers | - Potentiometric type - LVDT |
| Accele | eromet | er – Piezo electric type. | | | |
| | | | | | |
| Modu | le:8 | Contemporary issues: | | | 2 hours |
| | | | Total Lecture hou | rs: | 45 Hours |
| | | l | | | |
| Text H | Book(s |) | | | |
| 1. | | Patranabis, 'Principles of Ind | ustrial Instrumentation | n', Tata | McGraw Hill, 2010. |
| 2. | | | | | a Publishers, 6th edition New |
| | | hi 2010. | | , , | <i>,</i> |
| Refere | ence B | ooks | | | |
| 1. | J.P | Holman, 'Experimental Metl | hods for Engineers' T | 'ata McC | Graw Hill International, 2010. |
| 2. | Dor | ald. P Eckman, 'Industrial I | nstrumentation', CBS | publish | ners, 2012. |
| 3. | Doe | blein E.O, 'Measurement Sy | stems, Applications | and Desi | ign', McGraw Hill International, |
| | 201 | 3. | | | |
| | Ala | n S. Morris, 'Principles of M | easurement and Instr | umentat | ion', PHI, 2009. |
| 4. | | | 10 · 10 | + / Samir | 207 |
| | of Eva | luation: CAT / Assignment | / Quiz / FAT / Projec | t / Semm | lal |
| Mode | | luation: CAT / Assignment / ed by Board of Studies | 05/03/2016 | t / Sellill | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4033.1 | 3 | 2 | 1 | 1 | | | | 1 | | 1 | | 1 | 2 | 2 | |
| EEE4033.2 | 3 | 2 | 1 | 1 | | | | 2 | 1 | 1 | | 1 | 1 | 2 | 1 |
| EEE4033.3 | 3 | 2 | 1 | 1 | | | | 1 | | 1 | | 1 | 2 | 2 | |
| EEE4033.4 | 3 | 2 | 1 | 1 | | | | 1 | 1 | 1 | | 1 | 3 | 2 | |
| EEE4033.5 | 3 | 2 | 1 | 1 | | | | 1 | | 1 | | 1 | 2 | 2 | 2 |
| EEE4033.6 | 3 | 3 | 2 | 2 | 3 | 2 | 1 | 2 | 2 | 3 | 2 | 2 | 2 | 1 | 3 |
| | 3 | 3 | 2 | 2 | 3 | 2 | 1 | 2 | 2 | 2 | - | 2 | 3 | 2 | 2 |



| MAT20 | 02 Applications of Differential and Diff | orongo | L | Т | Р | J | С |
|-------------------|--|-------------|----------|-------|-------|--------|---------|
| | Equations | erence | | | T | J | C |
| | | | 3 | 0 | 2 | 0 | 4 |
| Pre-requisite | MAT1011 | | U | | | - | version |
| i i e i equisite | | | | v.1 | | | CISION |
| Course Object | ives | | | ,,1 | .0 | | |
| The course is a | | | | | | | |
| | he elementary notions of Fourier series, wh | nich is vit | tal in n | racti | cal l | narm | onic |
| analysis | | | mi iii p | 14011 | our i | 14111 | |
| • | he knowledge of eigenvalues and eigen vec | tors of m | atrices | and | the | trans | sform |
| | olve linear systems, that arise in sciences a | | | | | | |
| - | ne skills in solving initial and boundary val | 0 | U | | | | |
| | knowledge and application of difference | | | the | Z-tr | ansf | orm in |
| | is, that are inherent in natural and physical | | | | | | - |
| Expected Cou | · · · · · · · · · · · · · · · · · · · | 1 | | | | | |
| | ne course the student should be able to | | | | | | |
| 1. Employ the t | tools of Fourier series to find harmonics of | periodic | function | ons f | rom | the | |
| tabulated value | | 1 | | | | | |
| 2. Apply the co | oncepts of eigenvalues, eigen vectors and d | iagonalis | ation i | n lin | ear | syste | ems |
| | chniques of solving differential equations | C | | | | • | |
| 4. understand the | he series solution of differential equations a | and findi | ng eige | en va | lues | s, eig | en |
| functions of Str | rum-Liouville's problem | | | | | | |
| 5. Know the Z- | transform and its application in population | dynamic | es and | digit | al si | gnal | |
| processing | | | | | | | |
| 6. demonstrate | MATLAB programming for engineering | problems | | | | | |
| | | | | | | | |
| | Fourier series: | | | | | | 6 hours |
| | Euler's formulae - Dirichlet's conditions - | 0 | | erval | - Ha | alf ra | inge |
| | value – Parseval's identity – Computation of | of harmor | nics | | | | |
| | Matrices: | | | | | | 6 hours |
| Eigenvalues ar | nd Eigen vectors - Properties of eigenva | lues and | eigen | vec | tors | – (| Cayley- |
| | rem - Similarity of transformation - Orthog | onal tran | sforma | ation | and | nati | ure of |
| quadratic form | | | | | | | |
| | Solution of ordinary differential equation | | | | | | 6 hours |
| | order ordinary differential equation with c | | | | | | |
| | nd non-homogenous equations - Metho | | | | | | |
| | riation of parameters – Solutions of Ca | uchy-Eul | ler and | d Ca | uch | y-Le | gendre |
| differential equ | | 1 | | | | | |
| | Solution of differential equations throug | h | | | | 8 | 8 hours |
|] | Laplace transform and matrix method | | | | | | |



| ~ . | | (Deemed to be Univer | | | |
|-------|-------------|-------------------------------------|-------------------|---------------------------------|--------------|
| | | DE's - Nonhomogeneous terms in | | | |
| | | onhomogeneous system using La | | | |
| diffe | erential e | quation to first order system - So | lving nonhome | geneous system of | f first |
| orde | er differe | ntial equations $(X' = AX + G)_{a}$ | nd $X'' = AX$ | | |
| Mo | dule:5 | Strum Liouville's problems | and power | | 6 hours |
| | | series Solutions: | I | | |
| Th | e Strum-I | Liouville's Problem - Orthogonalit | v of Eigen fund | ctions - Series solu | tions of |
| | | equations about ordinary and regul | | | |
| | | on - Bessel's differential equation | <u>8</u> | 8 | |
| Mo | dule:6 | Z-Transform: | | | 6 hours |
| | | -transforms of standard functions | Inverse 7 tra | neform: by partial f | |
| | | tion method | - mverse z-ua | lisioini. Uy partiar i | lactions |
| | | | | | 5 hours |
| | dule:7 | 1 | | •.1 | 5 hours |
| | | uation - First and second order di | | | |
| | | equence - Solution of difference eq | | | |
| | | e method of undetermined coeffici | ients - Solution | of simple difference | ce equations |
| | g Z-trans | | | | |
| Mo | dule:8 | Contemporary Issues | | 2 hours | |
| Indu | istry Expe | ert Lecture | | | |
| | | Total Lo | ecture hours: | | 45 hours |
| Tex | t Book(s) | | | | |
| 1. | , | d Engineering Mathematics, Erv | vin Krevszig. | 10 th Edition, Joh | n Wilev |
| | India, 20 | U U | , | 10 D <i>u</i> 1001, 001 | |
| Ref | erence B | | | | |
| 1. | | Engineering Mathematics, B. S. Gr | wal 43rd Edi | tion Khanna Public | shers |
| 1. | India, 20 | 15 | | | |
| 2. | Advance | d Engineering Mathematics by M | ichael D. Greer | uberg, 2 nd Edition, | Pearson |
| | | on, Indian edition, 2006 | | - | |
| Mo | de of Eva | luation | | | |
| Dig | ital Assig | mments (Solutions by using soft | skills). Contin | uous Assessment | |
| 0 | | Final Assessment Test | ,, | | |
| 1. | - | g Homogeneous differential equati | ons arising in e | ngineering | 2 hours |
| 1. | problem | | | ngmeening | 2 1100115 |
| 2. | | g non-homogeneous differential eq | utions and Ca | uchy Legendre | 2 hours |
| 2. | equatio | | | deny, Legendre | 2 110013 |
| 3. | 1 | ng the technique of Laplace transf | orm to solve di | fforential | 2 hours |
| 5. | equatio | • • • | | ileieilliai | 2 110015 |
| 1 | - | | a avadiana ta N | [| 2 hours |
| 4. | 11 | ations of Second order differential | 1 | 1 0 | 2 hours |
| | | (damped, undamped, Forced oscil | | circuits etc. | |
| 5. | | zing Eigen value and Eigen vector | | | 2 hours |
| 6. | | system of differential equations a | arising in engin | eering | 2 hours |
| | application | tions | | | |
| 7. | Applyi | ng the Power series method to solv | ve differential e | quations arising | 2 hours |
| | in engi | neering applications | | 2 | |
| | | | | | |



| 8. | Applying the Frobenius method | l to solve diff | erential equation | ons arising in | 2 hours | | | | | | |
|--|--|-----------------|-------------------|----------------|----------|--|--|--|--|--|--|
| engineering applications | | | | | | | | | | | |
| 9. Visualising Bessel and Legendre polynomials | | | | | | | | | | | |
| 10. Evaluating Fourier series-Harmonic series | | | | | | | | | | | |
| 11. | Applying Z-Transforms to func | tions encount | tered in engine | ering | 2 hours | | | | | | |
| 12. | Solving Difference equations an | rising in engi | neering applica | tions | 2 hours | | | | | | |
| | | | Total Lab | oratory Hours | 24 hours | | | | | | |
| Mod | e of Evaluation: Weekly Assessm | nent, Final A | Assessment Te | st | | | | | | | |
| Reco | ommended by Board of Studies | 25-02-2017 | | | | | | | | | |
| Appr | Approved by Academic Council 37th AC Date 05-10-2017 | | | | | | | | | | |
| | | | | | | | | | | | |

| СО | | | | | | | | | | | | | | | |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| MAT2002.1 | | | | | | | | | | | | | | | |
| | 3 | 1 | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - |
| MAT2002.2 | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | - | - | - | - | - | 1 | - | 1 | - | - | - |
| MAT2002.3 | 3 | 1 | - | - | - | - | - | - | 1 | 1 | - | - | - | - | - |
| MAT2002.4 | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | 1 | - | - | - |
| MAT2002.5 | | | | | | | | | | | | | | | |
| | 3 | 2 | - | - | - | - | - | - | 1 | 1 | - | - | - | - | - |
| MAT2002.6 | 3 | 2 | - | - | 2 | - | - | - | 1 | 2 | - | 2 | - | - | - |
| | 3 | 2 | - | - | 2 | - | - | - | 1 | 2 | - | 2 | - | - | - |



| | Complex Variables and Partial Differential Equation | L | Τ | P | J | С |
|---|---|-------------------------------------|--------------------------------|--|------------------------------------|-----------------|
| | | 3 | 2 | 0 | 0 | 4 |
| Pre-requisite | MAT2002 | S | yllal | ous | vers | ion |
| | | | | | V. | 1.1 |
| Course Objec | | | | | | |
| most importan | s course is to present a comprehensive, compact and integrated t branches of applied mathematics for engineers and scientist omplex variable and Partial differential equations in finite and | s nam | ely t | he | | |
| Expected Cou | arse Outcome: | | | | | |
| At the end of t | he course the student should be able to | | | | | |
| | alytic functions and find complex potential of fluid flow and | elect | ric fi | elds | | |
| | age of straight lines by elementary transformations and | | | | | |
| | ytic functions in power series l integrals using techniques of contour integration | | | | | |
| | ial differential equations, and its applications, design the bound | dary y | value | nro | hlen | าร |
| | nal heat and wave equations) and find Fourier series, Fourier | luar y | varue | pro | UICII | 15 |
| | niques in their respective engineering problems. | | | | | |
| | | | | | | |
| | | | | | <u></u> | |
| | nalytic Functions | 1 | | | <u>6 ho</u> | urs |
| | ble-Analytic functions and Cauchy – Riemann equations - La ctions - Construction of Harmonic conjugate and analytic func | | | | | c |
| | ctions to fluid-flow and Field problems. | uons | - Apt | лса | uon | 3 |
| of analytic fai | | | | | | |
| | | | | | | |
| Module:2 | onformal and Bilinear transformations | | | | 5 ho | urs |
| | | on, rot | ation | | 5 ho | urs |
| Conformal ma | Conformal and Bilinear transformations pping - Elementary transformations-translation, magnification ponential and Square transformations ($w = e^z$, z^2) - Bilin | | | , | | |
| Conformal ma inversion. Exp | pping - Elementary transformations-translation, magnification | ear tra | ansfo | , rma | tion | |
| Conformal ma inversion. Exp | pping - Elementary transformations-translation, magnification ponential and Square transformations ($w = e^z$, z^2) - Bilin | ear tra | ansfo | , rma | tion | |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P | pping - Elementary transformations-translation, magnification conential and Square transformations ($w = e^z, z^2$) - Bilin ages of the regions bounded by straight lines under the above ower series | ear tra transf | ansfo forma | , rma atior | tion 1s. 4 ho | - |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P | pping - Elementary transformations-translation, magnification ponential and Square transformations ($w = e^z, z^2$) - Bilin ages of the regions bounded by straight lines under the above | ear tra transf | ansfo forma | , rma atior | tion 1s. 4 ho | - |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P Functions give | pping - Elementary transformations-translation, magnification conential and Square transformations ($w = e^z$, z^2) - Bilin ages of the regions bounded by straight lines under the above ower series on by Power Series - Taylor and Laurent series -singularities - | ear tra transf | ansfo forma | , rma atior , sidu | tion 1s. 4 ho es. | urs |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P Functions give Module:4 C | pping- Elementary transformations-translation, magnification bonential and Square transformations ($w = e^z, z^2$)- Bilin ages of the regions bounded by straight lines under the aboveower series-ower series-on by Power Series - Taylor and Laurent series -singularities -Complex Integration | ear tra transf | ansfo forma – Re | , rma atior , sidu 5 | tion 1s. 4 ho | urs |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P Functions give Module:4 C Integration of | pping- Elementary transformations-translation, magnification conential and Square transformations ($w = e^z, z^2$)- Bilin ages of the regions bounded by straight lines under the aboveower series | ear tra transf poles em- C | ansfo forma – Re auch | , rma atior sidu 5 y's | tion ns. 4 ho es. 5 ho | - urs urs |
| Conformal ma inversion. Exp Cross-ratio-Im Module:3 P Functions give Module:4 C Integration of | pping- Elementary transformations-translation, magnification bonential and Square transformations ($w = e^z, z^2$)- Bilin ages of the regions bounded by straight lines under the aboveower series-ower series-on by Power Series - Taylor and Laurent series -singularities -Complex Integration | ear tra transf poles em- C | ansfo forma – Re auch | , rma atior sidu 5 y's | tion ns. 4 ho es. 5 ho | - urs urs |
| Conformal ma inversion. Exp Cross-ratio-In Module:3 P Functions give Module:4 C Integration of integral formu integral. | pping- Elementary transformations-translation, magnification conential and Square transformations ($w = e^z, z^2$)- Bilin ages of the regions bounded by straight lines under the aboveower series | ear tra transf poles em- C | ansfo forma – Re auch | , rma atior sidu sidu 5 y's ed co | tion ns. 4 ho es. 5 ho | urs ur |



Formation and solution of partial differential equation - General, Particular, Complete and Singular integrals - Partial Differential equations of first order of the forms: F(p,q)=0, F(z,p,q)=0, F(x,p)=G(y,q) and Clairaut's form - Lagrange's equation: Pp+Qq = R.

Module:6 Applications of Partial Differential Equations

7 hours

2 hours

Linear partial differential equations of higher order with constant coefficients. Solution of a partial differential equation by separation of variables - Boundary Value Problems-one dimensional wave and heat equations- Fourier series solution.

Module:7 | Fourier transforms

Complex Fourier transform and properties - Relation between Fourier and Laplace transforms - Fourier sine and cosine transforms – Convolution Theorem and Parseval's identity.

Module:8Contemporary issues:Industry Expert Lecture

| | | | Total | Lectur | e hours: | 45 hours | | | | | |
|-----|------------------|--|---------------------|------------------|-------------------------|-------------------------------|--|--|--|--|--|
| Tut | torial | A minimum of 10 problems to be worked out by students inventory Tutorial Class Another 5 problems per Tutorial Class to be given as home work | | | | | | | | | |
| Tex | kt Book(| s) | | | | | | | | | |
| 1. | | ced Engineering Mathemat Wiley student Edison) (2013 | | eyszig, | 10 th Editio | on, John Wiley & | | | | | |
| Ref | ference l | Books | | | | | | | | | |
| 1 | 0 | Engineering Mathematics, hers, New Delhi | B. S. Grewal, | 43 rd | Edition (20 | 19), Khanna | | | | | |
| 2 | | course in complex analys tion, 2013, Jones and Bartl | 11 | | | | | | | | |
| 3 | | ced Engineering Mathemati ion (2006) | cs, Michael, D | . Gree | nberg, 2 nd | Edition, Pearson | | | | | |
| 4 | Advano (2012) | ced Engineering Mathemati | cs, Peter V. O | ' Neil, | 7 th Edition | , Cengage Learning | | | | | |
| 5 | | ex Analysis for Mathemat , Narosa Publishers (2013) | ics and Engine | ers, JH | I Mathews, | R. W. Howell, 5 th | | | | | |
| Mo | de of Ev | aluation: Digital Assignme | nts, Quiz, Con | itinuou | s Assessme | ents, Final Assessment Test | | | | | |
| Rec | commen | led by Board of Studies | 25-02-2017 | | | | | | | | |
| 1 | proved h | y Academic Council | 47 th AC | Date | 05-10-201 | - | | | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
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| | PUI | POZ | P05 | P04 | PUS | PU0 | PO/ | PU8 | P09 | POIU | POIT | POIZ | P301 | PS02 | P305 |
| MAT3003.1 | | | | | | | | | | | | | | | |
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| MAT3003.3 | - | 3 | - | - | - | 2 | - | - | - | - | - | - | 1 | - | 1 |
| MAT3003.4 | - | - | - | - | - | - | - | - | - | - | - | - | 2 | - | 1 |
| MAT3003.5 | | | | | | | | | | | | | | | |
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| MAT3005 Applied Numerical Methods L T P J 3 2 0 0 Pre-requisite MAT2002 Syllabus Version v.1.1 Voltabus Version v.1.1 Course Objectives v.1.1 Voltabus Version problems that arise in engineering and physical sciences. v.1.1 Voltabus Version 2. use MATLAB as the primary computer language to obtain solutions to a few problems that arise in their respective engineering courses. aimpart skills to analyse problems connected with data analysis, 4.solve ordinary and partial differential equations numerically Expected Course Outcome Voltabus Version version At the end of the course the student should be able to 1. Observe the difference between exact solution and approximate solution. version 2. Use the numerical techniques to find the solution of algebraic equations and system or equations. system or equations. 3. Fit the data using interpolation technique and spline methods. 4. Find the solution of ordinary differential equations, Heat and Wave equation numerically. 5. Apply calculus of variation techniques to extremize the functional and also fin approximate series solution to ordinary differential equations and also fin approximate series solution to ordinary differential equat |
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| Pre-requisite MAT2002 Syllabus Version Course Objectives v.1.1 The aim of this course is to 1. cover certain basic, important computer oriented numerical methods for analyzing problems that arise in engineering and physical sciences. 2. use MATLAB as the primary computer language to obtain solutions to a few problems that arise in their respective engineering courses. 3. impart skills to analyse problems connected with data analysis, 4. solve ordinary and partial differential equations numerically Expected Course Outcome At the end of the course the student should be able to 1. Observe the difference between exact solution and approximate solution. 2. Use the numerical techniques to find the solution of algebraic equations and system of equations. 3. Fit the data using interpolation technique and spline methods. 4. Find the solution of ordinary differential equations, Heat and Wave equation numerically. 5. Apply calculus of variation techniques to extremize the functional and also fin approximate series solution to ordinary differential equations |
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| Module:1 Algebraic and Transcendental Equations 5 hours |
| Module:1Algebraic and Transcendental Equations5 hours |
| |
| General iterative method- rates of convergence- Secant method - Newton - Raphson method |
| System of non-linear equations by Newton's method. |
| Module:2System of Linear Equations and Eigen6 hours |
| Value Problems |
| Gauss -Seidel iteration method. Convergence analysis of iterative methods-L |
| Decomposition -Tri diagonal system of equations-Thomas algorithm- Eigen values of |
| matrix by Power and Jacobi methods. |
| |
| Module:3Interpolation6 hours |
| Finite difference operators- Newton's forward-Newton's Backward- Central differences |
| Stirling's interpolation - Lagrange's interpolation - Inverse Interpolation-Newton's divide |
| difference-Interpolation with cubic splines. |
| |
| Module:4Numerical Differentiation and Integration6 hours |
| Numerical differentiation with interpolation polynomials-maxima and minima for tabulated |
| values-Trapezoidal rule, Simpsons $1/3^{rd}$ and $3/8^{th}$ rules. –Romberg's method. Two and Three |
| point Gaussian quadrature formula. |
| Module:5 Numerical Solution of Ordinary 8 hours |
| Differential Equations |
| First and second order differential equations - Fourth order Runge – Kutta method. Adams- |
| Bashforth-Moulton predictor-corrector methods. Finite difference solution for the second |
| order ordinary differential equations. |
| Module:6 Numerical Solution of Partial Differential 6 hours |



Classification of second order linear partial differential equations-Laplace equation –Gauss-Seidal method-One dimensional heat equation- Schmidt explicit method-Crank-Nicolson implicit method.-One dimensional wave equation–Explicit method.

| Module:7 | e:7 Variational Methods 6 hours | | | | | | | | | |
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| | onal –variational proble | ems- extremals of f | unctional of | | | | | | | |
| | t derivative- functional | | | | | | | | | |
| problems- Galerkins | s- Rayleigh Ritz method | s. | | - | | | | | | |
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| Module:8 | Contemporary Issues | 5 | | 2 hours | | | | | | |
| Industry Expert Lec | ture | | | | | | | | | |
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| | | ours: | 45 hours | | | | | | | |
| Tutorial | 1. A minimum of 10 | | | 30 hours | | | | | | |
| | out by students in e | • | | | | | | | | |
| | 2. Another 5 problem | 1 | s to | | | | | | | |
| | be given for practis | se. | | | | | | | | |
| Text Book(s) | | | | | | | | | | |
| | Numerical Methods for Scientific and Engineering, M. K. Jain, S. R. K. Iyengar and R. K. Jain, New Age International Ltd., 6 th Edition, 2012. | | | | | | | | | |
| | Applied Numerical Analysis, C. F. Gerald and P.V. Wheatley, Addition- Wesley, 7 th Edition, 2004. | | | | | | | | | |
| Reference Books | 251Cy, 7 Edition, 2004. | | | | | | | | | |
| | ctory Methods of Nun | parical Analysis | CC Castry | DHI Dyt I td 5th | | | | | | |
| Edition | ntroductory Methods of Numerical Analysis, S.S. Sastry, PHI Pvt. Ltd., 5th dition, New Delhi, 2009. | | | | | | | | | |
| 2. Applied and | ied Numerical Methods Using MATLAB, W.Y. Yang, W. Cao, T.S. Chung | | | | | | | | | |
| 3. J. Mori | ris, Wiley India Edn., 2007. | | | | | | | | | |
| 4. Numeri | cal Methods for Engineers with Programming and Software Applications, | | | | | | | | | |
| | ren C. Chapra and Ra P. Canale, 7 th Edition, Tata McGraw Hill, 2014. | | | | | | | | | |
| 5. Numeri | cal Analysis, R.L. Burden and J. D. Faires, 4 th Edition, Brooks Cole, 2012. | | | | | | | | | |
| 6. Numeri | nerical Methods: Principles, Analysis and Algorithms, Srimanta Pal, Oxford | | | | | | | | | |
| Univers | University Press India, 2009. | | | | | | | | | |
| Mode of Evaluation | : Digital Assignments, (| Continuous Assessi | ment Tests, | Final Assessment | | | | | | |
| Test | | | | | | | | | | |
| Recommended by B | oard of Studies | 25-02-2017 | | | | | | | | |
| Approved by Academic Council47th ACDate05-10-2017 | | | | | | | | | | |



| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
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| MAT3005.2 | | | | | | | | | | | | | | | |
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| MAT3005.4 | | | | | | | | | | | | | | | |
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| MAT3005.5 | | | | | | | | | | | | | | | |
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| EEE1007 | | Neural N | etworks and Fu | Neural Networks and Fuzzy Control | | | | | | | | | | |
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| Pre-requisite | I | IAT1011 | | | Syl | labus | s vers | ion | | | | | | |
| Anti-requisite | 1 | IL | | | | | v. | 1.1 | | | | | | |
| Course Object | ives: | | | | | | | | | | | | | |
| 1. Apply | the de | ign concepts of fe | ed forward and | feedback neural | networks | for | solv | ing | | | | | | |
| Enginee | 01 | | | | | | | | | | | | | |
| | 1 I I | ate weight and learn | 0 | 2 | 0 | | - | | | | | | | |
| | | analyze the real tim | e system with the | e knowledge of fuzz | y logic c | ontro | 1 | | | | | | | |
| Expected Cou | | | 4 | | | | | | | | | | | |
| - | | nis course the studer | | | r roal tin | | toma | | | | | | | |
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| solution | | e concepts of feed to | n waru anu re-cu | field field fielworr | | uie (| pum | ai | | | | | | |
| | | cepts of Recurrent a | nd feedback net | works in multilaver | neurons | | | | | | | | | |
| - | | petitive learning net | | • | | olems | 5. | | | | | | | |
| 0 | | rformance of Self or | | 0 0 | 81 | | | | | | | | | |
| | - | systems for non-lin | | | ple | | | | | | | | | |
| 0 | | ship functions with s | | ± | 1 | uro-f | uzzy | | | | | | | |
| inference | ce syste | n concepts to mode | n controllers. | | | | | | | | | | | |
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| | | | | | | | | | | | | | | |
| Module:1 I | [ntrodu | ction to Artificial | Neural Networ | rks and Learning I | Laws | 7 H | Iours | 6 | | | | | | |
| Artificial neura | al netw | orks and their biolo | gical motivation | n – Terminology – | Models | | | | | | | | | |
| Artificial neura Topology – Ch | al netw aracter | orks and their biolostics of artificial neu | gical motivation ral networks – T | n – Terminology – Types of activation for | Models unctions. | of ne | euron | _ | | | | | | |
| Artificial neura Topology – Cha Learning Law | al netw aracter v s: Lea | orks and their biolo stics of artificial neu ning methods – Err | gical motivation ral networks – T or correction lea | u – Terminology – ypes of activation furning – Hebbian le | Models unctions. arning – | of ne | euron | _ | | | | | | |
| Artificial neura Topology – Cha Learning Law | al netw aracter v s: Lea | orks and their biolostics of artificial neu | gical motivation ral networks – T or correction lea | u – Terminology – ypes of activation furning – Hebbian le | Models unctions. arning – | of ne | euron | _ | | | | | | |
| Artificial neura Topology – Cha Learning Law XOR problem - | al netw aracter vs: Lea – Perce | orks and their biolo stics of artificial neu ning methods – Err otron learning rule co | gical motivation ral networks – T or correction lea | u – Terminology – ypes of activation furning – Hebbian le | Models unctions. arning – | of ne Perc | eptro | _ n – | | | | | | |
| Artificial neura Topology – Cha Learning Law XOR problem - Module:2 F | al netw aracter v s: Lea – Perce F eed F o | orks and their biolo stics of artificial neu ning methods – Err otron learning rule co rward Networks | gical motivation ral networks – T or correction lea onvergence theor | u – Terminology – ypes of activation for rning – Hebbian le rem – Adaline – Ma | Models unctions. arning – daline. | of ne Perc | euron eptro 4 Ho | n – urs | | | | | | |
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| Artificial neura Topology – Chance Learning Law XOR problem - Module:2 F Multilayer Perce approximation Module:3 F Bi-directional a Module:4 L Competitive lear | al netw aracter vs: Lea – Perce Feed For ceptron – Asso Associat Jnsupe arning | orks and their biolo stics of artificial neu ning methods – Err otron learning rule co rward Networks – Delta Learning – E itative memory: auto nt Neural Network ve memory – Hopfi vised Learning eural networks – M | gical motivation ral networks – T or correction lea onvergence theor Back Propagation association and s eld neural netwo | n – Terminology – ypes of activation for urning – Hebbian le rem – Adaline – Ma n learning algorithm hetero association. rk – Travelling Sale | Models unctions. arning – daline. n – Univ | of ne Perc ersal 2 Hou oblem | euron eptro 4 Ho funct 1rs 1. 3 Ho | n – urs ion | | | | | | |
| Artificial neuraTopology – ChiLearning LawXOR problem –Module:2FMultilayer PercapproximationModule:3FBi-directional aModule:4LCompetitive leaModule:5S | al netw aracter vs: Lea – Perce Feed For ceptron – Asso Recurron associat Jnsupe arning p | orks and their biolo stics of artificial neu ning methods – Err otron learning rule co rward Networks – Delta Learning – Err diative memory: auto nt Neural Network ve memory – Hopfi vised Learning eural networks – M anizing Networks | gical motivation ral networks – T or correction lea onvergence theor Back Propagation association and s eld neural netwo | n – Terminology – 'ypes of activation for the set of activation for the set of activation for the set of t | Models unctions. arning – daline. n – Univ | of ne Perc ersal 2 Hou oblem | euron eptro 4 Ho funct n. 3 Ho ours | n – urs ion | | | | | | |
| Artificial neura Topology – Cha Learning Law XOR problem - Module:2 F Multilayer Perce approximation Module:3 F Bi-directional a Module:4 U Competitive lea Module:5 S Kohonen Self | al netw aracter vs: Lea – Perce Feed For ceptron – Asso Associat Jnsupe arning for Self Or organiz | orks and their biolo stics of artificial neu- ning methods – Err otron learning rule co rward Networks – Delta Learning – T itative memory: auto nt Neural Network ve memory – Hopfi vised Learning eural networks – M anizing Networks ing Feature Map – | gical motivation ral networks – T or correction lea onvergence theor Back Propagation association and s eld neural netwo ax net – Maxicar Counter propag | n – Terminology – ypes of activation for the set of activation for the | Models unctions. arning – daline. n – Univ esman Pro- et. | of ne Perc ersal 2 Hou oblem | euron eptro 4 Ho funct n. 3 Ho ours zation | n – urs ion urs | | | | | | |
| Artificial neuraTopology – ChiLearning LawXOR problem –Module:2FMultilayer PercapproximationModule:3FBi-directional aModule:4LCompetitive leaModule:5SKohonen SelfAdaptive Reso | al netw aracter vs: Lea – Perce Feed For ceptron – Asso Associat Jnsupe arning p Self Or organiz | orks and their biolo stics of artificial neu- ning methods – Err otron learning rule co- rward Networks – Delta Learning – diative memory: auto nt Neural Network ve memory – Hopfi vised Learning eural networks – M anizing Networks ing Feature Map – Theory – Concept | gical motivation ral networks – T or correction lea onvergence theor Back Propagation association and s eld neural netwo ax net – Maxicar Counter propag of support vec | Terminology – 'ypes of activation for the sem – Adaline – Magenta end of the sem – Adaline – Magenta end of the second statistical statis statistical statistical statistical statistical statistica | Models unctions. arning – daline. n – Univ esman Pro- et. | of ne Perc ersal 2 Hou oblem 5 H uanti | euron eptro 4 Ho funct n. 3 Ho ours zation | urs | | | | | | |
| Artificial neura Topology – Chi Learning Law XOR problem - Module:2 F Multilayer Perc approximation Module:3 F Bi-directional a Module:4 U Competitive lea Module:5 S Kohonen Self Adaptive Reso networks in ima | al netw aracter vs: Lea – Perce Feed For ceptron – Asso Associat Jnsupe arning f Self Or organiz | orks and their biolo stics of artificial neu- ning methods – Err otron learning rule co rward Networks – Delta Learning – T itative memory: auto nt Neural Network ve memory – Hopfi vised Learning eural networks – M anizing Networks ing Feature Map – | gical motivation ral networks – T or correction lea onvergence theor Back Propagation association and s eld neural netwo ax net – Maxicar Counter propag of support vec ssing, modeling | Terminology – 'ypes of activation for the sem – Adaline – Magenta end of the sem – Adaline – Magenta end of the second statistical statis statistical statistical statistical statistical statistica | Models unctions. arning – daline. n – Univ esman Pro- et. | of ne Perc ersal 2 Hou oblem 5 H uanti ns or | euron eptro 4 Ho funct n. 3 Ho ours zation | n – urs ion urs n – ral | | | | | | |



| principle. | - Fuzzy to Crisp conversi | on, Fuzzy Arith | imetic, nu | mbers, vectors and | extension |
|-------------|---|---------------------|-------------|-----------------------|--------------|
| Module:7 | Fuzzy Decision Making | | | | 2 Hours |
| methods. | ased systems – Fuzzy nonlin | | • | - | uzzification |
| Neuro Fuzz | y: Mathematical formulation | of adaptive Neur | ro – Fuzzy | inference systems. | |
| Module:8 | Contemporary issues: | | | | 2 Hours |
| Text Book(| s) | | | | |
| 1. | Jacek. M. Zurada, "Intro House, 2006. | oduction to Arti | ficial Neu | iral Systems", Jaico | Publishing |
| 2. | Simon Haykin, Neural Ne New York, 2016. | tworks and learni | ing Machir | nes", Mac Millen Col | lege Pubco. |
| Reference E | Books | | | | |
| 1. | Laurene Fausett, Fundam applications, Pearson Educ | | Networks | - Architectures, alg | orithms and |
| 2. | Timothy J.Ross, Fuzzy L 2017. | ogic with Engine | eering App | plications, John Wile | ey and sons |
| 3. | J.S.R. Jang, C.T. Sun, computational Approach Inc., 2010. | | | • • | 0 |
| Mode of Eva | aluation: CAT / Assignment | / Quiz / FAT / Pr | oject / Sem | ninar | |
| Recommend | led by Board of Studies | 05/03/2016 | | | |
| A 11 | y Academic Council | 40 th AC | Date | 18/03/2016 | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1007.1 | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 1 | 3 | 1 | 1 |
| EEE1007.2 | 3 | 2 | 1 | 1 | 1 | - | - | I | 1 | - | - | 1 | 3 | 1 | 1 |
| EEE1007.3 | 3 | 2 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE1007.4 | 3 | 2 | 3 | 1 | 1 | - | - | - | 1 | - | - | 1 | 3 | 1 | 1 |
| EEE1007.5 | 3 | 3 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE1007.6 | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 1 | 3 | 1 | 1 |
| | | | | | | | | | | | | | | | |
| EEE1007.7 | 3 | 3 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 1 | 3 | 1 | 1 |



| | (Deemed to be University under section 3 of UGC Act, 1956) | |
|---------------------------|--|-------------------------|
| EEE1008 | Bio-Medical Instrumentation | L T P J C |
| | | 3 0 0 4 4 |
| Pre-requisite | NIL | Syllabus version |
| Anti-requisite | NIL | v. 2.0 |
| Course Objectives: | | |
| 1. To give an u | nderstanding of the biological signals and signal acquisition | |
| 1 | he design concepts of bioelectric amplifiers | |
| * | principle and operation of various biomedical systems | |
| Expected Course (| Dutcomes: | |
| On the completion of | of this course the student will be able to: | |
| | analyse the different physiological signals | |
| | nowledge to select appropriate medical instruments | |
| - | io electric devices used for diagnostic equipment | |
| - | analyse the therapeutic devices. | |
| | he procedure for blood analysis in medical laboratory | |
| | process involved in blood cell counters and sensors | |
| | the advanced diagnostic techniques. | 1 |
| 8. Design a con | nponent or a product applying all the relevant standards with r | realistic constraints |
| | | |
| Module:1 Intro | duction to Biomedical Instrumentation and Measurement | 8 Hours |
| | | |
| | ric potentials, cardiovascular system, Central nervous system | • • |
| | lysis of different physiological signals (ECG, EEG, EMG | |
| | sis including Nernst equation, Goldman equation, Electrics for ECG, EEG & EMG. | ical conductivity of |
| | ral Considerations of Medical Instruments | 8 Hours |
| | fiers, Bioelectric Amplifiers, Selection of biomedical an | |
| | mplifiers and Chopper amplifier. Characteristics of biomedica | - |
| | is of electric currents, Electric shock hazards and leakage | |
| Methods of accident | | currents, |
| | nostic Equipment | 7 Hour |
| 0 | ation, Vector cardiograph, Phono-cardiograph, EEG and EMC | |
| - | ment of various volumes/capacity of lungs, Spirometer. Mea | • |
| output, blood flow a | | |
| | apeutic Equipment | 6 Hours |
| | , cardiac defibrillators, nerve & muscle stimulators, diathern | |
| Dialyzer. | | ily types, ventilators, |
| - | cal Laboratory Instrumentation | 5 Hours |
| | Aeasurement of pH, pO2 and pCO2 value of blood using pH/g | |
| - | cal Laboratory Measurement | 4 Hours |
| | tology, Blood cell counters, Electrophoresis- Serum detection | |
| | ors, GSR measurements. | |
| | nced Diagnostic Techniques | 5 Hours |
| | d Visualization (X-Ray, MRI, CT), Biomedical Spectroscop | |
| - | scence based Bio-detection & Bio-imaging- Case study: To | |
| health care monitori | | |
| | temporary issues: | 2 hours |
| Text Book(s) | × V | |
| (~) | | |



| | (Deemed to be Oniversity under section 5 of OGC Act, 1936) |
|---------|--|
| 1. | Leslie Cromwell, Fred J, Weibell & Erich A and P Feiffer, 'Biomedical Instrumentation and Measurements', 2 nd Edition, PHI, 2011. |
| 2. | J.J. Carr & J.M. Brown, 'Introduction to biomedical Equipment Technology', Prentice Hall, 4 th Edition, 2011. |
| Refere | ence Books |
| 1. | R. S. Khandpur, 'Handbook of Biomedical Instrumentation', Tata Mc-Graw Hill, 2nd edition, 2014. |
| 2. | John.E. Hall, Guyton and Hall, Textbook of Medical Physiology, Saunders; 13 th Edition, 2015. |
| 3. | Rangaraj M. Rangayyan, 'Biomedical Signal Analysis', A Case-Study Approach, Wiley, 2 nd Edition, 2015. |
| Mode of | f Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% |
| Recomm | nended by Board of Studies 30/11/2015 |
| Approve | ed by Academic Council 39th AC Date 17/12/2015 |

| G 0 | DOI | DOA | DOG | DOI | 705 | DOC | D07 | DOG | DOG | DO10 | DO 11 | D010 | DOOL | DGOO | DGOO |
|------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|-------|------|------|------|------|
| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE1008.1 | 3 | 3 | 2 | 2 | - | - | - | - | 2 | 2 | - | 1 | 2 | 2 | 1 |
| EEE1008.2 | 3 | 2 | 2 | 1 | 2 | - | - | - | 2 | 1 | - | - | 3 | 3 | 1 |
| EEE1008.3 | 3 | 3 | 2 | 3 | 3 | - | - | - | 2 | 2 | - | 1 | 3 | 3 | 1 |
| EEE1008.4 | 3 | 2 | 2 | 2 | 2 | - | - | - | 1 | 2 | - | 2 | 2 | 2 | 1 |
| EEE1008.5 | 3 | 2 | 1 | 2 | 3 | - | - | - | 2 | 1 | - | - | 3 | 3 | 1 |
| EEE1008.6 | 3 | 3 | 1 | 2 | 2 | - | - | - | 1 | - | - | 1 | 3 | 3 | 1 |
| EEE1008.7 | 3 | 2 | 1 | 2 | - | - | - | - | 2 | 1 | - | 2 | 1 | 1 | 1 |
| EEE1008.8 | 2 | 2 | 2 | 1 | 3 | - | - | - | 3 | 3 | _ | 2 | 3 | 3 | 2 |
| | 3 | 2 | 2 | 2 | 2 | - | - | - | 2 | 2 | - | 2 | 3 | 3 | 1 |



| Pre-requisite | | |
|---|---|---|
| Pre-requisite | | |
| - | EEE3002 | Syllabus version |
| Anti-requisite | NIL | v. 1.0 |
| Course Objectives | | |
| (ATE). 2. Providing h | ovide knowledge about the testing of IC's using auto nands-on in Simulation software's used to simulate t nowledge imparted on LabVIEW usage in PCBA tes | he evaluation conditions. |
| Expected Course | Outcome: | |
| On the completion | of this course the student will be able to: | |
| 1. Discover th | e component faults in electronic manufacturing | |
| 2. Classify the | e faults in PCBs | |
| • | e practical skills involved in troubleshooting | |
| | rious parameters involved in automated test enginee | ring |
| | the Boundary Scan and Board Testing | |
| 6. Conduct the | e experiments on automated testing techniques | |
| Printed Circuit Bo Surface Mount To manufacturing pro | oduction Topcb Assemblies:ard (PCB)-types of PCB-multilayer PCBs-Plat Plaechnology (SMT) – Ball Grid Array (BGA) Tecess – Bare board testing– PCB Inspection method– Electrical tests in PCBs | chnology – PCB Bare board |
| Module:2 PCI | BA Troubleshoot Methods: | 2 Hours |
| – Fault types and c | ubleshoot – locating faults & Manual troubleshoot – auses in circuits – Tools and instruments for usage - y Oscilloscope) - Logic probes – Logic pulser – Log | - DMM(Digital Multimeter) - |
| Module:3 PCI | BA Troubleshoot Methods: | 2 Hours |
| Automated Testing analysis – Board F | g of PCBs – Out-circuit & In-circuit test methods – V unctional Testing Techniques– Boundary Scan Test Automated Testing – PCB diagnostic testers – 1 | VI Trace Technique – signature Strategy & methods – External |
| Module:4 Auto | omated Test Techniques: | 5 Hours |
| Automated Test Te | chniques – Various parameters – AC – DC Parametr ne failures of parameters– Environmental, Electrical | |



| Test I | Fixtures | – Reverse I | Engg to rebuild | he Schematic D | iagram u | sing ATE and So | ftware. |
|---------------------------------|---------------------------------|---|--|---|-------------------------------|--|---|
| Modu | ule:5 | Board Fu | inctional Tes | ting (BFT): | | | 6 Hours |
| Back Com testin testin | ktrackin 1prehens ng– BC | g Techniqu siveness of SS– Interfa ternal Instru | e – Simulators Board program ce adaptor or p | General Continuer General Content Fault Diction Content Content | Offline nary– A or(Pod) | Simulation - F nalysis – BS and - Sample board p | – Guided Probe Fault Simulation– d Non-BS device programming and Integration of PXI |
| Modu | ule:6 | DFT: | | | | | 4 Hours |
| Desi | | estability (D | PFT)- test issues | – Fault Models | — Boun | dary Scan Test– S | Self Test design – |
| Modu | ule:7 | DFM: | | | | | 6 Hours |
| – stra applic | itegies – cations. | new strateg | y for DFM – be | | | - | Production process acturing – Various |
| Modu | ule:8 | Contemp | orary issues: | T () T (| | | 2 Hours |
| | | | | Total Lecture | hours: | | 30 Hours |
| 1. Refe 1. 2. | Edit rence B Gord Floy | ion, 2011. ooks don Rogers a d , "The Fi | and Yon Mayhe | q , "Engineering | Thermo | ware", Tata McC dynamics", Pears Testing", Pearson | |
| T • 4 | - | 2005 | • • • • • | | | | |
| | | 001 | eriments (Indi | | | | 21 |
| 1. 2. | | | ing Boundary So Boundary Scan | | | | 2hours 2 hours |
| 3. | | cuit Functio | | Tester | | | 2 hours |
| 4. | | uit Function | | | | | 2 hours |
| 5. | | I Signature ' | | | | | 2 hours |
| 6. | | hain Test | | | | | 2 hours |
| 7. | | | ing Short Locate | er | | | 2 hours |
| 8. | | Test Using | 0 | | | | 2 hours |
| 9. | Parame | tric Testing | DC and AC par | ameters | | | 2 hours |
| 10. | | | esting using AT | | | | 2 hours |
| | | | | | Total L | aboratory Hour | s 20 hours |
| Mode | e of Eva | luation: | CAT I & II – 3 | 0%, DA I & II - | $-\overline{20\%}, Q$ | uiz – 10%, FAT | - 40% |
| | | ed by Board | | 05/03/2016 | | | |
| Appro | oved by | Academic (| Council | 40 th AC | Date | 18/03/2016 | |



| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1011.1 | 3 | 2 | - | 2 | 2 | - | - | 1 | 1 | 1 | - | 1 | 2 | 1 | 1 |
| EEE1011.2 | 3 | 2 | 1 | 1 | 2 | - | - | 1 | 2 | 1 | - | 1 | 2 | 1 | 1 |
| EEE1011.3 | 3 | 3 | 2 | 2 | 2 | - | - | 1 | 1 | 1 | - | 1 | - | 3 | 2 |
| | | | | | | | | | | | | | | | |
| EEE1011.4 | 3 | 3 | 2 | 3 | 2 | - | - | 1 | 1 | 1 | - | 1 | 3 | 2 | 3 |
| EEE1011.5 | 3 | 2 | 1 | 1 | 3 | - | - | 1 | 1 | 1 | - | 1 | 3 | 2 | 1 |
| EEE1011.6 | 3 | 2 | 1 | 1 | 3 | - | - | 1 | 1 | 1 | - | 1 | 2 | 2 | 3 |
| | 3 | 2 | 2 | 2 | 2 | | | 1 | 1 | 1 | | 1 | 2 | 2 | 3 |



| EEE1012 | (Deemed to be University under section 3 of UGC Act, 1956) Optoelectronic Instrumentation | L T P J C |
|---|--|--|
| | | |
| D | | |
| Pre-requisite | PHY1001/PHY1701 | Syllabus version |
| Anti-requisite | NIL | v. 1.0 |
| Course Object | | |
| instrume 2. To desig | erstand the principles underlying the theory and wide applicentation. If and develop an optical instrument for non-contact meas ide an exposure on latest developments of optical instrume | surements. |
| Course Outcor | ne: | |
| On the complet | ion of this course the student will be able to: | |
| 1. Compre | hend the various types of noncontact optical instruments | |
| 2. Underst | and the working principle of various optical sources and d | letectors |
| 3. Infer the | e optical fiber characteristics and their usage in measureme | ent. |
| | the fiber optic sensor for various physical parameter measured | urements. |
| | the laser based optical instrumentation. | |
| | and the use of laser in optical non-destructive testing. | , . . |
| 7. Develop | o solutions for real world problems using optical instrumer | itation |
| Module:1 C | Overview Of Optical Instrumentation: | 3 Hours |
| | | |
| optical measure | advantages of noncontact measurements, competing tech | mologies, classification of |
| optical measure | ments. | |
| Module:2 | Optical Sources and detectors : | 10 Hours |
| Principle of ligh | t emission, materials, population inversion, pumping proce | esses, optical amplification. |
| Semiconductor | Optical Sources - homojunction and double heterostruct | ture - LEDs and LASERs. |
| Response time, | design of drive circuitry. Classifications: Ruby lasers, N | Neodymium Lasers, He-Ne |
| Lasers, CO2 La | asers, Dye Lasers, Fiber lasers. Detectors: PN, P-i-N ar | nd Avalanche Photodiodes |
| (APD), gain an | nd responsivity calculation. Quadrant photodiode, CCD | cameras and |
| displays. | | |
| Module:3 F | undomentals of Fiber Onties | 5 Uoung |
| | undamentals of Fiber Optics: haracteristics and Classifications. Manufacturing of Optic | 5 Hours |
| - | power coupling, calculations, Fiber connectors and spli | - |
| | and optical modulators. | ices - sphenig teeninques. |
| | | |
| Module:4 | Fiber Optic Instrumentation: | 5 Hours |
| | sors – measurement of displacement, pressure, tempera | |
| FIDEL ODLIC SEL | | ,,,, . , . , |
| | el and flow. Electric and magnetic field sensors. | |
| | el and flow. Electric and magnetic field sensors. | |
| strain, fluid leve | el and flow. Electric and magnetic field sensors. | 10 Hours |
| strain, fluid leve Module:5 L | aser Instrumentation: | |
| strain, fluid leve Module:5 L Principles of la | | r- principle, performance |
| strain, fluid leveModule:5LPrinciples of laparameters and | aser Instrumentation: ser measurements and applications. Laser Interferometer | r- principle, performance - position detecting sensor |



| Modu | le:6 | Optical | Non-D |)estruc | tive T | Festing : | | | | | | 5 | 5 Hours |
|---|--|--|--|---|--|---|---|---|---|--|---|--|---------|
| | optics ology. | s, Laser | speckl | le, Inf | rared | thermo | ograph | , end | oscopy, | holog | raphy a | and ter | ahertz |
| Modu | le:7 | Advanc | ed opti | ical In | strum | entatio | n: | | | 5 Hou | rs | | |
| | | e sensing | | DAR), | advar | nced op | otical | pollutio | on mea | sureme | nts, op | otical ir | naging, |
| | | spectrome | | | | | | | | I | | | |
| Modu | le:8 | Conter | nporar | ry issu | es: | | | | | | | | 2 Hours |
| | Book(s) | | | | | Te | otal Le | cture l | iours: | | | 45 | Hours |
| 2. | Fund Silva | id A. Kr lamental ano Dona 2010. | and Ap | oplicati | ons", | SPIE, 4 | th Edit | on, 20 | 15. | | | - | |
| 2 | | | | | | | | | | | | | |
| 3. | Opti | Osten and cal Imagi KGaA, 20 | ing and | - | | | | | - | | | | - |
| | Opti Co. | cal Imagi KGaA, 20 00ks | ing and 012. | Metro | ology: | Advand | ced Tec | chnolog | gies", W | viley-V | CH Ver | lag Gm | bH & |
| Refer | Opti Co. 2 ence Bo Gero | cal Imagi KGaA, 20 D oks I Keiser, [†] | ing and 012. "Optica | Metro | logy: r Com | Advanc | tions", | chnolog Tata N | gies", W AcGraw | Hill, 5 | CH Ver | lag Gml | bH & |
| Refer | Opti Co. 2 ence Bo Gero | cal Imagi KGaA, 20 00ks I Keiser, Ganguly | ing and 012. "Optica | Metro | logy: r Com | Advanc | tions", | chnolog Tata N | gies", W AcGraw | Hill, 5 | CH Ver | lag Gml | bH & |
| Refer | Opti Co. ence Bo Gerce A.K 2010 John Seco | cal Imagi KGaA, 20 00ks I Keiser, Ganguly | ing and 012. "Optica , " Op oster, H ion: H | Metro al Fiber tical a Ialit En Electron | r Com nd Op ren, "I | Advand munica ptoelect Measur etic, C | tions", ronics ement, | Tata N Instrui | gies", W AcGraw mentation mentation | /iley-V(/ Hill, 5' on", Al | CH Ver th Editic pha Sc l Senso | lag Gml on, 2013 ience In rs Hanc | bH & |
| Refer 1. 2. 3. Mode | Opti Co. ence Bo Gerce A.K 2010 John Secco Mea of valu | cal Imagi KGaA, 20 ooks I Keiser, Ganguly Ganguly G. Web ond Edit surement ation: | ing and 012. "Optica , " Op oster, H ion: H ion: H .", CRC | Metro al Fiber tical a Halit En Electron C press, | r Com nd Op ren, " magne 2014 – 309 | Advance munica ptoelect Measur etic, C %, DA | tions", ronics ement, ptical, | Tata N Instru Radi | gies", W <u>AcGraw</u> mentation mentation, | /iley-V(/ Hill, 5' on", Al | CH Ver th Editic pha Sc l Senso cal, an | lag Gml on, 2013 ience In rs Hanc d Bion | bH & |
| Refer 1. 2. 3. Mode Record | Opti Co. ence Bo Gerce A.K 2010 John Secc Mea of valu | cal Imagi KGaA, 20 boks I Keiser, Ganguly G. Web ond Edit surement ation: ed by Boa | ing and 012. "Optica , " Op oster, H ion: F ion: F ion: F ion: A ind of S | A Fiber al Fiber tical a Halit En Electron C press, C I & II Studies | r Com nd Op ren, " magne 2014 – 309 | Advand munica ptoelect Measur etic, C %, DA 1 05/03/2 | tions", ronics ement, optical, [& II – 2016 | Tata N Instru Radi 20%, | gies", W AcGraw mentation mentation, Quiz – | /iley-V(/ Hill, 5' on", Al on, and Chemic 10%, F. | CH Ver th Editic pha Sc l Senso cal, an AT – 40 | lag Gml on, 2013 ience In rs Hanc d Bion | bH & |
| Refer 1. 2. 3. Mode Record | Opti Co. ence Bo Gerce A.K 2010 John Secc Mea of valu | cal Imagi KGaA, 20 ooks I Keiser, Ganguly Ganguly G. Web ond Edit surement ation: | ing and 012. "Optica , " Op oster, H ion: F ion: F ion: F ion: A ind of S | A Fiber al Fiber tical a Halit En Electron C press, C I & II Studies | r Com nd Op ren, " magne 2014 – 309 | Advance munica ptoelect Measur etic, C %, DA | tions", ronics ement, optical, [& II – 2016 | Tata N Instru Radi | gies", W AcGraw mentation mentation, Quiz – | /iley-V(/ Hill, 5' on", Al on, and Chemic 10%, F. | CH Ver th Editic pha Sc l Senso cal, an | lag Gml on, 2013 ience In rs Hanc d Bion | bH & |
| Refer 1. 2. 3. Mode Record | Opti Co. ence Ba Gerce A.K 2010 John Secco Mea of valu nmende | cal Imagi KGaA, 20 poks I Keiser, Ganguly G. Web ond Edit surement ation: ed by Boa Academi | ing and 012. "Optica , " Op oster, H ion: F ion: F ion: F ion: A ind of S | A Fiber al Fiber tical a Halit En Electron C press, C I & II Studies | r Com nd Op ren, " magne 2014 – 309 | Advand munica ptoelect Measur etic, C %, DA 1 05/03/2 40 th A | tions", ronics ement, optical, [& II – 2016 | Tata N Instru Radi 20%, | gies", W AcGraw mentation mentation, Quiz – | /iley-V(/ Hill, 5' on", Al on, and Chemic 10%, F. | CH Ver th Editic pha Sc l Senso cal, an AT – 40 | lag Gml on, 2013 ience In rs Hanc d Bion | bH & |
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| EEE1013 | Analytical Instrumentation | | L | T | Р | J | С |
|---------------------------|--|--------------|----|-----|----|-------------|-----|
| | | | 3 | 0 | 0 | 0 | 3 |
| Pre-requisite | PHY1001 | Syllabus ver | | | | rsi | on |
| Anti-requisite | NIL | | | | | v. . | 1.0 |
| Course Objectives: | | | | | | | |
| 2. To design the | nd interpret data from different chromatography spectrums. e radiation sources, detectors and optical systems for various d the working principles of spectrometry and spectrophoton | - | me | ter | s. | | |

On the completion of this course the student will be able to:

- 1. Demonstrate the interaction of electromagnetic radiations with matter and spectroscopy and its types
- 2. Apply and analyse the analytical techniques to determine the elements present in the given sample accurately.
- 3. Analyse the concepts of NMR, Spectrometers and their working.
- 4. Demonstrate contemporary measurement techniques related to analyzers.
- 5. Apply chromatography to analyse industrial environments.
- 6. Illustrate the working principle of Ion Selective Electrodes, PH electrodes and conductivity meters.
- 7. Measure and formulate the composition of dissolved oxygen, sodium, silica elements present in the given samples.

Module:1 **Electromagnetic Radiation:**

EM Radiation characteristics – interaction of EM radiation with matter; spectral methods of analysis - absorption spectroscopy - Beer-Lamberts Law - radiation sources - monochromators - filters prisms – diffraction gratings.

Module:2 **Instrumentation for Absorption and Emission spectroscopy:**

UV – Visible spectroscopy – single beam and double beam instruments – instrumentation, sources and detectors; IR spectroscopy - FTIR spectrometer - instrumentation- sources and detectors. Atomic absorption spectroscopy - instrumentation, sources and detectors; Flame emission photometry instrumentation, sources and detectors; Applications of absorption spectroscopy techniques.

| Module:3 | Nuclear Magnetic Resonance and Radiation Techniques: | 8 Hours |
|------------------|--|-------------|
| Nuclear Mag | gnetic Resonance - basic principles -Constructional features and working | of NMR |
| spectrometer | s - applications. Nuclear radiation detectors - GM counter - proportiona | l counter – |
| scintillation of | counter; X- ray diffraction- instrumentation and applications. | |
| | | |

| Module:4 | Mass sp | ectroscopy: | | | | | | | 4 | Hours |
|-----------|---------------|----------------------|------|-----------|--------------------|------|---------|---------|-----|--------|
| Mass spec | troscopy – ba | asic principles – Co | nsti | ructional | features and worki | ng a | ind app | licatio | ns. | |
| Module:5 | Chroma | tography: | | | | | | | 8 | Hours |
| Basic pr | ncinles-Gas | chromatography | _ | Liquid | chromatography | _ | High | nress | ure | liquid |

5 Hours

8 Hours



| emontatogra | aphy – instrumentation a | and approactions. | | |
|----------------------|---|---|------------|-----------------------------------|
| Module:6 | pH Conductivity & Analyser: | Dissolved Component | | 5 Hours |
| | ve electrodes – conduct silica analyser – moistu | | s – disso | olved oxygen analyser – sodium |
| Module:7 | Gas Analysers: | | | 5 Hours |
| • | ers for Oxygen, CO, N measurement. | NOx - dust and smoke | detector | rs – analysers based on thermal |
| Module:8 | Contemporary issu | es: | | 2 Hours |
| | | Total Lecture ho | urs: | 45 Hours |
| Text Book(| s) | | | |
| 1. | R.S.Khandpur, 'Hand Company Ltd., 3rd Ed | · · · · · · · · · · · · · · · · · · · | Instrum | ents', McGraw Hill Publishing |
| 2. | 0 | James Holler and Stanle rooks/Cole, 7 th Edition, 2 | • | rouch, 'Principles of Instrumenta |
| Reference l | • | · · · | | |
| 1. | Ewing G.W., 'Instrum | ental methods of chemica | al analys | sis, McGraw-Hill, Newyork.2009. |
| 2. | Sivasankar B, 'Instrum | nental Methods of Analys | is', Oxf | Ford University press.2012. |
| 3. | Willard, H.H., Merrit CBS Publishing and D | | F.L., 'Ins | strumental Methods of Analysis' |
| Mode of Ev | valuation: | CAT I & II – 30%, D 40% | AI&I | I – 20%, Quiz – 10%, FAT – |
| Recomment Studies | led by Board of | 05/03/2016 | | |
| | y Academic Council | 40 th AC | Date | 18/03/2016 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1013.1 | 3 | 2 | 1 | - | 2 | - | - | 1 | 2 | 1 | - | 2 | 3 | 3 | 2 |
| EEE1013.2 | 2 | 3 | 2 | 3 | 3 | - | - | 2 | - | 2 | - | 2 | 3 | 3 | 2 |
| EEE1013.3 | 2 | 3 | - | 2 | 2 | - | - | 1 | 2 | 2 | - | 2 | 2 | 2 | 2 |
| EEE1013.4 | 3 | 2 | 2 | 1 | 3 | - | - | 1 | 2 | - | - | 3 | 2 | 2 | 2 |
| EEE1013.5 | 2 | 3 | 2 | 3 | 3 | - | - | 1 | 2 | 1 | - | 3 | 2 | 2 | 2 |
| EEE1013.6 | 3 | 2 | 2 | 2 | 3 | - | - | 1 | 2 | - | - | 2 | 2 | 2 | 2 |
| EEE1013.7 | 3 | 3 | 2 | 2 | 3 | - | - | 1 | 2 | - | - | 3 | 2 | 2 | 2 |
| | 3 | 3 | 2 | 2 | 3 | - | - | 1 | 2 | 1 | - | 3 | 2 | 2 | 2 |



| EEE1014 | | | Fiber | Optic Sen | sors | | L | T | ΡJ | C |
|---|--|---|--|--|---|--|---|---|---|---|
| | | | | | | | 3 | 0 | 0 0 | 3 |
| Pre-requisite | | PHY1001/PH | Y1701 | | | | Sylla | bus | vers | ion |
| Anti-requisite | e | NIL | | | | | | | v. | 1.0 |
| Course Objec | ctives: | | | | | | | | | |
| 1. To | unders | stand the princi | ples underlyir | ng the theo | ry and its | wide appli | ication. | | | |
| | | and develop f | | | | | | | | |
| 3. To | design | and implement | ntation of fiber | r optic dist | ributed ser | nsors for v | various app | plica | ations | • |
| Expected Cou | Irso AI | utcome | | | | | | | | |
| - | | this course the | e student will | be able to: | | | | | | |
| - | | nd the overviev | | | | me applic: | ations | | | |
| | | he optical fiber | - | | ina no anng | lae applie | ations | | | |
| | - | end the workin | | | otical source | es and de | tectors | | | |
| | | he working pri | | | | | | | | |
| | • | fiber optic ser | - | - | | er measure | ements | | | |
| 6. De | sign the | e multiplexing | and distribute | ed sensing | of optical : | fiber sense | ors | | | |
| | | | | | | | | | | |
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| | | | | | | | | | | |
| Modulo:1 | Over | iow of Option | Songorg: | | | | | | <u>з По</u> | 11 16 |
| | | iew of Optical | | Competin | a taabaal | | acification | | 3 Ho | |
| Introduction - | | | | Competin | g technolo | ogies, Cla | assification | | | |
| | | | | Competin | g technolo | ogies, Cla | assification | | | |
| Introduction - sensors. | - Adva | | ical sensors, | Competin | g technolo | ogies, Cla | assification | n of | | cal |
| Introduction - sensors. Module:2 | - Adva Funda | ntages of opt | ical sensors, ber Optics: | | | | | n of | f opti 5 Ho | ical urs |
| Introduction - sensors. Module:2 Basic characte | - Adva Funda | ntages of opt | ical sensors, ber Optics: r, Classificatio | on, dispers | ion, attenu | ation, nor | nlinear op | n of | f opti 5 Ho effec | urs |
| Introduction - sensors. Module:2 Basic characte | - Adva Funda eristics M. Mo | mentals of Fi of optical fiber dal birefringen | ical sensors, ber Optics: r, Classification ce and polarized | on, dispers | ion, attenu | ation, nor | nlinear op | n of | f opti 5 Ho effec | urs |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP | - Adva Funda eristics M. Mo | mentals of Fi of optical fiber dal birefringen | ical sensors, ber Optics: r, Classification ce and polarized | on, dispers | ion, attenu | ation, nor | nlinear op | n of | f opti 5 Ho effec | urs |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo | - Adva Funda eristics M. Mo oints, fi | mentals of Fi of optical fiber dal birefringen | ical sensors, ber Optics: r, Classification ice and polariz optical fiber co | on, dispers | ion, attenu | ation, nor | nlinear op | n of | f opti 5 Ho effec | urs cts- g, |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 | - Adva Funda eristics M. Mo oints, fi Optica | amentals of Fi of optical fiber dal birefringen iber splicing, o | ical sensors, ber Optics: r, Classification the and polarize optical fiber co Detectors: | on, dispers zation main onnectors | ion, attenu ntaining fil | ation, nor | nlinear op rce to fiber | n of tical | f opti 5 Ho effec upling 5 Ho | urs urs cts- z, urs |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources | - Adva Funda eristics 'M. Mo oints, fi Optica 5 – LE | intages of opt imentals of Fi of optical fibe dal birefringen iber splicing, o il Sources and | ical sensors, ber Optics: r, Classification ace and polarize optical fiber control Detectors: diodes – van | on, dispers zation main onnectors rious strue | ion, attenu ntaining fil | ation, nor bers. Sour | nlinear op rce to fiber nttern, cha | tical | f opti 5 Ho effec apling 5 Ho teristi | urs cts- g, urs cs, |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources modulation of | - Adva Funda eristics M. Mo oints, fi Optica 5 – LE f light | mentals of Fi of optical fiber dal birefringen iber splicing, o al Sources and ED and laser | ber Optics: r, Classification optical fiber co Detectors: diodes – van | on, dispers zation main onnectors rious strue – PIN Pł | ion, attenu ntaining fil ctures, rad | ation, nor bers. Sour | nlinear op rce to fiber nttern, cha | tical | f opti 5 Ho effec apling 5 Ho teristi | urs cts- g, urs cs, |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources modulation or principles, qua | Funda Funda eristics M. Mo oints, fr Optica 5 – LE f light antum e | intages of opt mentals of Fi of optical fibe dal birefringen iber splicing, o al Sources and ED and laser sources. Pho | ber Optics: r, Classification optical fiber co Detectors: diodes – var oto detector | on, dispers zation main onnectors rious strue – PIN Ph ector noises | ion, attenu ntaining fil ctures, rad | ation, nor bers. Sour | nlinear op rce to fiber nttern, cha | n of tical | f opti 5 Ho effec apling 5 Ho teristi | urs cts- z, urs cs, es- |
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| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources modulation or principles, qua Module:4 Directional cor filters, waveler modulators. | Adva Funda eristics M. Mo oints, fi Optica antum e Optica ouplers, ngth di | intages of opt mentals of Fi of optical fibe dal birefringen iber splicing, o al Sources and ED and laser sources. Pho efficiency, resp al Fiber Comp polarizers, pol | ber Optics: r, Classification optical fiber co Detectors: diodes – var boto detector ponents and I larization split exers and dem | on, dispers zation main onnectors rious struc – PIN Pr ector noises Devices: tters, polar nultiplexers | ion, attenu ntaining fil ctures, rad notodiodes s. ization cor | liation, nor bers. Sour liation pa and Ava | nlinear op rce to fiber attern, cha alanche H | n of tical cou nract Photo lator d fr | f opti 5 Ho effect apling 5 Ho teristi odiod 3 Ho rs, fib | urs cts- g, urs cs, es- urs er ncy |
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| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources modulation or principles, qua Module:4 Directional cor filters, waveler modulators. Module:5 | Adva Funda eristics M. Mo oints, fr Optica antum e Optica uplers, ngth di Princij ulation | intages of opt imentals of Fi of optical fibe dal birefringen iber splicing, o iber splicing, o al Sources and ED and laser sources. Pho efficiency, resp al Fiber Comp polarizers, pol vision multiple | ber Optics: r, Classification ace and polarize optical fiber con- Detectors: diodes – van- boto detector ponents and I larization splite exers and dem Dptic Sensors insic and intri | on, dispers zation main onnectors rious struc – PIN Pr ector noises Devices: tters, polar nultiplexers | ion, attenu ntaining fil ctures, rad notodiodes s. ization cor s, switches – Transmis | liation, nor bers. Sour liation pa and Ava ntrollers, c , intensity | nlinear op ce to fiber ttern, cha alanche H optical iso c, phase an | n of tical tical cou nract Photo laton d fr 1 ficro | f opti 5 Ho effect apling 5 Ho teristic odiod 3 Ho cs, fib equer 0 Ho bend | urs cts- g, urs es- urs er ncy urs ing |
| Introduction - sensors. Module:2 Basic characte SRS, SBS, SP fiber to fiber jo Module:3 Light sources modulation of principles, qua Module:4 Directional co filters, waveler modulators. Module:5 Intensity modu and other Opti | - Adva Funda eristics M. Mo oints, fi Optica 5 – LE f light antum e Optica ngth di Princip ulation ic Effec | intages of opt imentals of Fi of optical fiber dal birefringen iber splicing, o il Sources and ED and laser sources. Pho efficiency, resp al Fiber Comp polarizers, pol vision multiple ples of Fiber C sensors – Extr | ber Optics: r, Classification optical fiber co Detectors: diodes – var oto detector – onsivity, detector ponents and I larization split exers and dem Dptic Sensors finsic and intri- | on, dispers zation main onnectors rious strue – PIN Pr ector noises Devices: tters, polar nultiplexers :: insic type – sensors – | ion, attenu ntaining fil ctures, rad notodiodes ization cor s, switches – Transmis Michelson | ation, nor bers. Sour liation pa and Ava ntrollers, c , intensity | nlinear op ce to fiber attern, cha alanche H optical iso y, phase an lective, M meters, Fa | n of tical tical cou aract Phote lator d fr 1 ficro abry | f opti 5 Ho effect upling 5 Ho teristic odiod 3 Ho cs, fib equer 0 Ho bend - Pe | urs cts- g, urs cs, es- urs er ncy urs ing rot |



Temperature Measurement, Pressure Measurement, Fluid – Level Measurement, Flow Measurement, Current – Voltage Measurement, Vibration Measurement. Laser Doppler velocimetry. Optical gyroscope. Fiber Bragg grating sensors – strain, temperature, pressure and acceleration measurement – distributed sensing. Nonlinear fiber optic sensor for very high temperature sensing.

| Module:7 | Sensor | Multiplexing, | Distributed | Sensors | and | 9 Hours |
|---------------|--------------|-------------------|------------------|-------------|---------|----------------------------------|
| | smart S | tructures: | | | | |
| Sensor netwo | ork archite | ectures. Multiple | exing of intensi | ty-based se | ensors. | Multiplexing of Interferometric |
| sensors. Dist | ributed se | ensing – quasi a | nd fully distril | outed sens | ing – I | linear backscattering, nonlinear |
| backscatterir | ig and fo | rward scattering | g systems. Fib | er optic si | mart se | ensor |
| system – Ap | plication of | of fiber optic sm | art structures a | nd skins | | |

| Modul | e:8 | Contemp | orary issues: | | | 2 Hours |
|---------|--------|----------------|--------------------------|---------------------|----------------|-------------------------------|
| | | | | Total Lectu | re hours: | 45 Hours |
| Text B | ook(s) |) | | | | |
| 1. | Dav | id A. Kroh | in, Trevor W. | MacDougall and | Alexis Me | ndez, "Fiber optic Sensors: |
| | Fund | damental and | d Applications", | SPIE, Fourth Edi | tion, 2015. | |
| 2. | Eric | Uddand Wi | illiam B. Spillm | an, Jr., "Fiber opt | ics sensors: A | An introduction for Engineers |
| | and | scientists", J | ohn Wiley & So | ons, Second Editio | n, 2011. | |
| Refere | nce B | ooks | | | | |
| 1. | Gerc | l Keiser, "O | ptical Fiber Con | nmunications", Ta | ta McGraw H | lill, Fifth Edition, 2013. |
| 2. | José | Miguel Lo | ópez-Higuera, ' | 'Handbook of O | ptical Fibre | Sensing Technology", John |
| | Wile | ey & Sons L | td., 2002. | | | |
| 3. | Zuji | e Fang, Kei | n Chin, Ronghu | i Qu, Haiwen Ca | ai, Kai Chan | g, "Fundamentals of Optical |
| | Fibe | r Sensors", J | John Wiley &So | ons Inc, 2012. | | |
| 4. | Eric | Udd, Willia | m B. Spillman <u>.</u> , | "Field guide to Fi | ber optics ser | nsors", SPIE, 2014. |
| Mode of | of Eva | luation: | CAT I & II – 3 | 0%, DA I & II – 2 | 20%, Quiz – 1 | 0%, FAT – 40% |
| Recom | mende | ed by Board | of Studies | 05/03/2016 | | |
| Approv | ed by | Academic (| Council | 40 th AC | Date | 18/03/2016 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1014.1 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 3 | 2 | - |
| EEE1014.2 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 3 | - |
| EEE1014.3 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 2 | - |
| EEE1014.4 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 2 | - |
| EEE1014.5 | 3 | 3 | 2 | 1 | 2 | - | - | - | 1 | - | - | 1 | 2 | 2 | 3 |
| EEE1014.6 | 3 | 3 | 2 | 1 | 2 | - | - | - | 1 | - | - | 1 | 2 | 2 | 3 |
| | 3 | 3 | 1 | 1 | 2 | | | | 1 | | | 1 | 2 | 2 | 3 |



| EEE1015 | (Deemed to be University Micro Electro | mechanical Systems | L T P J C |
|---------------------------|---|--------------------------------|------------------------|
| | | | |
| Pre-requisite | MAT2002 | | Syllabus version |
| Anti-requisite | NIL | | v. 1.1 |
| Course Objective | es: | | |
| | tand the operation principles of N | | |
| | tand the various micromachining | | |
| | e familiar with a wide variety of | | h as MEMS sensors, |
| KF WEWS | S, Optical MEMS, and Fluidic M | ENIS | |
| Expected Course | e Outcome: | | |
| | n of this course the student will b | e able to: | |
| 1. Understan | d microfabrication techniques a | nd scaling laws for miniaturi | zation |
| | nanufacturing process and strate | | |
| | e working principles of MEMS | | 7 0 |
| • | ne measurement and characteriza Bio-MEMS and relevant detectio | 1 | 18 |
| | EMS based devices for various ap | | |
| 0 | | Privations | |
| | | | |
| | | | |
| | | | |
| | roduction to MEMS: | 4 Hours | |
| Introduction - Ev MEMS | volution from microelectronics- | Comparative Study - Multi | disciplinary nature of |
| | | | |
| Module:2 MI | EMS and Miniaturization: | 6 Hours | |
| Scaling Laws of | Miniaturization - Scaling in G | eometry - Rigid Body Dyr | namics - Electrostatic |
| | agnetic Forces – Electricity - Flu | | |
| | | | |
| | terials and Process: | 10 Hours | |
| | n, Glass, Ceramics; Photolithogra | | |
| | sotropic Etching; Dry Etching Micromachining: basic process f | | |
| | VD, PVD; Epitaxy | iow, release, Stretton, mater | lai enoices, |
| | CMS Actuators and Sensors: | | 10 Hours |
| Cantilevers, Hing | es, Pumps, Motors; comb drive | , levitation, equivalent circu | its; resonator, SAW, |
| Piezoelectric trans | sducers; Thermoelectric devices; | accelerometers & gyroscope | es; RF MEMS Switch |
| | | | |
| Modulo 5 | M for MEMS. | | 5 11 |
| | M for MEMS: | & characterization of m | 5 Hours |
| | aterial properties, measurement and strain, flexural rigidity, | | - |
| combinations | and strain, nexutur ngitity, | restaur stress, soundary | conditions, spring |
| | | | |
| | | | |
| | DEMS and Bio-MEMS: | | 4 Hours |
| MOEMS : Over | DEMS and Bio-MEMS: view, MOEM technology and nicro-optic components, testing | | |



| | e:7 | Applications of MEMS: | | | 4 Hours |
|----------|--------|---|--------------------|-----------|---|
| | | | | | ectrostatic Projection Displays |
| | | Gyroscope; DNA Amplifica | tion; Thermoelect | ric Inkje | et Print heads; Micro valves and |
| Pumps | | | | | |
| Modul | e:8 | Contemporary issues: | | | 2 Hours |
| | | Tota | al Lecture hours: | | 45 Hours |
| Text B | ook(s |) | | | |
| 1. | | hard C. Jaeger, "Introductio cation South Asia, 2014. | on to Microelectr | onic Fa | brication", Singapore: Pearson |
| 2. | Step | ohen D Senturia, "Microsyste | em design", Kluwe | r Acade | emic Publishers, 2003. |
| Refere | ence B | ooks | | | |
| 1. | Mai | | | | nanotechnology. Volume II, technology", Boca Raton, FL |
| 2. | P. R | ai-Choudhury, "MEMS and N | MOEMS Technolo | ogy and | Applications", SPIE, 2017. |
| 3. | | mas Adams and Richard Lay inger, 2010. | ton, "Introductory | MEMS | : Fabrication and Applications", |
| 4. | | H. Bao, "Micromechanical oscopes", Elsevier, 2000. | Transducers: F | ressure | sensors, accelerometers and |
| 5. | | njun Wang, Steven A. Sope ss, 2007. | er, "Bio-MEMS: | Technol | logies and Applications", CRC |
| Mode | of Eva | luation: CAT / Assignment / | Quiz / FAT / Proje | ect / Sen | ninar |
| <u> </u> | mend | ed by Board of Studies | 05/03/2016 | | |
| Recom | monu | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1015.1 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | 1 | - | 1 | 3 | 1 | - |
| EEE1015.2 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | 1 | - | 1 | 2 | 1 | - |
| EEE1015.3 | 3 | 2 | 2 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 2 | - |
| | 2 | 2 | 2 | 1 | | | | | 1 | 1 | | 1 | 2 | 2 | |
| EEE1015.4 | 3 | 3 | 2 | 1 | - | - | - | - | 1 | 1 | - | 1 | 2 | 3 | - |
| EEE1015.5 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 2 | - |
| EEE1015.6 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 2 | - |
| | 3 | 2 | 1 | 1 | | - | - | - | 1 | 1 | | 1 | 2 | 2 | |



| EEE1016 | | | Non Destru | uctive Testin | g | L | Т | P J | C |
|---|---|---|--|---|---|--|--|--|---|
| | | | | | | 3 | 0 | 0 0 | 3 |
| Pre-requisite | • | PHY1001 | | | | Sylla | bus | s vers | sion |
| Anti-requisit | e | NIL | | | | | | v. | 1.0 |
| Course Obje | ctives: | | | | | | | | |
| | • | inderstand the v strial application | | estructive Eva | duation and To | esting meth | ods | , theo | ory |
| Expected Co | ourse O | itcome: | | | | | | | |
| On the compl | letion of | this course the | student will be | able to: | | | | | |
| industrial con 2. Study and 3. Develop an | nponent realize nd demo | on Destructive T s the visual testing nstrate liquid pe of magnetic part | g netrant testing | g methods | | d character | izat | ion o | f |
| | | al implementati ment ultrasonic | | | | | | | |
| | | nent of research | | | E technology | | | | |
| N/ 1 1 1 | X 7• | T | | | | | | | |
| Module:1 | | Testing: | | | | 1.0 | | 6 Ho | |
| | | ual Testing - Vi | | | | | | | |
| · | | l indirect metho | | 0 | - | - · | | | |
| and codes. | ght sour | ces and special | ighting, A sys | stems, compu | iter enhanced | system, sta | nda | rds u | nits |
| | | | | | | | | | |
| Module:2 | Liquid | Penetrant Tes | ing: | | | | | 6 Ho | ours |
| | - | Penetrant Tes | 0 | ants - develo | pers – advant | ages and li | mit | | |
| Principles – | types a | | liquid penetra | | - | - | | ation | s of |
| Principles – various methe | types and a construction of the second se | d properties of | liquid penetra materials - Ap | plication of p | enetrants to pa | arts, remov | al o | ation: f surf | s of |
| Principles – various metho penetrants, p | types and types | d properties of paration of test | liquid penetra materials - Ap | plication of p | enetrants to pa | arts, remov | al o | ation: f surf | s of |
| Principles – various metho penetrants, p | types and types | id properties of eparation of test uning select units and codes | liquid penetra materials - Ap ion of penetr | plication of p | enetrants to pa | arts, remov | al o | ation: f surf | s of face |
| Principles – various metho penetrants, p washable, sta Module:3 | types an ods - Pro ost clea ndards Magno | d properties of eparation of test uning select units and codes etic Particle Tes | liquid penetra materials - Ap ion of penetr ting: | plication of p ant method | - solvent ren | arts, remov novable, w | al o ater | ations f surf 7 Ho | s of face |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m | types an ods - Pro ost clea ndards Magne agnetism | id properties of eparation of test uning select inits and codes tic Particle Tes n -magnetisation | liquid penetra materials - Ap ion of penetr ting: n by means of | plication of p ant method | enetrants to pa - solvent ren | arts, remov novable, w | al o ater | ation: f surf 7 Ho strer | s of face ours |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic | types an ods - Pro ost clea ndards Magne agnetism s - Dep | ad properties of eparation of test uning select units and codes tic Particle Tes n -magnetisation th of penetratic | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir | plication of p ant method f direct and rect pulsating | enetrants to pa - solvent ren alternating cur | arts, remov novable, w rrent - surf cal fields, a | al o ater face | ation: f surf 7 Ho strer | s of face ours ngth es - |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag | types an ods - Pro ost clea ndards Magno agnetist s - Dep netisation | ad properties of eparation of test uning select units and codes etic Particle Test n -magnetisation th of penetration on techniques, f | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a | plication of p ant method f direct and rect pulsating strength con | enetrants to pa - solvent ren alternating cur current typic ductors, right | rrent - surf hand rule t | al o ater face | ations f surf 7 Ho strer antage 1 - Pr | s of face ours ngth es - cods |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu | types an ods - Pro ost clea ndards Magnet agnetism s - Dep netisation | d properties of eparation of test uning select units and codes tic Particle Tes n -magnetisation th of penetratic on techniques, f culation - Long | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne | plication of p ant method f direct and rect pulsating strength con etization - fie | enetrants to pa - solvent ren alternating cur current typic ductors, right d produced by | rrent - surf cal fields, a hand rule to current in | al o ater face adva fielo a co | ations f surf 7 Ho strer antag d - Pr pil, sh | s of face ours ngth es - cods |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu | types an ods - Pro ost clea ndards Magnet agnetism s - Dep netisation | ad properties of eparation of test uning select units and codes etic Particle Test n -magnetisation th of penetration on techniques, f | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne | plication of p ant method f direct and rect pulsating strength con etization - fie | enetrants to pa - solvent ren alternating cur current typic ductors, right d produced by | rrent - surf cal fields, a hand rule to current in | al o ater face adva fielo a co | ations f surf 7 Ho strer antag d - Pr pil, sh | s of face ours ngth es - cods |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). | types an ods - Pro- ost clea ndards <u>Magne</u> agnetism s - Dep netisation rrent ca coils, fio | ad properties of eparation of test uning select units and codes tic Particle Tes n -magnetisation th of penetratic on techniques, f culation - Long eld strength, cur | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne | plication of p ant method f direct and rect pulsating strength con etization - fie | enetrants to pa - solvent ren alternating cur current typic ductors, right d produced by | rrent - surf cal fields, a hand rule to current in | al o ater face adva fielo a co | ations f surf 7 Ho strer antag 1 - Pr pil, sh is | s of face ours ngth es - cods ape |
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| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope | types an ods - Pro- ost clea ndards <u>Magne</u> agnetisr s - Dep netisation rrent ca coils, fion Radiog erties of | ad properties of eparation of test uning select units and codes tic Particle Tes n -magnetisation th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculatio | plication of p ant method f direct and rect pulsating strength con etization - fiel ons, Magneti | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan | arts, removinovable, worknovable, worknova | al o ater ater acce adva field a co alys | ation: f surf 7 Ho strer antage f - Pr pil, sh is 6 Ho of filt | s of face ours ngth es - rods aape ours ers, |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope screens, geor | types an ods - Pro- ost clea ndards - Magne agnetist s - Dep netisation rrent ca coils, fice Radiog erties of netric f | d properties of eparation of test uning - select units and codes tic Particle Tes n -magnetisation th of penetration th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant actors, inverse s | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculatio | plication of p ant method f direct and rect pulsating strength con etization - fiel ons, Magneti orption of ra lm type and | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan ys,scattering, t processing, ch | arts, removinovable, worknovable, worknovabl | al o ater | ation: f surf 7 Ho strer antag d - Pt oil, sh is 6 Ho of filt | s of face ours ngth es - cods ape ours ers, ns - |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope screens, geor density, spee | types an ods - Pro- ost clea ndards - Magno agnetisn s - Dep netisation rrent ca coils, fio Radiog erties of netric fa- ed, cor | d properties of eparation of test uning - select units and codes tic Particle Tes n -magnetisation th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant actors, inverse s trast, Characte | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculatio | plication of p ant method f direct and rect pulsating strength con etization - fiel ons, Magneti orption of ra lm type and Penetramet | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan ys,scattering, t processing, ch ers, Exposure | arts, removinovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, archarts, removinovable, removinovable, archarts, removinovable, removinovable, removinovable, removinovable, worknovable, workanacteristice, worknovable, workanacteristice, workanacteristi | al o ater ater acce adva field a cc alys use o cs c radi | ation: f surf 7 Ho strer antage 1 - Pr oil, sh is 6 Ho of filt ograf | s of face ours ngth es - cods ape ers, ns - phic |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope screens, geor density, spec equivalence, | types an ods - Pro- ost clea ndards - Magno agnetisn s - Dep netisation rrent ca coils, fio Radiog erties of netric fa- ed, cor | d properties of eparation of test uning - select units and codes tic Particle Tes n -magnetisation th of penetration th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant actors, inverse s | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculatio | plication of p ant method f direct and rect pulsating strength con etization - fiel ons, Magneti orption of ra lm type and Penetramet | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan ys,scattering, t processing, ch ers, Exposure | arts, removinovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, archarts, removinovable, removinovable, archarts, removinovable, removinovable, removinovable, removinovable, worknovable, workanacteristice, worknovable, workanacteristice, workanacteristi | al o ater ater acce adva field a cc alys use o cs c radi | ation: f surf 7 Ho strer antage 1 - Pr oil, sh is 6 Ho of filt ograf | s of face ours ngth es - cods ape ers, ns - phic |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope screens, geor density, spece equivalence, Techniques | types an ods - Pro- ost clea ndards of Magne agnetism s - Dep netisation rrent ca coils, fiel Radiog erties of netric fiel ed, cor Radiog | d properties of eparation of test uning - select units and codes tic Particle Tes n -magnetisation th of penetration th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant actors, inverse s trast, Characte caphy of pipes, | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculatio | plication of p ant method f direct and rect pulsating strength con etization - fiel ons, Magneti orption of ra lm type and Penetramet | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan ys,scattering, t processing, ch ers, Exposure | arts, removinovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, worknovable, archarts, removinovable, removinovable, archarts, removinovable, removinovable, removinovable, removinovable, worknovable, workanacteristice, worknovable, workanacteristice, workanacteristi | al o ater ater acce adva field a cc alys use o cs c radi | ation: f surf 7 Ho strer antag d - Pr bil, sh is 6 Ho of filt ograp | s of face ours ngth es - cods ape ours ers, ns - ohic |
| Principles – various metho penetrants, p washable, sta Module:3 Theory of m characteristic Circular mag technique, cu and size of c (MBN). Module:4 X-rays, Prope screens, geor density, spec equivalence, Techniques Module:5 | types an ods - Pro- ost clea ndards <u>Magne</u> agnetist s - Dep netisation rrent ca coils, fio Radiog erties of netric fa ed, cor Radiog | d properties of eparation of test uning - select units and codes tic Particle Tes n -magnetisation th of penetration on techniques, f culation - Long eld strength, cur graphy: X-rays relevant actors, inverse s trast, Characte | liquid penetra materials - Ap ion of penetr ting: n by means of n factors, Dir ield around a tudinal magne rent calculation to NDE. Abs quare, law, fill ristic curves, welds and ca | plication of p ant method f direct and rect pulsating strength con etization - fielons, Magneti orption of ra lm type and Penetramet stings. Safet | enetrants to pa - solvent ren alternating cur g current typic ductors, right d produced by c Burghausan ys,scattering, t processing, ch ers, Exposure y with X-rays | arts, removinovable, with novable, with novable, with novable, with novable, with novable, with novable, with normal fields, a hand rule to current in Noise An in Noise An in Noise An in types and unaracteristic e charts, the charts, the special R | al o ater ater acce adva field a cc alys use o cs o radi | ation: f surf 7 Ho strer antag d - Pr oil, sh is 6 Ho of filt ograp ograp 7 Ho | s of face purs ngth es - cods nape ers, ns - phic phic |



instrumentation - properties of eddy currents - eddy current sensing elements, probes, type of arrangement - a) absolute b) differential lift off, operation, applications, advantages, limitations - Through encircling or around coils, type of arrangements a)absolute b) differential fill factor, operation, application, advantages, limitations - Factors affecting sensing elements and coil impedance - test part and test system - Signal to noise ratio, relationship to eddy current testing - equipment's

| Module: | Ultrasonic | Festing: | | | | 6 Hours |
|-----------|------------------------------------|------------------|-----------------------------------|---------------------|-------------|--------------------------|
| Ultrason | ic NDT principle | es, Different ty | pes of wave mode | s, Phys | ics of wave | e generation, reception, |
| | | | | | | nd interpretation, New |
| | | | | Low Fi | requency M | Methods; Angle beam |
| inspectio | on – thickness me | easurements – A | Applications. | | | |
| | | • | | | | 5 11 |
| Module:7 | | | | | | 5 Hours |
| | • | | - | | - | Condition monitoring of |
| | | | - | | - Destructi | ve testing standards - |
| ASTM, IS | SO, ASNT, API, | ASME boiler a | and pressure vesse | l code. | | |
| Module:8 | Contempo | rary issues: | | | | 2 Hours |
| wiouule.c | , contempo | Tal y Issues. | Total Lastrona ha | | | |
| - | • / > | | Total Lecture ho | burs: | | 45 Hours |
| Text Boo | () | | | | | |
| | | - | [•] , S.l. : Springer, 2 | | | |
| | Ravi Prakash,"No Science, 2012. | on-Destructive | Testing Techniqu | es , Tu | nbridge W | ells : New Academic |
| Referenc | e Books | | | | | |
| 1. (| Charles, J. Hellier | r, Handbook of | Non destructive e | valuati | on, McGrav | w Hill, New York 2013. |
| 2. H | Baldev Raj, T.Ja | yakumar, M.T | havasimuthu , Pr | actical | Non-Destr | uctive Testing", Narosa |
| | Publishing House | | | | | - |
| | - | | n-destructive testi | ng: a t | raining gui | de", Wiley, 2nd Edition |
| | New Jersey, 2005 | | | 0 | 00 | , , |
| Mode of I | Evaluation: | CAT I & II – | 30%, DA I & II – | 20%, 0 | Quiz – 10% | , FAT – 40% |
| Recomme | ended by Board o | of Studies | 05/03/2016 | | | |
| | by Academic Co | | 40 th AC | Date | 18/03/2 | 2016 |
| | | | 1 | | 1 | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| | | | | | | | | | | | | | | | |
| EEE1016.1 | 2 | 1 | - | - | - | - | - | 1 | 3 | 1 | - | - | 2 | - | - |
| EEE1016.2 | 2 | 1 | - | - | - | - | - | 1 | 3 | 1 | - | - | 2 | - | - |
| EEE1016.3 | 3 | 2 | 1 | - | 1 | - | - | 1 | - | 1 | - | - | - | - | - |
| EEE1016.4 | 3 | 2 | - | - | 1 | - | - | - | 3 | 1 | - | - | 2 | 2 | - |
| EEE1016.5 | 3 | 2 | 1 | 1 | 2 | - | - | 3 | 3 | 1 | - | - | 2 | - | 1 |
| EEE1016.6 | 3 | 2 | 1 | - | 2 | - | - | 3 | - | 1 | - | - | 2 | - | 1 |
| EEE1016.7 | 3 | 3 | 2 | - | 2 | - | - | 3 | 3 | 1 | - | 1 | - | - | 1 |
| | 3 | 2 | 1 | 1 | 2 | - | - | 2 | 3 | 1 | - | 1 | 2 | 2 | 1 |



| EEE1018 | Nano Technology Fundamentals And Its Applications | L | ΤI | P J C |
|---|--|---|--------------------------------------|--|
| | | 3 | 0 (| 0 3 |
| Pre-requisit | te PHY1001 | Sy | llabı | us versi |
| Anti-requisi | | · | | v. |
| Course Obj | ectives: | | | |
| 1. To u | nderstand the basic concepts involved in Nanoscience | | | |
| 2. To g | gain knowledge about various methods of synthesis, characterization ar | id appl | icati | ons in |
| | otechnology. | | | |
| | ourse Outcomes: | | | |
| - | pletion of this course the student will be able to: | | | |
| | erstand the fundamental aspects of nanoscience | | | |
| | tify various types of nanomaterials, their properties and applications | | | |
| | pare the different nano fabrication processes | • ~ | | |
| | hesize and understand the properties & application of Carbon Nanotub acterize nanoscale particles using various characterization techniques | es | | |
| | erstand the limitations of current technology and advancements of nanc | scale 4 | electi | onic |
| devic | | Source | | 51110 |
| | y nanotechnology in photonic devices | | | |
| | | | | |
| Module:1 | Basic Concepts | | 8 | B Hours |
| Basic prope | rties of Conductors, Insulators and Semiconductors; Band diagram | n cond | ept | of typi |
| | | | - | • 1 |
| sennconduct | tors, basic Chemistry Concepts, Physical aspects, bonding, w | ave-pa | rticl | e duali |
| | tors; Basic Chemistry Concepts; Physical aspects, Bonding, W Uncertainty Principle, Schrödinger wave equation, Quantum confiner | - | | |
| Heisenberg | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. | - | | |
| Heisenberg 3-D; Effects | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. | - | |), 2-D a |
| Heisenberg 3-D; Effects Module:2 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials | nent ir | 1-D | 0, 2-D a |
| Heisenberg 3-D; Effects Module:2 Basic Types | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube | nent ir | owir | 0, 2-D a |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Func- | nent ir | owir | 0, 2-D a |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs | nent ir | owir | 0, 2-D a 6 Hou es; |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods | nent ir s, Nan tionali | owir | b), 2-D a 6 Hou es; 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc | nent ir s, Nan tionali | owir | b), 2-D a 6 Hou es; 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods | nent ir s, Nan tionali | owir | b), 2-D a 6 Hou es; 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Funces Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. | nent ir s, Nan tionali | owir | b), 2-D a 6 Hou es; 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pu Ablaton met Module:4 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications | s, Nan tionali | owirzed | 6 Hou 6 Hou 5 Hou od, Lase 6 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Funce s Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Classes | s, Nan tionali | owirzed | 6 Hou 6 Hou 5 Hou od, Lase 6 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications | s, Nan tionali | owirzed | 6 Hou 6 Hou 5 Hou od, Lase 6 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials Image: Carbon Nanotubes of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube Description ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Functs Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- CL CNTs for solar cell and energy storage applications Characterization Techniques Characterization Techniques | nent ir s, Nan tionali harge | n 1-D owir zed meth | 6 Hou 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials Image: Construction of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube Scarbon Nanotubes Fabrication Methods Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Cl Characterization Techniques on of characterization methods, Different Microscopy technique Scarbon Vacue | nent ir s, Nan tionali harge r NTs as | n 1-D owir zed meth inte | b), 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials | s, Nan tionali harge NTs as s-Ligh (SEM | t M | b), 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop inciple |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & Resolution, | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials Image: Construction of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube Scarbon Nanotubes Fabrication Methods Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Cl Characterization Techniques on of characterization methods, Different Microscopy technique Scarbon Vacue | s, Nan tionali harge NTs as s-Ligh (SEM | t M | b), 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop inciple |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Don nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & Resolution, Microscopy | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials Image: Carbon Nanotube of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube Description ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Funce Section Fabrication Methods Image: Carbon Nanotube rocesses, Bottom-up processes, Nanolithography techniques, Arc disc Note: Carbon Nanotubes & its applications Carbon Nanotubes & its applications Image: Construction of the cons | s, Nan tionali harge NTs as s-Ligh (SEM | t M | b), 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop finciple mic For |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & Resolution, Microscopy Module:6 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials Image: Carbon Nanotuber of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotuber State Colloidal nanoparticle crystals, Function State Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Function Fabrication Methods Image: Carbon Nanotuber rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Clear State Clear Cl | nent ir s, Nan tionali harge r NTs as s-Ligh (SEM M) & | t M Ator | o, 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop inciple mic For 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Don nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & Resolution, Microscopy Module:6 Si Technolo | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Funces Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Clear cell and energy storage applications Characterization Techniques on of characterization methods, Different Microscopy technique Resolution, Electron Microscopy- Scanning Electron Microscopy Scanning Probe Microscopy- Scanning Tunneling Microscopy (ST. (AFM), Principle & Resolution. Nanoelectronics gy and its limitations, Nanoscale Devices, Single Electron Devices, | nent ir s, Nan tionali harge r NTs as s-Ligh (SEM M) & | t M Ator | o, 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop inciple mic For 5 Hou |
| Heisenberg 3-D; Effects Module:2 Basic Types Quantum Do nanoparticles Module:3 Top-down pr Ablaton met Module:4 Synthesis of CNTFETs, C Module:5 Classificatio Principle & Resolution, Microscopy Module:6 | Uncertainty Principle, Schrödinger wave equation, Quantum confiner of the nanometer length scale- Change in properties. Nanomaterials of Nanostructures- Quantum wells, Quantum Wires-Carbon Nanotube ots, Nanoclusters; Nanoparticles- Colloidal nanoparticle crystals, Funces Fabrication Methods rocesses, Bottom-up processes, Nanolithography techniques, Arc disc hod, Ion Implantation, Chemical Vapour deposition. Carbon Nanotubes & its applications CNTs, Electronic properties, Mechanical properties; Applications- Clear cell and energy storage applications Characterization Techniques on of characterization methods, Different Microscopy technique Resolution, Electron Microscopy- Scanning Electron Microscopy Scanning Probe Microscopy- Scanning Tunneling Microscopy (ST. (AFM), Principle & Resolution. Nanoelectronics gy and its limitations, Nanoscale Devices, Single Electron Devices, | nent ir s, Nan tionali harge r NTs as s-Ligh (SEM M) & | t M Ator | o, 2-D a 6 Hou es; 5 Hou od, Lase 6 Hou rconnec 8 Hou icroscop inciple mic For 5 Hou |



| Phot | tonic Cry | stals and their applications, | Plasmonics, Near fie | eld optic | s, Q-Dot Lasers | |
|------|-----------|-----------------------------------|-----------------------------|-----------|-------------------------|----------|
| Mod | dule:8 | Contemporary issues: | | | | 2 Hours |
| | | | Total Lecture hour | rs: | | 45 Hours |
| Tex | t Book(s) |) | | | | |
| 1 | Jeremy | J. Ramsden, Nanotechnolog | gy-An Introduction, | Second I | Edition, Elseiver, 2016 | |
| 2 | Amreta | shis Sengupta , Chandan Ku | umar Sarkar (Eds.) ' | "Introdu | ction to Nano-Basics to | |
| | Nanosc | ience and Nanotechnology" | , Springer, 2015 | | | |
| Refe | erence B | ooks | | | | |
| 1 | Chri | s Binns , "Introduction to N | lanoscience and Nan | otechnol | ogy", Wiley, 2010 | |
| Mod | le of Eva | luation: CAT / Assignment | / Quiz / FAT / Project | ct / Semi | nar | |
| Reco | ommende | ed by Board of Studies | 05/03/2016 | | | |
| App | roved by | Academic Council | 40 th AC | Date | 18/03/2016 | |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1018.1 | 2 | 2 | 1 | - | - | - | - | 1 | 1 | 2 | - | - | 1 | 1 | - |
| | | | | | | | | | | | | | | | |
| EEE1018.2 | 3 | 2 | 1 | - | - | - | - | 1 | 2 | 2 | - | 1 | 1 | 1 | - |
| EEE1018.3 | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | - | 1 | 1 | - |
| | | | | | | | | | | | | | | | |
| EEE1018.4 | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | - | 1 | 1 | - |
| | | | | | | | | | | | | | | | |
| EEE1018.5 | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | 1 | 1 | 1 | - |
| | | | | | | | | | | | | | | | |
| EEE1018.6 | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | - | 1 | 1 | - |
| EEE1018.7 | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | 1 | 1 | 1 | - |
| | 3 | 3 | 1 | - | - | - | - | 1 | 2 | 2 | - | 1 | 1 | 1 | - |



| EEE1020 | | Engineering Optimization | L T P J C |
|--|---|---|--|
| | | | |
| Pre-requisite | | NIL | Syllabus version |
| Anti-requisit | | NIL | v. 1.1 |
| Course Obje | | | |
| - | | and learning of engineering optimization concepts applied ac | cross the spectrum of |
| course | es in en | gineering curriculum | |
| Expected Co | ourse O | utcome: | |
| | | f each module the student will be able to: | |
| - | | he basic concepts of engineering optimization techniques | |
| | | search methods | |
| • | | ent based optimization method for various algorithms | |
| 4. Form | ulate al | gorithms using conjugate direction methods | |
| 5. Analy | ze dyna | mic optimization techniques | |
| 6. Explo | ore gradi | ent-free optimization techniques and its limitations | |
| | | | |
| | | | |
| | | | |
| N. 1 1. 1 | | | 7 11 |
| Module:1 | | cal Optimization basics | 7 Hours |
| | | le-variable optimization, Multivariable optimization withou | |
| inequality con | iistraints | s, Definitness of matrices, Sylvester's criterion, Convex prog | gramming problem. |
| Module:2 | 1-D se | arch methods | 5 Hours |
| Golden Section | on Sear | ch, Fibonacci Search, Inexact line search. | |
| Madulas? | Creadi | ant based entimization | 7 Цония |
| Module:3 | | ent based optimization | 7 Hours |
| algorithm. | cent me | hod, method of steepest descent, Newton's Method, Leven | berg-Marquardi |
| Module:4 | Coniu | gate Direction Methods: | 7 Hours |
| | • | and conjugate gradient method, Fletcher-Reeves formula. C | |
| of all algorith | | and conjugate gradient method, r fetener-keeves formula. C | onvergence analysis |
| | | | |
| Module:5 | Miscel | laneous topics | 6 Hours |
| D | grammi | ng. Dynamic optimization. Sample applications of gradient | |
| Dynamic prog | | ng. Dynamie opumization. Sample applications of gradient | based and gradient free |
| methods in er | 0 | ng. | based and gradient free |
| methods in er Module:6 | Appli | ng. cation of optimization methods to neural networks | 5 Hours |
| methods in er Module:6 NN basics, ca | Appli apabiliti | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron | 5 Hours |
| methods in er Module:6 | Appli apabiliti | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron | 5 Hours |
| methods in er Module:6 NN basics, ca based and gra | Appli apabiliti adient fr | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. | 5 Hours n. Training by gradient |
| methods in er Module:6 NN basics, ca based and gra Module:7 | Appli apabiliti adient fr Gradi | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization | 5 Hours n. Training by gradient 6 Hours |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and inc | Appli apabiliti adient fr Gradi direct m | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization nethods, Limitations of gradient based methods, metaheurist | 5 Hours n. Training by gradient 6 Hours tic algorithms, |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and inc | Appli apabiliti adient fr Gradi direct m | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization | 5 Hours n. Training by gradient 6 Hours tic algorithms, |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and inc Introduction t | Appli apabiliti adient fr Gradi direct m to the ge | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization nethods, Limitations of gradient based methods, metaheurist enetic algorithm, particle swarm optimization. Simulated and | 5 Hours n. Training by gradient 6 Hours tic algorithms, nealing. |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and inc | Appli apabiliti adient fr Gradi direct m to the ge | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization nethods, Limitations of gradient based methods, metaheurist | 5 Hours n. Training by gradient 6 Hours tic algorithms, |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and ind Introduction to Module:8 | Appli apabiliti adient fr Gradi direct m to the ge | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization nethods, Limitations of gradient based methods, metaheurist enetic algorithm, particle swarm optimization. Simulated and | 5 Hours n. Training by gradient 6 Hours tic algorithms, nealing. |
| methods in er Module:6 NN basics, ca based and gra Module:7 Direct and inc Introduction t Module:8 Text Book | Appli apabiliti adient fr Gradie direct m to the ge Conte | ng. cation of optimization methods to neural networks es and limitations of single perceptron, multilayer perceptron ee methods. ent-free Optimization nethods, Limitations of gradient based methods, metaheurist enetic algorithm, particle swarm optimization. Simulated and | 5 Hours n. Training by gradient 6 Hours tic algorithms, nealing. 2 Hours |



| Refere | ence Books | | | |
|--------|--------------------------------------|---------------------|--------------------|-----------------------------|
| 1. | Engineering Optimization, Theo 2009. | ry and Practic | e by S S Rao, John | Wiley & Sons, Inc., IV Ed., |
| 2. | Practical Methods of Optimizati | on, by Fletche | r, John Wiley & So | ons, Inc., II Ed., 2006 |
| 3. | Current literature. | | | |
| Mode | of Evaluation: CAT / Assignment / | / Quiz / FAT / | Project / Seminar | |
| Recom | nmended by Board of Studies | 05/03/2016 | | |
| Approv | ved by Academic Council | 40 th AC | Date | 18/03/2016 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE1020.1 | 3 | 2 | 1 | 1 | 1 | - | - | - | 1 | 1 | - | 1 | 1 | 1 | 1 |
| EEE1020.2 | 3 | 3 | 1 | 1 | 1 | - | - | 1 | - | - | - | 1 | 1 | 1 | 1 |
| | | | | | | | | | | | | | | | |
| EEE1020.3 | 3 | 2 | 2 | 1 | 1 | - | - | 1 | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE1020.4 | 3 | 2 | 1 | 1 | 1 | - | - | - | 1 | 1 | - | 1 | 2 | 1 | 1 |
| EEE1020.5 | 3 | 2 | 1 | 1 | 1 | - | - | 1 | - | - | - | 1 | 2 | 1 | 1 |
| | | | | | | | | | | | | | | | |
| EEE1020.6 | 3 | 3 | 1 | 1 | 1 | - | - | - | - | - | - | 1 | 2 | 1 | 1 |
| | 3 | 2 | 1 | 1 | 1 | | - | 1 | 1 | 1 | | 1 | 2 | 1 | 1 |



| EEE2006 | Communication Engineering | L | T | P J | С |
|---|---|---|------------------------------------|--|---|
| | | 3 | 0 | 2 0 | 4 |
| Pre-requisite | EEE1005 | Sylla | ibus | s vers | sion |
| Anti-requisite | NIL | · | | | 2.0 |
| Course Objectives | 5: | | | | |
| fundamenta 2. To teach th 3. To provide | e students various communication systems and its analysis & basic understanding of appropriate tools and technologies to ation-engineering solutions. | applicat | | - | |
| | of this course the student will be able to: | | | | |
| 1 | te the need for modulation. | | | | |
| | e presence of noise in communication systems. | | | | |
| | odulation techniques for analog and digital Signals. | | | | |
| | smitters and receivers for communication systems | | | | |
| 0 | ous shift keying techniques. | | | | |
| 6. Demonstrat | te spread spectrum techniques and channel assignment strateg | gies. | | | |
| 2 | d design modern communication systems. | | | | |
| 8. Design and | Conduct experiments, as well as analyze and interpret data | | | | |
| | | | | | |
| | oduction to Communication System | | | 6 Ho | |
| | stems: Introduction, need, importance, elements, block diagr | | | | ch |
| | ency ranges – bandwidth– pre-emphasis and de-emphasis –m | odulatio | n ar | nd its | |
| | of electronic communications. | | | 4 11 | |
| | e in CW Modulation System | • | | 4 H o | ours |
| | ternal noise – noise voltage – signal-to-noise ratio– noise figu | re - not | se | | |
| 1 | e in CW modulation systems. | | | 8 Ho | |
| 1 | blitude Modulation | | VCI | | JUIS |
| - | l generation of analog modulation systems including AM, SS n, power relation– different types of modulators – AM transm | | | | d |
| | ion – SSB transmitter – AM demodulators: Square-law detec | | | | lu |
| | letector, synchronous detector – characteristics of receivers – | | | | - |
| | per heterodyne receiver – SSB receiver – comparison of diffe | | | | |
| <u></u> | | | - Jo | ••••••••• | |
| | | | | | |
| Module:4 Phas | se Modulation: | | 1 | 1 0 H a | JUIS |
| Representation and NBFM and WBFM conversion of FM | Se Modulation: d generation of frequency and phase modulation (FM and M – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and of FM super heterodyne receiver– slope detectors – HF Comm. | son of Foscillator | gene M a | nd Pl quenc | n of M – cies |
| Representation and NBFM and WBFM conversion of FM – AVC – AFC – I diversity reception | d generation of frequency and phase modulation (FM and A – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and cFM super heterodyne receiver– slope detectors – HF Comm. | son of Foscillator | gene M a | ration and Pl quence eceive | n of M – cies er – |
| Representation and NBFM and WBFM conversion of FM - AVC - AFC - H diversity receptionModule:5Puls | d generation of frequency and phase modulation (FM and A – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and c FM super heterodyne receiver– slope detectors – HF Comm. | son of F oscillator unicatio | gene M a fre n Ro | ration and Pl quence eceive 5 Ho | n of M – cies er – |
| RepresentationNBFM and WBFMconversion of FM- AVC - AFC - Hdiversity receptionModule:5PulsePulse modulations | d generation of frequency and phase modulation (FM and A – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and of FM super heterodyne receiver– slope detectors – HF Comm. e Modulation Systems – sampling theorem – pulse amplitude modulation– pulse | son of F oscillator unicatio width m | gene M a fre n Ro nodu | ration and Pl quence eceive 5 Ho alatio | n of M – cies er – ours n – |
| RepresentationNBFM and WBFMconversion of FM- AVC - AFC - Idiversity receptionModule:5PulsePulse modulationspulse position mode | d generation of frequency and phase modulation (FM and A – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and of FM super heterodyne receiver– slope detectors – HF Comm. e Modulation Systems – sampling theorem – pulse amplitude modulation– pulse lulation – signal to noise ratio of pulse modulation systems – | son of F oscillator unicatio width m | gene M a fre n Ro nodu | ration and Pl quence eceive 5 Ho alatio | n of M – cies er – ours n – |
| RepresentationNBFM and WBFMconversion of FM- AVC - AFC - Hdiversity receptionModule:5PulsePulse modulationspulse position modpulse code modulations | d generation of frequency and phase modulation (FM and A – FM transmitters – comparison of AM and FM – comparito PM and PM to FM – TRF Receivers – Choice of IF and of FM super heterodyne receiver– slope detectors – HF Comm. e Modulation Systems – sampling theorem – pulse amplitude modulation– pulse lulation – signal to noise ratio of pulse modulation systems – | son of F oscillator unicatio width m | gene M a fre n Ro nodu | ration and Pl quence eceive 5 Ho alatio | n of M – cies er – ours n – |



| disac | lvantage | es of digital communication s | systems. | | | |
|-------|------------|---|------------------------|-----------|--------------------|---------------------------------------|
| | | | | | | |
| Mod | lule:7 | Cellular concept | | | | 5 Hours |
| Char | nnel assi | gnment strategies – interfere | ence and system ca | apacity – | spread spectrum | n modulation – |
| direc | t seque | nce spread spectrum – Frequ | uency hop spread | spectrui | n – code divisio | on multiplexing – |
| OFD | M for w | vireless communication – Bro | oadband integrate | d service | es network. | |
| Mod | lule:8 | Contemporary issues: | | | | 2 Hours |
| | | | Total Lecture h | ours: | | 45 Hours |
| Text | t Book(s |) | | | | |
| 1. | Sim Cor | on Haykin; Michael M nmunications.", Hoboken : V | | | n to Analog | and Digital |
| 2. | Leo | n W Couch, "Digital and an | alog communicat | ion syste | ms", Upper Sad | dle River, N.J, |
| | | ntice Hall, 2013 | e | | | , , , , , , , , , , , , , , , , , , , |
| 3. | Rap | paport T.S., "Wireless Com | nunications", Pea | rson Edu | cation, 2010. | |
| Refe | erence B | | | | · | |
| 1. | | bert Taub; Donald L Sch ems", New Delhi : McGrew | | | Principles of c | ommunication |
| 2. | Ran | njee Prasad, "OFDM for ech House, 2004. | | | systems", Bos | ston; London: |
| 3. | Way | yne Tomasi, "Electronic | Communication | System | s – Fundame | ntals through |
| | | anced", 4th edition, Pearson | | 5 | | U |
| 4. | Joh | n G Proakis; Masoud Sal Graw-Hill 2014. | | mmunic | ation", 5th edi | tion, New York |
| 5. | Ken 200 | nedy and Davis, "Electronic 8. | Communication | Systems | ", 4th edition, Ta | ata McGraw Hill, |
| Mod | e of Eva | luation: CAT / Assignment | / Quiz / FAT / Pro | ject / Se | minar | |
| | | | - | | | |
| List | of Chal | lenging Experiments (Indic | cative) | | | |
| 1. | | ude Modulation | - | | | 2 hours |
| 2. | Pre-En | nphasis and De-Emphasis | | | | 2 hours |
| 3. | | Amplitude Modulation | | | | 2 hours |
| 4. | | Width Modulation | | | | 2 hours |
| 5. | | ncy Modulation/Mixer | | | | 2 hours |
| 6. | - | tion of Shift Keying Method | s | | | 2 hours |
| 7. | | SSB Modulation and Detection | | | | 2 hours |
| 8. | , | d PM Modulation and Detect | | | | 2 hours |
| 9. | | Code Modulation and Delta N | | | | 2 hours |
| 10. | | tion and Detection of spread | | | | 2 hours |
| | | rr- | 1 | otal Lab | oratory Hours | 30 hours |
| Reco | ommend | ed by Board of Studies | 30/11/2015 | | J | |
| | | Academic Council | 39 th AC | Date | 17/12/2015 | |
| | | | | | | |



| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE2006.1 | 2 | 1 | - | - | - | - | - | 2 | 2 | 2 | - | 2 | 2 | - | 2 |
| EEE2006.2 | 2 | 1 | - | - | 1 | - | - | - | 1 | 2 | - | 1 | 2 | 1 | 2 |
| EEE2006.3 | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | 3 | - | 1 | 2 | - | 2 |
| EEE2006.4 | 2 | 1 | - | - | - | - | - | - | - | - | I | - | 3 | - | 2 |
| EEE2006.5 | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | 3 | I | 1 | 2 | - | 2 |
| | | | | | | | | | | | | | | | |
| EEE2006.6 | 3 | 3 | - | - | 2 | - | - | - | - | 1 | - | - | 2 | - | 2 |
| EEE2006.7 | 3 | 3 | - | - | 2 | - | - | - | - | 1 | I | - | 2 | - | 2 |
| | | | | | | | | | | | | | | | |
| EEE2006.8 | 3 | 3 | 3 | 2 | 3 | - | - | 2 | 3 | 2 | - | 1 | 2 | 2 | 2 |
| | 3 | 3 | 3 | 2 | 2 | - | - | 2 | 2 | 2 | - | 2 | 3 | 2 | 2 |



| EEE2008 | Electrical Technology | L | Т | P | J | С |
|--|---|------------------------------|---|--|---|--|
| | | 3 | 0 | 2 | 0 | 4 |
| Pre-requisite | EEE1002 | | Sylla | bus | vers | ion |
| Anti-requisite | NIL | | v | | | 1.0 |
| Course Objectives | | | | | | |
| | he basic working principle of DC Machines | | | | | |
| - | nd the various performance and testing of transformer | | | | | |
| | e various characteristics of AC Machines and Special Machines | nes | | | | |
| Expected Course | _ | | | | | |
| - | of this course the student will be able to: | | | | | |
| - | the constructional details and working principle of DC Gen | erato | or | | | |
| | evaluate the performance characteristics of DC motor | | | | | |
| • | the theory and operation of transformer | | | | | |
| | e equivalent circuit parameters of transformer | | | | | |
| | working principle of synchronous generator | | | | | |
| - | d the working principle of synchronous motor and application | ons | | | | |
| 7. Understand | the different types of induction motor and miscellaneous ma | achi | nes | | | |
| | | | | | | |
| | | | | | | |
| Module:1 DC 0 | enerators: | | | 7 | Ho | urs |
| Constructional det | ails of DC machines, Operation of DC generators - | - E | MF | equa | ation | _ |
| | ifferent types of generators. | | | • | | |
| Module:2 DC M | Iotors: | | | (| 6 Ho | urs |
| Principle of operat | ion of DC motors – Torque and speed equation – Charac | teris | stics | of d | liffer | ent |
| types of DC motors | - Starting, braking and speed control of DC motors, Simple | e pro | blen | ns of | emf | • |
| Module:3 Cons | truction of Transformers: | | | (| 6 Ho | urs |
| | | | | | | |
| Principle – Types – | general constructional feature of single phase and three pha | ise ti | ansf | orme | ers. | |
| | general constructional feature of single phase and three phaormance evaluation of Transformers:6 Hours | ise ti | ansf | orme | ers. | |
| Module:4 Perfo | | | | | | on |
| Module:4PerformPhasor diagramsa | ormance evaluation of Transformers: 6 Hours | C a | nd S | SC 7 | ſest | |
| Module:4PerformPhasor diagramsa | ormance evaluation of Transformers:6 Hoursand equivalent circuit – Regulation and efficiency – O | C a | nd S | SC 7 | ſest | |
| Module:4PerformersPhasor diagrams a transformers- Si Autotransformers. | ormance evaluation of Transformers:6 Hoursand equivalent circuit – Regulation and efficiency – O | C a | nd S | SC 7 v wi | ſest | gs, |
| Module:4PerformanPhasor diagrams atransformersAutotransformers.Module:5Synce | ormance evaluation of Transformers:6 Hoursand equivalent circuit – Regulation and efficiency – Omple problems on emf induced in the Primary & S | C a ecoi | nd S ndary | SC 7 / wi | Fest ndin 6 Ho | gs, urs |
| Module:4PerformPhasor diagrams atransformers - SiAutotransformers.Module:5Sync.Principle of operation | ormance evaluation of Transformers:6 Hoursand equivalent circuit – Regulation and efficiency – Omple problems on emf induced in the Primary & Shronous Generator: | C a ecoi | nd S ndary | SC 7 / wi | Fest ndin 6 Ho | gs, urs |
| Module:4PerformanPhasor diagrams atransformersAutotransformers.Module:5SyncPrinciple of operatCharacteristics – El | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. | C a ecoi | nd S ndary | SC 7 / wi gener | Fest ndin 5 Ho rators | gs, urs s – |
| Module:4PerformanPhasor diagrams atransformersAutotransformers.Module:5SyncPrinciple of operatCharacteristics – ElModule:6Sync | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: | C a ecor ronc | nd S ndary ous g | SC 7 / wi gener | Fest ndin 6 Ho rators | gs, urs s – urs |
| Module:4PerformanPhasor diagrams atransformers - SiAutotransformers.Module:5SyncPrinciple of operatCharacteristics - ElModule:6SyncPrinciple of operat | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. | C a ecor ronc | nd S ndary ous g | SC 7 / wi gener | Fest ndin 6 Ho rators | gs, urs s – urs |
| Module:4PerformanPhasor diagrams atransformersAutotransformers.Module:5SyncPrinciple of operatCharacteristics – ElModule:6Sync | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: | C a ecor ronc | nd S ndary ous g | SC 7 / wi gener | Fest ndin 6 Ho rators | gs, urs s – urs |
| Module:4PerformanPhasor diagrams a transformers - Si Autotransformers.Si SynchModule:5SynchPrinciple of operat Characteristics - ElModule:6SynchPrinciple of operat Hunting. | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: ation-Phasor diagram of synchronous motor – V curve – | C a ecor ronc | nd S ndary ous g | SC 7 v wi gener gener | Fest ndin 5 Ho ators 5 Ho thod | gs, urs 5 urs 8, |
| Module:4PerformanPhasor diagrams a transformers - Si Autotransformers.Si SyncModule:5SyncPrinciple of operat Characteristics - ElSyncModule:6SyncPrinciple of operat Hunting.Indu | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: ation-Phasor diagram of synchronous motor – V curve – ction and Miscellaneous Machines: | ronc | nd S ndary ous g | GC 1 7 wi gener | Test ndin 5 Ho thod | gs, urs s – urs s, urs |
| Module:4PerformanPhasor diagrams a transformers – Si Autotransformers.Si SynchModule:5SynchModule:5SynchPrinciple of operat Characteristics – ElModule:6SynchPrinciple of operat Hunting.Module:7IndueTypes – Construct | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: ation-Phasor diagram of synchronous motor – V curve – ction and Miscellaneous Machines: ional features of 3-phase induction motors – phasor diagram | C a econ rond - Sta | nd S ndary ous g urting n – | SC 7 wi gener g me | Test ndin 5 Ho thod 7 Ho tor | gs, urs s – urs s, urs que |
| Module:4PerformanPhasor diagrams a transformers – Si Autotransformers.Si Autotransformers.Module:5SyncPrinciple of operat Characteristics – ElModule:6SyncPrinciple of operat Hunting.Module:7InduTypes – Construct characteristics – St | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: ation-Phasor diagram of synchronous motor – V curve – ction and Miscellaneous Machines: ional features of 3-phase induction motors – phasor dia arting and speed control methods – principles of operation | C a econ ronc Sta | nd S ndary ous g urting n – | y wi gener g me Slip es of | Fest ndin 5 Ho 5 Ho thod 7 Ho tore 5 sing | gs, urs 3 – urs s, urs que gle- |
| Module:4PerformanPhasor diagrams a transformersSiAutotransformersSiAutotransformersSyncModule:5SyncPrinciple of operat Characteristics – ElModule:6SyncPrinciple of operat Hunting.SyncModule:7Indue Types – Construct characteristics – St phase induction mode | ormance evaluation of Transformers: 6 Hours and equivalent circuit – Regulation and efficiency – O mple problems on emf induced in the Primary & S hronous Generator: ion – Types and general constructional features – synch MF equation – Regulation –Simple problems on emf. hronous Motor: ation-Phasor diagram of synchronous motor – V curve – ction and Miscellaneous Machines: ional features of 3-phase induction motors – phasor diagram | C a econ ronc Sta | nd S ndary ous g urting n – | y wi gener g me Slip es of | Fest ndin 5 Ho 5 Ho thod 7 Ho tore 5 sing | gs, urs 3 – urs s, urs que gle- |



| Module:8 Contemporary issues: | | | | | | | | |
|-------------------------------|--|--|-------------------|------------------|----------------------|--|--|--|
| | | Total | Lecture hours | : | 45 Hours | | | |
| List | of Chall | enging Experiments (Indicative) | | | | | | |
| 1. | OCC of | f DC shunt generator | | | 2 hours | | | |
| 2. | Load c | naracteristics of DC shunt generato | r | | 2 hours | | | |
| 3. | Load te | est on DC compound generator | | | 2 hours | | | |
| 4. | No load | l saturation characteristics of separ | ately excited I | C generator | 2 hours | | | |
| 5. | Load c | naracteristics of DC series generato | r | | 2 hours | | | |
| 6. | 2 hours | | | | | | | |
| 7. | 2 hours | | | | | | | |
| 8. | Load te | est on DC shunt motor | | | 2 hours | | | |
| 9. | Speed of | control of DC shunt motor | | | 2 hours | | | |
| 10. | Swinbu | rne's Test | | | 2 hours | | | |
| 11. | OC/SC | test on a single phase transformer | | | 2 hours | | | |
| 12. | Load te | st on single phase transformer | | | 2 hours | | | |
| 13. | Paralle | operation of single phase transform | ner | | 2 hours | | | |
| 14. | Predete | rmination of percentage regulati | on of alternation | or by synchron | ous 2 hours | | | |
| | impeda | nce method | | | | | | |
| 15. | Load te | st on three phase alternator with re | sistive load | | 2 hours | | | |
| 16. | Load te | st on three phase alternator with R | L load | | 2 hours | | | |
| 17. | | st on single phase Induction motor | | | 2 hours | | | |
| 18. | | st on three phase squirrel cage indu | | | 2 hours | | | |
| 19. | Load te | st on three phase slip-ring inductio | | | 2 hours | | | |
| | | | Tota | l Laboratory Ho | ours 30 hours | | | |
| Text | Book(s | | | | | | | |
| 1. | | Kothari and I.J. Nagrath, "Electric ion, 2014. | al Machines", | Tata McGraw-H | fill Education, 4th | | | |
| 2. | | ijit Chakrabarti, Sudipta Debnat cation, 2012. | h, "Electrical | Machines", Ta | ata McGraw-Hill | | | |
| Refe | erence B | ooks | | | | | | |
| 1. | Cott | on H, "Advanced Electrical Tech | nology", CB | S Publishers and | d Distributors, New. | | | |
| | Dell | ni, 2001. | | | | | | |
| | R.K.Rajput, "A Text Book Electrical Machines", Laxmi Publication, 4 th Edition, 2016. | | | | | | | |
| | B.L.Theraja and A.K.Theraja, "A Text Book of Electrical Technology", S.Chand, Vol. No. | | | | | | | |
| | 2, 9 ^t | ^h Edition, 2014. | | | | | | |
| Mod | e of Eva | luation: CAT I & II $-$ 30%, D | A I & II – 20% | , Quiz – 10%, FA | AT - 40% | | | |
| Reco | ommende | ed by Board of Studies 05/03/ | 2016 | | | | | |
| App | roved by | Academic Council 40th A | C Da | te 18/0 | 3/2016 | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE2008.1 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | 2 | 1 | - |
| EEE2008.2 | 3 | 3 | 3 | 1 | - | - | - | - | 1 | - | - | - | 1 | 3 | - |
| EEE2008.3 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | 1 | 1 | - |
| EEE2008.4 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | - | 1 | 3 | - |
| EEE2008.5 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | - | 1 | 2 | - |
| EEE2008.6 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | 1 | 1 | - |
| EEE2008.7 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | 2 | 1 | - |
| | 3 | 3 | 3 | 3 | - | - | - | - | 1 | - | - | - | 2 | 3 | - |



| EEE3008 | Data Communication Net | work | L T P J C |
|---|--|---|---|
| | | | |
| Pre-requisite | EEE2006 | | Syllabus version |
| Anti-requisite | NIL | | v. 1.0 |
| Course Object | | | |
| · | h the basic fundamentals in network topology. | | |
| | vide essential knowledge on various layer in OSI r | nodel | |
| | ose the students to the recent advances in various | | ation layer. |
| 4. To teac | h various networking. | | |
| | | | |
| Expected Cou | | | |
| - | ion of this course the student will be able to: | _ | |
| | and the overview of a data communication and ne | | |
| - | e the bandwidth utilization and switching of data i | networks | |
| | and the protocol of seven layer model. Thend and configure Local Area Networks | | |
| - | he various communication methods in transmission | on media | |
| 11.4 | and the different coding methods to avoid error in | | in data link laver. |
| | ate the strategies for QoS network applications | r communication | in dutu inik iugor. |
| | ate usefulness and importance of application laye | er protocol in toda | y life and society |
| 11 | | 1 | 55 |
| Module:1 | Overview of data communication: | | 4 Hours |
| Introduction- I | Data Communications, Networks, The Internet, | Protocols and St | andards, Network |
| Models- The O | OSI Model, Layers in the OSI Model, TCP/IP I | Protocol Suite, A | ddressing, Physical |
| Layer and Med | ia. | | |
| | | | |
| | Bandwidth utilization and switching: | | 6 Hours |
| | nd Spreading, Transmission Media Wireless. Sw | | Switched Networks, |
| Datagram Netw | orks, Virtual-Circuit Networks, Structure of a Sw | vitch. | |
| 1 | | | |
| Module:3 | Data Link Layer: | | 7 Hours |
| | \cdot | | |
| Error Detection | and Correction- Block Coding, Liner Block Co | • | |
| Error Detection Link Control - | Framing, Flow and Error Control, Protocols, Noise | eless Channels, H | DLC, Point-to- Point |
| Error Detection Link Control - Protocol, Mult | Framing, Flow and Error Control, Protocols, Noise apple Access - Random Access, Controlled Acces | eless Channels, Hl s, Channelization | DLC, Point-to-Point a, IEEE Standards - |
| Error Detection Link Control - Protocol, Mult Standard Ethe | Framing, Flow and Error Control, Protocols, Noise ple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, | eless Channels, Hl s, Channelization | DLC, Point-to-Point a, IEEE Standards - |
| Error Detection Link Control - Protocol, Mult | Framing, Flow and Error Control, Protocols, Noise ple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, | eless Channels, Hl s, Channelization | DLC, Point-to-Point a, IEEE Standards - |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto | Framing, Flow and Error Control, Protocols, Noise ple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, oth | eless Channels, Hl s, Channelization | DLC, Point-to- Point a, IEEE Standards - , IEEE |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto Module:4 | Framing, Flow and Error Control, Protocols, Noise ple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, oth | eless Channels, HI s, Channelization Gigabit Ethernet | DLC, Point-to- Point a, IEEE Standards - , IEEE <u>6 Hours</u> |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto Module:4 | Framing, Flow and Error Control, Protocols, Noise pple Access - Random Access, Controlled Acces met, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con | eless Channels, Hi s, Channelization Gigabit Ethernet necting Devices, | DLC, Point-to- Point a, IEEE Standards - , IEEE <u>6 Hours</u> Cellular Telephony, |
| Error Detection Link Control - T Protocol, Mult Standard Ether 802.11, Blueto Module:4 Connecting LA Satellite Netwo | Framing, Flow and Error Control, Protocols, Noise iple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con orks, Sonet/SDH, Architecture, STS Multiplexing, | eless Channels, Hi s, Channelization Gigabit Ethernet necting Devices, Sonet Networks, | DLC, Point-to- Point n, IEEE Standards - , IEEE 6 Hours Cellular Telephony, , Virtual Tributaries, |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto Module:4 Connecting LA Satellite Netwo Virtual-Circuit | Framing, Flow and Error Control, Protocols, Noise pple Access - Random Access, Controlled Access met, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con orks, Sonet/SDH, Architecture, STS Multiplexing, Networks: Frame Relay and ATM, Frame Relay, | eless Channels, Hi s, Channelization Gigabit Ethernet necting Devices, Sonet Networks, | DLC, Point-to- Point a, IEEE Standards - , IEEE <u>6 Hours</u> Cellular Telephony, , Virtual Tributaries, Ns. |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto Module:4 Connecting LA Satellite Netwo Virtual-Circuit Module:5 | Framing, Flow and Error Control, Protocols, Noise iple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con orks, Sonet/SDH, Architecture, STS Multiplexing, Networks: Frame Relay and ATM, Frame Relay, Network Layer: | eless Channels, HI s, Channelization Gigabit Ethernet necting Devices, Sonet Networks, ATM, ATM LA | DLC, Point-to- Point n, IEEE Standards - , IEEE 6 Hours Cellular Telephony, , Virtual Tributaries, Ns. 6 Hours |
| Error Detection Link Control - Protocol, Mult Standard Ether 802.11, Blueto Module:4 Satellite Network Virtual-Circuit Module:5 Network Laye | Framing, Flow and Error Control, Protocols, Noise apple Access - Random Access, Controlled Access met, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con orks, Sonet/SDH, Architecture, STS Multiplexing, Networks: Frame Relay and ATM, Frame Relay, Network Layer: r: Internet Protocol, Internetworking, IPv4, IP | eless Channels, HI s, Channelization Gigabit Ethernet necting Devices, Sonet Networks, ATM, ATM LA | DLC, Point-to- Point a, IEEE Standards - , IEEE 6 Hours Cellular Telephony, Virtual Tributaries, Ns. 6 Hours From IPv4 to IPv6, |
| Error Detection Link Control - T Protocol, Mult Standard Ethe 802.11, Blueto Module:4 I Connecting LA Satellite Network Virtual-Circuit Module:5 N Network Laye Address Mapp | Framing, Flow and Error Control, Protocols, Noise iple Access - Random Access, Controlled Acces rnet, Changes in the Standard, Fast Ethernet, oth Local Area Network: Ns, Backbone Networks, and Virtual LANs, Con orks, Sonet/SDH, Architecture, STS Multiplexing, Networks: Frame Relay and ATM, Frame Relay, Network Layer: | eless Channels, HI s, Channelization Gigabit Ethernet necting Devices, Sonet Networks, ATM, ATM LA | DLC, Point-to- Point a, IEEE Standards - , IEEE 6 Hours Cellular Telephony, Virtual Tributaries, Ns. 6 Hours From IPv4 to IPv6, |



| Module:6 | Transport Layer: | 6 Hours | | | | | | | | | | |
|--|--|--|--|--|--|--|--|--|--|--|--|--|
| Process-Proc | cess Delivery: UDP, TCP and SCTP, Process-to | -Process Delivery, User Datagram | | | | | | | | | | |
| • | DP), TCP, SCTP, Congestion Control and Quality o | | | | | | | | | | | |
| 0 | Control, Quality Service, Techniques to improve QoS | S, Integrated Services, Differentiated | | | | | | | | | | |
| Services, Qo | S in Switched Networks. | | | | | | | | | | | |
| | | | | | | | | | | | | |
| Module:7 | Application Layer: | 8 Hours | | | | | | | | | | |
| Domain Nar | ne System - Name Space, Domain Name Space, Dist | tribution of Name Space, DNS in the | | | | | | | | | | |
| Internet, Res | olution, DNS Messages, Types of Records, Registra | ars, Dynamic Domain Name System | | | | | | | | | | |
| (DDNS), End | capsulation, Remote Logging, Electronic Mail and Fi | le Transfer, Remote Logging, Telnet, | | | | | | | | | | |
| | lail, File Transfer. | | | | | | | | | | | |
| WWW and | | | | | | | | | | | | |
| | , Web Documents, HTTP, Network Management: SN | č . | | | | | | | | | | |
| | | | | | | | | | | | | |
| Video Comp | pression. Streaming Stored Audio/Video. Streaming | Simple Network Management Protocol (SNMP), Multimedia, Digitizing Audio and Video, Audio and Video Compression, Streaming Stored Audio/Video, Streaming Live Audio/Video, Real- Time | | | | | | | | | | |
| | | ing Live Hudio, video, iteur Time | | | | | | | | | | |
| Interactive A | udio/Video, RTP, RTCP, Voice over IP. | | | | | | | | | | | |
| | udio/Video, RTP, RTCP, Voice over IP. | | | | | | | | | | | |
| Interactive A Module:8 | udio/Video, RTP, RTCP, Voice over IP. Contemporary issues: | 2 Hours | | | | | | | | | | |
| Module:8 | udio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours: | | | | | | | | | | | |
| Module:8 Text Book(s | udio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours: | 2 Hours 45 Hours | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A | udio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours: | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tanes | Ludio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours:) . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 50 | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tanez Reference B | Ludio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours:) . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 50 | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tane Reference B 1. W. T | udio/Video, RTP, RTCP, Voice over IP. Contemporary issues: Total Lecture hours:) . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 51 ooks | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tanez Reference B 1. W. T 4thEc | Contemporary issues: Total Lecture hours: O Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 51 ooks 'omasi, "Introduction to Data communications and dition, 2005. | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, | | | | | | | | | | |
| Module:8 Text Book(s 1. Behrouz A 2. A. S. Tane Reference B 1. W. T 4thEc 2. G.S.H | Contemporary issues: Total Lecture hours: Ontemporary issues: Total Lecture hours:) . . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 50 ooks 'omasi, "Introduction to Data communications and dition, 2005. Hura and M.Singhal, "Data and Computer Communications | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, cations", CRC Press, 2001. | | | | | | | | | | |
| Module:8 Text Book(s 1. Behrouz A 2. A. S. Tane Reference B 1. W. T 4thEc 2. G.S.H 3. S.Kes | Contemporary issues: Total Lecture hours: O Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 51 ooks 'omasi, "Introduction to Data communications and dition, 2005. | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, cations", CRC Press, 2001. | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tanes Reference B 1. W. T 4thEo 2. G.S.H 3. S.Kes 2ndE | Contemporary issues: Total Lecture hours: Ontemporary issues: Total Lecture hours:) . . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 50 ooks 'omasi, "Introduction to Data communications and dition, 2005. Hura and M.Singhal, "Data and Computer Communications shav, "An Engineering Approach to Computer dition, 2010. | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, cations", CRC Press, 2001. Networks", Pearson Education, | | | | | | | | | | |
| Module:8 Text Book(s 1. Behrouz A 2. A. S. Tane Reference B 1. W. T 4thEo 2. G.S.H 3. S.Kes 2ndE 4. W.A. | Contemporary issues: Total Lecture hours: Otal Lecture hours:) . . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 51 ooks 'omasi, "Introduction to Data communications and lition, 2005. Hura and M.Singhal, "Data and Computer Communications and Computer Communications, 2010. Shay,"Understanding communications and Network | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, cations", CRC Press, 2001. Networks", Pearson Education, | | | | | | | | | | |
| Module:8 Text Book(s 1.Behrouz A 2.A. S. Tane: Reference B 1. W. T 4thEc 2. G.S.H 3. S.Kes 2ndE | Contemporary issues: Total Lecture hours: O Total Lecture hours:) . . Forouzan, "Data Communications and Networking" nbaum, "Computer Networks", Pearson education, 50 ooks 'omasi, "Introduction to Data communications and dition, 2005. Hura and M.Singhal, "Data and Computer Communications hav, "An Engineering Approach to Computer dition, 2010. Shay,"Understanding communications and Network | 2 Hours 45 Hours ', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. Networking", Pearson education, cations", CRC Press, 2001. Networks", Pearson Education, cks",Cengage Learning,3rd Edition, | | | | | | | | | | |

40th AC

Date

Approved by Academic Council

18/03/2016



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE3008.1 | 3 | 2 | 2 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 1 | - |
| EEE3008.2 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 1 | 3 | - |
| EEE3008.3 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 1 | 1 | - |
| EEE3008.4 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 1 | 1 | - |
| EEE3008.5 | 3 | 3 | 3 | 2 | - | - | - | - | 1 | - | - | 1 | 2 | 1 | - |
| EEE3008.6 | 3 | 2 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 1 | 1 | - |
| EEE3008.7 | 3 | 3 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 1 | 3 | - |
| EEE3008.8 | 3 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | 1 | 2 | 3 | - |
| | 3 | 3 | 3 | 1 | - | - | - | - | 1 | - | - | 1 | 3 | 3 | - |



| EEE3009 | Digital Image Processing | | | ΓΡJΟ |
|---|--|---|--|--|
| | | | 3 | 0 0 4 4 |
| Pre-requisite | EEE2005 | | Syllab | us versio |
| Anti-requisite | NIL | | | v. 2. |
| Course Objective | es: | | | |
| associated | p student's skills in performing spatial and trans with image processing and skills associated with e complex algorithms and to reinstate sophistica ce. | techniques rela | ited to coo | ling. |
| Expected Course | Outcome: | | | |
| - | tion of this course the student will be able to: | | | |
| - | d the fundamentals of digital image processing | | | |
| | e various image transform techniques | | | |
| | frequency domain in image enhancement | | | |
| - | nd the image compression techniques | | | |
| | e images using various segmentation techniques | | | |
| • | and describe the image processing techniques | | | |
| - | image processing techniques in various application | ns | | |
| 0 D | omponent or a product applying all the relevant sta | andards with re | alistic | |
| 8. Design a c | omponent of a product apprying an are relevant su | | | |
| 8. Design a c constraints | | | | |
| constraints | | | | 0.11 |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete imaging | age mathematic | cal charac | terization |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia | Image Processing (DIP): damental steps in DIP – Elements of visual percepti | age mathemations – Histog | cal charac gram Pro | Acquisitio |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformat l filters- Sharpening spatial filters -color Image | age mathemations – Histog | cal charac gram Pro | Acquisitio |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete ima between pixels. Basic Gray level Transformat l filters- Sharpening spatial filters -color Imag lor image processing- color transformations. | age mathemations – Histog | cal charac gram Pro | Acquisitio terization cessing |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete ima between pixels. Basic Gray level Transformat l filters- Sharpening spatial filters -color Imag lor image processing- color transformations. | age mathemations – Histog ge Processing-(| cal charac gram Pro Color | Acquisitio eterizatior cessing 10 Hour |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image b between pixels. Basic Gray level Transformat l filters- Sharpening spatial filters -color Image lor image processing- color transformations. | age mathemations – Histoge Processing-C | cal charac gram Pro Color | Acquisition eterization cessing 10 Hour C- Discret |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate all filters- Sharpening spatial filters -color Image olor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transformations | age mathemations – Histoge Processing-Control of the second secon | cal charac gram Pro Color /erse FF1 | Acquisition eterization cessing 10 Hour C- Discret e Wavele |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate l filters- Sharpening spatial filters -color Image lor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transform- Properties – Fast Fourier Transform- Properties and KL transform-Discrete Short time Fourier Haar wavelet family-Multirate solution analytical | age mathemations – Histoge Processing-Control of the second secon | cal charac gram Pro Color /erse FF1 | Acquisition eterization cessing 10 Hour C- Discret e Wavele |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation up | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate l filters- Sharpening spatial filters -color Image lor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transform- Properties – Fast Fourier Transform- Properties and KL transform-Discrete Short time Fourier Haar wavelet family-Multirate solution analytical | age mathemations – Histoge Processing-Control of the second secon | cal charac gram Pro Color /erse FF1 | Acquisitio eterization cessing 10 Hour C- Discret e Wavele |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation understorm | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate l filters- Sharpening spatial filters -color Image lor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transform- Properties – Fast Fourier Transform- Properties and KL transform-Discrete Short time Fourier Haar wavelet family-Multirate solution analytical | age mathemations – Histoge Processing-Control of the second secon | cal charac gram Pro Color /erse FF1 | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation und Module:3 | Image Processing (DIP): damental steps in DIP – Elements of visual percepti g and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate l filters- Sharpening spatial filters -color Image lor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transform-Inscrete Short time Fourier Haar wavelet family-Multirate solution analysing filters. | age mathemations – Histoge Processing-Constructions – Invite Processing-Construction – Invite Transform – Invites and the | cal charac gram Pro Color verse FF1 Discrete scaling | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function 8 Hour |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformate al filters- Sharpening spatial filters -color Image olor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier TransformDiscrete Short time Fouri Haar wavelet family-Multirate solution analysing filters. nent in Frequency domain: | age mathemations – Histoge Processing-Constructions – Histoge Processing-Construction – Invite Transform. System and the filters- Homor | cal charac gram Pro Color verse FF1 Discrete scaling | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function 8 Hour Tiltering, A |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque model of the image | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformate and filters- Sharpening spatial filters -color Image olor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier TransformDiscrete Short time Fouri Haar wavelet family-Multirate solution analysing filters. nent in Frequency domain: ency domain filters- sharpening frequency domain | age mathemations – Histoge Processing-Oransform – Invier Transform. System of the system of the syst | cal charac gram Pro Color //erse FF1 . Discrete scaling morphic f filtering, | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function 8 Hour Tiltering, A |
| constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque model of the ima domain filtering – | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformate al filters- Sharpening spatial filters -color Image or image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier Transform- Properties – Fast Fourier Transform-Inscrete Short time Fouri Haar wavelet family-Multirate solution analysing filters. nent in Frequency domain: ency domain filters- sharpening frequency domain ge degradation and restoration process, Noise model | age mathemations – Histoge Processing-Oransform – Invier Transform. System of the system of the syst | cal charac gram Pro Color //erse FF1 . Discrete scaling morphic f filtering, | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function 8 Hour Tiltering, A |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque model of the image | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformation d filters- Sharpening spatial filters -color Image lor image processing- color transformations. | age mathemations – Histoge Processing-Oransform – Invier Transform. System of the system of the syst | cal charac gram Pro Color //erse FF1 . Discrete scaling morphic f filtering, | Acquisition eterization cessing 10 Hour C- Discrete Wavelee function 8 Hour Tiltering, A Frequenc |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque model of the ima domain filtering – Module:4 | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image between pixels. Basic Gray level Transformation d filters- Sharpening spatial filters -color Image lor image processing- color transformations. | age mathemations – Histoge Processing-Ceransform – Invite Transform. Transform – Invite Transform. Tysis and the filters- Homorodels, Spatial filters | cal charac gram Pro Color Verse FFT Discrete scaling morphic f filtering, ring | Acquisition eterization cessing 10 Hour C- Discrete function 8 Hour Thering, A Frequenc 4 Hour |
| Constraints Module:1 Basics of Digital Introduction, Fund – Image Sampling Basic relationship Smoothing spatia models-pseudo co Module:2 Image Transform Two dimensional cosine transform Transform- the Implementation us Module:3 Image Enhancen Smoothing freque model of the ima domain filtering – Module:4 Image Compress | Image Processing (DIP): damental steps in DIP – Elements of visual percepti and Quantization – Imaging geometry, discrete image p between pixels. Basic Gray level Transformate a filters- Sharpening spatial filters -color Image loor image processing- color transformations. ns: Fourier Transform- Properties – Fast Fourier TransformDiscrete Short time Fouri Haar wavelet family-Multirate solution analysing filters. nent in Frequency domain: ency domain filters- sharpening frequency domain ge degradation and restoration process, Noise model Inverse filtering ,Wiener filtering, Constrained Lear ion: | age mathemations – Histoge Processing-Ceransform – Invite Transform. Transform – Invite Transform. Tysis and the filters- Homorodels, Spatial filters | cal charac gram Pro Color Verse FFT Discrete scaling morphic f filtering, ring | Acquisition eterization cessing 10 Hour C- Discrete function 8 Hour Thering, A Frequenc 4 Hour |



Image Segmentation:

Detection of discontinuities – edge linking and boundary detection- thresholding -edge based segmentation-region based segmentation- matching-morphological segmentation- watershed algorithm

Module:6

Representation and Description:

Boundary descriptions-Region descriptors- Use of Principal Components and Description, Texture description.

Module:7

Applications of Image Processing:

Machine Vision- Image Analysis-pattern recognition and introduction to video processing

| Modul | e:8 | Contemporary issues: | | | 2 Hours | | | | | | |
|--|--|-------------------------------|----------------------|------------|--|--|--|--|--|--|--|
| | | | Total Lecture ho | urs: | 45 Hours | | | | | | |
| Text B | ook(s) | | | ŀ | | | | | | | |
| 1. | Rafa | el C.Gonzalez, Richard E.Wo | ods, "Digital Imag | ge Process | ing", Pearson Education 4th | | | | | | |
| | Editi | on, 2017. | | | | | | | | | |
| 2. | Anil. | K.Jain, "Fundamentals of Dig | gital Image Proces | sing", Pea | rson Education, 2000. | | | | | | |
| Refere | nce Bo | ooks | | | | | | | | | |
| 1. | | E Umbaugh, "Digital Image | Processing and An | nalysis: H | uman and Computer Vision | | | | | | |
| | Appl | ications with CVIPtools", Sec | cond Edition, CRC | press, Ta | ylor and Francis, 2 nd Edition, | | | | | | |
| | 2016 | | | | | | | | | | |
| 2. | Willi | am K. Pratt, "Digital Image F | Processing", John V | Wiley & S | ons, 2016. | | | | | | |
| 3. | Steph | nane Mallat , "A Wavelet tour | r of signal processi | ng: The S | parse Way", 3 rd Edition, | | | | | | |
| | | emic Press, 2009. | | | | | | | | | |
| 4. | | • | | ind Image | Processing", Elsevier's Science | | | | | | |
| _ | | chnology Publicatiton, Secon | | | | | | | | | |
| 5. | | Soman, K.I Ramchandran, N. | • | s into Way | elets: From Theory to | | | | | | |
| | | ice", Third Edition, PHI, 201 | | | | | | | | | |
| 6. | | anda,D.DuttaMajumder, "Dig | gital Image Process | sing and A | Analysis", Prentice Hall of | | | | | | |
| | India | , 2011 | | | | | | | | | |
| | | | | | | | | | | | |
| Mode of | e of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar | | | | | | | | | | |
| Recommended by Board of Studies 05/03/2016 | | | | | | | | | | | |
| Approv | ved by | Academic Council | 40 th AC | Date | 18/03/2016 | | | | | | |

3 Hours

3 Hours



| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE3009.1 | 2 | 1 | - | - | - | - | I | 1 | - | - | - | 1 | - | - | - |
| EEE3009.2 | 3 | 3 | 2 | 1 | 2 | - | I | 1 | 1 | 1 | - | 1 | - | 3 | 2 |
| EEE3009.3 | 3 | 2 | 1 | - | 1 | - | I | 1 | - | - | - | - | - | 3 | 2 |
| EEE3009.4 | 2 | 1 | 1 | - | 1 | - | I | 1 | - | - | - | - | - | - | - |
| EEE3009.5 | 3 | 3 | 2 | 1 | 2 | - | I | 1 | 1 | 1 | - | 1 | - | 2 | 2 |
| EEE3009.6 | 3 | 2 | 1 | 1 | 2 | - | I | 1 | 1 | 2 | - | 1 | - | - | 2 |
| EEE3009.7 | 3 | 2 | 1 | 1 | 2 | - | I | 1 | 1 | 2 | - | 1 | - | - | 2 |
| | | | | | | | | | | | | | | | |
| EEE3009.8 | 3 | 3 | 3 | 3 | 3 | - | - | 3 | 3 | 3 | 1 | 2 | 2 | - | 3 |
| | 3 | 3 | 2 | 2 | 2 | - | - | 2 | 2 | 2 | 1 | 2 | 2 | 3 | 3 |



| EEE4018 | | (Deemed to be University under section 3 of UGC Act, 1956) Advanced Control Theory | | L T P J C |
|----------------|-----------|--|------------|------------------|
| LEE4010 | | Advanced Control Theory | | |
| Pre-requisit | ρ | EEE 3001 | 5 | Syllabus version |
| Anti-requisi | | NIL | | v. 2.0 |
| Course Obje | | | | v. 2.0 |
| • | | pth knowledge in the field of control theory, analysis an | nd design | of MIMO |
| systems | | | iu uesign | |
| • | | nding on features of linear and nonlinear systems | | |
| | | features of linear and nonlinear systems using phase pla | ne analys | sis and |
| | | tion analysis | ine analys | |
| | | stability of linear and nonlinear systems using stability | concepts | |
| Expected Co | | | 1 | |
| - | | f this course the student will be able to: | | |
| | | ical systems using state variable approach | | |
| | - · | MO systems by state space approach | | |
| | | feedback controller and observer for simple and practic | al dynam | ic systems |
| | | classify the nonlinearities in the physical systems | · | - |
| 5. Anal | yze the | features and stability of nonlinear systems using phase | portraits | |
| 6. Anal | yze the | systems with common nonlinearities using describing f | function | |
| 7. Anal | lyze stal | pility of linear and non – linear systems | | |
| | 0 | mponent or a product applying all the relevant standards | with rea | listic |
| const | raints | | | |
| | | | | |
| Module:1 | | Variable Representation | | 6 Hours |
| | | pt of State Equation for Dynamic Systems, Non Uni | | |
| | | hysical Systems and State Assignments - State | space re | presentation of |
| multivariable | | | | < T |
| | | on Of State Equations | | 6 Hours |
| | | atrix – Properties and Computation. Controllabi | lity and | Observability, |
| Stabilizabilit | | | | 7 11 |
| Module:3 | - | n In State Space | | 7 Hours |
| | | tput Feedback, Design Methods, Pole Assignment, I production to Linear Quadratic problems. | Full Orde | er and Reduced |
| Module:4 | Intro | luction To Non Linear Sytems | | 5 Hours |
| | | res of Linear and Non Linear Systems, Types of a | non-linea | |
| | | trol systems, Typical Examples, Concept of phase por | | • |
| Limit cycles | 5 m con | ator systems, Typical Examples, concept of phase por | traits Di | ingular points |
| Module:5 | PHAS | SE PLANE ANALYSIS | | 7 Hours |
| | | ase portrait, Concepts of phase plane analysis Phase | plane ar | |
| | | r system, Existence of limit cycles. | | |
| Module:6 | Descr | ibing Function Analysis | | 6 Hours |
| | | fundamentals, Describing functions of common no | nlineariti | |
| | | nonlinear systems, Limit cycles, Stability of Oscillation | | , 200000000 |
| | | | | |
| Module:7 | | ity Analysis | | 6 Hours |
| Stability Co | oncepts, | Equilibrium Points, BIBO and Asymptotic Stab | ility, Ly | apunov theory, |
| | | | | |



Lyapunov's Direct method, Variable gradient method Frequency Domain Stability Criteria, Popov's Method & its Extension.

| Modul | e:8 | Contemporary issues: | | 2 Hours | | | | | | | |
|---|--|---|----------------------|--|--|--|--|--|--|--|--|
| | | Total Lecture | Total Lecture hours: | | | | | | | | |
| Text B | ook(s) | | | | | | | | | | |
| 1. | Kats | suhiko Ogata, "Modern Control Engineering | ", PHI Lea | rning Pvt Ltd, 5 th Edition, 2010. | | | | | | | |
| 2. | Hass | san K Khalil, "Nonlinear Control ", Pearson | Prentice Ha | all, 1 st Edition, 2014. | | | | | | | |
| Refere | nce B | ooks | | | | | | | | | |
| 1. | M. (| Gopal, "Modern Control Systems Theory", N | Jew Age Pu | ge Publishers, 3 rd Edition, 2014. | | | | | | | |
| 2. | Rich 2010 | hard C. Dorf, Robert H. Bishop, "Modern C). | ontrol Syste | ems", Prentice Hall, 12 th Edition, | | | | | | | |
| Mode of | of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar | | | | | | | | | | |
| Recommended by Board of Studies 05/03/2016 | | | | | | | | | | | |
| Approved by Academic Council40th ACDate18/03/2016 | | | | | | | | | | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4018.1 | 3 | 3 | 2 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 2 | 2 |
| EEE4018.2 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4018.3 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| EEE4018.4 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4018.5 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4018.6 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 2 | 3 |
| EEE4018.7 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4018.8 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | - | - | 3 | 3 | 3 | 3 |
| | 3 | 3 | 3 | 3 | 3 | - | - | I | 2 | - | - | 3 | 3 | 3 | 3 |



| EEE4019 | (Deemed to be University under section 3 of UGC Act, 1956) Advanced Digital Design with FPGAs | L | Т | P | J | С |
|--------------------------|---|----------|----------|---------------|------------|---------------|
| | Auvanceu Digitai Design with FI GAS | 2 | 0 | I 0 | J 4 | $\frac{c}{3}$ |
| Pre-requisite | EEE3002 | | llab | - | | - |
| Anti-requisite | NIL | Sy | nau | us v | V. | |
| Course Objectives: | NIL | | | | ۷. | 1.0 |
| | lex digital systems using Hardware Description | angua | ge. | | | |
| 1 | programmable gate array (FPGA) technologies a | <u> </u> | <u> </u> | soci | ated | 1 |
| - | design (CAD) tools to synthesize and analyze di | | | | | |
| Expected Course Outo | | <u> </u> | | | | |
| On the completion of the | is course the student will be able to: | | | | | |
| 1. Design and reco | gnize the trade-offs involved in digital design flo | ows for | syst | em | | |
| | nthesize Verilog HDL. | | | | | |
| • | thesize digital modules and circuits for a wide a | pplicat | ion ra | ange | | |
| - | chines to control complex systems. | | | | | |
| | est bench to test Verilog modules. | | | | | |
| 5 | phous DSP system in Verilog and verify its performance of point arithmetic using the IEEE-754 Standard. | mance | • | | | |
| - | nent or a product applying all the relevant standard. | rds wit | h rea | licti | c | |
| constraints | nent of a product apprying an are relevant stand | | | | C | |
| | | | | | | |
| Module:1 | Introduction to FPGAs | | | | Hou | |
| | ogic architectures, Complex Programmable Lo | | vices | (CF | PLD | s), |
| Field Programmable Ga | te Arrays (FPGAs), Design Flow, Design Tools | | | | | |
| Module:2 | Introduction to Verilog HDL | | | 5 | Hou | irs |
| Review of Verilog HD | L, Modeling styles: Behavioral, Dataflow, and | Struct | ural | Moc | lelir | ıg, |
| gate delays, switch-leve | el Modeling, Hierarchal structural modeling. | | | | | |
| Module:3 | Implementing Logic using MSI Combinatio | nal | | 4 | Hou | irs |
| Wibuure.5 | Logic Blocks | 1141 | | Т. | 1100 | 11.5 |
| Multiplexer, DeMultipl | exer, Encoder, Decoder, ROM, PAL, PLA. | | | | | |
| Module:4 | Verilog Modelling of Sequential Circuits | | | 4 | Hou | irs |
| Flip-Flops, Shift Regist | ers, Counters, Finite State Machine Modelling. | | | | | |
| Module:5 | Verification | | | 2 | Hou | |
| | , simulation types, Test Bench design, value | ahanaa | dun | | | |
| files. | , simulation types, Test Bench design, value | change | uun | ıp (| VC. | D) |
| | | | | | | |
| Module:6 | Design | | | 6 | Hou | irs |
| | rs, Multiplication Digital Signal Processing mod | ules: F | IR an | | | |
| Filters, Bus structures, | Synchronous & Asynchronous data transfer, UA | ART ba | ud | | | |
| rate generator, A simp | le CPU design. | | | | | |
| | | | | - | | |
| Module:7 | Floating point arithmetic circuits | | | 3 | Hou | irs |
| Adders, Subtractors, M | ultipliers | | | | | |
| Module:8 | Contemporary issues: | | | 2 | Hou | ire |
| 14100010.0 | Total Lecture hours: | | | | пос Нот | |
| Tort Darl-(r) | I otal Lecture nours: | | | 50 | 1100 | 115 |
| Text Book(s) | | | | | | |



- 1. Michael D Ciletti, "Advanced Digital Design with the Verilog HDL" Prentice Hall, 2nd Edition, 2011.
- 2. Samir Palnitkar, "Verilog HDL: A Guide to Digital Design and Synthesis" Pearson, Second Edition, 2009.

Reference Books

- 1. Stephen Brown & Zvonko Vranesic, "Fundamentals of digital Logic with Verilog Design" TATA Mc Graw Hill Ltd. 3rd Edition 2014.
- 2. Ming-Bo Lin., Digital System Designs and Practices Using Verilog HDL and FPGAs. Wiley, 2008.
- 3. Woods, R., McAllister, J., Yi, Y. and Lightbody, G. FPGA-based implementation of signal processing systems. John Wiley & Sons, 2017.

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

| Recommended by Board of Studies | 05/03/2016 | | |
|---------------------------------|---------------------|------|------------|
| Approved by Academic Council | 40 th AC | Date | 18/03/2016 |

| | | r | | r | r | | | | | 1 | | | | | |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE4019.1 | 3 | 2 | 2 | 2 | 1 | - | - | - | 2 | - | - | 3 | 1 | 2 | 1 |
| EEE4019.2 | 3 | 2 | 3 | 2 | 3 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |
| EEE4019.3 | 3 | 3 | 2 | 2 | 1 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |
| EEE4019.4 | 3 | 3 | 3 | 2 | 3 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |
| EEE4019.5 | 3 | 3 | 1 | 3 | 3 | - | - | - | 3 | - | - | 3 | 2 | 1 | 1 |
| EEE4019.6 | 3 | 3 | 3 | 3 | 3 | - | - | - | 2 | - | - | 3 | 2 | 1 | 3 |
| EEE4019.7 | 3 | 3 | 3 | 3 | 3 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |
| EEE4019.8 | 3 | 3 | 3 | 3 | 3 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |
| | 3 | 3 | 3 | 3 | 3 | - | - | - | 2 | - | - | 3 | 3 | 2 | 3 |



| EEE4020 | Embedded System Design | | J C |
|---|---|---|---|
| | | | 1 3 |
| Pre-requisite | EEE4001 | Syllabus ver | rsion |
| Anti-requisite | NIL | | v. 1.0 |
| Course Objectives | | | |
| 1. To give an emph | asis on the characteristics and hardware architecture | of embedded system ar | nd |
| real time operati | | | |
| - | ntial knowledge on various communication protoc | cols and understanding | of |
| Mealy and Moor | | | |
| 3. To provide the machines. | essential knowledge in the embedded modeling | and design of finite | state |
| machines. | | | |
| Expected Course (| Dutcome: | | |
| On the completion | of this course the student will be able to: | | |
| | characteristics and concepts of embedded system. | | |
| | architecture of hardware embedded system | | |
| | oncepts of RTOS with general purpose OS. | | |
| | re components/architecture for embedded system ap red and wireless communication protocols. | plications. | |
| - | ace model using Moore and Mealy technique | | |
| | bedded system modelling with state transition and F | FSM. | |
| | onent or a product applying all the relevant standard | | ts |
| 8. Design a comp | onent of a product apprying an the relevant standard | s with realistic constrain | |
| 8. Design a comp | onent of a product apprying an the relevant standard | s with realistic constrain | |
| | | | |
| Module:1 Intro | oduction to Embedded systems: | 3 H | lours |
| Module:1 Intro Embedded system- | Definition, Categories, Requirements. Challeng | 3 H es and issues in embe | lours dded |
| Module:1IntroEmbedded system- software developm | oduction to Embedded systems: | 3 H es and issues in embe | lours dded |
| Module:1IntroEmbeddedsystem- | Definition, Categories, Requirements. Challeng | 3 H es and issues in embe | lours dded |
| Module:1IntroEmbedded system- software developm systems. | Definition, Categories, Requirements. Challeng | 3 H es and issues in embe Applications of embedd | lours dded |
| Module:1IntroEmbedded system- software developm systems.Module:2HardProcessor, Memory | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Time | 3 H es and issues in embe Applications of embedd 4 H hers, reset circuit, Watch | lours dded ed lours dog |
| Module:1IntroEmbedded system- software developm systems.Module:2HardProcessor, Memory timer, chip select | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Time logic circuit, ADC and DAC, Display units, | 3 H es and issues in embe Applications of embedd 4 H hers, reset circuit, Watch | lours dded ed lours dog |
| Module:1IntroEmbedded system- software developm systems.Module:2HardProcessor, Memory | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Time logic circuit, ADC and DAC, Display units, | 3 H es and issues in embe Applications of embedd 4 H hers, reset circuit, Watch | lours dded ed lours dog |
| Module:1 Intro Embedded system- software developm software developm systems. Module:2 Hard Processor, Memory timer, chip select Introduction to emu emu | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa | lours dded ed lours dog aces, |
| Module:1IntroEmbedded system- software developm systems.Module:2HardProcessor, Memory timer, chip select Introduction to emuModule:3Real | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H | lours dded ed lours dog aces, lours |
| Module:1 Intro Embedded system- software developm systems. systems Module:2 Hard Processor, Memory timer, chip itimer, chip select Introduction to emu Module:3 Real RTOS vs General p | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro | lours dded ed lours dog aces, lours ccess |
| Module:1 Intro Embedded systems systems software developm systems Module:2 Hard Processor, Memory timer, chip select Introduction to emu module:3 Module:3 Real RTOS vs General p Scheduling, Resource | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task S | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro | lours dded ed lours dog aces, lours ccess |
| Module:1 Intro Embedded system- software developm software developm systems Module:2 Hard Processor, Memory timer, chip select Introduction to emp select Module:3 Real RTOS vs General p Scheduling, Resourd software developm software developm | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed | lours dded ed lours dog aces, lours lded |
| Module:1 Intro Embedded systems systems software developm systems Module:2 Hard Processor, Memory select Introduction to emu select Module:3 Real RTOS vs General p Scheduling, Resourd software developm Software developm Module:4 Serial | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H | lours dded ed lours dog aces, lours lded |
| Module:1 Intro Embedded system- software developm software developm systems. Module:2 Hard Processor, Memory timer, chip select Introduction to emu select Module:3 Real RTOS vs General p Scheduling, Resourd Software developm Seria Module:4 Seria | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu | lours dded ed lours dog aces, lours lded lours re of |
| Module:1 Intro Embedded system- software developm software developm systems. Module:2 Hard Processor, Memory timer, chip select Introduction to emu select Module:3 Real RTOS vs General p Scheduling, Resourd Software developm Seria Module:4 Seria | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA ata Rates, Frame types. USB- Physical interface, En | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu | lours dded ed lours dog aces, lours lded lours re of |
| Module:1 Intro Embedded systems systems software developm systems Module:2 Hard Processor, Memory timer, chip select Introduction to emu select Module:3 Real RTOS vs Gereral p Scheduling, Resourd Software developme software developme Module:4 Serial I2C- Features, Arb CAN, properties, D Types of packets, T | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA ata Rates, Frame types. USB- Physical interface, En ypes of transfers. | 3 H es and issues in embe Applications of embedd 4 H hers, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu umeration process in US | lours dded ed lours dog aces, lours lded lours re of SB, |
| Module:1 Intro Embedded systems systems software devolopm systems Module:2 Hard Processor, Memory timer, chip select Introduction to emu select Module:3 Real RTOS vs Gerral p Scheduling, Resourd Software devolopm Software devolopm Module:4 Seria 12C- Features, Arburg CAN, properties, D Types of packets, T Module:5 | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA ata Rates, Frame types. USB- Physical interface, En ypes of transfers. less Applications: | 3 H es and issues in embe Applications of embedd 4 H ners, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu umeration process in US | lours dded ed lours dog aces, lours lded lours re of SB, |
| Module:1IntroEmbedded systemssoftware developmsystems.Module:2HardProcessor, M =morytimer, chip selectIntroduction to emuModule:3RealRTOS vs G=ral pScheduling, Resoursoftware developmModule:4SeriaI2C- Features, ArbCAN, properties, DTypes of packets, TModule:5WireIntroduction to with | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities cc management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA ata Rates, Frame types. USB- Physical interface, En ypes of transfers. less Applications: reless networking –Basics. Bluetooth – Overvie | 3 H es and issues in embe Applications of embedd 4 H hers, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu umeration process in US 4 H ww, power levels, Dev | lours dded ed lours dog aces, lours lded lours re of SB, lours ice |
| Module:1IntroEmbedded system- software developm systems.HardModule:2HardProcessor, Memory timer, chip select Introduction to emuModule:3RealRTOS vs General p Scheduling, Resour software developmedModule:4SeriaI2C- Features, Arb CAN, properties, D Types of packets, TModule:5WireIntroduction to with communication, B | oduction to Embedded systems: Definition, Categories, Requirements. Challeng ent, Trends in embedded software development, A Iware architecture of embedded system: , Memory models, Latches and Buffers, crystal, Tim logic circuit, ADC and DAC, Display units, lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities rce management (Semaphores and Mutex), Task Sent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CA ata Rates, Frame types. USB- Physical interface, En ypes of transfers. less Applications: | 3 H es and issues in embe Applications of embedd 4 H ers, reset circuit, Watch Communication interfa 4 H - Task management, Pro Synchronization. Embed 5 H AN- Layered Architectu umeration process in US 4 H w, power levels, Devit t types and packet tin | lours dded ed lours dog aces, lours lded lours re of SB, lours ice ning. |



| Module:6 | Introduction to Moore an | d Mealy models | | 4 Hours |
|---|---|--------------------------------|-------------|----------------------------|
| definition of | a Level to Pulse converter of the state, building state tr els of sequential machines- In | ansition diagram to | | |
| Module:7 | Embedded System Model | ling: | | 4 Hours |
| Finite State | Machine (FSM) - Rules for | designing FSM, Des | sign examp | les implementing state and |
| state transiti | on diagram for vending mach | nine, ATM, digital lo | ck. | |
| | | | | |
| Module:8 | Contemporary issues: | | _ | 2 Hours |
| | | Total Lecture | hours: | 30 Hours |
| Text Book(s | · | | | |
| | d.E. Simon, "An Embedded S | 1 | | |
| 2. Tam | ny Noergaard, "Embedded s | ystems architecture: | a comprehe | nsive guide for engineers |
| and j | programmers" Berlin: Elsevie | er, 2014. | | |
| Reference I | ooks | | | |
| | ong Fan, "Real-time embedd | ed systems: Design p | rinciples a | nd engineering practices", |
| | | 0015 | | |
| 1. Xiac | terdam [Netherlands]: Newno | es, 2015. | | |
| 1. Xiac Ams | terdam [Netherlands]: Newno | <i>,</i> | Design: A U | Jnified Hardware/Software |
| 1. Xiac Ams 2. Fran | L 3 | "Embedded System I | Design: A U | Jnified Hardware/Software |
| Xiac Ams Fran Appr | K Vahid and Tony Givargis, | "Embedded System I n, 2010. | | Jnified Hardware/Software |
| 1. Xiac Ams 2. Fran Appr Mode of Eva | x Vahid and Tony Givargis, ' oach", Wiley; Student editio | "Embedded System I n, 2010. | | Jnified Hardware/Software |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4020.1 | 3 | 3 | - | - | - | - | - | - | - | - | - | 3 | - | - | 2 |
| EEE4020.2 | 3 | 3 | - | - | - | - | - | - | - | - | - | 3 | - | - | 2 |
| EEE4020.3 | 3 | 3 | - | - | - | - | - | - | - | - | 3 | 3 | - | - | 2 |
| EEE4020.4 | 3 | 3 | 3 | - | 3 | - | - | - | - | - | 3 | 3 | 3 | 2 | 2 |
| EEE4020.5 | 3 | 3 | 2 | - | 3 | - | - | - | - | - | 3 | 3 | 2 | 3 | 3 |
| EEE4020.6 | 3 | 3 | 3 | - | 3 | - | - | - | - | - | 3 | 3 | 3 | 3 | |
| EEE4020.7 | 3 | 3 | 3 | - | 3 | - | - | - | I | - | 3 | 3 | 3 | 3 | 3 |
| EEE4020.8 | 3 | 3 | 3 | - | 3 | - | - | - | - | - | 3 | 3 | 3 | 3 | 3 |
| | 3 | 3 | 3 | | 3 | | | | | | 3 | 3 | 3 | 3 | 2 |



| EEE4022 | | Analog VLSI Design | | L T P J C |
|--------------------|-----------|--|------------------|---------------------|
| | | | | 3 0 0 0 3 |
| Pre-requisit | e | EEE3002 | | Syllabus version |
| Anti-requisi | | NIL | | v. 1.0 |
| Course Obj | | | | |
| | | nd about various types of Analog systems, Cl | | and oscillators. |
| 2. To u | nderstar | d Applications of MOSFET in Analog device | es. | |
| Expected Co | ourse (| utcome. | | |
| _ | | f this course the student will be able to: | | |
| - | | he characteristics of MOS and sizing of trans | istors | |
| | | S based amplifier circuits with various config | | |
| | | ential amplifiers using MOS for various appli | - | |
| | - | rational Amplifiers for linear ICs using CMO | | |
| 5. Desig | gn oscill | ators using MOS devices | | |
| 6. Study | y the co | ncepts of Phase-Locked Loops | | |
| | T | | | |
| Module:1 | | luction to Analog VLSI design: | | 4 Hours |
| Basic MOS of | device, | I/V characteristics, small-signal model, long- | channel and sho | rt channel devices. |
| Module:2 | Single | e-Stage MOS Amplifier: | | 7 Hours |
| | <u> </u> | h resistive load, diode-connected load, current | t source load, S | |
| common gate | | | , | , |
| | I | | | |
| Module:3 | | rential Amplifiers: | | 8 Hours |
| - | | ferential operation, basic differential pair and | • | mode response, |
| differential p | air with | MOS loads and Frequency response of Amp | lifter. | |
| Module:4 | Curre | ent Mirrors: | | 5 Hours |
| | | rs, cascade current mirrors, Active current | mirrors- small | |
| common mo | | | | signal analysis and |
| | 1 1 | | | |
| Module:5 | Opera | ational Amplifiers: | | 7 Hours |
| Basic CMOS | S Op-Ar | np, One stage Op-amps, Two-stage Op-Amps | s, Gain Boosting | g, Noise in Op-Amp. |
| | | | | |
| Module:6 | Oscill | | | 7 Hours |
| Ring Oscill | ators, L | C Oscillators, Voltage-Controlled Oscillators | | |
| Module:7 | Phase | -Locked Loops: | | 5 Hours |
| | | Pump PLLs, Non-ideal effects in PLLs. | | |
| | | · | | |
| Module:8 | Cont | emporary issues: | | 2 Hours |
| | | Total Lecture hours: | | 45 Hours |
| Text Book(s |) | | | _ |



| 1. | Tony Chan Carusone David A. Johns Kenneth W. Martin, "Computer System |
|---------|---|
| | Architecture", John Wiley & Sons, Inc, Second Edition, 2012. |
| 2. | Behzad Razavi, "Design of Analog CMOS integrated circuits", Tata McGraw Hill, |
| | Second Edition, 2003. |
| | |
| Refere | nce Books |
| 1. Jaco | b Baker, "CMOS circuit design", Wiley-IEEE press, Third Edition, 2010 |
| Mode | of valuation: CATL& II 30% DAL& II 20% Ouiz 10% FAT 40% |

| Mode of valuation: | CAT 1 & $II - 30$ | %, DA I & II – 20 | 0%, Qu1z – 10% | , FAT – 40% |
|----------------------|-------------------|---------------------|----------------|-------------|
| Recommended by Board | l of Studies | 05/03/2016 | | |
| Approved by Academic | Council | 40 th AC | Date | 18/03/2016 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4022.1 | 3 | 2 | 1 | - | 1 | - | - | - | - | - | 1 | 1 | 2 | 3 | 1 |
| | | | | | | | | | | | | | | | |
| EEE4022.2 | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4022.3 | 3 | 3 | 3 | 1 | 1 | - | - | - | - | - | 1 | 1 | 2 | 3 | 3 |
| EEE4022.4 | 3 | 2 | 1 | - | 1 | - | - | - | 1 | - | 1 | 1 | 2 | 2 | 3 |
| EEE4022.5 | 3 | 3 | 3 | 1 | 1 | - | - | - | - | - | - | 1 | 2 | 3 | 2 |
| EEE4022.6 | 3 | 2 | 3 | - | 1 | - | - | - | 1 | - | - | 1 | 2 | 3 | 2 |
| | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | 1 | 1 | 2 | 3 | 3 |



| Image: Constraint of the second sec | rsion v. 1.0 |
|---|-----------------|
| Pre-requisite EEE3002 Syllabus ver Anti-requisite NIL Syllabus ver Course Objectives: Image: Course Objectives: Syllabus ver 1. To gain an understanding of computer data representation and manipulation. To understand the basic organization for data storage and access across various media. Expected Course Outcome: Syllabus ver On the completion of this course the student will be able to: Interpret the data flow between various modules of the computer and data representation various formats. 2. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. 4. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. 6. Realize the various mapping techniques and familiarize the various data transfer mechanis | rsion v. 1.0 |
| Anti-requisite NIL Course Objectives: 1. To gain an understanding of computer data representation and manipulation. 2. To understand the basic organization for data storage and access across various media. Expected Course Outcome: On the completion of this course the student will be able to: 1. Interpret the data flow between various modules of the computer and data representation various formats. 2. Analyze the performance of processor and their interconnections. 3. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. 4. Acquaint the knowledge about floating point and decimal arithmetic's. 5. Design the various register transfer functions and develop programs for various CPU organizations. 6. Realize the various mapping techniques and familiarize the various data transfer mechanis | v. 1.0 |
| Course Objectives: To gain an understanding of computer data representation and manipulation. To understand the basic organization for data storage and access across various media. Expected Course Outcome: Interpret the data flow between various modules of the computer and data representation various formats. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanis | n in |
| To gain an understanding of computer data representation and manipulation. To understand the basic organization for data storage and access across various media. Expected Course Outcome: On the completion of this course the student will be able to: Interpret the data flow between various modules of the computer and data representation various formats. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanise | |
| 2. To understand the basic organization for data storage and access across various media. Expected Course Outcome: On the completion of this course the student will be able to: | |
| On the completion of this course the student will be able to: Interpret the data flow between various modules of the computer and data representation various formats. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanism. | |
| Interpret the data flow between various modules of the computer and data representation various formats. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanism. | |
| various formats. Analyze the performance of processor and their interconnections. Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanis | |
| Perform the various arithmetic tasks and familiarize the various multiplication algorithms. Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanism. | |
| Acquaint the knowledge about floating point and decimal arithmetic's. Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanis | |
| Design the various register transfer functions and develop programs for various CPU organizations. Realize the various mapping techniques and familiarize the various data transfer mechanis | m |
| organizations. 6. Realize the various mapping techniques and familiarize the various data transfer mechanis | m |
| 6. Realize the various mapping techniques and familiarize the various data transfer mechanis | m |
| | 111. |
| | |
| | |
| | |
| | ours |
| Introduction- Generation of Computer, Computer families and developments, Functional units, H | Basic |
| operational concepts, Data Representation-Fixed point and Floating point numbers. | |
| | |
| L L | ours |
| CPU organization by Vou-Newmann model, CPU transistor count-Moore's law, Perform | ance |
| analysis of CPU, Typical Mother board, interconnection of components. | |
| Module:3 Computer Arithmetic 7 H | r |
| | ours |
| Fixed-Point Arithmetic, Addition, Subtraction, Multiplication and Division, Combinational Sequential ALUs, Carry look ahead adder, Robertson algorithm, booth's algorithm, Modified boo | |
| Algorithm. | ui s |
| | |
| Module:4Floating point and Decimal Arithmetic3 H | ours |
| Floating Point Arithmetic, Decimal Arithmetic unit-Decimal Arithmetic operations. | |
| | |
| Module:5Introduction to CPU Design9 H | ours |
| Function of CPU, Register Classification and organization, ALU and control unit, instruction set | with |
| examples, addressing modes, stack organization, Register Transfer, Bus and memory transfers, I | nput |
| - Output and Interrupt. Micro programmed control CPU design. | |
| | |
| | ours |
| Basic concepts semiconductors, RAM memories, Read-only memories- Cache memory and rela mapping- Virtual memories. Introduction to buses and connecting I/O devices to CPU | ted |



| | | | (Deeme | d to be oniversity under section 5 c | 1000 Act, 1500) | |
|---------|----------|-------------------------|--------------------|--------------------------------------|-----------------|-------------------------------------|
| memo | ory-Pro | grammed | controlled I/O tra | nsfer- Interrupt co | ontrolled I | /O transfer-DMA Controller. |
| Modul | le:7 | Pipeline | and Vector Proce | essing | | 8 Hours |
| Introdu | iction | to pipelini | ng and pipeline ha | zards-design issu | es of pipe | line architecture-Instruction level |
| paralle | lism a | nd advanc | ed issues-parallel | processing conc | epts-Vect | or Processing, Array Processors, |
| CISC, | and RI | SC & VL | W. | | | |
| Modul | e:8 | Contem | porary issues: | | | 2 Hours |
| | | | | Total Lecture h | ours: | 45 Hours |
| 1. | | iam Stalli on, 2016. | ngs, "Computer | Organization and | d Archite | ecture", Prentice Hall, Tenth |
| 2. | Car | | , | c, SafeaZaky, "C | Computer | Organization", McGraw Hill, |
| Refere | ence B | ooks | | | | |
| 1. Dav | vid A. | Patterson | & John L. Henr | nessy, "Computer | Architec | ture: A Quantitative Approach", |
| Elsevie | er, Fift | h Edition, | 2012. | | | |
| Mode | of valu | ation: | CAT I & II – 30 | %, DA I & II – 20 |)%, Quiz - | – 10%, FAT – 40% |
| moue | | | | 0=10212016 | | |
| | mende | ed by Boar | d of Studies | 05/03/2016 | | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4024.1 | 2 | 1 | - | - | - | - | - | 1 | 1 | 1 | - | - | - | - | - |
| EEE4024.2 | 3 | 2 | 1 | 1 | - | - | - | 1 | 1 | 1 | - | - | - | - | - |
| EEE4024.3 | 3 | 2 | - | 1 | 2 | - | - | 1 | 1 | 1 | - | - | 1 | - | 2 |
| EEE4024.4 | 2 | 1 | - | - | 2 | - | - | 1 | 1 | 1 | - | 2 | 1 | - | 2 |
| EEE4024.5 | 3 | 2 | _ | _ | | _ | _ | 2 | 2 | 1 | - | 1 | 2 | _ | _ |
| EEE4024.6 | 3 | 2 | | | | | | 2 | 2 | 1 | | 1 | 2 | | _ |
| EEE4024.7 | 2 | 1 | | | | | | 1 | | 1 | | 1 | | | _ |
| EEE4024.7 | 3 | 1 2 | - | - | - 2 | - | - | 1 2 | 1 2 | 1 | - | 2 | 2 | - | 2 |



| EEE4026 | Digital Control Systems | | L | Т | P J | C |
|-------------------------|--|----------------------|--------|----------------|--------------|-------|
| | | | 2 | 0 | 0 4 | 3 |
| Pre-requisite | EEE3001 | | Sylla | bus | s vers | sion |
| Anti-requisite | NIL | | | | V. | . 1.(|
| Course Objectiv | | | | | | |
| 2. To unders properties | of this course is to understand the discretization of stand the discrete state space modelling of physic is such as controllability, observability. the digital controller. | | | t th | e | |
| Expected Course | e Outcome: | | | | | |
| - | n of this course the student will be able to: | | | | | |
| 1 | discrete and continuous system | | | | | |
| | he response of the discrete system. | | | | | |
| • | he stability of the discrete system. | | | | | |
| | rollability/ observability of a system | | | | | |
| | nd design digital PID controllers | | | | | |
| - | nd analyze State variable methods | | | | | |
| | ad the mechanization of control algorithms | | | | | |
| | component or a product applying all the relevant | standards with rea | listic | con | strair | nts |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| Module:1 Int | roduction: | | | | 4 Ho | ours |
| Overview of des | ign approaches, continuous versus digital cont | rol, sampling proc | ess, | San | nple | and |
| | D, D/A conversion. Calculus of difference equ | | | | | |
| function | | | | | | |
| | bility Analysis of discrete systems: | | | | 2 H o | ours |
| location of poles | s, Jury's stability criterion, stability analysis th | rough bilinear tra | nsfor | ms. | | |
| | | | | | | |
| | te variable analysis : | | | | 4 H o | |
| * | of discrete data systems – State transition equa | | - | etw | een s | tate |
| equation and tran | sfer functions - Characteristic equations - Eigen | value – Eigen vect | or. | | | |
| Module:4 Sta | te Space Model Transformation: | | | | 4 H o | |
| | of Matrix – Jordan canonical form – Methods of | computing state to | oncit | ion | | |
| | Decomposition of discrete data transfer function. | | | | | |
| | ant discrete data systems. | Controllability and | 1 0050 | <i>.</i> 1 v a | Jonny | 01 |
| | an discrete data systems. | | | | | |
| Module:5 De | sign of Digital Control Systems - Classical | | | | 6 Ho | ours |
| | ethod: | | | | 0 110 | |
| | ollers and frequency domain compensation desig | gn. | | | | |
| - | | | | | | |
| Module:6 De | sign of Digital Control Systems – State | | | | 5 Ho | ours |
| | edback Design: | | | | | |
| | thods - Pole placement design, Observer design | and the discrete lin | ear re | gul | ator | |
| problem. | - 0 | | | | | |
| | | | | | | |



| Module | e :7 | Microprocessor Implementation: | Based | Digital | Conti | rol | 3 Hours |
|--------|-------------|---|-------------|---------------------|-----------|-----------|----------------------------------|
| | | processors – Mecha cal, cascade realizat | | | algorith | nms. Ite | rative computation via parallel, |
| Module | e:8 | Contemporary is | sues: | | | | 2 Hours |
| | | | r | Fotal Lectu | ire hou | rs: | 30 Hours |
| Text B | ook(s) | | | | | | |
| 1. | K. 0 | gata, "Discrete-time | e control s | systems", Po | earson, 2 | 2015. | |
| 2. | | . Franklin, J. D. Po rson), 2008. | well and | M Workm | an, 'Dig | gital Con | ntrol of Dynamic Systems' PHI |
| Refere | nce B | ooks | | | | | |
| 1. | | . Franklin, J. D. Pov rson), 2015. | vell and A | A. E. Naein | i, 'Feed | back Co | ntrol of Dynamic Systems' PHI |
| 2. | | D. Landau, Gian ementation' Springe | | o, 'Digital | Contro | l Syster | ms, Design, Identification and |
| 3. | D. It | orahim, 'Micro-conti | roller base | ed Applied | Digital | Control | John Wiley & Sons Ltd., 2006 |
| 4. | .M.C | opal, "Digital Contr | rol Engine | eering", Ne | w Age I | Publishe | rs, 2008. |
| Mode o | of Eva | luation: CAT / Assig | gnment / (| Quiz / FAT | / Projec | et / Semi | nar |
| Recom | mende | ed by Board of Studi | es | 05/03/2016 | | | |
| Approv | ed by | Academic Council | | 40 th AC | Ľ | Date | 18/03/2016 |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4026.1 | 3 | 3 | 2 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 2 | 2 |
| EEE4026.2 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| EEE4026.3 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| EEE4026.4 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| EEE4026.5 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| EEE4026.6 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 2 | 3 |
| EEE4026.7 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| | | | | | | | | | | | | | | | |
| EEE4026.8 | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |
| | 3 | 3 | 3 | 3 | 3 | - | - | 1 | 2 | 2 | - | 3 | 3 | 3 | 3 |



| | | | Rob | otics and Co | ontrol | | L | Т | P J | C |
|--|--|---|---|---|---|---|---|--|---|--|
| | | | | | | | 2 | 0 | - | - |
| Pre-requisite | | EEE3001 | | | | | Sylla | abus | s vers | |
| Anti-requisite | | NIL | | | | | | | v. | 1.0 |
| Course Objec | ctives: | | | | | | | | | |
| To development To development To development | velop s ns & so velop | tudent's skills in ome knowledge a | n perform and analy in perfor | ing spatial tr vsis skills ass ming kinema | ansfor ociated atic an | ctures and their v mations associat d with trajectory alysis of robotic | ed with plannin | rigi g. | | - |
| Expected Cor | - | | | | | | | | | |
| Select Apply Analys Derive Identif Genera Implen | differe spatial se forw Jacob y the d ate join nent th | ard and inverse l an matrix and ic ynamics of the r t trajectories for e multivariable c | ors and ac to obtain kinematic lentify sin obotic ma motion p controller | tuators for re the forward l s for simple ngularities. anipulator us planning. for setpoint | obotic kinema robot ing Eu trackin | atic equation of r | pproach | n tion | | |
| Module:1 | Introd | luction | | | | | | | 2 Ho | urs |
| | ydrauli | | | | | um and other n robots, specifie | | | | |
| Module:2 | Rigid | Motion | and | Homoger | 200110 | | | | 5 Ho | urs |
| | transf | ormation | | | ieous | | | | | |
| Position definition rotations and r frame, param Homogeneous | itions. elative eterisa s transf | Coordinate fram motion, Compo tion of rotatior ormation | sition of | rent orientat | ion des | scriptions. Free vith respect to fixet, yaw, axis/a | ed fram | e an | d curi entat | rent ion, |
| Position definer rotations and r frame, param Homogeneous Module:3 | itions. elative eterisa transf Forwa | Coordinate fram motion, Compo tion of rotatior ormation rd Kinematics | sition of n, Euler | rent orientat rotation, rota Angele, rol | ion des ition w ll, pito | ith respect to fix ch, yaw, axis/a | ed fram ngle re | e an pres | d curi entat 4 H o | rent ion, urs |
| Position definition rotations and r frame, param Homogeneous Module:3 | itions. elative eterisa transf Forwa te fran artesian of mai | Coordinate fram motion, Compo tion of rotation ormation rd Kinematics nes. Denavit-Han | sition of h, Euler tenberg of ion of DF er elbow | rent orientation, rota rotation, rota Angele, rol convention. A | ion des ation w ll, pito Assign and fo | ith respect to fixe | ed fram ngle re nate frar equatio | e an pres ne, 1 n of | d curr entat 4 Ho Joint | rent ion, ours and |
| Position definition rotations and reframe, param Homogeneous Module:3 Link coordina end effector Ca configuration Spherical Write | itions. elative eterisa s transf Forwa te fran artesian of man st and o | Coordinate fram motion, Compo tion of rotatior ormation rd Kinematics nes. Denavit-Har n space. Calculat nipulator, Planne | sition of h, Euler tenberg of ion of DF er elbow | rent orientation, rota rotation, rota Angele, rol convention. A | ion des ation w ll, pito Assign and fo | ith respect to fix ch, yaw, axis/a ment, of coordin rward kinematic | ed fram ngle re nate frar equatio | e an pres ne, 1 n of | d curr entat 4 Ho Joint | ours and rent |
| Position definition rotations and reframe, param Homogeneous Module:3 Link coordination end effector Carconfiguration Spherical Wrise Module:4 Forward kinet | itions. elative eterisa s transf Forwa te fran artesian of man st and o Veloci matics | Coordinate fram motion, Compo- tion of rotation ormation rd Kinematics nes. Denavit-Har n space. Calculat nipulator, Planne other configuration ty Kinematics: transformations | sition of n, Euler rtenberg of ion of DH er elbow on. | rent orientat rotation, rota Angele, rol convention. A I parameters manipulator tion Transla | ion des ation w ll, pito Assign and fo , Cylin | ith respect to fix ch, yaw, axis/a ment, of coordin rward kinematic | ed fram ngle re ate frar equatio | e an pres ne, 1 n of RA, | d curr entat 4 Ho Joint differ 4 Ho | ours |
| Position definition rotations and reframe, paramediamediamediamediamediamediamediamedi | itions. relative acterisa s transf Forwa te fran artesian of man st and o Veloci matics ons. Sin | Coordinate fram motion, Compo- tion of rotation ormation rd Kinematics nes. Denavit-Har n space. Calculat nipulator, Planne other configuration ty Kinematics: | sition of n, Euler rtenberg of ion of DH er elbow on. | rent orientat rotation, rota Angele, rol convention. A I parameters manipulator tion Transla | ion des ation w ll, pito Assign and fo , Cylin | ith respect to fix ch, yaw, axis/a ment, of coordin rward kinematic idrical three link | ed fram ngle re ate frar equatio | e an pres ne, 1 n of RA, | d curr entat 4 Ho Joint differ 4 Ho | rent ion, urs and rent urs city |
| Position definit rotations and r frame, param Homogeneous Module:3 Link coordina end effector Ca configuration Spherical Wris Module:4 Forward kinen Transformatio Module:5 Lagrangian fo Newton-Euler | itions. relative stansf Forwa te fran artesian of man st and o Veloci matics ons. Sin Robot | Coordinate fram motion, Compo- tion of rotation ormation rd Kinematics nes. Denavit-Har n space. Calculat nipulator, Plannet other configuration ty Kinematics: transformations gularity, The Ma Dynamics ion, general exp | sition of n, Euler rtenberg of ion of DH er elbow on. s of posi anipulato pression f | rent orientat rotation, rota Angele, rol convention. A l parameters manipulator tion Transla r Jacobian. | ion dest tion w ll, pito Assign and fo , Cylin tional | ith respect to fix ch, yaw, axis/a ment, of coordin rward kinematic idrical three link | ed fram ngle re nate frar equatio c, SCAF velociti n-link 1 | e an pres ne, . n of RA, es. man | d curr entat 4 Ho Joint differ 4 Ho Veloc 4 Ho | rent ion, urs and rent urs city urs or, |
| Position definition rotations and reframe, paramediate | itions. celative acterisa s transf Forwa ate fran artesian of man st and of Veloci matics ons. Sin Robot ormulat | Coordinate fram motion, Compo- tion of rotation ormation rd Kinematics nes. Denavit-Har n space. Calculat nipulator, Plannet other configuration ty Kinematics: transformations gularity, The Ma Dynamics ion, general exp | sition of n, Euler rtenberg o ion of DF er elbow on. s of posi anipulato pression f Derivati | rent orientat rotation, rota Angele, rol convention. A l parameters manipulator tion Transla r Jacobian. | ion dest tion w ll, pito Assign and fo , Cylin tional | ith respect to fix ch, yaw, axis/a ment, of coordin rward kinematic drical three link and rotational ential energy of | ed fram ngle re nate frar equatio c, SCAF velociti n-link 1 | e an pres ne, . n of RA, es. man | d curr entat 4 Ho Joint differ 4 Ho Veloc 4 Ho | rent ion, urs and rent urs city ours cor, ink |



| time transformed time transformed and Ro | | ry, Trajectories for Paths Sp ftware | pecified by Via P | oints. R | obot langua | ges, computer control |
|--|----------------|---|---------------------|------------|---------------|-------------------------------------|
| Modul | e:7 | Independent Joint Contro | ol: | 4 | Hours | |
| Actuate | or dyn | amics, Set point tracking Fe | ed forward control | l, Drive 7 | Frain dynam | ics. Introduction to |
| force c | ontrol | and multivariable control. | | | | |
| Modul | e:8 | Contemporary issues: | | | | 2 Hours |
| Text B | ook(s) | | | | | |
| 1. | | . Spong, S. Hutchinson, and edition, 2012 | d M. Vidyasagar, | Robot M | Iodeling and | d Control, Wiley, 2nd |
| 2. | J.J. C 2017 | Craig, Introduction to Robot | ics: Mechanics an | d Contro | ol, Pearson I | Education, 4 th Edition, |
| 3. | | Groover, et.al., Industrial Re 2 nd indian edition, 2012. | obots: Technology | v, Progra | mming and a | applications, McGraw |
| Refere | nce B | ooks | | | | |
| 1. | | ot Manipulators : Modeling ma Khalil, Somerset : Wile | | nalysis a | nd Control. | by Etienne Dombre; |
| 2. | | Tokhi, A K M Azad,Flexilon, 2017. | ble robot manipul | ator :mo | delling,simu | lation and control 2 nd |
| 3. | | tava Ghosal.Robotic fundar ession 2015. | mental Concept a | nd Anal | ysis,Oxford | University Press 11 th |
| Mode of | of Eva | luation: CAT / Assignment / | / Quiz / FAT / Pro | ject / Ser | ninar | |
| | | ed by Board of Studies | 05/03/2016 | | | |
| Approv | ed by | Academic Council | 40 th AC | Date | 18/03/20 | 16 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4027.1 | 3 | 2 | 1 | 1 | - | - | - | 2 | 1 | 1 | - | 1 | - | _ | - |
| EEE4027.2 | 3 | 2 | 1 | 1 | 1 | - | - | 2 | 1 | 1 | - | 1 | 2 | 2 | 2 |
| EEE4027.3 | 3 | 3 | 2 | 2 | - | - | - | 2 | 1 | 1 | - | 1 | 2 | 2 | _ |
| EEE4027.4 | 3 | 2 | 1 | 1 | 1 | - | - | 2 | 1 | 1 | - | 1 | 2 | 2 | 2 |
| EEE4027.5 | 3 | 2 | 1 | 1 | 2 | - | - | - | 1 | 1 | - | - | 2 | 2 | 2 |
| EEE4027.6 | 3 | 2 | 1 | 2 | 3 | - | - | - | 1 | 1 | - | 1 | 2 | 2 | 2 |
| EEE4027.7 | 3 | 2 | 1 | 2 | 3 | - | - | - | 1 | 1 | - | 1 | 2 | 2 | 2 |
| EEE4027.8 | 3 | 3 | 2 | 3 | 3 | - | - | 2 | 3 | 3 | 1 | 2 | 2 | 2 | 3 |
| | 3 | 3 | 2 | 2 | 3 | - | - | 2 | 2 | 2 | 1 | 2 | 2 | 2 | 3 |



| EEE4028 | | VLSI Design | | L | Т | ΡJ | C |
|--|--|--|---|--|------------|---|------------------------------------|
| 1 | | | | 3 | 0 | 2 0 | |
| Pre-requisite | 1 | EE3002 | | | | s ver | - |
| Anti-requisite | | | | | inu | | . 2.0 |
| Course Object | | | | | | • | . 2.0 |
| • | | nderstanding of the digital VLSI conce | ots, circuit design | . principle | es. | | |
| - | | oduction to architecture and design co | | | | omple | X |
| VLSI. | | 6 | j i i i i j | 0 | | I | |
| 3. To prov | vide stu | ents with the background needed to des | ign, develop, and | test digit | al c | ircuit | s |
| 0 | | ardware Description Language (VHDL | , U | | | | |
| 4. To prov | vide the | tudents to design the digital circuits us | ing transistors for | complex | sys | tems. | |
| Exposted Cour | | | | | | | |
| Expected Cour | | is course the student will be able to: | | | | | |
| - | | ntify the methodologies for fabricating | the ICs | | | | |
| • | | | ule ICS. | | | | |
| • | | design arithmetic circuits using HDL. | | | | | |
| 0 | • | cuits using CMOS and its equivalent la | • | | 1 | • | |
| 4. Analyze circuits. | | racteristics of CMOS to reduce the dela | iy and power diss | ipation in | 108 | ,1C | |
| | | or configurations for better performance | e in logic circuits | | | | |
| • | | devices using transistors. | e in logie chedits. | | | | |
| _ | | ign arithmetic circuits for various appli | actions | | | | |
| • | • | duct experiments, as well as analyze ar | | | | | |
| o. Design a | | duct experiments, as well as analyze an | iu interpret data | | | | |
| Module:1 (| Overvi | w of VLSI Design Methodology | | | | 4 H | ours |
| The VLSI designed | ign pro | ess, Architectural design, logical desig | gn, Physical desig | gn, layout | t st | yles, | Full |
| | -9-1 P-10 | | | | | | |
| custom, Semi c | | | | | | | |
| custom, Semi c | custom | pproaches. | | | | | |
| custom, Semi c Module:2 In | custom Introdu | pproaches. tion to Verilog HDL | | 10 | | 6 H | ours |
| custom, Semi c Module:2 In Introduction Ve | custom Introdu erilog F | pproaches. tion to Verilog HDL DL, Gate level, data flow, behavioral m | | es and Op | pera | | ours |
| custom, Semi c Module:2 In Introduction Ve | custom Introdu erilog F | pproaches. tion to Verilog HDL | | es and Op | pera | | ours |
| custom, Semi c Module:2 In Introduction Ve Blocking and ne | Introdu Introdu Terilog F non-bloo | pproaches. tion to Verilog HDL DL, Gate level, data flow, behavioral m | | es and Or | pera | | ours |
| custom, Semi custom, Semi custom, Semi custom Module:2 Introduction Verblocking and module:3 | Introdu erilog H non-bloo | pproaches. tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices | es. 6 Hours | | | tors, | ours |
| custom, Semi custom, Semi custom, Semi custom Module:2 Introduction ∨e Blocking and ne Module:3 Introduction volution | Introdu erilog F non-bloo Introdu o MOS | pproaches. tion to Verilog HDL DL, Gate level, data flow, behavioral m sing assignment statements. Test bench tion to MOS Devices ransistor Theory: nMOS, pMOS Enhar | es. 6 Hours ncement Transisto | or, MOSF | ET | tors, | |
| custom, Semi custom, Semi custom, Semi custom, Semi custom, Semi custom Version Version Version and not substitute to the semiconduction to Switch, Threshold to the semiconduction to Switch, Threshold to the semiconduction to Switch, Threshold to the semiconduction to the semiconductio | Introdu erilog F non-bloo Introdu to MOS nold vol | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices Transistor Theory: nMOS, pMOS Enhan age, MOS Device Design Equations, Bo | es. 6 Hours neement Transiste ody effect, Second | or, MOSF | ET | tors, | |
| custom, Semi custom, Semi custom, Semi custom Module:2 Introduction Verblocking and methods Blocking and methods Introduction to Switch, Threshop Transistor Circuit Introduction to Switch, Threshop | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo | pproaches. tion to Verilog HDL DL, Gate level, data flow, behavioral m sing assignment statements. Test bench tion to MOS Devices ransistor Theory: nMOS, pMOS Enhar | es. 6 Hours neement Transiste ody effect, Second | or, MOSF | ET | tors, | DS |
| custom, Semi custom, Semi custom, Semi custom, Semi custom Module:2 Introduction Verblocking and module:3 Module:3 Introduction to Switch, Threshor Transistor Circut Module:4 | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices Fransistor Theory: nMOS, pMOS Enhan age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance | es. 6 Hours neement Transiste ody effect, Second | or, MOSF | ET | tors, as a s. MC | DS |
| custom, Semi custom, Semi custom, Semi custom Module:2 In Introduction Ver Blocking and module:3 Module:3 In Introduction to Switch, Threshor Transistor Circu Module:4 C DC Characterist E | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices ransistor Theory: nMOS, pMOS Enhan age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance on CMOS Inverter, Switching Characteri | es. 6 Hours Incement Transisto ody effect, Second a. Instics of CMOS | or, MOSF order eff | ET Tra | tors, as a s. MC 6 H o nsisto | DS Durs |
| custom, Semi custom, Semi custom, Semi custom, Semi custom, Semi custom version versio | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of ical De | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices transistor Theory: nMOS, pMOS Enhan age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance on CMOS Inverter, Switching Characterity y model- Rise Time, Fall Time. Gat | es. 6 Hours Incement Transisto ody effect, Second S. Istics of CMOS e Delays, RC De | or, MOSF order eff | ET Tra | tors, as a s. MC 6 H o nsisto | DS Durs |
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| custom, Semi custom, Semi custom, Semi custom Module:2 In Introduction Verbilder Blocking and mediate Module:3 In Introduction to Switch, Threshord Switch, Threshord C Module:4 C DC Characterist Sizing Analytice Effort. Power D C | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of ical De Dissipat | tion to Verilog HDL DL, Gate level, data flow, behavioral m ting assignment statements. Test bench tion to MOS Devices Transistor Theory: nMOS, pMOS Enhan- age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance Dn CMOS Inverter, Switching Characterity model- Rise Time, Fall Time. Gat on: Static- Dynamic-Short Circuit Power | es. 6 Hours Incement Transisto ody effect, Second S. Istics of CMOS e Delays, RC De | or, MOSF order eff | ET Tra | tors, as a s. MC 6 H o nsisto | OS Durs Dor ical |
| custom, Semi custom, Semi custom, Semi custom, Semi custom, Introduction version and | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of ical De Dissipat | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices transistor Theory: nMOS, pMOS Enhan age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance on CMOS Inverter, Switching Characterity y model- Rise Time, Fall Time. Gat | es. 6 Hours Incement Transistor ody effect, Second istics of CMOS e Delays, RC De er Dissipation | or, MOSF order eff Inverter, elay Mod | ET Fect | tors, as a s. MC 6 Ho , Log 6 Ho | os ours or ical |
| custom, Semi custom, Semi custom, Semi custom Module:2 In Introduction Veresting and module:3 In Module:3 In Introduction to Switch, Threshow Transistor Circut Module:4 C DC Characterists Sizing Analytice Effort. Power D Module:5 C Introduction, S C | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of ical De Dissipat Combin Static C | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices transistor Theory: nMOS, pMOS Enhan- age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance on CMOS Inverter, Switching Characterity model- Rise Time, Fall Time. Gat on: Static- Dynamic-Short Circuit Power tional logic Circuits | es. 6 Hours Incement Transistor ody effect, Second Stics of CMOS e Delays, RC De er Dissipation Ratioed Logic, P | Inverter, elay Mod | ET Fect | tors, as a s. MC 6 He , Log 6 He or Lo | os or ical ours gic, |
| custom, Semi custom, Semi custom, Semi custom Module:2 In Introduction Veresting and module:3 In Module:3 In Introduction to Switch, Threshow Transistor Circut Module:4 C DC Characterists Sizing Analytic Effort. Power D Module:5 C Introduction, S Transmission g Speed and Power C | Introdu erilog F non-bloo Introdu o MOS nold vol cuit Moo Circuit Estimat istics of ical De Dissipat Combin Static C gate Lo ver Diss | tion to Verilog HDL DL, Gate level, data flow, behavioral m king assignment statements. Test bench tion to MOS Devices transistor Theory: nMOS, pMOS Enhan- age, MOS Device Design Equations, Bo el. Stick Diagram, Layout Design Rules Characterization And Performance on CMOS Inverter, Switching Characterity model- Rise Time, Fall Time. Gat on: Static- Dynamic-Short Circuit Power tional logic Circuits MOS Design- Complex Logic Gates, | es. 6 Hours Ancement Transistor body effect, Second distics of CMOS e Delays, RC De er Dissipation Ratioed Logic, P bynamic Logic D | Inverter, elay Mod ass-Trans | ET ect | tors, as a s. MC 6 He , Log 6 He or Lo leratio | or ical ours gic, ons. |



Static and Dynamic Latches and Registers, Timing issues, pipelining

| Module:7 | Designing arithmetic circuits 9 | | | | | | | |
|---------------|--|---------------------------------|--|--|--|--|--|--|
| Adders-Ripp | le carry, Carry-Look ahead, Multiplier using Array b | ased-Ripple carry adder, Carry- | | | | | | |
| Save adder, I | Multiplier using Tree based-Wallace Tree, Dadda Tre | ee, Booth Multiplier, Squarer. | | | | | | |
| Modeling of | arithmetic circuits using HDL: | | | | | | | |

Pipelined Multiplier and Accumulator, FIR filter design. Verilog Coding for arithmetic circuits.

| Mod | ule:8 | Contemporary issues: | 2 Hours | | | |
|------|----------|---|---------------|--|--|--|
| | | Total Lecture hours: | 45 Hours | | | |
| List | of Chall | lenging Experiments (Indicative) | | | | |
| 1. | Four b | it adder using different approaches for delay and Area reduction | 2 Hours | | | |
| 2. | Four B | it Wallace tree multiplier | 2 Hours | | | |
| 3. | Four b | it dada tree multiplier | 2 Hours | | | |
| 4. | Four bi | t squarer design | 2 Hours | | | |
| 5. | Multip | lier and Accumulator design | 2 Hours | | | |
| 6. | FIR filt | 2 Hours | | | | |
| 7. | CMOS | 2 Hours | | | | |
| 8. | CMOS | 2 Hours | | | | |
| 9. | Implem | nentation of Boolean function using various transistors | 2 Hours | | | |
| 10. | Positiv | e and negative edge triggered register design | 2 Hours | | | |
| | | Total Laboratory Hours | 30 hours | | | |
| Text | Book(s | | | | | |
| 1 | . Jan | Rabaey, Anantha Chandrakasan, B.Nikolic, "Digital Integrated circui | ts: A design | | | |
| | persp | pective". Second Edition, Prentice Hall of India, 2013. | | | | |
| 2 | l. Neil | H.E.Weste, David Money Harris, "CMOS VLSI DESIGN: a circuits a | nd systems | | | |
| | persp | pective", Fourth edition, Pearson 2015. | | | | |
| | | | | | | |
| Refe | erence B | Books | | | | |
| 1 | . Sam | ir Palnitkar, "Verilog HDL", Prentice Hall, 2010. | | | | |
| 2 | 2. Sung | g-Ma Kong, Yusuf Leblebici and Chulwoo Kim, "CMOS digital integra | ted circuits: | | | |
| | - | ysis and design", 4th edition, McGraw-Hill Education, 2015. | | | | |
| | | | | | | |
| | e of Eva | | 6 | | | |
| | | ed by Board of Studies 05/03/2016 | | | | |
| Appı | roved by | Academic Council 40 th AC Date 18/03/2016 | | | | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4028.1 | 3 | 2 | 1 | 1 | 1 | | | | | | | 2 | | | |
| EEE4028.2 | 3 | 2 | 1 | 2 | 2 | | | 2 | 2 | 2 | | 2 | 2 | 2 | 2 |
| EEE4028.3 | 3 | 1 | 1 | | | | | | | | | 1 | 2 | 1 | 1 |
| EEE4028.4 | 3 | 3 | 2 | 1 | 1 | | | 1 | 1 | 1 | | 1 | 1 | | 1 |
| EEE4028.5 | 3 | 3 | 2 | 1 | 1 | | | 1 | 1 | 1 | | 1 | 1 | | 1 |
| EEE4028.6 | 3 | 3 | 2 | | | | | | | | | 1 | 1 | | 1 |
| EEE4028.7 | 3 | 2 | 1 | 2 | 2 | | | 2 | 2 | 2 | | 2 | 2 | 2 | 2 |
| EEE4028.8 | 3 | 3 | 3 | 3 | 3 | | | 2 | 2 | 3 | | | 2 | 1 | 2 |
| | 3 | 3 | 2 | 1 | 2 | - | - | 2 | 2 | - | - | 1 | 2 | 2 | 2 |



| EEE4029 | | Advanced Microcontrollers | | | L | Τ | P | J | C |
|---------------|----------|---|---------|--------------|-------|-------------------|------------|-------|-----|
| | | | | | 2 | | | | 3 |
| Pre-requisite | • | EEE4001 | | , | Sylla | bus | s ver | sio | n |
| Anti-requisit | | | | | U | | | 1. 1. | |
| Course Obje | | | | | | | | | |
| 1. To giv | ve an er | nphasis on the features of ARM Processors & PIC Micr | ocon | troll | er | | | | |
| - | | ssential knowledge on various operating modes, I/O por | | | | | | | |
| | | inters, control register and the various types of interrupts | s of th | nose | | | | | |
| | ocontro | | | | | | | | |
| Expected Co | | | | | | | | | |
| - | | f this course the student will be able to: | | | | | | | |
| | | architecture of ARM processor Peripherals of ARM processor | | | | | | | |
| • | | Program for processor peripherals | | | | | | | |
| | - | owledge to utilize the ARM processor for real time appl | icatio | ne | | | | | |
| | | the architecture of PIC18FXX microcontroller | ireativ | J 115 | | | | | |
| | | program for PIC18FXX microcontroller | | | | | | | |
| | | PLAB software to simulate PIC18FXX microcontroller | prog | ram | s | | | | |
| | | ponent or a product applying all the relevant standards | | | | con | strai | nts | |
| U | | | | | | | | | |
| | | | | | | | | | |
| Module:1 | | tecture of LPC 21XX | | | | | <u>3 H</u> | our | S |
| | | of LPC 21XX architecture, Various registers of 21XX, p | orts (| of L | PC 2 | 1X. | | | |
| Module:2 | | ional Blocks of LPC 21XX | | | | | 4 H | our | `S |
| | | AC, Serial communication and Interrupt. | | | | | <u> </u> | | |
| Module:3 | | amming of LPC21XX Functional Blocks | - 4 | | | | 6 H | our | `S |
| | - | C 21XX: GPIO, Timer, ADC, DAC, UART and Interrup | ot. | | | | 2 11 | | |
| Module:4 | | Studies | 00.11 | ina | into | | <u>3 H</u> | our | S |
| | | sing temperature sensor, generation of delay, multitaski tecture of PIC 18FXX | ng u | sing | me | rup | | | |
| | | nitecture — PIC18F Family, Programming Model and Its | ragi | atore | | | 3 H | our | 5 |
| Module:6 | | ction Set & Functional Blocks of PIC | legi | 51015 | • | | 6 H | 0111 | - |
| Wiouule.0 | 18FXX | | | | | | 0 11 | oui | . 3 |
| Data Transfe | | metic, and Branch Instructions, Introduction to Logic, | Bit N | lani | pula | ion | and | 1 | |
| | | perations, Stack and Subroutines. Input/output (I/O | | | | | | | |
| Timers. | | | · | , | | 1 | | | |
| | | | | | | | | | |
| Module:7 | Appli | cation Programs | | | | | 3 H | our | :s |
| MPLAB intro | oduction | n, solving real time problems using PIC 18FXX. | | | | | | | |
| Module:8 | Cont | emporary issues: | | | | | 2 H | our | .s |
| | | Total Lecture hours: | | | | | 80 H | our | :s |
| Text Book(s) | | | | | | | | | _ |
| 1. And | rew N | Sloss , Dominic Symes , Chris Wright, " ARM Syst | em I | Deve | elope | er's | Gui | de: | |
| Desi | gning a | and Optimizing System Software ", Morgan Kaufmar | n Pu | ıblis | hers | , 1 st | edi | tior | ı, |
| 2009 |) | | | | | | | | |



| 2. | Muhammad Ali | Mazidi , Rolir | n D. McKinlay, I | Danny Causey, | "PIC Microcontroller and | | | | | |
|---------|--|------------------|---------------------|-----------------|---------------------------------------|--|--|--|--|--|
| | Embedded Syste | ems Using Asser | nbly and C for PI | C 18", Prentice | Hall, 2 nd Edition, 2009. | | | | | |
| Referen | rence Books | | | | | | | | | |
| 1. | David Seal, "AR | M Architecture | Reference Manua | ıl ", Addison W | Vesley, 2 nd Edition, 2007 | | | | | |
| 2. | Peatman, "Desig | gning with PIC N | Aicrocontroller", 1 | Pearson Educat | ion, 1 st Edition, 2011. | | | | | |
| 3. | P.V Guruprasad, | , "Arm Architec | ture System on Cl | nip and More " | , Apress, 2013. | | | | | |
| 4. | http://www.nxp.o | com/documents/ | user_manual/UM | 10114.pdf. | | | | | | |
| Mode o | of Evaluation: | CAT I & II – 3 | 0%, DA I & II – 2 | 20%, Quiz – 10 | %, FAT – 40% | | | | | |
| Recom | ommended by Board of Studies 05/03/2016 | | | | | | | | | |
| Approv | broved by Academic Council 40 th AC Date 18/03/2016 | | | | | | | | | |

| CO | DO1 | DO2 | DO 2 | | DO5 | DOC | DO7 | | DOO | DO10 | DO11 | DO12 | DCO1 | DGO2 | DSO2 |
|-----------|-----|-----|-------------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE4029.1 | 3 | 2 | 2 | 1 | 1 | - | - | - | 1 | - | - | 2 | 1 | 1 | 1 |
| EEE4029.2 | 3 | 3 | 2 | 1 | 1 | - | - | - | 1 | - | - | 2 | 1 | 3 | 1 |
| EEE4029.3 | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 2 | 1 | 1 | 1 |
| | | | | | | | | | | | | | | | |
| EEE4029.4 | 3 | 2 | 2 | 1 | 1 | - | - | - | 1 | - | - | 2 | 1 | 1 | 1 |
| EEE4029.5 | 3 | 2 | 2 | 1 | 1 | - | - | - | 1 | - | - | 2 | 2 | 1 | 1 |
| EEE4029.6 | 3 | 3 | 3 | 2 | 2 | - | - | - | 1 | - | - | 2 | 1 | 1 | 2 |
| | | | | | | | | | | | | | | | |
| EEE4029.7 | 3 | 2 | 2 | 2 | 2 | - | - | - | 1 | - | - | 2 | 1 | 1 | 2 |
| | | | | | | | | | | | | | | | |
| EEE4029.8 | 3 | 3 | 3 | 3 | 3 | - | - | - | 1 | - | - | 2 | 1 | 1 | 2 |
| | 3 | 3 | 3 | 3 | 3 | - | - | - | 1 | - | - | 2 | 2 | 3 | 3 |



| EEE4030 | | | Svs | stem on | Chip I |)esign | ı | | | L | ΤP | J | С |
|--|---|---|---|---|--|---|---|--|--|---------------|-------------------------|--|------------------------------|
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| Pre-requisite | NIL | 1 | | | | | | | | Syl | labu | s vei | rsion |
| Anti-requisite | NIL | | | | | | | | | | | | v. 2.1 |
| Course Object | tives: | | | | | | | | | | | | |
| 1. To prov | vide an over | view on | the prese | ent day o | design t | echno | logy fo | r Syste | m-On- | Chip | | | |
| | erstand how | | | s integra | te with | each o | other su | ch as h | ardwai | re and | d sof | twar | e, |
| analogu | ue and digit | al constru | actions. | | | | | | | | | | |
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| | e the variou | | | | 10 | | | | | | | | |
| | a compone | | | | all the re | levan | t stand | ards wi | th real | istic | const | raint | ts |
| U | 1 | 1 | 1 | 1 5 0 | | | | | | | | | |
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| | [ntroductio | | | | | | | | | | | 3 H | lours |
| Technology tre | ends, design | challeng | ges, Over | view of | SoC D | esign | Flow. | | | | | | |
| | | | | | | | | | | | | 7 T | r |
| | SoC Design | | | turna Car | | | Faaraa | ian M | | ~~~~~ | in Ca | | lours |
| Hardware Syst | | | | lure, Se | micona | ICIOT | ECONOD | mes, ivi | ajor is | sues | 111 SC |)(| |
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| | n for Integra ssors. | tion. Ac | celerating | g Proces | ssor for | | | | | | | | |
| multiple proces | | ation. Ac | celerating | g Proces | ssor for | | | | | | | | |
| multiple proces | | | | g Proces | ssor for | | | | | | | sign | lours |
| multiple proces | ssors. System Lev | rel Desig | n | | | traditi | ional so | ftware | task. S | ystei | m des | sign 5 H | ours |
| Module:3 | ssors. System Lev system arch | el Designitecture, | n Processo | or centri | c SoC o | traditi rganiz | ional so zation, o | ftware | task. S | ystei | m des | sign 5 H | lours |
| Module:3 \$ Complex SoC Hardware and | ssors. System Lev system arch Software in | r el Desig itecture, terconne | n Processo | or centri | c SoC o | traditi rganiz | ional so zation, o | ftware | task. S | ystei | m des | 5 H 1 – | |
| Module:3 S Complex SoC Hardware and Module:4 I | ssors. System Lev system arch Software in RTL Synth | el Design itecture, terconne esis | n Processo cts, Non- | or centri -process | c SoC o sor build | traditi rganiz ling b | ional so zation, d lock in | ftware Commu SoC de | task. S inications ini | on D | n de: esign | sign 5 H 1 – 8 H | ours |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Version Version | ssors. System Lev system arch Software in RTL Synth rilog - RTL | el Design itecture, terconne esis Coding | n Processo cts, Non- and RT | or centri -process L Syntl | c SoC o sor build | traditi rganiz ling b | ional so zation, d lock in | ftware Commu SoC de | task. S inications ini | on D | n de: esign | sign 5 H 1 – 8 H | ours |
| multiple process Module:3 S Complex SoC Hardware and Module:4 I | ssors. System Lev system arch Software in RTL Synth rilog - RTL | el Design itecture, terconne esis Coding | n Processo cts, Non- and RT | or centri -process L Syntl | c SoC o sor build | traditi rganiz ling b | ional so zation, d lock in | ftware Commu SoC de | task. S inications ini | on D | n de: esign | sign 5 H 1 – 8 H | ours |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Complex Soc | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, I | el Design itecture, terconne esis Coding Memory | n Processo cts, Non- and RT | or centri -process L Syntl | c SoC o sor build | traditi rganiz ling b | ional so zation, d lock in | ftware Commu SoC de | task. S inications ini | on D | m des esign izabl | 5 H 1 – 8 H e co | l ours ding |
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| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Complex Soc Module:5 Module:5 S Verification term S | ssors. System Lev system arch Software in RTL Synth rilog - RTI ding style, 1 SoC Verific schnology o | el Design itecture, terconne esis Coding Memory | n Processo cts, Non- and RT Modeling | or centri -process L Synth g. | c SoC o sor build nesis R | rganiz ling b | ional so zation, o lock in ding gu | ftware Commu SoC de | unications in the sign. | on D | m des esign | sign 5 H 1 – 8 H e co | lours ding lours |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Constraints Style, FSM Constraints Module:5 S | ssors. System Lev system arch Software in RTL Synth rilog - RTI ding style, 1 SoC Verific schnology o | el Design itecture, terconne esis Coding Memory | n Processo cts, Non- and RT Modeling | or centri -process L Synth g. | c SoC o sor build nesis R | rganiz ling b | ional so zation, o lock in ding gu | ftware Commu SoC de | unications in the sign. | on D | m des esign | sign 5 H 1 – 8 H e co | lours ding lours |
| multiple process Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Construction Module:5 S Verification te verification. Ti | ssors. System Lev system arch Software in RTL Synth rilog - RTI ding style, 1 SoC Verific schnology o | el Design itecture, terconne esis Coding Memory cation ptions, V cation. | n Processo cts, Non- and RT Modeling | or centri -process L Synth g. | c SoC o sor build nesis R | rganiz ling b | ional so zation, o lock in ding gu | ftware Commu SoC de | unications in the sign. | on D | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev | lours ding lours el |
| multiple process Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Construction Module:5 S Verification te verification. Ti | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, I SoC Verific chnology of iming verifi | el Design itecture, terconne esis Coding Memory ation ptions, V cation. | n Processo cts, Non- and RT Modeling Verificati | or centri -process 'L Synth g. ion met | c SoC o sor build nesis R7 hodolog | rganiz ling b FL co | zation, v lock in ding gr | ftware Commu SoC de uideline evel ve | inications in the sign. | on D nthes | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev 7 H | lours ding lours el |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Construction S Verification terverification. Tri S Module:6 I | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, 1 SoC Verific chnology co ming verifi Physical De Floor Planni | el Design itecture, terconne esis Coding Memory itemory iterions, ' cation esign ing, Place | n Processo cts, Non- and RT Modeling Verificati | or centri- -process L Synth g. ion met | c SoC o sor build nesis R7 hodolog Goals o | rganiz ling b FL co gy. Sy | ional so zation, o lock in ding gu vstem lo | ftware Commu SoC de uideline evel ve | unications of the sign. | on D nthes | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev 7 H | lours ding lours el |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Cod Module:5 S Verification te verification. Ti Module:6 I Partitioning, F Detailed routi | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, I SoC Verific chnology of ming verifi Physical De Floor Planni ng, Over th | el Design itecture, terconne esis Coding Memory itemory iterions, ' cation esign ing, Place | n Processo cts, Non- and RT Modeling Verificati | or centri- -process L Synth g. ion met | c SoC o sor build nesis R7 hodolog Goals o | rganiz ling b FL co gy. Sy | ional so zation, o lock in ding gu vstem lo | ftware Commu SoC de uideline evel ve | unications of the sign. | on D nthes | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev 7 H iting | lours ding el lours |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Construction S Module:5 S Verification I Verification I Partitioning, F Detailed routi Module:7 I | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, 1 SoC Verific chnology controls ming verifi Physical De Floor Planning, Over th Routing | el Design itecture, terconne esis Coding Memory i ation options, ' cation. esign ing, Place e Cell Re | n Processo cts, Non- and RT Modeling Verificati ement, R puting, P | or centri- -process 'L Synth g. ion met outing, hysical | c SoC o sor build nesis R7 hodolog Goals o verifica | rganiz ling b FL co gy. Sy f rout tion a | ional so zation, o lock in ding gu vstem lo | ftware Commu SoC de uideline evel ve | unications of the sign. | on D nthes | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev 7 H iting | lours ding lours el |
| Module:3 S Complex SoC Hardware and Module:4 I Review of Verstyle, FSM Cod Module:5 S Verification te verification. Ti Module:6 I Partitioning, F Detailed routi | ssors. System Lev system arch Software in RTL Synth rilog - RTL ding style, 1 SoC Verific chnology controls ming verifi Physical De Floor Planning, Over th Routing | el Design itecture, terconne esis Coding Memory ation ptions, V cation. esign ing, Place e Cell Ro Ground 1 | n Processo cts, Non- and RT Modeling Verificati ement, R puting, P | or centri- -process 'L Synth g. ion met outing, hysical | c SoC o sor build nesis R7 hodolog Goals o verifica | rganiz ling b FL co gy. Sy f rout tion a | ional so zation, o lock in ding gu vstem lo | ftware Commu SoC de uideline evel ve | unications of the sign. | on D nthes | m des esign izabl | 5 H 5 H 1 – 8 H e co 10 H c-lev 7 H uting 3 H | lours ding el lours |



| | | | Total Lec | ture hours: | | 45 Hours |
|------|----------|-------------------------------|---------------------|----------------|--------------------------|----------------|
| Text | Book(s |) | | | | |
| 1. | Chri | is Rowen, "Engineering th | he Complex | SOC: Fast, F | lexible Design with Co | onfigurable |
| | Proc | cessors", Pearson, 2004. | _ | | - | - |
| 2. | Roc | hit Rajsuman, 'System-on- | -a-Chip: Des | sign and Test' | , Artech House, 2006. | |
| Refe | rence B | ooks | | | | |
| 1. | Prak | ash Rashinkar, Peter Pater | rson, Leena | Singh, "Syste | m on a chip verification | n: Methodology |
| | and | Verification", Kluwer Aca | demic Publ | ishers, 2013 | 1 | |
| 2. | Him | anshu Bhatnagar, "Advanc | ced ASIC Ch | nip Synthesis' | , Kluwer Academic Pu | ublishers, 2nd |
| | Edit | ion, 2002. | | | | |
| 3. | Rao | Tummala, Madhavan Swa | aminathan , ' | 'Introduction | to System-On-Package | : |
| | | iaturization of the entire sy | | | | |
| Mode | | luation: CAT / Assignmen | | | | |
| | | | | J | | |
| Reco | ommende | ed by Board of Studies | 05/03/201 | .6 | | |
| Appr | roved by | Academic Council | 40 th AC | Date: | | 18/03/2016 |

| | D O 1 | | D 00 | 201 | 201 | DOL | | D 00 | D 00 | D010 | D 044 | D010 | Daoi | D 000 | D 000 |
|-----------|--------------|-----|-------------|-----|-----|-----|-----|-------------|-------------|------|--------------|------|------|--------------|--------------|
| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| EEE4030.1 | 3 | 2 | 2 | 1 | 1 | - | - | - | 1 | - | - | 2 | 2 | 1 | 1 |
| EEE4030.2 | 3 | 3 | 2 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 3 | 1 |
| EEE4030.3 | 3 | 2 | 2 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 1 | 1 |
| EEE4030.4 | 3 | 2 | 3 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 1 | 3 |
| EEE4030.5 | 3 | 2 | 3 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 1 | 3 |
| EEE4030.6 | 2 | 2 | 2 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 1 | 1 |
| EEE4030.7 | 3 | 3 | 2 | 1 | 1 | - | - | I | 1 | - | - | 2 | 2 | 3 | 1 |
| | | | | | | | | | | | | | | | |
| EEE4030.8 | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 2 | 2 | 1 | 3 |
| | 3 | 3 | 3 | 1 | 1 | - | - | - | 1 | - | - | 2 | 2 | 3 | 3 |



| EEE4034 | | Wireless Sensor Networks | | LT | P J | C |
|---|---|---|--|--|--|--|
| | | | | 3 0 | 0 4 | 4 |
| Pre-requisit | e | EEE4021 | Sy | llabu | s ver | sion |
| Anti-requisi | te | NIL | | | V | . 1.0 |
| Course Obj | ectives: | | | | | |
| | | sic fundamentals in wireless sensor technology. | | | | |
| - | | dents to the recent advances in various wireless networ | | | | |
| 3. To discov | er vario | us routing mechanism and the storage requirement for | networking | of set | nsors. | |
| Expected Co | ourse O | utcome: | | | | |
| | | f this course the student will be able to: | | | | |
| - | | fundamentals and basic features of wireless sensor netw | works. | | | |
| 2. Analyze | the loca | alization and tracking techniques of wireless sensor net | works | | | |
| - | | wledge about Medium access and sleep based control s | trategies for | wire | less | |
| channels | | | | | | |
| | | rious routing protocols, energy minimization and | security iss | ues i | n sei | isor |
| network | | fundamentals of sensor tasking and control | | | | |
| | | storage management, retrieval and solve security chal | lenges | | | |
| | | rtance of wireless sensors security and reliability | lenges | | | |
| | | nent or a product applying all the relevant standards w | ith realistic | const | raints | 5 |
| | | | | | | |
| Module:1 | | luction: | NT . 1 | | 8 H | |
| | | ork architectural elements, Advantages of Sensor | Networks, | Appli | catio | |
| Technologic | -1 T | de Stevense en de Detriere le Netere de Deules | | | | |
| - | | ds- Storage, search and Retrieval - Network Deploy | yment - Str | | ed ve | ersus |
| randomized | deploy | ment - Network topology- Connectivity in geo | yment - Str | | ed ve | ersus |
| randomized | deploy | | yment - Str | | ed ve | ersus |
| randomized Connectivity Module:2 | deploy using p | ment - Network topology- Connectivity in geo ower control-Coverage metrics- Mobile deployment ization and Tracking : | yment - Str metric rand | lom | ed ve graph | ersus 1s - ours |
| randomized Connectivity Module:2 Localization | deploy using p Local and T | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide | yment - Str metric rand | lom | ed ve graph | ersus 1s - ours |
| randomized Connectivity Module:2 Localization | deploy using p Local and T | ment - Network topology- Connectivity in geo ower control-Coverage metrics- Mobile deployment ization and Tracking : | yment - Str metric rand | lom | ed ve graph | ours |
| randomized Connectivity Module:2 Localization analysis of lo | deploy using p Local and Tr ocalizati | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods | yment - Str metric rand | lom | ed ve graph 6 He heore | ersus 1s - ours tical |
| randomized Connectivity Module:2 Localization | deploy using p Local and Tr ocalizati | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology | yment - Str metric rand | lom | ed ve graph 6 He heore | ours |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 | deploy using p Local and Tr ocalizati Mediu Contr | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: | yment - Str metric rand localization | lom - Tl | ed ve graph 6 He heore 6 He | ours ours ours ours |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc | deploy using p Local and Tr ocalizati Mediu Contr cess and | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology | yment - Str metric rand localization | lom - Tl | ed ve graph 6 He heore 6 He | ours tical ours ion- |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi | deploy vusing p Locali and Tr ocalizati Mediu Contr cess and um Acc | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Met | yment - Str metric rand localization | lom - Tl | ed ve graph 6 He heore 6 He | ours tical ours ion- |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi | deploy vusing p Locali and Tr ocalizati Mediu Contr cess and um Acc | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Meters ess -Wireless MAC Protocols - Characteristics of M | yment - Str metric rand localization | lom - Tl | ed ve graph 6 He heore 6 He | ours tical ours ion- |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi | deploy vusing p Locali and Tr ocalizati Mediu Contr cess and um Acc | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Metrics ress -Wireless MAC Protocols - Characteristics of M IAC Protocols-Sleep based topology control | yment - Str metric rand localization | lom - Tl | ed ve graph 6 Ho 6 Ho ontent a Sen | ours tical ours ion- |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Ene | deploy vusing p Local and Trocalizati Mediu Contro cess and um Acco lybrid M Routin ergy awa | ment Network topology- Connectivity in geore ower control-Coverage metrics- Mobile deployment ization and Tracking : ization and Tracking : racking Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Meters cess -Wireless MAC Protocols - Characteristics of M AC Protocols-Sleep based topology control ng: are routing – Unicast geographic routing, routing on a fill | yment - Str metric rand localization dium Acces IAC Protoc | lom - Tl ss -Cc ols ir y mir | ed ve graph 6 Ho heore 6 Ho ontent n Sen 7 Ho nimizi | ours ion- sor |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Ene broadcast, en | deploy vusing p Local and Tr ocalizati Mediu Contr cess and um Acc lybrid M Routin ergy awa | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Me ress -Wireless MAC Protocols - Characteristics of M fAC Protocols-Sleep based topology control mg: are routing – Unicast geographic routing, routing on a few ware routing to a region, Attribute based routing – | yment - Str metric rand localization dium Acces IAC Protoc | lom - Tl ss -Cc ols ir y mir | ed ve graph 6 Ho heore 6 Ho ontent n Sen 7 Ho nimizi | ours ion- sor |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Ene | deploy vusing p Local and Tr ocalizati Mediu Contr cess and um Acc lybrid M Routin ergy awa | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking – Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Me ress -Wireless MAC Protocols - Characteristics of M fAC Protocols-Sleep based topology control mg: are routing – Unicast geographic routing, routing on a few ware routing to a region, Attribute based routing – | yment - Str metric rand localization dium Acces IAC Protoc | lom - Tl ss -Cc ols ir y mir | ed ve graph 6 Ho heore 6 Ho ontent n Sen 7 Ho nimizi | ours ion- sor ours |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Enc broadcast, er routing, geog | deploy vusing p Local and Tr ocalizati Mediu Contr cess and um Acc lybrid M Routin ergy awa nergy a graphic | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking — Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Met cess -Wireless MAC Protocols - Characteristics of M fAC Protocols-Sleep based topology control ng: are routing — Unicast geographic routing, routing on a of ware routing to a region, Attribute based routing — hash tables. | yment - Str metric rand localization dium Acces IAC Protoc | lom - Tl ss -Cc ols ir y mir | ed ve graph 6 Ho heored 6 Ho ontent n Sen 7 Ho nimizion, ru | ours ion- sor ours ing mor |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Ene broadcast, er routing, geog | deploy vusing p Local and Tri ocalizati Mediu Contri cess and um Acc (ybrid N Routin ergy awa nergy a graphic | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking — Localization approaches -Network-wide on techniques-Tracking Methods m Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Metrics Sleep Based Topology Control - Contention-Free Metrics ware routing MAC Protocols - Characteristics of M IAC Protocols-Sleep based topology control ng: are routing – Unicast geographic routing, routing on a feature ware routing to a region, Attribute based routing – hash tables. | yment - Str metric rand localization edium Acces IAC Protoc | lom - Tl ss -Cc ols ir y mir ffusic | ed ve graph 6 Ho heorer 6 Ho ontent n Sen 7 Ho nimizion, ru 5 Ho | ours ion- sor ours ing mor |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Enc broadcast, en routing, geog Module:5 Sensor Task | deploy vusing p Locali and Tr ocalizati Mediu Contr cess and um Acc lybrid M Routin ergy awa nergy awa graphic T | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking — Localization approaches -Network-wide on techniques-Tracking Methods im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Metrics ess -Wireless MAC Protocols - Characteristics of M fAC Protocols-Sleep based topology control mg: are routing — Unicast geographic routing, routing on a ware routing to a region, Attribute based routing — hash tables. r Tasking and Control: Control — Task driven sensing, roles of sensor nodes | yment - Str metric rand localization localization edium Access IAC Protoc | lom - Tl - Tl - ss -Cc ols ir y mir ffusic | ed ve graph 6 Ho heored 6 Ho ontent 5 Ho forma | ours ion- sor ours ing mor ours tion |
| randomized Connectivity Module:2 Localization analysis of lo Module:3 Medium Acc Based Medi Networks -H Module:4 Routing–Ene broadcast, ex routing, geog Module:5 Sensor Task based sensor | deploy vusing p Local and Tri ocalizati Mediu Contri cess and um Acc (ybrid N Routin ergy awa nergy a graphic 1 Senso ing and tasking | ment - Network topology- Connectivity in geor ower control-Coverage metrics- Mobile deployment ization and Tracking : racking — Localization approaches -Network-wide on techniques-Tracking Methods m Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Metrics Sleep Based Topology Control - Contention-Free Metrics ware routing MAC Protocols - Characteristics of M IAC Protocols-Sleep based topology control ng: are routing – Unicast geographic routing, routing on a feature ware routing to a region, Attribute based routing – hash tables. | yment - Str metric rand localization edium Access IAC Protoc curve, energ directed di s and utilitie in tracking 1 | lom - Tl ss -Cc ols ir y mir ffusic es, inf relatic | ed ve graph 6 Ho heore 6 Ho ontent n Sen 7 Ho nimizion, ru 5 Ho forma ons, jo | ours ion- sor ours ion- sor ours ing mor ours tion ours |



Data-centric networking- Data-centric routing -Data-gathering with compression - Querying -

Data-centric networking:

| Data-c manag | | • | e database perspec | ctive on so | ensor networks-sensor group |
|-----------------|---------|-------------------------------|---------------------|-------------|----------------------------------|
| | | | | | |
| Module | e:7 | Transport reliability and | Security: | | 5 Hours |
| Transpo | ort rel | iability and Security - Basic | mechanisms and | tunable pa | rameters- Reliability guarantees |
| -Securit | ty Att | acks in Sensor Networks - P | rotocols and Mech | nanisms fo | r Security- Case Studies. |
| | | | | | |
| Module | e:8 | Contemporary issues: | | | 2 Hours |
| | | | Total Lecture h | ours: | 45 Hours |
| Text Bo | ook(s) | | | I | |
| 1. | Bha | skarKrishnamachari, "Netw | orking Wireless S | Sensors", (| Cambridge University Press, |
| | 201 | | - | | |
| 2. | Ian I | Fuat Akyildiz, "Wireless sen | sor networks", Ch | ichester [u | ı.a.] : Wiley, 2011. |
| Referen | nce B | ooks | | | |
| 1. | Dan | iel Minoli, TaiebZnati,Ka | azemSohra, 'Wi | reless Se | nsor Networks: Technology, |
| | Prot | ocols, and Applications' Joh | n wiley& sons, 20 | 007. | |
| 2. | Feng | g Zhao, Leonidas. J.Guil | oas, 'Wireless S | ensor Ne | etworks', Morgan Kaufamann |
| | Pub | ishers, 2008. | | | |
| 3. | Ivan | Stojmenovi, 'Handbook of | Sensor Networks: | Algorithn | ns and Architectures', Hoboken: |
| | Johr | Wiley & Sons, 2005. | | | |
| 4. | Rag | havendra, C. S., Sivalinga | m, Krishna M., | Znati, Ta | ie, Wireless Sensor Networks, |
| | Kluv | ver Academic publishers, 20 | 007. | | |
| Mode o | f Eva | luation: CAT / Assignment / | / Quiz / FAT / Pro | ject / Semi | nar |
| | | | | • | |
| | | ed by Board of Studies | 05/03/2016 | | |
| Approv | ed by | Academic Council | 40 th AC | Date | 18/03/2016 |

management.

Module:6

5 Hours



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4034.1 | 3 | 1 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE4034.2 | 1 | 3 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 3 | 1 |
| EEE4034.3 | 3 | 1 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE4034.4 | 3 | 1 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE4034.5 | 3 | 1 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE4034.6 | 1 | 3 | 1 | 3 | 1 | - | - | - | 1 | - | - | 1 | 2 | 2 | 1 |
| EEE4034.7 | 3 | 1 | 1 | 1 | 1 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| EEE4034.8 | 1 | 1 | 3 | 3 | 3 | - | - | - | 1 | - | - | 1 | 2 | 1 | 1 |
| | 3 | 3 | 3 | 3 | 3 | - | - | - | 3 | 3 | - | 1 | 2 | 1 | 1 |



| EEE40 . | 35 | V | irtual Instrumen | tation | | L | Т | P. | JC |
|----------------|--------------|--------------------------|---------------------------|-------------|---------------|-----------|------|-------|--------|
| | | | | | | 0 | 0 | 2 4 | 4 2 |
| Pre-req | uisite | EEE4021 | | | | Sylla | abu | s ver | sion |
| Anti-re | | NIL | | | | | | | v. 1.0 |
| | Objectives | | | | | | | | |
| | | ng Virtual Instrument | concepts | | | | | | |
| 2. | Developing | Virtual Instruments fo | r practical works. | | | | | | |
| 3. | Analog and | digital measurement p | rinciples | | | | | | |
| 4. | Data Acquis | ition operation | | | | | | | |
| Expect | ed Course (| Dutcome: | | | | | | | |
| | | of this course the stude | nt will be able to: | | | | | | |
| | - | analog and digital sigr | | devices. | | | | | |
| 2. | Design a con | mponent or a product a | pplying all the rel | evant stan | dards with re | ealistic | con | strai | nts |
| List of | Challenging | g Experiments (Indica | ative) | | | | | | |
| 1 | | arithmetic and boolea | | | | | | | |
| 2 | | am using SUBVI conc | - | | | | | | |
| 3 | - | e forms & Graphs | epu. | | | | | | |
| 4 | | ive data processing usi | ng (FOR WHILE | Loops, Fo | rmula Node |) | | | |
| 5 | | Structures. | | 20000,10 | | · / | | | |
| 6 | | duction to various tool | boxes | | | | | | |
| 7 | | and string operations. | | | | | | | |
| 8 | | bg signals interfacing u | sing DAQ. | | | | | | |
| 9 | | al signals interfacing u | | | | | | | |
| 10 | NI EI | | 0 | | | | | | |
| Text Bo | ook(s) | | | | | | | | |
| 1. | | I Bishop, "LabVIEW" | Pearson 2016 | | | | | | |
| Defense | nce Books | | , 1 cu ison, 2010. | | | | | | |
| | | | | | | | _ | | |
| 1 | • | Johnson, Richard Jenn | - | Fraphical P | rogramming | g", 4th / | e, T | ata | |
| | McGraw | Hill, New York, 2006. | | | | | | | |
| 2. | LabVIE | W. Core 3, Exercises- | manual by Nationa | al instrume | nts,2013. | | | | |
| 3. | Ronald | W Larsen, "LabVIEW | for Engineers, Pre | entice Hall | , 2011. | | | | |
| 4. | S Suma | thi, "LabVIEW based | advanced instrum | entation sy | vstems", Spr | inger, 2 | 007 | | |
| Mode of | Evaluation | CAT / Assignment / | Quiz / FAT / Proje | ect / Semin | ar | | | | |
| Recom | nended by E | Board of Studies | 05/03/2016 | | | | | | |
| | • | emic Council | 40 th AC | Date | 18/03/2016 | 6 | | | |



| EEE40 3 | 37 | | to be University under section 3 of d Prototyping wi | | | L T P J C |
|---|------------------|--------------------------|---|-----------------|----------------|------------------|
| | | | | | | 0 0 4 0 2 |
| Pre-req | uisite | NIL | | | | Syllabus version |
| Anti-re | | | | | | v.1.0 |
| Course | - Objectives: | | | | | |
| | | rse exposes students | | | design and | test of a wide |
| | | f prototype electric an | | | | |
| | | ing design by appl | | | | y and modern |
| | computat | tional tools to the synt | hesis of a simple of | component or s | ystem. | |
| Expecte | ed Course O | utcome: | | | | |
| On the c | completion o | f this course the stude | nt will be able to: | | | - |
| 1. I | Design and C | Conduct experiments, | as well as analyze | and interpret d | ata | |
| Tict of | Funonimort | | | | | |
| <u>1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 </u> | Experiments | nulator design in Veri | log | | | |
| $\frac{1}{2}$ | | design in Verilog | log | | | |
| 3 | | programming- Adder, | Subtractor Multr | lexer Demultin | lexer | |
| 4 | | converter | Subtractor, marp | lexer, Demultip | ICACI | |
| 5 | | register/Universal shif | t register | | | |
| 6 | | inter/Downcounters | 8 | | | |
| 7 | FIR fi | | | | | |
| 8 | Array | multiplier | | | | |
| 9 | | Prototyping of P | ower Electronics | Converters | for Photo | ovoltaic System |
| 9 | | cation Using Xilinx S | | | | |
| 10 | | n Principles for Rapid | | | | |
| 11 | | Control Prototyping | g of Active Vil | oration Control | l Systems | in Automotive |
| 12 | | Prototyping of a Lo | w-Cost Solar Arr | ay Simulator U | Using an C | Off-the-Shelf DC |
| 12 | Power | Supply | | | | |
| 13 | Rapid | Prototyping of Minia | 1 | | | |
| | | | Total I | Laboratory Ho | urs | 60 hours |
| | ice Books | | | | | |
| 1. | | Chua, Kah Fai Lee | | Lim Rapid Pi | rototyping: | Principles and |
| 2 | | s,3rd Edition, Kindle | | A 11 .1 | D 1 - 1 | D 11 |
| 2. | Miltiadis B | oboulas, CAD-CAM | x Rapid prototypi | ng Application | Evaluation | , Bookboon |
| 3. | R. C. Cofer | Benjamin Harding , I | Rapid System Prot | otyping with F | PGAs | |
| Recomm | nended by B | oard of Studies | 10-05-2017 | | | |
| Approve | ed by Acade | mic Council | 53 th AC | Date 13- | 12-2018 | |



| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4037.1 | | | | | | | | | | | | | | | |
| | 3 | 3 | 3 | 2 | 3 | - | - | - | 1 | - | - | 1 | 3 | 1 | 3 |
| EEE4037.2 | 3 | 3 | 3 | 2 | 3 | _ | - | _ | 1 | _ | - | 1 | 3 | 1 | 3 |



| EEE4038 | Testing and Calibration Systems | L T P J C |
|-------------------|---|------------------|
| | | 0 0 2 0 1 |
| Pre-requisite | EEE4021/EEE2004 | Syllabus version |
| Anti-requisite | NIL | v. 1.0 |
| Course Objectives | | |
| 1 To explor | e the basic concepts and terminology of testing and calibration | systems |

1. To explore the basic concepts and terminology of testing and calibration systems.

Expected Course Outcome:

On the completion of this course the student will be able to:

1. Design and Conduct experiments, as well as analyze and interpret data

| 1 | Perform a comparative experimental study on Calibration of a Pressure Gauge Using a | | | | | | | | | |
|---|---|--|--|--|--|--|--|--|--|--|
| | Dead Weight Pressure Gauge Calibrator and the Digital Pressure Calibrator. | | | | | | | | | |
| 2 | Evaluate the errors and estimate the uncertainties during pressure measurement. Perform an experimental study on calibration of pressure gauge to overcome the same. | | | | | | | | | |
| 3 | Perform an experimental study on calibration of rotameter. Evaluate the same by estimation of uncertainties during flow measurement. | | | | | | | | | |
| 4 | Perform uncertainty calculations for the given Voltmeter and ammeter and calibrate the same using multifunctional calibrator system. Validate the meters for a given electrical circuit. | | | | | | | | | |
| 5 | Conduct a verification and validation of a three-phase wattmeter and a single-phase wattmeter. Perform uncertainty calculations for the same | | | | | | | | | |
| 6 | Configure and calibrate the given K-type thermocouple for measuring temperature of a kettle between 25°C to 250°C. Perform uncertainty analysis. | | | | | | | | | |
| 7 | Perform a calibration and uncertainty analysis for a given thermistor for measuring temperature of a system between 25°C to 150°C. | | | | | | | | | |
| | Conduct a verification and validation of a hygrometer for measuring humidity. Perform | | | | | | | | | |
| 8 | Conduct a verification and validation of a hygrometer for measuring humidity. Perform measurement uncertainty for the same. | | | | | | | | | |
| 8 9 | | | | | | | | | | |
| 9 | measurement uncertainty for the same. | | | | | | | | | |
| 9 | measurement uncertainty for the same.Perform an experiment for RTD and Thermocouple probe calibration. | | | | | | | | | |
| 9 10 | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours | | | | | | | | | |
| 9 10 Referenc | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours | | | | | | | | | |
| 9 10 Reference 1 | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours e Books | | | | | | | | | |
| 9 10 Reference 1 2.cti | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours e Books Calibration Handbook of Measuring Instruments by Alessandro Brunelli ,Ist Edition,ISA. ion to Measuration and Calibration by Paul.D.Q. Campbell Industrial Press Inc | | | | | | | | | |
| 9 10 Reference 1 0 2.cti 3 S | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours e Books Calibration Handbook of Measuring Instruments by Alessandro Brunelli ,Ist Edition,ISA. | | | | | | | | | |
| 9 10 Reference 1 2.cti 3 S V | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours Books Calibration Handbook of Measuring Instruments by Alessandro Brunelli ,Ist Edition,ISA. ion to Measuration and Calibration by Paul.D.Q. Campbell Industrial Press Inc Sensors and Signal Conditioning by Ramon Pallas-Areny/John.G.Webster , Second Edition, | | | | | | | | | |
| 9 10 Reference 1 2.cti 3 S V Mode of H | measurement uncertainty for the same. Perform an experiment for RTD and Thermocouple probe calibration. Conduct an experiment for torque transducer calibration and check the errors Total Laboratory Hours 30 hours e Books Calibration Handbook of Measuring Instruments by Alessandro Brunelli ,Ist Edition,ISA. ion to Measuration and Calibration by Paul.D.Q. Campbell Industrial Press Inc Sensors and Signal Conditioning by Ramon Pallas-Areny/John.G.Webster , Second Edition, Wiley India. | | | | | | | | | |

| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| EEE4038.1 | | | | | | | | | | | | | | | |
| | 3 | 3 | 3 | 3 | 3 | - | - | - | 1 | - | - | 1 | 3 | 3 | 3 |
| | 3 | 3 | 3 | 3 | 3 | - | - | - | 1 | - | - | 1 | 3 | 3 | 3 |



| | Applied Mechanics and Thermal | Engineering | L T P J C |
|--|---|---|---|
| | | 8 8 | 2 0 2 0 3 |
| Pre-requisite | NIL | `Syll | abus version |
| • | | | 2.1 |
| Course Objective | NIL Syllabus version tives: 2.1 he students to understand the principles of solid mechanics. he students with the properties of fluids and the applications. rize the students to understand the principles of thermodynamics and to get broad in its applications. e the students a gist of the theory behind the refrigeration and air conditioning sy he students to understand the principles of heat transfer. rrse Outcome: eable to he allowable loads and associated allowable stresses before mechanical failure in ypes of structures. vibrations associated with various mechanical systems. fundamental laws of thermodynamics for the analysis of wide range of namic systems. usic concepts of fluid mechanics and their applications. ate and analyze various refrigeration and air conditioning systems. teat transfer through different modes. Solid Mechanics 5 forced on systems- Un-damped and damped-Natural frequency- transverse vib cal speed by Rayleigh's and Dunkerley's method.Forced vibration-Harmonic gnification factor- Vibration isolation-Torsional vibration-Holzer's analysis. Fluid Mechanics 4 uid- Uniform and steady flow- Euler's and Bernoulli's Equations- pressure losses w measurement - Venturi meter and Orifice meters, Pipes in series and pups - classification of turbines - specific speed and lassification of pumps- characteristics and efficiency. | | |
| | | | |
| | | | |
| | | | |
| | | dynamics and to | o get broad |
| | | | |
| 5. To provide the | e students a gist of the theory behind the refrig | eration and air | conditioning system. |
| 6. To make the s | tudents to understand the principles of heat tra | inster. | |
| Europeted Course | Outcomo | | |
| Student will be ab | | | |
| Student will be ab | | | |
| 1. Evaluate the a | llowable loads and associated allowable stress | es before mech | anical failure in |
| | | | |
| • • | | stems. | |
| | | | ige of |
| | | 5 | 8 |
| • | • | ions. | |
| 5. Demonstrate a | nd analyze various refrigeration and air condi | tioning systems | |
| 6. Evaluate heat | transfer through different modes. | | |
| | | | |
| | | | |
| Modulo 1 Soli | d Machanias | | 5 hour |
| | | ionchin batwa | |
| Concept of stress | s and strain-Normal and shear stress -relat | - | en stress and strain |
| Concept of stress Elasticity- poisso | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer | nt diagrams fo | en stress and strain |
| Concept of stress Elasticity- poisso | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer | nt diagrams fo | en stress and strain |
| Concept of stress Elasticity- poisso cantilever and ove | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r | nt diagrams fo | |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r hanical Vibrations | nt diagrams fo nembers | en stress and strain- or simply supported 5 hou |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na | nt diagrams for nembers tural frequency | en stress and strain or simply supported 5 hou - transverse vibration |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. | nt diagrams for nembers tural frequency Forced vibration | en stress and strain or simply supported 5 hou - transverse vibratior n-Harmonic |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. | nt diagrams for nembers tural frequency Forced vibration | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r hanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v | nt diagrams for nembers tural frequency Forced vibration | en stress and strain or simply supported 5 hou - transverse vibratior n-Harmonic 's analysis. |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magniff Module 3 Flui | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics | tural frequency Forced vibratio | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif Module 3 Flui Properties of fluid | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernou | nt diagrams for nembers tural frequency Forced vibratio ibration-Holzer | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magniff Module 3 Flui Properties of fluid- the flow. Flow r Introduction to T | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernou neasurement- Venturi meter and Orifice m furbines and pumps - classification of tur | tural frequency Forced vibration ibration-Holzer illi's Equations neters, Pipes ir rbines - specifi | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon a series and paralle |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif Module 3 Flui Properties of fluid- the flow. Flow r Introduction to T governance. Class | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernou neasurement- Venturi meter and Orifice m furbines and pumps - classification of tur- | tural frequency Forced vibration ibration-Holzer illi's Equations neters, Pipes ir rbines - specifi | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon a series and paralle fic speed and speed |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif Module 3 Flui Properties of fluid- the flow. Flow r Introduction to 7 governance. Class Module 4 The | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernou neasurement- Venturi meter and Orifice m furbines and pumps - classification of turi ification of pumps- characteristics and efficier rmodynamic systems | tural frequency forced vibration ibration-Holzer alli's Equations neters, Pipes ir rbines - specificy. | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon n series and paralle fic speed and speed 3 hour |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif Module 3 Flui Properties of fluid- the flow. Flow r Introduction to 7 governance. Class Module 4 The Basic concepts of | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernow neasurement- Venturi meter and Orifice m Curbines and pumps - classification of turi ification of pumps- characteristics and efficier rmodynamic systems Thermodynamics - First law of thermodynam | tural frequency forced vibratio ibration-Holzer alli's Equations- teters, Pipes ir rbines - specificy. | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon a series and paralle fic speed and speed 3 hour w of thermodynamics |
| Concept of stress Elasticity- poisso cantilever and ove Module 2 Mec Single degree of fr of shafts- critical s excitation-Magnif Module 3 Flui Properties of fluid- the flow. Flow r Introduction to 7 governance. Class Module 4 The Basic concepts of | s and strain-Normal and shear stress -relat n's ratio-shear force and bending momer rhanging beams - Analysis of forces in truss r chanical Vibrations reedom systems- Un-damped and damped- Na speed by Rayleigh's and Dunkerley's method. ication factor- Vibration isolation-Torsional v d Mechanics - Uniform and steady flow- Euler's and Bernou neasurement- Venturi meter and Orifice m furbines and pumps - classification of turi ification of pumps- characteristics and efficier rmodynamic systems | tural frequency forced vibratio ibration-Holzer alli's Equations- teters, Pipes ir rbines - specificy. | en stress and strain or simply supported 5 hou - transverse vibration n-Harmonic 's analysis. 4 hou - pressure losses alon a series and paralle fic speed and spee 3 hour w of thermodynamic |



| |))))))))))))))))))))))))))))))))))))))) | iversity under section 3 of UGC | Act, 1956) | |
|------------------|---|---------------------------------|------------------|----------------------|
| Module 5 | Steam Boilers and Turbines | | | 3 hour |
| | of steam – Thermal power plant – | | | |
| Mour | ntings and accessories - Steam turbin | es: Impulse and | reaction princip | ple. |
| | | | | |
| Module 6 | Compressors, Refrigeration conditioning | and Air | | 5 hour |
| 1 | essors- Principle of operation of rec | 1 0 | 0 | 1 |
| | ons of refrigeration- Vapour Compression | 1 | ur absorption s | ystems-Principle of |
| air condition | ning system- Types and comparison. | | | |
| Module 7 | Heat Transfer | | | 3 hour |
| | als of heat transfer-conduction, con | vection and radi | iation - Free c | |
| | - Applications like cooling of electro | | | |
| | | | | |
| | Contemporary Discus | sion | | 2 hour |
| Module 8 | | 51011 | | |
| | Total hours | | 30 hour | |
| Mode Elir | ped Class Room, [Lecture to be v | ideotaned] Use | of physical c | it section models to |
| - | it to Industry, Min of 2 lectures by in | - | or physical et | at section models to |
| | xperiments | idabily enperior | | |
| | on of Engineering Stress / Strain Diag | gram on Steel roo | d, Thin and Tw | isted Bars under |
| tension. | | | , | |
| 2. Compres | sion test on Bricks, Concrete blocks. | | | |
| - | requency of longitudinal vibration of | spring mass sys | tem. | |
| | ation of torsional vibration frequenc | | | |
| | ed free vibration of equivalent spring | | | |
| | vibration of equivalent spring mass s | | | |
| 7. Flow three | ough Venturimeter | | | |
| 8. Flow three | ough Orifice Meter | | | |
| 9. Verificat | ion of Bernoulli's Apparatus | | | |
| 10. Perform | ance test on air-conditioning system | | | |
| 11. Perform | ance test on vapour compression ref | rigeration system | 1 | |
| | nsfer in natural/forced convection | | | |
| | nsfer through a composite wall. | | | |
| Mode of Ev | aluation | Continuous Ass Assignments/Q | | les CAT I, CAT II, |
| Text Book(| | | | |
| 1. R.K. F | Rajput, (2010), Thermal Engineering, | , Lakshmi Public | ations | |
| Reference | Books | | | |
| | rs and Mayhew, 'Engineering Thern ey, New Delhi, 1999. | nodynamics – W | ork and Heat T | Transfer', Addision |
| 2. B.K. | Sarkar, 'Thermal Enginerring', Tata | McGraw Hill, N | lew Delhi, 199 | 8. |
| | adal Ameen 'Refrigeration and Airco | | | |
| 4. P.K. | Nag, 'Heat Transfer', Tata McGraw | Hill 2002. | | |



| | R.K. Rajput, (2006), Strength of mater | ials (Mechani | cs of solids), | S. Chand & Company Ltd. |
|----|--|---------------------|----------------|-----------------------------|
| 5. | | | | |
| 6. | P.K. Nag, 'Basic and Applied Engin Delhi,2010. | eering Therm | odynamics', | Tata McGraw Hill, New |
| 7. | B.K. Sachdeva, 'Fundamentals of Eng International (P) Limited (2009). | ineering Heat | and Mass Tra | insfer (SI Units)', New Age |
| 8. | C.P. Arora 'Refrigeration and Air Con | ditioning', Ta | ta McGraw H | ill (2001). |
| | Recommended by Board of Studies | | 17.08.2017 | 7 |
| | Approved by Academic Council No. | 47 th AC | Date | 05.10.2017 |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| MEE1006.1 | 2 | 1 | 1 | 1 | - | - | - | - | - | - | - | - | - | - | - |
| MEE1006.2 | 2 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | - | - | - |
| MEE1006.3 | 2 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | - | - | - |
| MEE1006.4 | 2 | 1 | 1 | 1 | - | - | - | - | - | - | - | - | - | - | - |
| MEE1006.5 | 2 | 1 | 1 | 1 | - | - | - | - | 1 | - | - | - | - | - | - |
| MEE1006.6 | 2 | 1 | 1 | 1 | - | - | - | - | - | - | - | - | - | - | - |



| ECE3501 | (Deemed to be University under section 3 of UGC Act, 1956) IoT Fundamentals | L | Т | P | J | С |
|---|--|---------------|----------|-------|-------|------|
| | Job Role: SSC/Q8210 | 2 | 0 | 2 | 4 | 4 |
| Pre-requisite | NIL | | yllab | 1 | | ion |
| 1 | | ~. | <i>,</i> | | | 1.0 |
| Course Objective | 5: | | | | | |
| technologies of 2. To analyse, do 3. To explore the | owledge on the infrastructure, sensor technologies and networf IoT. esign and develop IoT solutions. e entrepreneurial aspect of the Internet of Things concept of Internet of Things in the real world scenarios | vork | ting | | | |
| Expected Course | | | | | | |
| Identify the n Program the c | y completing the course the student should be able to nain component of IoT controller and sensor as part of IoT ent Internet of Things technologies and their applications | | | | | |
| Module:1 | 2 hour | | | | | |
| | istry – An Introduction, the relevance of the IT-ITeS secto General overview of the Future Skills sub-sector | r, F i | utur | e Sk | ills | _ |
| Module:2 | Internet of Things - An Introduction: | | 3 | hou | rs | |
| Evolution of IoT a and applications ac | nd the trends, Impact of IoT on businesses and society, Ex cross industries. | istir | ng Io | T us | se ca | ises |
| Module:3 | IoT Security and Privacy: | | 6 | hou | rs | |
| | cy risks, analyze security risks, Technologies and methods tandards and regulations, Social and privacy impacts | tha | t mit | igate | e | |
| Module:4 | IoT Solutions | | 6 | hou | rs | |
| Planning for IoT Solution: Evaluate | opment, Need and Goals for IoT solution, Adoption of IoT costs, competition, technology challenges and internal reserved for stakeholder buy-in | | | ıs, | | |
| Module:5 | Prototyping the Pilot execution: | | 5 | hou | rs | |
| | ng Stages, deploy real-time UI/UX visualizations, Method y business outcomes, feedback and data obtained from exe | | | etric | s to | |
| Module:6 | Scalability of IoT Solutions: | | 5 | hou | rs | _ |
| | loping complete IoT solutions, Strategies for implementati Solutions, Methods, platforms and tools. Web and Mobile | | | | stor | ie, |
| Module:7 | Build and Maintain Relationships at the Workplace, Team Empowerment | | | hou | rs | |



| Total Lecture h | ours: | | | 30 hours |
|---|--------------------|-------------|------------------|------------|
| Text Book(s) | | | | |
| 1. Arshdeep Bahga, Vijay Madisetti University Press, 2015. | | - | | |
| 2. Adrian McEwen & Hakim Cassin 2013, (1 st edition) | nally, "Designing | the Interne | et of Things", V | Viley,Nov |
| Claire Rowland, Elizabeth Gooda Designing Connected Products: U edition),2015 | | | | |
| Reference Books | | | | |
| 1. Rethinking the Internet of things: Francis daCosta, Apress, 2014 | A Scalable Appro | bach to Co | nnecting Every | thing by |
| 2. Learning Internet of Things by P | eter Waher, Packt | Publishing | , 2015 | |
| 3. Designing the Internet of Things, Private Limited | , by Adrian Mcewe | en, Hakin (| Cassimally , W | iley India |
| 4. Cloud Computing, Thomas Erl, H | Pearson Education, | 2014 | | |
| 5. Foundations of Modern Network Stallings, Addison-Wesley Profe | 0 | oE, IoT, a | nd Cloud, Will | liam |
| 6. https://nsdcindia.org/sites/default/ T- Domain%20Specialist_09.04. | _ | 210_V1.0_ | Io | |
| List of Experiments | | | | |
| 1. Measure the light intensity in th | | | | |
| 2. Control your home power outle | - | | • • | |
| 3. Build a web based application to recognition. | o automate door th | at unlocks | itself using fac | cial |
| 4. Drinking water monitoring and | analytics consists | of IoT dev | vice cloud and | mobile and |
| web app. | | 01 101 401 | ice, eloud, und | inoone una |
| 5. Smart Parking System | | | | |
| 6. IoT based Healthcare applicatio | n | | | |
| 7. Real-time environmental monit | oring and weather | prediction | | |
| 8. Traffic pattern prediction | | | | |
| 9. Smart Street light | | | | |
| 10. Plant health monitoring | | | | 1 |
| | | Total Lab | oratory Hours | 30 hours |
| Recommended by Board of Studies | | | | |
| Approved by Academic Council | | | | |

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| CO | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ECE3501.1 | 3 | 2 | 2 | 2 | 1 | - | - | - | 2 | - | - | 1 | 3 | 2 | 3 |
| ECE3501.2 | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | - | - | 1 | 3 | 2 | 2 |
| ECE3501.3 | 3 | 3 | 3 | 3 | 2 | - | - | - | 2 | - | - | 1 | 2 | 2 | 2 |
| | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | - | - | 1 | 3 | 2 | 2 |



| ECE3502 | (Deemed to be University under section 3 of UGC Act, 1956) IoT Domain Analyst | L | Т | P | T | C |
|---|---|--|----------------------------|---------------|----------------------|------|
| | Job Role: SSC/Q8210 | 2 | 0 | 2 | J | 4 |
| Pre-requisite | JUD KUIC, DDV/Q0410 | Z Sylla | - | _ | - | |
| | | Syna | | - 1 BI | | 1.0 |
| Course Objectives: | <u>ا</u> ا | | | | | |
| of IoT. 2. To analyse, desig 3. To explore the end | ledge on the infrastructure, sensor technologies and ne gn and develop IoT solutions. ntrepreneurial aspect of the Internet of Things neept of Internet of Things in the real world scenarios | etworki | ng te | chno | olog | les |
| Expected Course (| | | | | | |
| Identify the n Program the c | y completing the course the student should be able to nain component of IoT controller and sensor as part of IoT ent Internet of Things technologies and their applicatio | ons | | | | |
| Module:1 | IoT Solution Models: | | 3 h | our | | |
| Models applied in I models, information categories. | oT solutions, Semantic models for data models, Appli n models, information models to structure data, relation | cation of the second se | of ser betwe | nant een c | ic lata | |
| Module:2 | Data Models : | | 3 ho | ours | | |
| Tags to organize dat Application of pred | ta, tag data to pre-process large datasets, predictive mo ictive models. | odels fo | r fore | ecas | ting, | ' |
| Module:3 | Simulation Scenarios: | | 4 ha | ours | | |
| reuse existing IoT s | real-world scenarios, Application of the models, stage olutions, reusability plan. | s of da | | | le, | |
| Module:4 | Use Case Development | | 4 ho | | | |
| | er business requirements, defining problem statements oment, Assets for development of IoT solutions. | , busin | ess re | equi | reme | ents |
| Module:5 | Value engineering and Analysis: | | 4 ho | ours | | |
| IoT solutions, cost- Value Engineering, | es of Value Engineering and Analysis, Frameworks fo function analysis of IoT solution components, actio Data modelling requirements, Development model nonetization models for IoT use cases - 'Outcomes As Data Analytics for IoT Solutions: | n plans s: Wate | s to i erfall ice' i | incoi , Ag | rpor gile, el. | |
| | ta gathering, Data Pre-processing, data analyzation, ap orithms, Exploratory Data Analysis. | oplicati | on of | ana | lytic | cs, |
| 1 0 | Deployment of Analytics Solutions | | 6 | hou | irs | |
| | and Data Clustering, Predictive Analytics and Stream s, integrating analytics models, performance of analytic riving insights. | | | | plat | es |
| | Total Lecture hours: | | 30 |) ho | urs | |
| Text Book(s) | | | | | | |



| | (Deeme | d to be University under section 3 of | UGC Act, 1956) | |
|--------|--|---------------------------------------|----------------|-----------------------------|
| 1. | Arshdeep Bahga, Vijay Madisett University Press, 2015. | i, "Internet of Thi | ngs: A han | ds-on Approach", |
| 2. | Adrian McEwen & Hakim Cassi 2013, (1 st edition) | mally, "Designing | the Intern | et of Things", Wiley,Nov |
| 3. | Claire Rowland, Elizabeth Good Designing Connected Products: edition),2015 | | | |
| Refere | nce Books | | | |
| 1. | Rethinking the Internet of things Francis daCosta, Apress, 2014 | : A Scalable Appro | oach to Co | onnecting Everything by |
| 2. | Learning Internet of Things by P | eter Waher, Packt | Publishing | g, 2015 |
| | Designing the Internet of Things Private Limited | | | |
| 4. | Cloud Computing, Thomas Erl, l | Pearson Education | , 2014 | |
| 5. | Foundations of Modern Network Stallings, Addison-Wesley Profe | 0 | QoE, IoT, a | and Cloud, William |
| 6. | https://nsdcindia.org/sites/default Specialist_09.04.2019.pdf | /files/MC_SSCQ8 | 210_V1.0 | IoT- Domain %20 |
| | Experiments | | | |
| | Measure the light intensity in th | | | |
| | Control your home power outle | | | |
| 3. | Build a web based application to recognition. | o automate door th | at unlocks | itself using facial |
| 4. | Drinking water monitoring and web app. | analytics, consists | of IoT dev | vice, cloud, and mobile and |
| 5. | Smart Parking System | | | |
| 6. | IoT based Healthcare applicatio | n | | |
| 7. | Real-time environmental monitor | oring and weather | prediction | |
| 8. | Traffic pattern prediction | - | - | |
| 9. | | | | |
| 10 | . Plant health monitoring | | | |
| | | 1 | Total Lab | boratory Hours 30 hours |
| | mended by Board of Studies | | | |
| Approv | ed by Academic Council | | Date | |
| | | | - | |

| СО | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
|-----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|
| ECE3502.1 | 3 | 2 | 2 | 2 | 2 | - | - | - | 2 | - | - | 1 | 3 | 2 | 3 |
| ECE3502.2 | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | - | - | 1 | 3 | 2 | 2 |
| ECE3502.3 | 3 | 3 | 3 | 3 | 2 | - | - | - | 2 | - | - | 1 | 2 | 2 | 2 |
| ECE3502.4 | | | | | | | | | | | | | | | |
| | 3 | 3 | 2 | 2 | 2 | - | - | - | 2 | - | - | 1 | 3 | 2 | 2 |